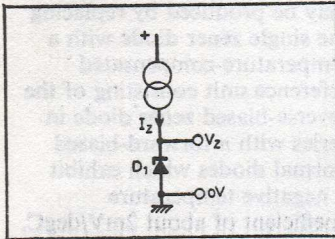


### Zener diode characteristics

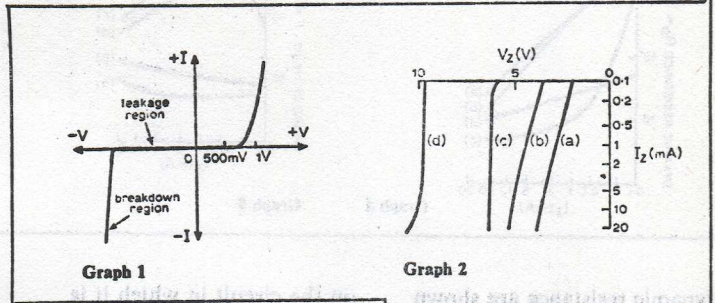


**Performance (see graphs)**  
 Constant current source:  
 0-20mA from commercial  
 generator,  $\pm 0.05\%$ .  
 $V_Z$  measured with 5-digit d.v.m.  
 D<sub>1</sub> (a) BZX83C3V3  
 (b) BZX83C4V7  
 (c) BZX83C6V2  
 (d) BZX83C10.

#### Description

The zener diode exhibits three distinct regions: forward, leakage and breakdown. The forward-bias region is virtually identical with a normal diode, the forward-voltage temperature coefficient for a constant forward current being about  $-1.4$  to  $-2.0\text{mV/degC}$ . Under reverse bias, up to the breakdown region, a leakage current exists which, although being temperature dependent, is

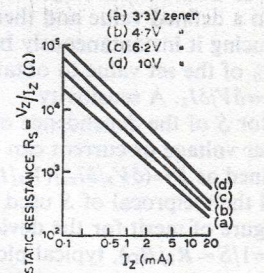
normally less than  $1\mu\text{A}$  over the whole temperature range. When the reverse bias reaches some definite value, which depends on the p-n junction doping levels, the diode current rapidly increases and the breakdown or zener region has been reached. This region is the one used to provide a d.c. reference voltage by supplying the device from a constant-current source, as shown above left. At the onset



Graph 1

Graph 2

of breakdown the resistance of the zener diode will be high but as the current increases the number of breakdown sites increases and the resistance falls to a small value. The reverse-breakdown characteristics for several zener diodes are shown at upper right, and their corresponding typical plots of static resistance as a function of zener current are shown lower right. The corresponding plots of slope or

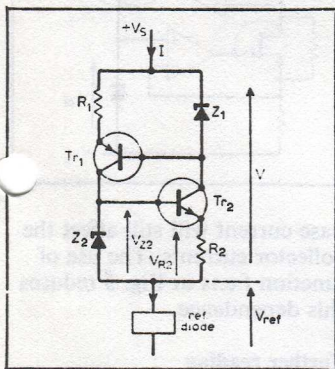


Graph 3

# wireless world circard

## Set 23: Reference circuits—2

### Williams ring-of-two reference



#### Circuit description

This circuit may be used to supply a constant current to a high capability reference diode, which is itself used as the voltage reference source. If it is assumed that diode  $Z_2$  provides a constant voltage at the base of transistor  $Tr_2$ , then this forces a constant current to flow through the emitter

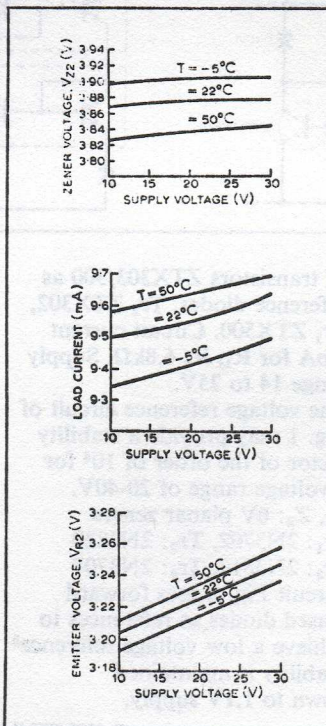
#### Typical data

$Tr_1$ : BC126,  $Tr_2$ : BC125  
 $Z_1, Z_2$ : BZY88 (3.9V)  
 $R_1, R_2$ :  $680\Omega$

For test requirement, I was determined by measuring voltage across a standard resistance  $50\Omega \pm 0.05\%$  with a 5 digit voltmeter. Temperature levels obtained in a controlled oven.

Minimum  $V_S \approx 10\text{V}$ .

resistor  $R_2$ . For reasonably high gain transistors, the collector-current will almost equal the emitter current, and hence the current through  $Z_1$  will be constant. But this diode will maintain a constant potential at the base of transistor  $Tr_1$ , which in turn forces a constant current through  $R_1, Tr_1$  to operate the



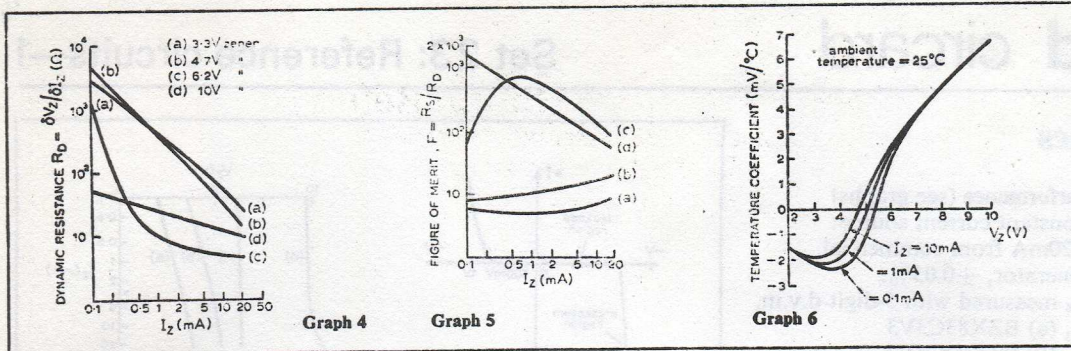
original diode  $Z_2$ , which was initially assumed to provide a stable voltage. The total current drawn by the circuit is approximately the sum of the collector currents and is substantially constant.

An increase in the supply voltage  $V_S$  largely appears between the collector and emitter of the transistors. At  $22^\circ\text{C}$ , change in  $V_{Z2}$  6.4mV change in  $V_S$  20V  
 Stability  $\Delta V_S / \Delta V_{Z2} \approx 3300$   
 At  $V_S = 20\text{V}$ ,  $\Delta V_{Z2} = +84\text{mV}$  for overall temperature change from  $50^\circ\text{C}$  to  $-5^\circ\text{C}$ .

Temperature coefficient is  $-1.5\text{mV/degC}$ .

Note that the graph plots are obtained from a circuit using unselected diodes, and no attempt was made at temperature compensation. Maximum supply voltage allowable will depend on permitted  $V_{CE}$  of transistors.





dynamic resistance are shown above, extreme left. The curves were obtained by setting  $I_Z$  to a defined value and then reducing it instantaneously by 20% of the set value to obtain  $R_D = \delta V / \delta I_Z$ . A sensitivity factor  $S$  of the dependence of zener voltage or current can be defined as  $S = (\delta V_Z / \delta I_Z) / (V_Z / I_Z)$  and the reciprocal of  $S$  used as a figure of merit for the device ( $F = 1/S = R_S / R_D$ ), typical plots being as shown above, centre left. This figure of merit refers to the device only and will be degraded to a degree dependent

on the circuit in which it is used and the zener current flowing. These figures may be used to assess the ability of the circuit to maintain a desired reference voltage against supply variations. Thus, if  $I_Z$  changes by  $x\%$  due to supply variation the reference voltage will change by approximately  $(x/F)\%$  if the current source resistance is much larger than that of the zener diode. This would indicate the use of high-voltage supplies and high-voltage zener diodes operated at relatively low current levels.

However, high voltages are not necessarily available and a compromise must normally be made between wasted volts and required stability of the reference voltage. Often the stability of the reference voltage against temperature changes is of prime importance and the choice of zener diode will depend on its temperature coefficient. Typical plots at room temperature are shown above centre right which indicate the use of diodes having a breakdown voltage of about 5V. Note that all these

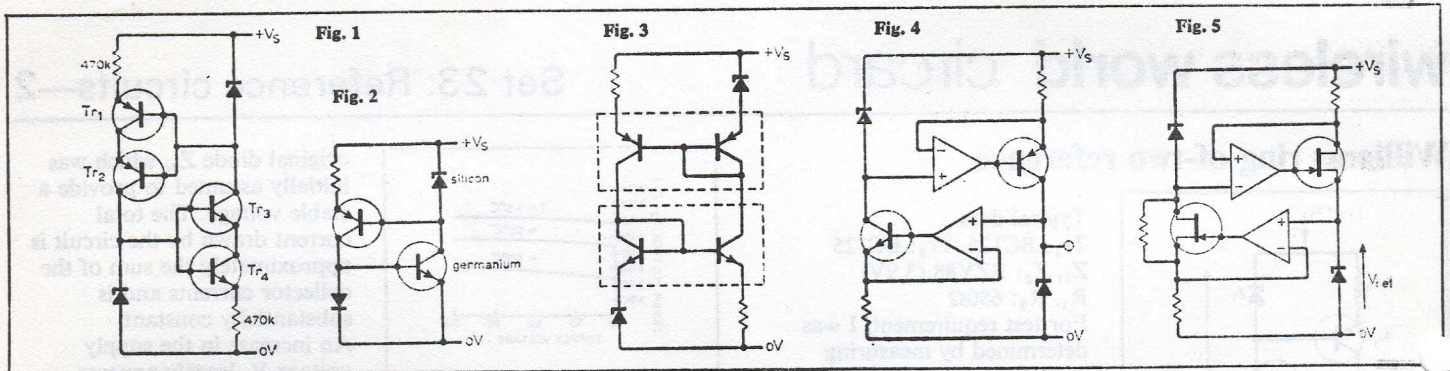
curves indicate that a positive temperature coefficient may be a distinct advantage as all the curves merge at a temperature coefficient exceeding about  $+4mV/degC$ . Thus a temperature-stable reference may be produced by replacing the single zener diode with a temperature-compensated reference unit consisting of the reverse-biased zener diode in series with  $n$  forward-biased normal diodes which exhibit a negative temperature coefficient of about  $2mV/degC$ . If the zener diode has, for example, a temperature coefficient of  $+6mV/degC$  it could be series-connected with three forward-biased diodes.

**Further reading**

Patchett, G. N. Automatic Voltage Regulators and Stabilizers, 3rd edition, chapter 6, Pitman, 1970.  
Buchanan, J. K. et al. Zener Diode Handbook, Motorola 1967.

**Cross references**

Set 23, cards 2, 3, 4



For  $V_S = 20V, I = 0.224mA$  for  $T = 55°C$ .

$\Delta I / \Delta T \approx 4\mu A / degC$   
At  $22°C, \Delta V_S = 20V,$   
 $\Delta I = 128\mu A$   
 $\Delta I / \Delta V_S \approx 4\mu A / V$

Percentage change  $\approx +1.3\%$   
Note. If self-starting difficulties arise, a resistor between bases or resistors across collector-emitter terminals may be used.

**Circuit modifications**

Stabilization ratio  $\Delta V_S / \Delta V_Z$  of  $10^5 : 1$  is claimed for the circuit (Ferranti) using reverse biased base-emitter junctions

of transistors ZTX303/300 as reference diodes.  $Tr_2$  ZTX302,  $Tr_1$  ZTX500. Circuit current  $1mA$  for  $R_1, R_2$   $6.8k\Omega$ . Supply range 14 to 25V.

The voltage reference circuit of Fig. 1 may provide a stability factor of the order of  $10^6$  for a voltage range of 20-40V.

$Z_1, Z_2$ : 6V planar zeners  
 $Tr_1$ : 2N3702,  $Tr_2$ : 2N3820  
 $Tr_3$ : 2N3819,  $Tr_4$ : 2N3707

Circuit Fig. 2 uses forward biased diodes as references to achieve a low voltage reference<sup>2</sup>. Stability is maintained down to 1.1V supply.

Temperature change compensation is obtained by matching forward voltage drift on the silicon diode against that of base-emitter junction of germanium transistor. The circuit of Fig. 3 includes diode connected transistors to offset the base-emitter voltage variation with temperature<sup>1</sup>. As temperature also affects the transistor common emitter current gains, this effect is minimized by feeding these via op-amps<sup>1</sup>. Notice in Fig. 4 current feedback is to inverting inputs. Also slight variations in

base current will still affect the collector currents. The use of junction f.e.t.s in Fig. 5 reduces this dependence.

**Further reading**

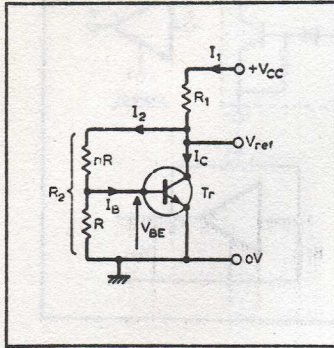
Williams, P. Ring-of-two reference, *Wireless World*, July 1967. See also *Proc. IEEE*, January 1968.

**References**

1. Applied Ideas, *Electronic Engineering*, December 1974.
2. Williams, P. Low-voltage ring of two reference, *Electronic Engineering*, November 1967.



### Variable reference diodes

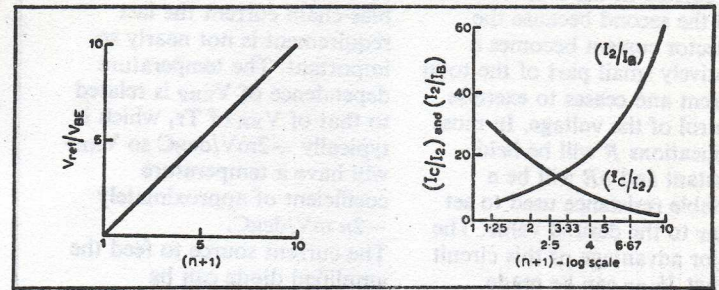


**Typical performance**  
 $+V_{cc}: +15V$   
 $R_1: 4.7k\Omega \pm 5\%$ ,  $R_2: 10k\Omega$   
 multiturn  $\pm 1\%$ , linearity  
 $\pm 0.1\%$   
 $Tr_1: BC125$   
 Currents for  $n=1$  condition  
 $I_1: 2.91mA$ ,  $I_C: 2.77mA$   
 $I_2: 144.6\mu A$ ,  $I_B: 16\mu A$   
 (see graph opposite)  
 Voltages for  $n=1$  condition  
 $V_{BE}: 644mV$ ,  $V_{REF}: 1.371V$   
 (see graph opposite)

#### Description

Although the zener diode is the most common device used to produce a stable reference voltage, they may be replaced by any device, combination of devices or circuit that behaves as a two-terminal element having a stable p.d. across it and some internal resistance.

Like the zener diode, such elements can normally only produce a definable, fixed reference. Many instances arise, especially under laboratory conditions, where a variable reference voltage is required and which has a range of required values that are not necessarily available from a

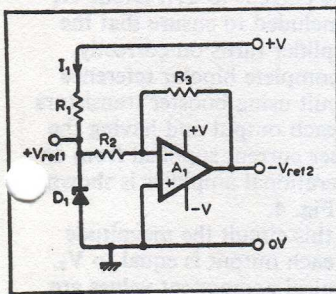


single device or a combination of devices.

The circuit shown above left is an example of a simple d.c. reference which can often meet these requirements. If the transistor is assumed to have infinite current gain,  $I_B$  tends to zero, and the current  $I_2$  in  $R_2$  will produce p.d. across  $R$  and  $nR$  proportional to the p.d.s across them. The p.d. across  $R$  is  $V_{BE}$ , which is dependent on the transistor current, and the p.d. across

resistor  $nR$  will be  $n$  times that across  $R$ , i.e.  $nV_{BE}$ . Hence, the reference voltage will be  $V_{BE} + nV_{BE} = (n+1)V_{BE}$ . Since the factor  $(n+1)$  cannot be less than unity the circuit is normally referred to as the amplified diode or the  $V_{BE}$  multiplier. In practice most commonly-available transistors have sufficiently high current gain to allow predictable performance. Departure from the ideal condition of  $V_{REF} = (n+1)V_{BE}$  will occur at both

### Bipolar references

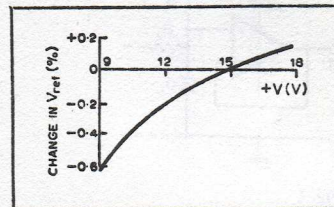


**Typical performance**  
 Supply:  $\pm 15V$ ,  $+3.4mA$ ,  
 $-1.8mA$   
 $A_1: 741$ ;  $D_1: BZX830, 6.2V$   
 $R_1: 4.7k\Omega \pm 5\%$   
 $R_2, R_3: 22k\Omega \pm 5\%$   
 $I_1: 1.94mA$   
 $V_{REF1}: V_z + 6.16V$   
 $-V_{REF2}: -6.20V$

#### Circuit description

The reference element is the zener diode  $D_1$ , the basic reference circuit consisting of  $R_1$  and  $D_1$  in series, the current in  $D_1$  being determined by  $R_1$  for a given positive supply voltage. In the above arrangement the positive supply to the zener is, for, convenience, made the same as that provided for the operational

amplifier  $A_1$ . The reference voltage  $V_{REF1}$ , which is positive and equal to the zener voltage, is fed to the inverting operational amplifier so that  $V_{REF2} = -V_{REF1}R_3/R_2$ . Thus, with  $R_3 = R_2$ , a simple bipolar reference circuit is obtained with outputs having the same voltage magnitude. In the experimental arrangement, the resistors were  $\pm 5\%$  tolerance



types which were not selected for equality resulting in  $V_{REF2} = -1.0065V_{REF1}$ . A close match between the reference voltages can be obtained by carefully matching  $R_3$  and  $R_2$ . Note that whilst  $V_{REF1}$  is fixed for a given zener diode and choice of supply and component values,  $-V_{REF2}$  may be varied over a wide range by adjusting the ratio  $R_3/R_2$ . However, the values of these resistors should not be so small as to appreciably load  $V_{REF1}$ . The negative reference voltage output can be much more heavily loaded than the

$V_{REF1}$  output, since the former is available from the low-output-resistance operational amplifier. The change in the values of the reference voltages with temperature changes are essentially due to the zener diode characteristics, since the operational amplifier drift is very small in comparison and with  $R_3 = R_2$  the resistor temperature coefficients match to maintain a unity gain inversion of  $V_{REF1}$ .

#### Circuit modifications

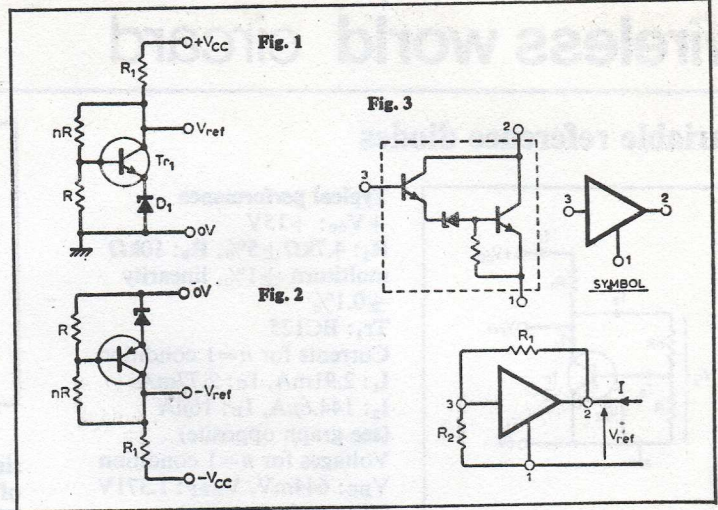
To allow the  $V_{REF1}$  output to be more heavily loaded an operational amplifier voltage follower may be added to the basic circuit as shown in Fig. 1; this reference then being available from a low-output-resistance source.

Although this arrangement makes the current in the zener diode independent of the load currents taken from the



high and low current levels, the first because  $I_B$  eventually becomes an appreciable part of the current in the bias resistors and the second because the collector current becomes a relatively small part of the total current and ceases to exercise control of the voltage. In most applications  $R$  will be held constant and  $nR$  will be a variable resistance used to set  $V_{REF}$  to the desired value. The major advantage of this circuit is that  $V_{REF}$  can be made almost any number of times greater than  $V_{BE}$  including non-integral values. The graphs shown overleaf show the linearity obtainable in practice between desired value of  $(n+1)$  and actual value of  $(V_{REF}/V_{BE})$  up to  $(n+1)=10$ . This graph was obtained by keeping  $R_2$  fixed, by using a potentiometer, and varying the ratio of  $nR$  to  $R$ . The second graph overleaf shows the corresponding ratios of collector current to bias-chain current and bias-chain current to base current. Whilst the design aim should be to

keep the bias-chain current much greater than the base current and the collector current much greater than the bias-chain current the last requirement is not nearly so important. The temperature dependence of  $V_{REF}$  is related to that of  $V_{BE}$  of  $Tr_1$  which is typically  $-2mV/degC$  so  $V_{REF}$  will have a temperature coefficient of approximately  $-2n mV/degC$ . The current source to feed the amplified diode can be realized by a current mirror so that three transistors in an i.c. transistor array may be used. At the expense of raising the lower limit of  $V_{REF}$  a zener diode with a suitably chosen positive temperature coefficient can be included in series with the emitter as shown in Fig. 1. To provide a negative, variable reference voltage a p-n-p transistor and zener diode are connected as shown in Fig. 2. Circuits of the amplified diode type are available in monolithic, integrated circuit form which can be operated



over a wide range of voltages and currents and which have a definable temperature coefficient. An example of this form is the General Electric D13V which is a combination of a Darlington-type transistor pair and a zener diode. The internal circuitry and normal connection arrangements are shown in Fig. 3.

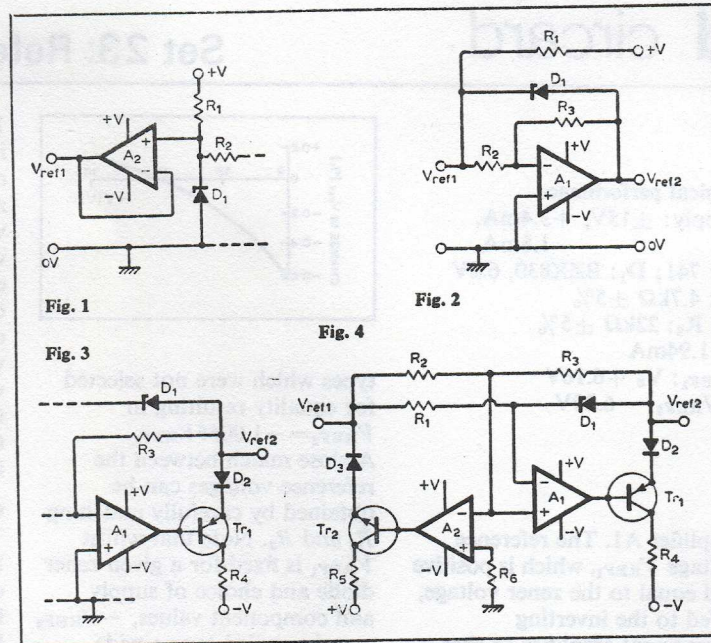
**Further reading**  
Williams, P. The Amplified Diode, *Design Electronics* January 1968, pp. 32-4. General Electric D13V data sheet, 1970.

**Cross references**  
Set 6, card 4  
Set 23, cards 1, 6  
Set 7, card 8

© 1975 IPC Business Press Ltd

$V_{REF1}$  and  $V_{REF2}$ , the zener current is still subject to variations in the positive supply rail voltage. Since an operational amplifier is a device which provides an output voltage that is inherently isolated from supply rail variations, the circuits above can be improved by supplying the direct voltage to  $R_1$  from an operational amplifier instead of directly from the supply rail.

Irrespective of how the zener diode is supplied, its operating current may be more precisely defined and made independent of loading by placing the zener diode in the feedback path of an operational amplifier. This technique also allows the ability to provide a pair of opposite-polarity reference voltages having a summation equal to the zener voltage, including the particular case where they have equal magnitude. The basic form is shown in Fig. 2. In this circuit  $R_1$  again supplies the current to  $R_2$  and



$R_3$  as well as the zener diode current. Since the junction of  $R_2$  and  $R_3$  is a virtual earth, the output voltages are given by  $V_{REF1} = V_z R_2 / (R_2 + R_3)$  and  $V_{REF2} = -V_z R_3 / (R_2 + R_3)$  so

with  $R_2 = R_3$ ,  $V_{REF2} = -V_{REF1} = V_z / 2$ . The operational amplifier must be capable of sinking all currents except the load current at the  $V_{REF1}$  output. If the operational

amplifier is to be an inexpensive type a transistor current booster can be added as shown in Fig. 3. The operational amplifier now only has to supply the base current to  $Tr_1$ . Diode  $D_2$  is included to ensure that the amplifier turns on correctly. A complete bipolar reference circuit using booster transistors at each output and having the zener current supplied from an operational amplifier is shown in Fig. 4.

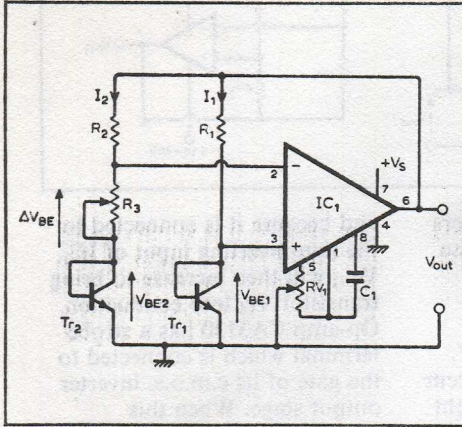
In this circuit the magnitude of each output is equal to  $V_z$ . Typical component values are  $\pm V: \pm 15V$ ,  $A_1, A_2: 301A$ ,  $Tr_1: 2N3964$ ,  $Tr_2: 2N2222$ ,  $D_1: 1N829$  (6.2 volt zener),  $D_2, D_3: 1N914$ ,  $R_2, R_3: 6.2k\Omega$ ,  $R_1: 826\Omega$ ,  $R_4, R_5: 300\Omega$ ,  $R_6: 3.1k\Omega$

**Further reading**  
Miller, W. D. & DeFreitus, R. E. Op.amp. stabilizes zener diode in reference-voltage source, *Electronics*, Feb. 2, 1975 pp. 101-5.

© 1975 IPC Business Press Ltd



### Low temperature coefficient voltage reference



**Typical data**  
 Tr<sub>1</sub>, Tr<sub>2</sub>: Matched pair or  $\frac{2}{3}$  CA3086.  
 IC<sub>1</sub>: CA3130AT  
 R<sub>1</sub>: 4.7k $\Omega$ , R<sub>2</sub>: 47k $\Omega$ , R<sub>3</sub>: 10k $\Omega$  (variable)  
 RV<sub>1</sub>: 100k $\Omega$   
 C<sub>1</sub>: 1000pF  
 V<sub>S</sub>: +10V  
 At ambient temperature:  
 V<sub>out</sub> = 600mV + 10.(26mV)(2.3) = 1200mV

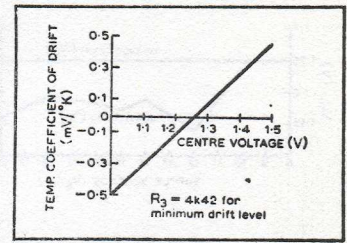
**Circuit Description**  
 Transistors Tr<sub>1</sub> and Tr<sub>2</sub> have identical parameters and hence equal saturation currents whose ratio is therefore temperature independent. The op-amp gain may be considered infinite and therefore the

potentials of terminals 2 and 3 can be considered equal, for a finite output, V<sub>out</sub>.

$$V_{out} = V_{BE1} + I_2 R_2 = V_{BE1} + \Delta V_{BE} R_2 / R_3$$

It is arranged by choice of R<sub>1</sub> and R<sub>3</sub>, that I<sub>1</sub> is about ten times R<sub>2</sub>.

Since  $V_{BE} = (KT/q) \ln(I/I_s) + 1$  and  $V_{BE} = V_{BE1} - V_{BE2}$ , then  $V_{out} = V_{BE1} + (R_2/R_3) \cdot (KT/q) \ln(I_1 + I_{S1}/I_2 + I_{S2}) \cdot I_{S2}/I_{S1} = V_{BE1} + (R_2/R_3) \cdot (KT/q) \ln(R_2/R_1)$  because I<sub>1</sub>/I<sub>2</sub> is in the ratio of R<sub>2</sub>/R<sub>1</sub> and I<sub>S2</sub> = I<sub>S1</sub>. For R<sub>2</sub>/R<sub>1</sub> = 10, then V<sub>out</sub> is approximately defined at 1.2V at room temperature, for R<sub>2</sub>/R<sub>3</sub> = 10. See typical data. The base emitter junction voltage is also approximately given by  $V_{g0} - CT$  where V<sub>g0</sub> is gap energy voltage at 0 K and C is a constant. When the negative temperature coefficient of V<sub>BE1</sub> and the positive temperature coefficient of the second term above, cancel, then V<sub>out</sub> = V<sub>g0</sub>, and is then essentially temperature independent. Quoted value at 300K for V<sub>out</sub> is 1.236V. Although the op-amp used in this circuit has temperature drift in excess of bipolar op-amp, it has the advantage

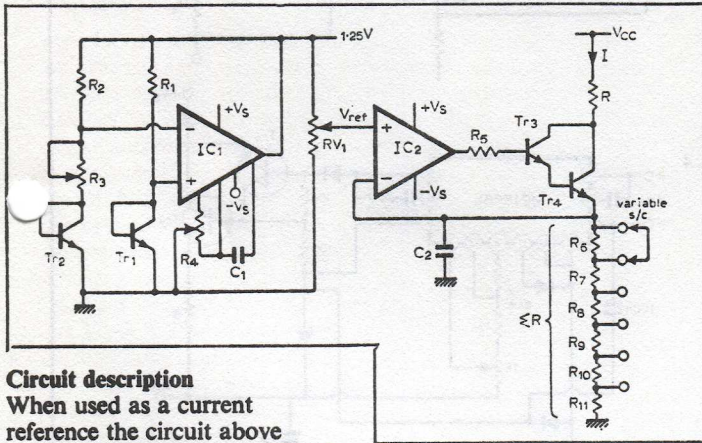


of operating from a single-ended supply and provides the facility of strobing such that a pulsed output is clamped between 0V (due to the c.m.o.s. output stage) and the temperature independent reference level. Centre voltage is the value at ambient, adjusted by R<sub>3</sub>. Temperature range imposed on transistor package was +70° to -30°. Minimum drift obtained at V<sub>out</sub> ≈ 1.25V.

**Component changes**  
 Supply voltage: 10V-19V maximum. Change in

# wireless world circard

### μA—mA/mV—V calibrator

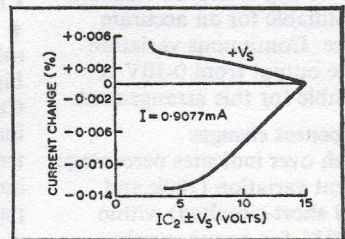
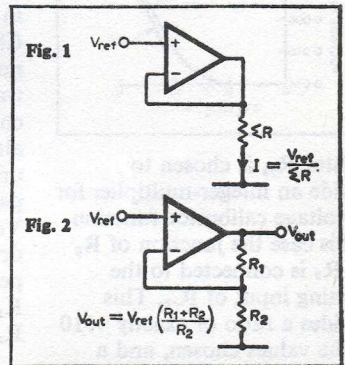


**Circuit description**  
 When used as a current reference the circuit above simplifies to Fig. 1, and as a voltage reference, Fig. 2 shows the relationship between the output voltage and the input reference. The potential difference between the inverting and non-inverting inputs of IC<sub>2</sub> is very small for a high gain amplifier used in this

negative feedback mode, and hence V<sub>ref</sub> appears across the resistor chain R<sub>6</sub> to R<sub>11</sub>. The current drawn from the V<sub>cc</sub> supply depends on V<sub>ref</sub>/R, giving for the above values, a range from about 10μA to a safe maximum of 10mA

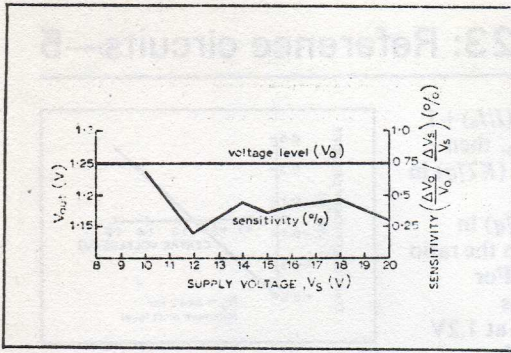
**Typical data**  
 Supply: ±10V, IC<sub>1</sub>: 3130AT  
 IC<sub>2</sub>: 741, Tr<sub>1</sub> to Tr<sub>4</sub> use CA3086  
 R<sub>1</sub>: 4.7k $\Omega$ , R<sub>2</sub>: 481 $\Omega$ , R<sub>3</sub>: 10k $\Omega$  pot.  
 R<sub>4</sub>: 100k $\Omega$ , R<sub>5</sub>: 1k $\Omega$ , R<sub>6</sub>: 100k $\Omega$   
 R<sub>7</sub>: 10k $\Omega$ , R<sub>8</sub>: 1k $\Omega$ , R<sub>9</sub>: 100 $\Omega$   
 R<sub>10</sub>: 10 $\Omega$ , R<sub>11</sub>: 1.11 $\Omega$ , RV<sub>1</sub>: 10k $\Omega$   
 C<sub>1</sub>: 1nF, C<sub>2</sub>: 10μF tantalum  
 R: variable load. For measurement, standard resistance used ( $\pm 0.05\%$ ) and five digit digital voltmeter across R.  
 V<sub>ref</sub>: Adjusted for 1.000V

(approx.) if R<sub>6</sub> - R<sub>8</sub> are shorted. Operation is such that if I did tend to increase, the voltage across R increases, which would thus tend to increase the voltage applied to the non-inverting terminal of IC<sub>2</sub>. This will reduce base drive to transistor Tr<sub>3</sub> and compensate for the assumed increase. Different values of current are



achieved by varying RV<sub>1</sub> in association with varying the shorting points across R.





$V_{out} = 0.75\%$ .  
Op-amp has heavy negative feedback and hence output impedance is low. This allows full current capability of op-amp to be drawn.

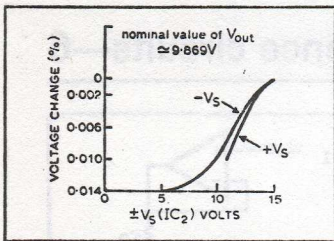
Typically:  
 $I_{out} = 0$ ,  $V_{out} = 1.251V$   
 $I_{out} = 10mA$ ,  $V_{out} = 1.249V$   
Maximum  $I_{out} = 22mA$ .  
Percentage sensitivity graph based on initial supply voltage  $V_s = +9V$ . Effective over load current range 0 to 20mA.  
Bipolar-op-amp using positive and negative power supplies would improve overall drift, once offset is nulled.

Increasing  $R_1$  to 10k,  $R_2$  to 100k demands  $R_3$  increased to 9k to maintain same reference level: i.e. values not too critical provided same ratio maintained.

**Circuit modification**  
Transistors can be series connected to increase available reference voltage—see middle right e.g. eight diodes per chain will provide output  $\approx 10V$  (Ref. 1). This will also allow a bipolar op-amp to be used from a single-ended supply because the inputs are held well above ground potential.

Certain operational amplifiers will operate with inputs close to the most positive supply rail. This permits the dual configuration on diagram extreme right.  $V_{out} - 1.25V$ . If self-starting difficulties occur the circuit shown middle right can be used. When the supply is switched on, the output of  $IC_1$  may remain at zero volts and hence there is no supply for transistors  $Tr_1$  and  $Tr_2$ . With the addition of diode  $D_1$  and transistor  $Tr_3$ ,  $D_1$  will conduct if  $V_{out}$  is low and  $Tr_3$  is therefore off. This means the collector of  $Tr_1$  will rise

and because it is connected to the non-inverting input of  $IC_1$ ,  $V_{out}$  will then increase to bring transistor  $Tr_3$  into conduction. Op-amp CA3130 has a strobe terminal which is connected to the gate of its c.m.o.s. inverter output stage. When this terminal is connected to  $V_s$  via an external gating network, e.g.  $\frac{1}{2}$  CD4007, the pulsed reference facility is obtained.  
**Further reading**  
1. Kuijk, K. E. A precision reference voltage source. IEEE Journal of Solid State Circuits, Vol. SC-8, No. 3, June 1973.



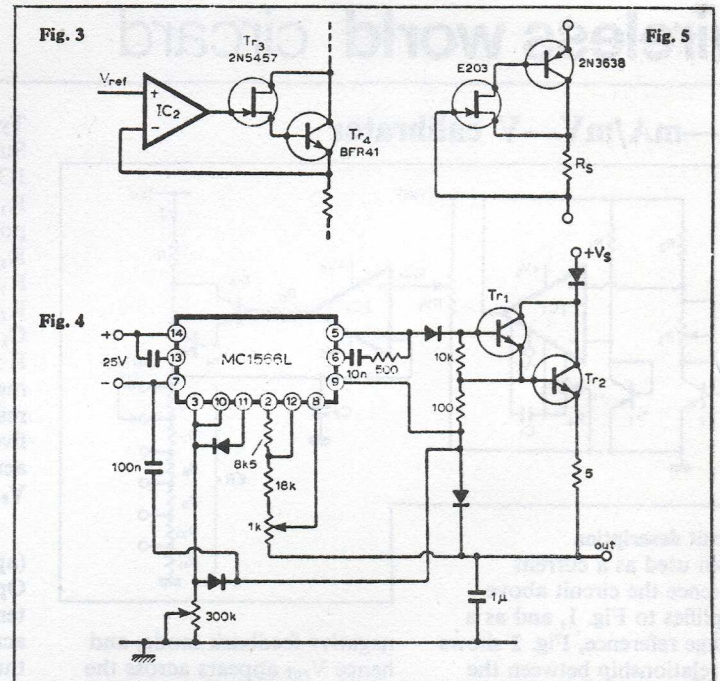
Resistor  $R_{11}$  is chosen to provide an integer-multiplier for the voltage calibrator function. In this case the junction of  $R_6$  and  $R_7$  is connected to the inverting input of  $IC_2$ . This provides a ratio of exactly  $\times 10$  for the values chosen, and a case for 1% tolerance resistors is justifiable for an accurate source. Continuous variation of the output from 0-10V is available for this arrangement.

**Component changes**  
Graph over indicates percentage current variation (100k and 10kΩ short-circuited) within  $\pm 0.01\%$  for power supply variations of  $IC_2$  up to 50% in  $\pm V_s$ .  
Range of  $V_s$  3.5 to 20V for above setting. Minimum value

depends on current required and load R.  
Graph left shows change of output voltage for 30% change in  $\pm V_s$  is within  $-0.01\%$ . Change in  $V_s$  of  $IC_2$  changes power dissipation of its input transistors and hence changes chip temperature. This slightly alters offset voltage due to unbalanced heating of input pair.

Value of  $R_5$  not critical because drive current is a small percentage of load current e.g.  $R_5$  1kΩ,  $I_B$  0.3μA,  $I_{LOAD}$  10mA,  $R_5$  100kΩ,  $I_B$  0.365μA

**Circuit modifications**  
● Drive current error can be minimized by using a f.e.t./bipolar combination as Fig. 3. Current capability can be increased provided appropriate transistors used for  $Tr_3$   $Tr_4$  combination e.g. Darlington package.  
● The above IC (MC1566L) allows a variable constant current adjustable from 200μA to 100mA (depending on rating of output transistor  $Tr_3$ ).

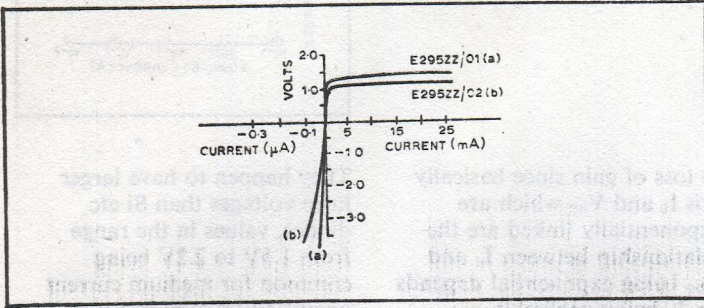


0.03%/degC at 20mA.  
A simpler current reference, programmed by resistor  $R_s$ , is shown right and uses a combination of bipolar p-n-p and n-type junction f.e.t. to

provide a low cost arrangement with claimed drift better than 0.03%/degC at 20mA.  
**Cross references**  
Set 23, cards 3, 5  
Set 6, card 1



### Non-zener device characteristics

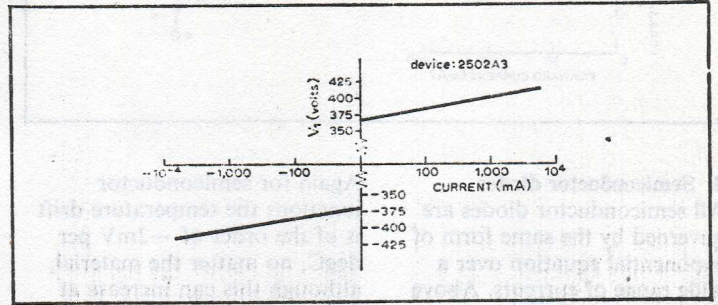


#### 1. Asymmetric voltage dependent resistors—low voltage

Non-linear resistors are made of certain polycrystalline materials having a voltage-current relationship given by  $V = CI^\beta$

where  $C$  and  $\beta$  are constants. This can be expressed as  $\log V = \beta \log I + \log C$  giving on log-log paper a straight line of slope  $\beta$  and intercept  $C$ .

In the case of asymmetric devices  $\beta$  and change with current direction and a zener diode type characteristic can be obtained as shown above. The particular devices shown have knee voltages intermediate between that of zener diodes and that of Si or Ge diodes. The temperature coefficient of forward voltage for both these types is  $-0.2\%$  per degC maximum.

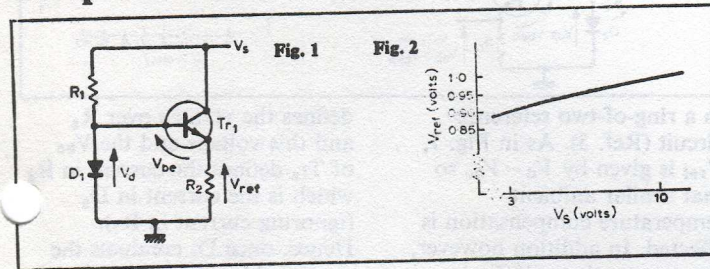


#### 2. Symmetrical voltage dependent resistors—high voltage

These devices have the same form of relationship as that of the asymmetric device but are essentially simpler in that  $C$  and  $\beta$  do not change with current direction. They are frequently used as transient suppressors or over voltage protection devices in high power systems but may be used

to regulate supplies. They are also used in some control applications where the non-linear characteristic is used intentionally. The characteristics shown are those obtained for a 2502 A3 metal-oxide varistor. The temperature stability is claimed to be excellent, our device at  $500\mu\text{A}$  on test giving a temperature coefficient of  $-0.13\text{mV}$  per degC.

### Compensated reference circuits



#### Circuit 1

##### Components

$R_1$ :  $470\Omega$ ,  $R_2$ :  $220\Omega$

$Tr_1$ : BC125

$D_1$ : 5082-4850 (Hewlett Packard)

Performance—see graphs 1 and 2

##### Description

$V_{ref}$  is given by  $-V_{be} + V_d$  i.e.  $-0.7 + 1.6 = 0.9\text{V}$  to a first order approximately. The variation of  $V_{ref}$  with respect to supply voltage changes is

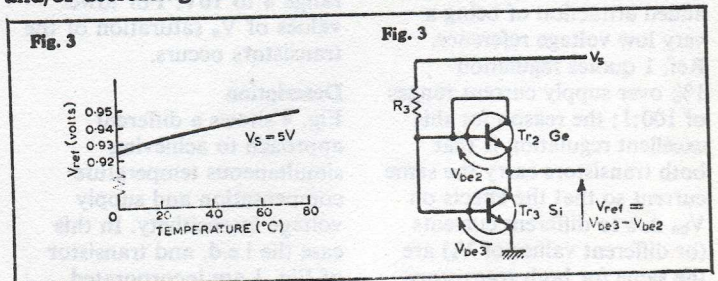
shown in Fig. 2. From this we observe a variation of approximately  $10\%$  in  $V_{ref}$  over the range shown so that compensation with respect to  $V_s$  is poor. The graph is approximately linear with slope  $+12\text{mV}$  per volt of  $V_s$ . Fig. 3 shows the variation of  $V_{ref}$  with temperature,  $V_s$  being  $5\text{V}$ . The graph is linear in the range shown with slope  $+0.27\text{mV}/\text{degC}$ . The variation of an independent p-n junction with temperature is

approximately  $-2\text{mV}/\text{degC}$ . Clearly there is an element of temperature compensation involved, arising from the fact that  $V_{ref}$  is the difference in two junction voltages. In this case the effect of temperature variation on  $V_{be}$  is greater than the effect on  $V_d$ . For any junction the variation of junction voltage with temperature is dependent on the voltage itself and is approximately  $+3\mu\text{V}/\text{degC}$  for each change of  $+1\text{mV}$ . Hence, increasing the i.e.d. current and/or decreasing the

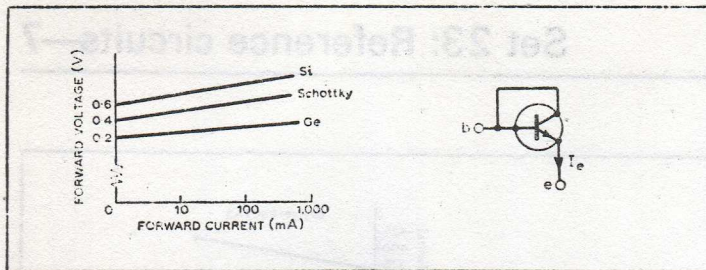
transistor current could improve the drift due to temperature. This can be done by decreasing  $R_1$  and/or increasing  $R_2$ .

#### Component changes

For any given  $V_s$ ,  $R_1$  and  $R_2$  are not critical if only first-order temperature compensation is required.  $R_1$  effectively controls the i.e.d. current since the transistor base current will be negligible and obviously  $R_1$  should not be so high as to prevent i.e.d. conduction.





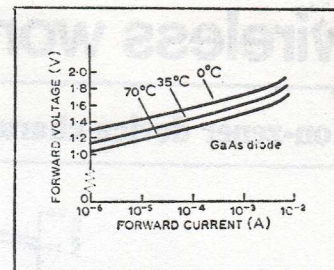


### 3. Semiconductor diodes

All semiconductor diodes are governed by the same form of exponential equation over a wide range of currents. Above is shown the approximate curves that are obtained as a result of linearising the exponential graphs. The slopes differ according to the material used as do the approximate constant voltages obtained across the diodes when conduction starts. The constant voltage obtained falls in general by 60mV for each decade drop in current although falls of up to 120mV per decade of current can occur at very high or very low values of current.

Again for semiconductor junctions the temperature drift is of the order of  $-2\text{mV per degC}$ , no matter the material, although this can increase at lower current densities. The range of voltages to be expected from Si diodes is 0.5 to 0.8V and from Ge diodes is 0.1 to 0.3V. Schottky diodes are intermediate. The diode connected transistor shown above will exhibit an exponential relationship between  $I_e$  and  $V_{be}$  over a much wider range of currents than is usual with simple diodes. The exponential relationship falls off at very low and very high currents due

to loss of gain since basically it is  $I_c$  and  $V_{be}$  which are exponentially linked are the relationship between  $I_e$  and  $V_{be}$  being exponential depends on  $I_b$  being negligible.



They happen to have larger knee voltages than Si etc diodes, values in the range from 1.5V to 2.2V being common for medium current operation (several mA usually). This knee value is reduced by the normal 60mV per decade of current. Low current operation may extinguish the light but does not alter the simple exponential action. As before the temperature drift is  $-2\text{mV per degC}$ . The above graph shows the results from a GaAs i.e.d. Higher knee voltages are obtained with the other common i.e.d. material viz GaAsP.

### 4. Light emitting diodes

Light emitting diodes are semiconductor diodes which tend to be used for their light emitting properties rather than for their other properties which are identical in form to those of any semiconductor diode.

© 1975 IPC Business Press Ltd

Likewise  $R_2$  carries the transistor current and should not be so low as to cause saturation of the transistor. Hence  $R_1$  and  $R_2$  are dictated by the particular i.e.d. and  $Tr_1$  used.

Most i.e.d.s and Si transistors will give the same reference voltage but if the transistor is replaced by a Ge transistor  $V_{ref}$  will become 1.3V approximately.

#### Circuit 2

The first circuit is not well compensated for supply voltage changes. In Fig. 3  $Tr_2$  is a Ge transistor and  $Tr_3$  is a Si transistor and, hence,  $V_{ref}$  is approximately 0.4V—giving the circuit the added attraction of being a very low voltage reference. Ref. 1 quotes regulation 1% over supply current ranges of 100:1; the reason for this excellent regulation is that both transistors carry the same current so that the effects on  $V_{be}$  due to different currents (or different values of  $V_s$ ) are the same for both transistors.

For the same reasons as before the circuit is also temperature compensated and indeed if the difference in the extrapolated band gaps at 0K is 0.43V complete temperature compensation is obtainable. Achieving this requires selection of appropriate transistors.

#### Circuit 3

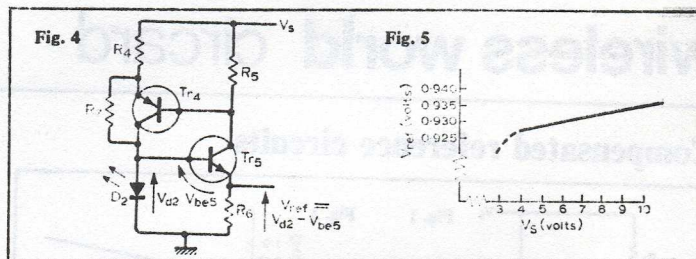
**Components**  
 $R_4, R_6$ : 220 $\Omega$   
 $R_5$ : 560 $\Omega$ ,  $R_3$ : 22k $\Omega$   
 $Tr_4$ : BC126,  $Tr_5$ : BC125  
 $D_2$ : 5082-4850 (HP)

#### Performance

Fig. 5 shows the regulation achievable with this circuit viz 1.5mV per volt of  $V_s$  in the range 4 to 10V. For lower values of  $V_s$  saturation of the transistors occurs.

#### Description

Fig. 4 shows a different approach to achieving simultaneous temperature compensation and supply voltage insensitivity. In this case the i.e.d. and transistor of Fig. 1 are incorporated



in a ring-of-two reference circuit (Ref. 3). As in Fig. 1,  $V_{ref}$  is given by  $V_d - V_{be}$  so that similar ambient temperature compensation is effected. In addition however, the current through  $Tr_4$  is largely independent of the supply voltage so that effects due to varying  $V_s$  are minimal. The action of the ring-of-two circuit is independent of  $V_s$  and is briefly as follows. Suppose  $D_2$  is made to conduct (insured by presence of  $R_4$  and  $R_7$ ). Then  $V_{d2}$  is approximately 1.6V and  $Tr_5$  will conduct with  $V_{be}$  approximately 0.7V. The current in  $R_7$  is, therefore, defined by  $V_{d2} - V_{be5}$  and this current all flows through  $R_5$  (ignoring base currents). This

defines the voltage over  $R_5$  and this voltage and the  $V_{be}$  of  $Tr_4$  defines the current in  $R_4$  which is the current in  $D_2$  (ignoring current in  $R_7$ ). Hence, once  $D_2$  conducts the current through it is fixed and so are all the other currents. Hence  $V_{d2} - V_{be5}$  is supply insensitive. Only the transistor collector-emitter voltages are supply dependent.

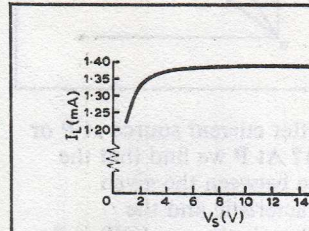
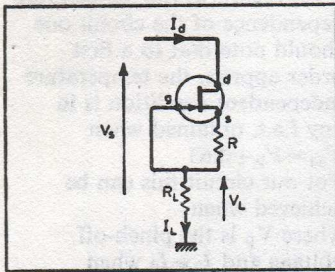
#### References

1. Very low voltage d.c. reference, P. Williams, *Electronic Engineering*, June 1968, pp. 348-349.
2. National Semiconductor LM311 voltage comparator data sheets.
3. Set 6, card 5

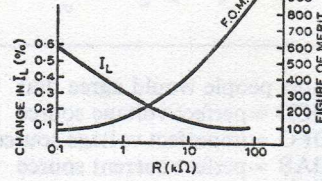
© 1975 IPC Business Press Ltd



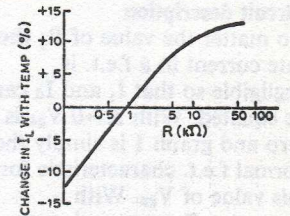
### Simple current reference



Graph 1



Graph 2



Graph 3

FET 2N5457

#### Performance

Graph 1 was obtained with  $R_s \approx 10\Omega$  and  $R = 0$ .

Graph 2 was obtained with  $R_s \approx 1k\Omega$ .  $V_s$  was set at 10V and  $I_L$  noted;  $V_s$  was then changed to 15V and the new  $I_L$  noted. From this was obtained the graph of % change in  $I_L$  for various values of  $R$ , the marked values of  $I_L$  on the graph being those at

$V_s \approx 10V$ . The figure of merit (f.o.m.) shown is defined as the slope resistance ( $= V_s/I_L$ ) ÷ static resistance ( $V_s/I_L$  at  $V_s = 10V$ ).

For a perfect current source this should be  $\infty$  (see main text). Points on this graph are directly connected to points on the graph of % change in  $I_L$  so we see clearly that the arrangement works best as a current source at low values of  $I_L$ . Note that from the

graph of % change in  $I_L$  we can reduce the static and slope resistances which ranged from  $8.1k\Omega$  and  $794k\Omega$  to  $1M\Omega$  and  $10^8M\Omega$  respectively over the range of  $R$  shown.

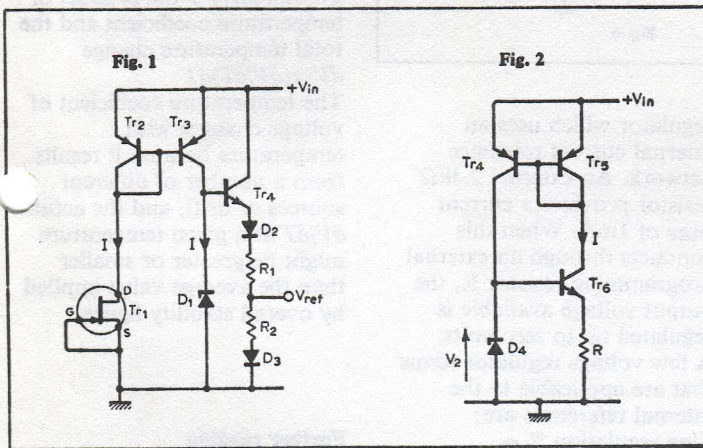
Graph 3 shows the percentage change in  $I_L$ , as a result of a temperature change from  $-5^\circ C$  to  $+70^\circ C$ , for various  $R$ . This was obtained with  $R_L = 1k\Omega$  and  $V_s = 11.4V$  (a choice intended to produce 10V across  $R_L$  with  $R = 0$ , but of

no material significance). In this respect it should be noted that although  $V_s$  is constant neither  $V_{dg}$  nor  $V_L$  is constant because of the varying  $I_L$ . The main point, however, is that a temperature independent condition is achieved at approximately  $R = 1k\Omega$  for the particular f.e.t. that we used. Whilst graph 3 shows the effect of a large temperature change, results were taken at intermediate temperatures.

# wireless world circard

## Set 23: Reference circuits—10

### Monolithic reference

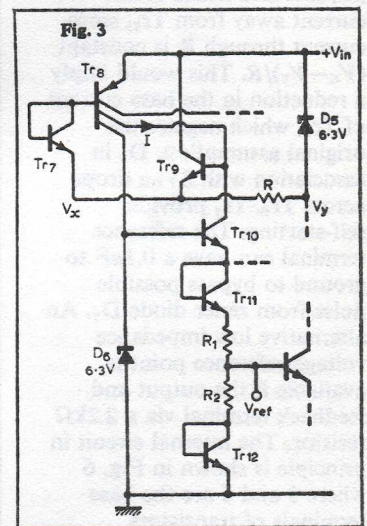


#### Circuit description

Internal reference circuits are based on the simpler voltage reference shown in Fig. 1, found in the low-cost LM376 voltage regulator. The self-starting technique used here

employs a f.e.t.  $Tr_1$ , with gate-source connected to ensure a constant current from drain to source.  $Tr_1$  will draw current initially via the base emitter-junctions of transistors  $Tr_2$  and  $Tr_3$ . These transistors

are therefore turned-on, and due to the current-mirror connection the current  $I$  through avalanche diode  $D_1$  is defined, and hence its voltage. This turns on transistor  $Tr_4$  and now produce a current through the  $D_2, R_1, R_2, D_3$  chain. The circuit suffers from lack of a feedback loop, which is evident in Fig. 2. As it stands it is not inherently self-starting, but with  $Tr_4$  conducting, the voltage  $V_z$  developed across avalanche diode  $D_4$ , will maintain a constant current through resistor  $R$ . The collector current  $I$  of  $Tr_6$  is mirrored in the collector of  $Tr_4$ , again to maintain a constant current through  $D_4$  thus completing the loop. This is shown more detailed in Fig. 3, reference circuit contained in the LM100 voltage regulator. The multi-collector transistor  $Tr_8$  in conjunction with  $Tr_7, Tr_9$  forms



a closed loop. The  $V_{BE}$ 's of these transistors will be essentially similar, and their collector currents closely related, but dependent on relative collector area, but if one collector current is

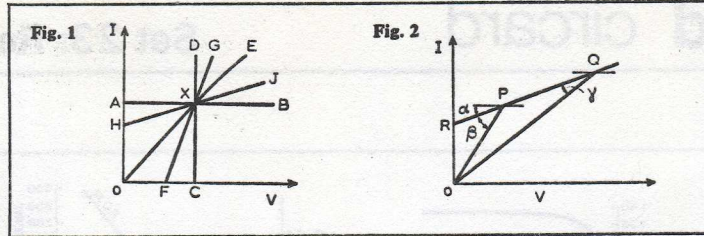


These indicated that to a first approximation, for any given R, the change in  $I_L$  is proportional to the change in temperature.

#### Circuit description

No matter the value of R, the gate current in a f.e.t. is negligible so that  $I_1$  and  $I_d$  can be equated. With  $R=0$   $V_{gs}$  is zero and graph 1 is simply the normal f.e.t. characteristic for this value of  $V_{gs}$ . With increasing R more and more negative current feedback is used and consequently, the circuit behaves more like a current source with the ensuing drop in output as graph 2 shows.

Some explanation of the figure of merit used seems in order because some people use different figures of merit (Ref. 1 & 2) and notably slope resistance is at least implied as being all important. Consider Fig. 1 and the device characteristics shown, all passing through the same operating point, X. From this



most people would agree that  
 OCD = perfect voltage source  
 OFG = imperfect voltage source  
 OAB = perfect current source  
 OHJ = imperfect current source  
 OE = indeterminate case.

From this we conclude that for a current source then (1) the slope resistance must be greater than the static resistance (HJ closer to horizontal than OE) (2) given 1 then the greater the slope resistance the better.

From this, one is tempted to conclude that slope resistance is all important. Consider, however, Fig. 2 where we have the same slope resistance but different static resistances at points P and Q. Is the device whose characteristic is ORPQ

a better current source at P or at Q? At P we find that the angle between the given characteristic and the indeterminate case (OP) is  $\beta$  and clearly  $\beta > \alpha$  i.e. at P we have a better current source. We could propose the figure of merit  $(\alpha + \beta) \div \alpha$ , which becomes larger as the device approaches a perfect current source but is rather devoid of meaning. However if we take  $\tan(\alpha + \beta) \div \tan \alpha = \text{slope resistance} \div \text{static resistance}$ . Since slope resistance and static resistance are meaningful we adopt this as our figure of merit. The inverse of this we

would adopt for a voltage source since we want any f.o.m. to become bigger the more the source resembles a perfect source.

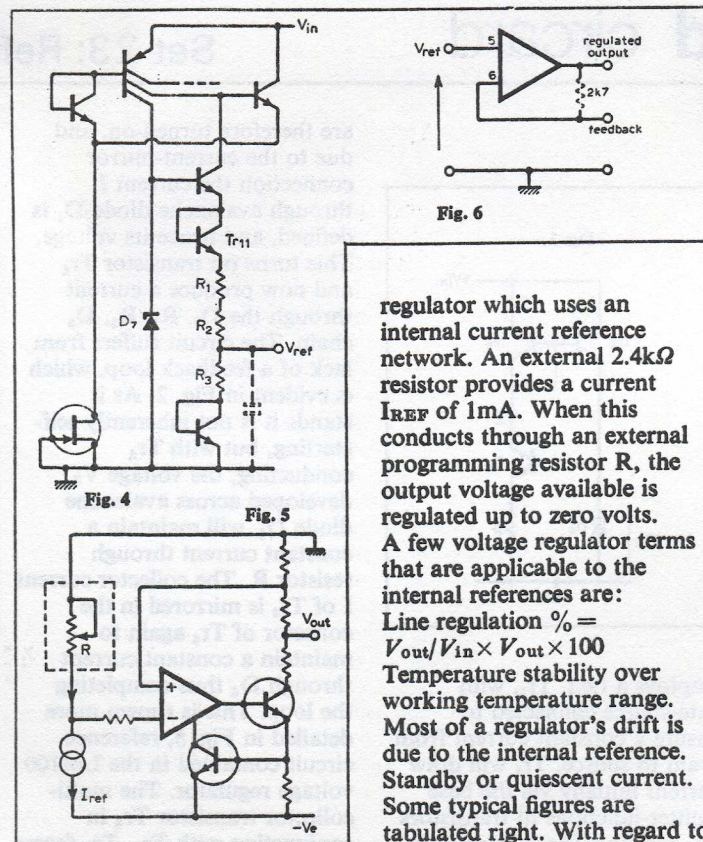
With regard to the temperature dependence of the circuit one should note that to a first order approx. the temperature independent condition is in any f.e.t. obtained when  $V_{gs} = V_p + 0.63$ . For our circuit this can be achieved when where  $V_p$  is the pinch-off voltage and  $I_o = I_d$  when  $V_{gs} = 0$ . The usefulness of these formulae is restricted because of the large range of  $V_p$  and  $I_o$  quoted by the manufacturer for any device and the difficulty of measuring both for any single device. However, Graph 3 has been plotted over a very large range of R and consequently tends to exaggerate the effect of temperature.

#### References

1. I.R.C. zener diode handbook.
2. Motorola zener diode handbook.

© 1975 IPC Business Press Ltd

stabilized the others must be. If I is assumed to increase, the base drive of  $Tr_8$  would increase and hence divert current away from  $Tr_7$ , since current through R is constant  $(V_x - V_y)/R$ . This would imply a reduction in the base current of  $Tr_8$ , which negates the original assumption.  $D_5$  in association with  $2V_{BE}$  drops across  $Tr_8$ ,  $Tr_7$  provide self-starting. The reference terminal can have a  $0.1\mu F$  to ground to bypass possible noise from zener diode  $D_7$ . An alternative low impedance voltage reference point is available if the output and feedback terminal via a  $2.2k\Omega$  resistor. The internal circuit in principle is shown in Fig. 6 where 5 and 6 are the base terminals of transistors connected as a long-tail pair. Diode connected transistors  $Tr_{11}$ ,  $Tr_{12}$  and resistors  $R_1$ ,  $R_2$ ,  $R_3$  provide a temperature compensation which is optimized to about 1.8V. Fig. 5 is a function block for the LM104 negative voltage



regulator which uses an internal current reference network. An external  $2.4k\Omega$  resistor provides a current  $I_{REF}$  of 1mA. When this conducts through an external programming resistor R, the output voltage available is regulated up to zero volts. A few voltage regulator terms that are applicable to the internal references are:  
 Line regulation % =  $V_{out}/V_{in} \times V_{out} \times 100$   
 Temperature stability over working temperature range.  
 Most of a regulator's drift is due to the internal reference. Standby or quiescent current. Some typical figures are tabulated right. With regard to

temperature dependence, if the output voltage is a linear function of temperature, then the temp-coefficient of voltage is a constant, and the total change in voltage (often called the stability) is the product of temperature coefficient and the total temperature change  $dV = (\delta V/\delta T)dT$

The temperature coefficient of voltage changes with temperature because it results from a number of different sources of drift, and the actual  $\delta V/\delta T$  at a given temperature might be greater or smaller than the average value implied by overall stability figure.

#### Further reading

Linear Applications—National Semiconductor Corporation.  
 Linear Integrated Circuits—National Semiconductor Corporation.

Cross reference  
 Set 23, card 1.

© 1975 IPC Business Press Ltd