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nri journal March/April 1980

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Photography Maxine Cohen Mike Taylor In this issue, Laurel Munk begins a three-part series on home security. Curt Feigel introduces us to a multi-trace adapter, and Ken Bigelow gets underway with his "Computer Corner."



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Ince upon a time, people had no need to lock their doors. Today, locks often are not enough. There are over 3 million reported residential burglaries each year in the United States. The causes of the increasing crime rate are varied and most are beyond your direct control. However, a majority of American homes are actually easy to break into.

The physical security of any home can be vastly improved with the use of even the simplest of devices. The first and most important step in planning a home security system is to take a critical look at your home and identify problem areas. Often, representatives from local police departments or security firms are willing to help you do this. Once you have evaluated your home, find out what systems are available that are appropriate for your application. A home security system can be as simple as some circuitry and switches purchased at an electronics supply store for a few dollars. A system can also be as sophisticated as space-age technology purchased from or installed by a professional security firm for hundreds of dollars.

Design a system that you and your family can live with - it is still your home, not a jail. A security system that

stays turned off because your family keeps triggering false alarms when it is on is a waste of money. Even worse, false alarms can tax the patience of both your neighbors and the local police. Too many false alarms, and your system will lose its credibility.

The more you understand about home security, the devices used, and the capabilities and limitations of each type of system, the more effectively you can spend your security dollar.

TYPES OF PROTECTION

There are three major categories of protection that you should consider when you decide to safeguard your home against intrusion. *Perimeter*, or point-of-entry, protection is designed to detect an intruder at the earliest possible moment – before any property is damaged or stolen. Doors, windows, gates, and fences are typical locations for perimeter intrusion detectors (usually electromechanical or photoelectric devices).

The major advantage of this type of protection is that an intruder or burglar doesn't want to spend the extra time and effort to get past your safeguards. Intruders like to do their work quickly and quietly — any delays or alarms (bells, sirens, lights, etc.) can discourage them. If you turn on a security system when you leave your home, the loud outdoor speakers will alert your neighbors even though you are not there.

The major disadvantage of perimeter protection is that it is not complete protection. Persistent burglars can cut through ceilings, floors, and walls, and some of the more skilled ones can even disable alarm systems with ease.

Zone protection provides an excellent addition to a perimeter system. This type of protection (often ultrasonic; infrared, or microwave) detects the presence or movement of an intruder in the guarded area. The advantage of this type of protection is that the system detects the intruder's movements long before the intruder can locate and disable the system. One disadvantage is that the devices used in such a system are very sensitive, and if not properly installed, can plague you with false alarms from incidental movements (by pets, drapery billowing in the breeze, etc.) within the protected area.

Spot protection provides even more security for specific objects, such as valuable art pieces, jewelry and silverware chests, and safes. The electromechanical or photoelectric devices used in this type of system sound an alarm if anyone touches or gets very close to the protected object. Spot protection is used more widely in business applications than in the home, yet it can be advantageous for the homeowner, too. For example, suppose you are having a party on the patio or ground floor and you have turned off your other alarm systems to prevent false alarms caused by the activities of your friends. A spot protection device can detect a cat burglar or an unwelcome guest who decides to "examine" your jewelry on the bureau in an upstairs bedroom.

A combination of perimeter, zone, and spot protection will not only give your home superior protection against intruders, but will also give you and your family peace of mind. Let's take a closer look at two types of security systems – electromechanical and ultrasonic – as a sample of what is used in home security today.

HOW ELECTROMECHANICAL DEVICES WORK

Most electromechanical alarms are based on the closed circuit. This is a more reliable method than a normally open circuit, which requires a contact to be made before the alarm will sound. Any time the closed circuit is broken, the alarm is activated. The basic circuitry in a closed circuit is the same, regardless of the type of sensor or detector that is used. Figure 1 shows an example of a basic circuit. Because Q1 is a pnp transistor, the positive voltage applied to its base by the 1.5 volt battery cuts the transistor off. This reverse bias in the base-emitter junction prevents any significant current from flowing through the protective circuit, shown within the dashed lines. When the protective circuit is broken, symbolized here as S1, the reverse bias on the transistor is removed. Current flow through R1 forward biases Q1, causing the transistor to conduct. Current flow through Q1 makes the voltage at the collector less negative than the -V

supply voltage. This signal is coupled to the gate of the SCR through C1. Because the gate of the SCR is now more positive (actually, less negative) than the cathode, the SCR begins to conduct. The resulting current flow through R5 develops the voltage needed to trigger the alarm. The alarm will continue to sound until it is reset by turning off the -V supply or pressing the reset switch, S2.

Any attempt to bypass the protective circuit results in the triggering of the alarm. As an example, suppose the intruder short circuits points A and B in the hope of disabling the alarm. Such a connection would cause current to flow through R1, R3, and D1. The silicon diode D1 requires a voltage drop of about 0.7 volt to conduct current. However, transistor Q1 is a germanium transistor requiring a base-emitter voltage of about 0.2 volt to conduct.





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FIGURE 2. (A) A JUMPER WIRE BETWEEN POINTS X AND Y WILL KEEP THE CIRCUIT CLOSED, WHILE THE REST OF THE GLASS CAN BE CUT OR BROKEN. (B) SINCE THE CIRCUIT IS NOT OBVIOUS, INSTALLING A JUMPER WIRE MIGHT TRIGGER THE ALARM INSTEAD OF DISABLING IT.

Therefore, the voltage developed across diode D1 would be sufficient to forward bias transistor Q1 and activate the alarm.

SOME TYPICAL DEVICES

There are many kinds of sensors and switches that can be connected to the basic alarm circuitry. Perhaps the most common of all electromechanical sensors is the metallic foil that is used to make a complete circuit around a window or glass door for perimeter protection. If you choose this type of circuit you should be careful to install the foil properly so that the circuit pattern is not obvious. Figure 2(A) shows a foil pattern where the entry and exit points of the tape are obvious – all the burglar has to do is connect a jumper between point X and point Y to keep the circuit intact and the "switch" closed. If the foil is properly installed, as shown in Fig.2(B), the intruder's attempts to break the glass or disable the circuit without triggering the alarm are made very difficult. The intruder would either have to guess which one of the four corners is the entry/exit point, or take the time to install four jumpers just to be sure.

Connections between the window foil and the rest of the circuitry should be made through special connection boxes specially designed for this purpose. Soldering wires directly to the foil will give you an unreliable system prone to false alarms. The foil tape should be inspected frequently, especially after window cleaning, to ensure that the foil has not peeled loose or become ragged or cracked. Any breakage in the foil due to improper maintenance will trigger the alarm just as surely as an intruder.

There are many types of electromechanical switches that can also be connected to the basic alarm circuitry. The most reliable ones will be those that meet the standards set by the Law Enforcement Assistance Association. Figure 3 shows a variety of electromechanical switches that a homeowner can install without a great deal of expense or difficulty. The plunger-type switch shown in Fig.3(A) is commonly used to detect the presence of an intruder entering through a door. As long as the door is closed, the plunger remains in its assembly, completing the closed circuit. When the door is opened, the pressure against the plunger is released, and the spring moves the plunger away from its contact point. The circuit is broken and the alarm sounds. This can be a very effective device as long as the intruder doesn't suspect it is there. If a burglar has suspicions or has observed that indeed there is such a device, he will

slide a thin metal plate between the door and the plunger as he opens the door, thus keeping the circuit closed.

Another reliable type of door or window switch is the magnetic proximity switch, shown in Fig.3(B). A magnetically operated reed switch is mounted on the door frame and a permanent magnet is mounted on the door itself. The switch is usually positioned so that the presence of the magnet on the closed door or window keeps the circuit closed. These magnetic switches, which cost between \$3 to \$5, can be installed just about anywhere in



your home and can be hooked up to any existing closed-circuit system.

spot protection can Good be provided with vibration switches and pressure-sensitive floor mats. The operation of a vibration switch is also very simple. As shown in Fig.3(C), a weight is suspended on a spring over its contact. If it is a closed circuit, the switch will be closed at rest. Any vibration will cause the weight to move away from the contact and open the circuit. The weight will return to its resting position. but once the circuit has been broken. the alarm will continue to sound. This device is particularly useful in protecting automobiles. Someone starting the car, removing a battery, or jacking up the car to steal the tires will cause enough vibration to open the switch.

Pressure-sensitive floor mats are also frequently used for spot protection particularly in businesses that have safes, jewelry cases, or file cabinets containing valuables. In the home, the mats are often concealed under a rug in a central hallway or staircase. When the intruder crosses the central area as he travels from room to room looking for valuables, the alarm will be triggered. In this way, you can protect several rooms with one device. A five-foot hall runner retails for about \$20.

ADVANTAGES AND DISADVANTAGES OF ELECTROMECHANICAL DEVICES

Because electromechanical devices are so simple in operation, their usefulness is often overlooked in favor of more sophisticated systems. Actually, their simplicity makes them very effective and highly reliable. The key to good protection with electromechanical devices is proper installation and maintenance. Proper installation means doing a complete job. All the locks and switches on the first floor of a home are useless if the second floor is left unprotected. Don't let the security of an apartment depend on one door switch use several throughout your home.

Choose the devices that are appropriate for your particular home and lifestyle. Window switches are not very effective if you prefer to cool your home in warm weather by opening the windows. Install switches that are hidden from view. Vandals and amateur burglars may be discouraged by highly visible devices, but most skilled thieves can avoid your safeguards if they spot them.

The major disadvantage of using electromechanical devices is that it is not practical or even feasible to protect every single entry point to your home. Remember, a determined thief who thinks that the rewards are great enough will find a way in that you haven't thought about. One way to outsmart a burglar is to use an electromechanical system for perimeter and spot protection, and use a more advanced system, such as ultrasonics, for backup zone protection.

ULTRASONIC DEVICES – HOW THEY WORK

Ultrasonic intrusion detectors provide excellent protection for the interior area of any home. The basic operating principle behind ultrasonic devices is simple. Ultrasonic energy is merely sound waves that are of such a high frequency that they are not audible to the human ear. As shown in Fig.4, ultrasonic waves from a transmitter completely fill a room. Most of the sound waves travel directly to the receiver. Some waves are reflected from the ceiling, walls, floor, and other hard



FIGURE 4. DIRECT AND REFLECTED SOUND WAVES COMBINE TO FORM A CONSTANT FREQUENCY AT THE RECEIVER. ANY MOVEMENT CAUSES A CHANGE IN THAT CONSTANT FREQUENCY.

surfaces before they reach the receiver. When the sound waves are reflected by various surfaces, their frequency changes. The frequencies of both the direct and reflected sound waves are constant and are combined into what is called the standing wave pattern. When these two different frequencies reach the receiver, they either reinforce or cancel each other, depending on the exact original frequency and the phase relationship between it and the changed frequency. As long as nothing in the room moves, the standing wave pattern remains constant. However, if an intruder enters the room, some of the reflected signals will change once again. The change in the reflected signal results





FIGURE 6. A BLOCK DIAGRAM OF AN ULTRASONIC TRANSMITTER AND RECEIVER.

in an amplitude-modulated signal, which is detected by the receiver. The alarm is then triggered.

A TYPICAL SYSTEM

A typical ultrasonic intrusion alarm is shown in Fig.5. A block diagram of the transmitter and receiver portions is shown in Fig.6. The transmitter portion consists of an oscillator operating at the desired frequency, and a transducer that converts the electrical signal from the oscillator into sound waves. The transducer used in an ultrasonic transmitter performs the same function as a conventional speaker. However, due to the high frequencies involved, it has a smaller, more rigid diaphragm. The oscillator and transmitter transducer are so simple in operation that they are often mounted in the same case as the receiver.

The receiver portion of the ultrasonic system also contains a transducer; however, its function is exactly the opposite of the transmitter transducer. The receiver transducer converts ultrasonic energy into an electrical signal. The signal is fed to a tuned circuit that is set to the frequency of the transmitter. It passes only frequencies that are close to the operating frequency, thus eliminating many false alarms caused by extraneous sounds. The signal is then fed to the amplifier and detector. The detector circuit varies in its sensitivity. It is normally set to detect the slowest and smallest moving object, yet not react to air currents. As long as nothing in the protected area moves, there will be no output from the detector. However, if an intruder causes an amplitudemodulated signal to arrive at the receiver, the detector will output an intrusion signal to the trigger circuit. The trigger circuit may contain a time delay so that only intrusion signals of at least 10 seconds duration will trigger the alarm. This eliminates false alarms due to transients on the line, curtains blowing in the breeze, or rf interference.

ADVANTAGES AND DISADVANTAGES OF AN ULTRASONIC SYSTEM

One of the major advantages of an ultrasonic system is that it cannot be easily detected by a burglar. The system is virtually tamperproof - even if the intruder could manage to locate the control unit without triggering the alarm. The key to using an ultrasonic system effectively lies in proper planning and installation. Figure 7 shows a home with an effective system. The detectors are placed for maximum coverage of critical areas without the inconvenience or expense of surplus units. Most detectors can be adjusted to be either highly directional (for narrow such as hallways) or omniareas, directional (for room-sized rectangular areas). Detectors should be mounted at least 10 feet away from objects such as telephones, doorbell chimes, and radiator pipes, that can emit high-frequency sounds in addition to their audible tones. Detectors should also be located



FIGURE 7. AN EXAMPLE OF ULTRASON-IC DETECTOR PLACEMENT. THE CON-TROL DETECTOR IS PLACED IN THE CEN-TRAL HALLWAY AND TWO "SLAVE" DE-TECTORS ARE SET UP IN ROOMS WHERE VALUABLES ARE KEPT.

away from electric fans, decorative mobiles, and other objects that might accidentally trigger the alarm.

Other than inadequate planning and improper installation, the major disadvantage of ultrasonic detectors is that they are extremely sensitive, and therefore prone to false alarms. Household pets must be confined to unprotected areas — unless the detectors are placed high enough and the wave pattern restricted enough so that their movements high enough and the wave pattern restricted enough so that their movements hard surfaces to reflect the sound waves. Rooms that are heavily curtained or contain sound-absorbing wall or ceiling material may not be effectively protected with an ultrasonic system.

SUMMARY

Whatever type of protection you may prefer to choose for your home, you should make careful plans first. There are a wide variety of options such as direct telephone dialing to the local police, bedside "panic" buttons, entry/ exit delay timers, and remote control devices, that can be added to any system, if you so desire. The protection you choose should be effective and economical for your particular situation and living habits. You should have enough protection to guard your valuables and give you peace of mind, but not so much that your home looks like Ft. Knox. It is also important to remember that no system is foolproof. A security system is not a guarantee that your home is burglarproof. However, any protection is better than leaving your home totally vulnerable. You might consider installing a few devices initially, and then expand or upgrade your protection at a later time.

ABOUT THE AUTHOR



Laurie joined the NRI staff in 1976, and is currently Publication Supervisor. She has a special interest in home security: She recalls, "When I was a child, my parents' home was burglarized. I shall never forget the sight of my ransacked room . . . everything I treasured either destroyed or gone." Laurie feels that there is truth in the old adage, "an ounce of prevention is worth a pound of cure."

Ham News





Ted Beach K4MKX

I'm sure that by now most of you know all about the outcome of the 1979 WARC convention in Geneva. That is, you know about the outcome at least as far as amateur radio is concerned. I must say that I was very pleased at the way we fared, and was not the least bit disturbed that we lost a few megahertz (1215 MHz to 1240 MHz) in the microwave region.

The really big news, of course, is the three new high-frequency bands. One is in the 30 meter range from 10.10 MHz to 10.15 MHz. That's only 50 kHz, but it should have some pretty neat propagation characteristics. The other two bands are 17 meters (18.068 MHz to 18.168 MHz) and 12 meters (24.890 MHz to 24.990 MHz). These two bands are presently occupied by various commercial services, and will not be available to amateurs until the present users have all moved to other frequencies. Some of the people who seem to know about these things say that this probably won't happen until 1984 at the very earliest, and maybe not before 1987! At the same time, the 10.1 to 10.15 MHz band might be available as early as January of 1982, only two years away.

One manufacturer, Ten Tec, has already announced a new rig that includes the three new hf bands. They plan to make production models available sometime this year. I'm sure Drake and the rest of the manufacturers will probably be coming out with new models in the very near future as well. In the meantime, if you like to do some home-brewing, you might try working up a simple converter for your ham bands-only rig so you can see what goes on these new bands.

Another bit of good news is that there is now full reciprocal operation permitted for U.S. and Canadian amateurs. That means, if you're planning a trip to Canada you can take your rig along with you and you can operate without making any prior arrangements with the Department of Communications. Unfortunately, Canada does not have a Novice (or comparable) class, so Novices will be excluded from this arrangement.

While we're on the subject of "new" things in amateur radio, here are a few items I found to be of interest in recent issues of *HR Report*, the weekly newsletter published by *Ham Radio* magazine.

First of all, in the very near future, the Federal Communications Commission may have to stop allowing volunteer examiners to be used to administer Novice tests. Volunteer examiners were declared to be illegal by the FCC's lawyers. If their opinion is upheld, it will mean that Novice tests will again have to be taken at FCC field offices like all other amateur (and commercial) tests. That, coupled with the "no fee" policy in effect right now, could really put a large dent in the FCC budget.

Another recent FCC action allows photocopies of licenses to be considered valid substitutes for the original. This rule became effective December 21, 1979. Also, the FCC is continuing work on "plain English" revisions for the amateur Rules and Regulations (Part 97), which should be available sometime this year. The Commission has also published new and updated individual syllabi for the various amateur license classes, copies of which are available from the FCC field offices. Hopefully, these will reflect some of the "new" examinations we've been hearing about lately.

Finally, the long-awaited authorization to use ASCII as well as Baudot teleprinter code on the ham bands will probably be coming early in 1980, if indeed the announcement has not already been made by now. I have a feeling that this will mean a great deal more computer interconnections, with much more widespread sharing of programs among the hams who are also interested in computers. We'll also probably see more data networks set up as a result of this decision. More about these interesting nets another time.

Now, let's see who we've heard from since last time. Again, not too many people have written in since our last issue. If you're a ham and haven't written in, please do so and let us know who you are and what your involvement in amateur radio is. We would all like to hear from you.

We received a photo of Conrad, KA5BUX, operating in his very neat shack, but unfortunately we were unable to reproduce it properly here in the Journal. It is a very good photograph, but there are two reasons we can't use it. First of all, it's a color print, which is quite difficult to redo in print as a black-and-white photo. Secondly, the overall shading is too dark. That would mean everything would be very muddy looking. The best type of photos are black-and-white pictures with normal to light contrast so the details will show up. We do welcome photos, and look forward to getting them from you.

At any rate, Conrad's photo showed a nicely built station console that houses a Swan 350 transceiver with calibrator. This, along with a Heath SWR meter and an MFJ antenna tuner, lets Conrad work cw to his heart's content on 80 and 40 with his 30 foot high dipole. He also works two meters using a Drake TR-33C and a Cushcraft beam. Very nice, Conrad, and we're just sorry we were unable to use your photograph.

WB8UTC is a graduate of the NRI amateur radio course and is now taking the Communications course, hoping to get a job one of these days with R.L. Drake Co. In addition, Chuck has a Realistic (Radio Shack) DX160 receiver that he feels does as good a job as the newer DX300 receiver I mentioned briefly in a recent "Ham News" column. This rig covers almost the same frequencies as the DX300 and costs about half as much. It does not have a digital readout, but Chuck says it's easy to add an \$85 kit-type digital readout. The one he used came from

> Torrestronics Inc. 4850 Hollywreath Ct. Dayton OH 45424

The unit has a 4-digit readout with resolution of 100 Hz, 1 kHz, 10 kHz, or 100 kHz and will read frequencies from 1 to 50 MHz. It should mate with most receivers and transceivers with little or no modification.

The DX160 (which I have not seen in stores or in recent catalogs) looks to be a very good receiver for the money, so by all means latch onto one if you can. Chuck uses his almost exclusively and likes it very much. The adjustable BFO is an added plus over the fixed BFO of the DX300.

PI3AX wrote to tell us that he had just gotten his Class A license, and included a copy of the Amateur Rules under which amateurs in the Netherlands must operate. The rules are quite short as compared to Part 97, and interestingly enough, the examinations on rules and theory are conducted orally. The Class A license is generally equivalent to our General Class license. and requires a 10 minute sending-andreceiving code test (five minutes receiving and five minutes sending), at 12 wpm. The Class B license is similar in many respects to our Novice license, requiring a code test at 8 wpm and less radio theory. Thanks for the information, A.P. It is always interesting to see how other countries handle their amateur radio licensing.

KC2M writes that he enjoys both his NRI course in Communications and the "Ham News" column in the *Journal*. Thanks on both counts, Walt. He was writing mainly to see if it would be all right to visit NRI when he comes to Washington in February. The answer, of course, is we are always glad to meet our students and graduates, and if we're

Bill	KA4KCP	N	Mt. Olivet KY
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A.P.	PJ3AX	A	Aruba Neth. Ant.
Walt	KC2M	E	Leroy NY
Paul	WA2DII	G	East Aurora NY
John	KA3CCK		Avonmore PA
Douglas	KASEDI	Ν	Connellsville PA
Danne	WD4HMC	A*	Sarasota FL
Glen	WB8EYT	G	Canton OH
Ralph	KA9CTD	A *	Galesburg I L 🚽 🚽
Joe	WB9NWR	G	Bloomington I L
Maurice	VE2ESK		Montreal PQ Can.
Bob	K9UJA	-	Schaumburg IL
	* Just Upgraded	Congratulat	ionsl

	75/80	15.	40	75/80	15	40
MARCH	4	11	18	25	22	20
MAY	6	13	20	27	22	29
JUNE		3	10	17	24	1
TIMES:			FRE	QUENCIES	CW*	SSB*
CW	8:30 - 9:0	00 p.m. EST	15	Meters	21,150	21.400
SSB	9:00 - 9:3	30 p.m. EST	40	Meters	7.130	7.280
			75	/80 Meters	3:730	3.980
*+5 kHz in	case of QR					

NRI "GET TOGETHER" SCHEDULE FOR 1980

given enough advance warning we can usually arrange to have someone give you the "grand tour" of your school so you can get to see and meet the people at the other end of the mailbox. As this is being written in January, Walt has not yet dropped by, but rest assured we're looking forward to his visit.

A few people have written concerning the Get Togethers, and Paul, WA2DII was the first. Paul warmed up his Kenwood TS120-S on November 18, 1979 to try out the 40-meter cw Get Together. Conditions were particularly bad that night, with the noise (QRM?) running about 20 dB over S9 at Paul's QTH. At any rate, a "CQ NRI" managed to net NØBFO (Jerry) in South Carolina, followed by WB3HNA in Baltimore. Jerry is an NRI graduate, but WB3HNA is not. He just dropped in to say "hi" since no one seemed to be responding to Paul's calls.

As the evening progressed (and conditions got worse!), Paul finally managed to work four more NRI students or graduates before things folded. They were: Dave, KAØP in Missouri; Lin, WDØHFR in Nebraska; Bob, N5ARM in Lousiana; and Larry, KB7BU in Montana. Not too bad, all things considered. We've heard from N5ARM before, but the others are new. Thanks, Paul.

KA3CCK also had some good luck on the December 4, 1979 Get Together on 75. What follows is a portion of John's letter to me. "Go arounds were run through about three times over the hour and a half session. There were eight of us on. The following list is the NRI students or grads who checked in.

WD4FHS	Mickey	SC
N4CET	Bob	GA
KAØDCS	Harry	MO
WA2VON	Mike	NY
WB5YQY	Emmett	AR
KA4ZYR	Bill	TN
KA4JAV	Jim	GA
KA3CCK	John	PA

So, Ted, get that rig of yours brewing and join us next time which is December 22, same time, same frequency. It was a really nice get together and I am looking forward to the next one."

Thanks very much, John, and I'm only sorry that I am still QRT at the moment. I would like nothing better than to meet you all on the air.

KA3EDI writes that he got his Novice license back in September and is really enjoying being an amateur. Doug says that he is still having problems with the code, but that some "on the air" practice should get him ready for the 13 wpm General test by May. His rig is a Kenwood TS520 that he uses with dipole antennas on 40 and 80. He has a converted CB antenna that he uses with an antenna tuner on 10 and 15. Doug usually gets together once or twice a week with a group of friends for a "Novice Net" code practice session. He says they all get a lot out of the session and suggests that more such nets be established around the country to encourage upgrading from Novice to General. Good idea, Doug, but it takes work and enthusiasm like yours to get things done.

Glen, WB8EYT, was written up first in this column in the November/ December issue. He phoned from Ohio on December 5, 1979 and we had a real nice telephone QSO, although I did not take notes. Thanks for the call, Glen.

KA9CTD has written before, but this time it was to let us know he had just passed his Advanced test. Nice going, Ralph. He met WB9NWR on two meters, and discovered that Joe is also an NRI student in the Communications course. Since then, they have had more or less regular get togethers at the high end of 40 (around 7295) and invite anyone interested to check in. They try for daily schedules from 1900 UTC to 1930 UTC since they both work evenings.

Ralph also does some work on other bands, and managed a QSO with KC4USV in Antarctica on 20 meters the other day. Ralph was using 180 watts to a dipole (on SSB), so it doesn't take fancy gear when conditions are right! We had a short, but very nice, eyeball QSO with VE2ESK, Maurice, and his lovely YML recently. Maurice and his wife were on their way to Florida from Montreal. From there, they planned to go to the Virgin Islands for a vacation. Maurice has listened in on some of the Get Togethers and even managed to work a station in Texas on one occasion, although he didn't remember the call or the date. Thanks, Maurice, and do stop in to see us any time you are in the Washington area.

Finally, I got a letter from Bob, K9UJA the other day, and Bob has an idea whose time has perhaps come. He has designed (patent pending) what he calls a "confirmation mailer" to encourage QSLs from reluctant stations. It's sort of a reverse QSL, in that the sender fills out the two-part card and sends it to the station operator who needs only sign it and return it to the sender. Bob has versions for amateur use and for CBers as well, and plans to begin advertising them in the amateur magazines very soon.

If you would like more information on this new card, drop Bob a line at:

> Bob Zittnan – K9UJA 513 S. Cedarcrest Dr. Schaumburg IL 60193

The cards come with complete instructions for both the sender and the receiver, and are printed on various colored card stock.

Well, that's about it for this time. We'll try and sit in with you on some of the upcoming Get Togethers. But, as always, if you don't hear me, do enjoy yourselves and let us know what's going on out there among the NRI amateur fratemity.

Very 73 – Ted K4MKX

CONAR Model 312



\$85.50 \$59.50 Assembled **Kit Form** Stock No. WT312 Stock No. UK312 Exclusively from CONAR . . . A superb instrument for the electronics technician, with solid-state circuitry and digital readout. The Model 312 uses two 7-segment LED displays visible through a window in the front panel - a foolproof method for determining the unknown value of a resistor or capacitor. Capacitance Range - 10 pF to 1 μ F. Resistance Ranges – 10 ohms to 10M. Power - 110-120 VAC; 60 Hz.

Tube Tester

Every full- or part-time technician needs the Model 224 for his bench. It helps you make better job estimates and pays for itself quickly in extra profits. It's perfect for experimenters and hobbyists, too. Accomodates all series string and other up-to-date tube types.

Stock No. WT224 Stock No. UK224 ONAR Model 224

Open element tests. Independent filament terminal selection. Visible filament continuity tests,
Interelement short tests,
Power Requirements --110-120 VAC; 50/60 Hz. Weight - 10 lbs. Dimensions - 10-1/2"H X 15-1/4"W X 4-3/4"D. See CONAR Electronics Catalog for complete specifications.

CONAR Model 281

Signal Generator



\$165 Assembled Stock No. WT281

\$129

Assembled

\$85

Kit Form

\$99 **Kit Form** Stock No. UK281 Digital readout. AM modulation from 0% to 50%. True FM modulation using a dual varactor modulator.

SPECIFICATIONS

Accuracy - Better than 1%. Attenuator - Continuously variable control provides a minimum attenuation of 40 dB at 30 MHz and below. Modulating Frequency - Lowdistortion 1000 Hz sine wave. Maximum Deviation - 0-40 kHz at 4.5 MHz, 0-80 kHz at 10.7 MHz, and 0-200 kHz at 21.4 MHz. Output - Unmodulated rf, amplitudemodulated rf, frequency-modulated rf, and 1000 Hz audio. Output Amplitude - 0 dBm (200,000 microvolts), 3 dB into 50 ohms, 180 kHz through 30 MHz. Audio Output (1000 Hz) - 8 volts peak-to-peak into 1 megohm, RF and Modulated RF - Continuously variable from 175 kHz to 30.500 MHz.

CONAR PanaVise Tool Systems

Original Base



Stock No. VS300

\$13.95

Vacuum Base



Model 366

Stock No. VS380

\$18.95

Attaches securely to any smooth, nonporous surface. Ideal for a variety of setups. Half-turn of mounting lever attaches and releases powerful suction pad.

> Height: 3-13/16". Base: 5" × 4-1/2".

> > Head



Stock No. VS366

\$14.95

Hold all types of items gently and firmly with the Model 366. It opens a full 6-1/2", has reversible neoprene jaws, and is an excellent all-round head for the craftsperson, hobbyist, or technician.

Designed for all normal, permanent installations. Three lugs spaced 120 degrees apart provide maximum mounting stability.

> Height: 3-13/16". Diameter: 5".



Model 303

Model 300



Stock No. VS303

\$14.95

Wide 2-1/2" jaws open to 2-1/4". Head is pressure diecast aluminum alloy with steel and brass inserts. Hammertone gray/green finish. Replaceable nylon jaws.

Multi-trace Adapter

This is an "idea" article for the advanced experimenter. It is not a stepby-step assembly project, and unless you have had considerable practice building circuits from "scratch," we suggest that you not attempt to build the multi-trace adapter. We do, however, recommend that you experiment with the various simple circuits discussed. Doing so will provide you with some very good "hands-on" experience using digital and analog circuits.

Working with logic circuits frequently requires a comparison of the time relationship between two or more signals. Propagation delays and coincidence of leading edges may determine how well a circuit works, if at all. In addition to a discussion of the basic theory of multiple signals on a single screen, we include in this article information on available hardware, and enough detail to allow the enterprising experimenter to construct his own adapter.

by Curtis Feigel

MULTIPLE TRACES

One method of showing two signals with a single trace is to *alternate*: First show one signal, then the other signal. But, it is quite possible that the signals as displayed may have a different phase relationship. To cure this we *chop*: Display a short segment of one signal, then a short segment of another. By chopping each signal into twenty or so segments, then showing alternate segments of each, we can ensure that the time relationship is maintained. The trace may resemble a dotted line, but it should still be readable.

THE ANALOG SWITCH

In order to chop signals, we need to switch the scope input between signals very quickly. As long as the chop frequency is faster than any incoming signal, the time relationship displayed remains accurate. One convenient device for performing this operation is the CMOS 4052 analog switch. The 4052 acts exactly like a two-pole, fourposition rotary switch, but it can be controlled digitally.

To use the 4052, we must supply +5 volts, -5 volts, and a ground reference. The chip can be controlled by TTL level signals (0 volts to +5 volts), but it must have a -5 volt supply to operate properly in the analog mode. A 2-bit binary word specifies which of the four possible positions the switch will be in.

In its OFF state, each switch is essentially an open circuit, while the ON state looks like a 120 ohm resistance, from input to output. Current may flow in either direction through the switch, and the switch may change at rates up to 3_7 MHz. Theoretically, we could switch between four input signals at this rate. Unfortunately, the switch operation is not instantaneous. There is a 5



FIGURE 1. A 2-BIT BINARY COUNTER USING JK-TYPE FLIP-FLOPS.

microsecond period between the OFF and ON states, which produces a nonlinear trace as the switch makes a transition from high to low impedance.

In order to display each of the input signals, we will need a 2-bit binary counter. This is easily implemented with two flip-flops by using the output of the first flip-flop to clock the second, as shown in Fig.1. Of course, this stage of the circuit could be built from a standard TTL dual JK flip-flop, but the CMOS chips are not much more expensive, and have greater noise immunity. Using 4013's or 4027's also maintains a stable design philosophy throughout the circuit.

Both the 4013 (D-type flip-flop) and the 4027 (JK-type flip-flop) will handle 10 volt signals. In fact, their maximum clock frequency is higher (10 MHz) at 10 volts than at 5 volts; but, since the analog switch requires TTL level control signals, we will use only 5 volts. This reduces the maximum clock frequency to an unspectacular, but adequate, 3 MHz.

We can generate the chop frequency with another common CMOS chip, the 4001 quad two-input NOR. Connected as inverters, two NOR gates produce a very nice square wave in the astable multivibrator circuit of Fig.2. Again, a low operating voltage (+5 volts) limits the frequency response of the integrated circuit. Propagation delay goes from 25 nanoseconds at 10 volts to 60 nanoseconds at 5 volts. The circuit shown



FIGURE 2. AN ASTABLE MULTIVIBRATOR SQUARE WAVE OSCILLATOR.

has a frequency range from about 4 kHz to about 200 kHz, and an almost 50% duty-cycle (symmetrical) output.

By stringing these three simple circuits together, we create the electronic equivalent of a two-pole, four-position rotary switch that automatically changes several thousand times a second. There are still a few details to take care of, though. The most important of these is that with the present setup, all the signals will be superimposed over the same ground reference line.

The easiest way to cure this is to offset each input by a different level, thus the second pole of the analog switch becomes useful. One pole is used to switch the input signals, while the other pole switches position levels. Un-



FIGURE 3. A UNITY-GAIN SUMMING AMPLIFIER.

fortunately, we cannot simply tie both outputs to the scope input. Remember that the analog switch allows current to flow in either direction, so we could end up feeding our position level into the circuit that is under test. We need a buffer between the two outputs that will sum the signal and the position level without providing a direct path between, yet provide an output that still resembles the test signals.

The key words here are *buffer* and *sum*. The output must be the sum of a signal and a dc voltage level, with the inputs electrically separate. Since the output must resemble the input, we might use a differential input op amp, such as shown in Fig.3. This version uses a 741 op amp, connected as a unitygain, noninverting summing amp. This prevents the position voltage from affecting the circuit under test.

One other possible problem involves the scope triggering. If the internal trigger function of the scope is used, the image will jitter; but if external triggering is used, the sweep may trigger on the chopped position level, rather than on the actual signal. The circuit of Fig.4 can be used to buffer one input signal, to drive the scope's external trigger circuitry.



FIGURE 4. A TRIGGER BUFFER.



FIGURE 5. THE COMPLETED CIRCUIT.

www.americanradiohistory.com

TABLE I SOURCES OF PARTS

Active Electronics Box 1035 Framingham MA 01701

Digi-Key Box 667 Thief River Falls MN 56701 Hobby World 19511 Business Center Drive Northridge CA 91324

JAMECO 1021 Howard Ave. San Carlos CA 94070

Poly Paks Box 942 Lynnfield MA 01940 Quest Electronics Box 4430 Santa Clara CA 95054

Solid State Sales Box 74A Somerville MA 02143

COMPLETING YOUR ADAPTER

The complete circuit diagram of the prototype unit is shown in Fig.5. This is simply the interconnection of the previous circuit ideas. Keep in mind that component values are not critical. You can probably get most of the parts from a Radio Shack store or from one of the mail-order suppliers listed in Table I.

Using the multi-trace adapter is not difficult. Simply provide a suitable ± 5 volt supply, connect the op amp output to the scope vertical input, and connect the trigger buffer to the external trigger input. It may be necessary to adjust the chop frequency for maximum readable display. Note the addition of a threeposition switch at the counter "B" output. This allows the converter to display only two traces at a time. In the prototype, this is the most commonly used mode. Although protection diodes and current-limiting resistors are provided, it is best to keep the input signal between +5 volts and -5 volts.

IMPROVEMENTS

There is quite a bit of room for improvement, all at the expense of simplicity. Perhaps most desirable would be a blanking circuit, which would eliminate the vertical lines as the trace alternates between signals. This would make the display much more readable.

More linear response is obtainable from complex summing amplifier circuits, especially when a reliable ± 15 volt supply is available. This could be augmented by input preamps with attenuators, and so on. You might also find adding an amplifier ahead of the 4001 Schmitt trigger would improve trigger sensitivity. Of course, all of this is very useful, but adds complexity. The main attraction of the circuit described here is its simplicity.



ABOUT THE AUTHOR

Curt Feigel is a former electronics engineer and consultant. He recently left the NRI Instruction team to take a position as technical editor with *Byte* magazine. Curt still finds time to work on projects like the multi-trace adapter at his own workbench at home.

www.americanradiohistorv.com

CONAR presents... Halide Leak Detector



Compact and lightweight, this halide gas leak detector has an accuracy of almost 100 parts per million of any chlorinated refrigerants, such as Freon, Carrene, methyl chloride, and ethyl chloride. One valve for positive flame control. Lights instantly, with brilliant color changes. Valve and burner parts are all brass.

- * Long-lasting, heavy-duty replaceable reaction plate
- * 2' flexible search hose
- * Can be used with either propane or LP fuel
- * Propane tank included



System Analyzer

A compact, lightweight, all brass body with easy-acting hand wheels. Full-floating, nonrotating piston valve with special refrigerant

"O" ring and nylon seat makes this manifold gauge suitable for deep vacuum and pressure applications. Supplied with 3' red and blue search hoses, and a 5' yellow charging hose.

- ★ 1/4" SAE male flare connections for hose
- ★ 2-1/2" standard gauges with unbreakable clear lens
- ★ Compound BLUE gauge 0-30" vacuum, 0-350 lbs pressure
- ★ Pressure RED gauge 0-500 lbs pressure
- * Temperature scale on both gauges for R-12, R-22, and R-502





Vacuum Pump by J/B Industries

This high-performance vacuum pump is the essential tool for all air-conditioning and refrigeration technicians. Provides for fast and complete evacuation of water contaminants. Built for continuous duty – performance may actually improve with age! A gas ballast allows for a clean vacuum on even the "wettest" system. Complete with 3-conductor cord. Features: single-stage rotary vane, direct drive, and rugged grip for easy carrying.

SPECIFICATIONS

Free Air Capacity: 84 liters/min (3 cfm). Ultimate Vacuum: 0.030 Torr. Pump Speed: 1725 rpm, 1/4 hp, 120 VAC. Operating Temperature: 40°C, ±5°C rise. Intake Port: 1/4" or 3/8" male flare. Oil Capacity: 21 oz (32 oz supplied). Weight: 24 lbs. Dimensions: 11" H X 5-1/2" W X 14" D.









Alumni News Harry Taylor



The NRI Alumni Association has been in existence more than 50 years, serving the need for continuing training for our graduates.

Many people who complete a technical training program feel the need for a little more practical knowledge before they go off on their own. This is where the Alumni Association can be useful. By meeting regularly with other NRI graduates, you have an opportunity to meet new friends, learn from each other, and develop potential employment contacts. Take a look at the following chapter reports to see what's going on in the chapter nearest you. The NRI staff is always ready and willing to help its active alumni and it's always a pleasure for me to help solve a difficult problem. Our chief instructor, Joe Schek is also available to members of the Alumni Association.

There is a lot of interest in video recording and in solar heating among the membership. We have, therefore, made copies of these lessons available to the Alumni Chapters. If your chapter librarian does not have them, please let me know and I'll be glad to send copies of your choice to the librarian.

DETROIT CHAPTER

The subject of the December meeting was TV troubleshooting. Ellsworth Umbreit, one of our members and a highly respected technician, talked about some of the problems and solutions he encountered during his service work.

Ellsworth has connections with the Detroit branch of a well-known manufacturer of electronics kits. From time to time, he is called on to look at unusual troubleshooting problems. He explained a number of the more interesting problems and their solutions at the meeting. One thing we learned is, you should approach a kit differently from the way you approach a factoryassembled unit. The kit may never have worked properly, therefore, normal troubleshooting logic may not be applicable.

Ellsworth's philosophy on education is very practical: If you need to know how to do a job, take a course and learn how to do it. In addition to Ellsworth's training in electronics, he has studied auto air conditioning. He feels this training lessens his dependance on other technicians.

Sam Mangiopane brought in a TV problem at the January meeting, and Ray Berus and Bruce Rittenhouse jumped on it right away. Sam's television, an RCA portable, would not receive one channel. After performing a number of tests, we found that the aft (automatic fine tuning) had a malfunction. After correcting the aft problem and re-adjusting the fine tuning, the problem was resolved.

Training on solid-state circuitry is planned for the near future and we will take up solid-state devices and their applications. If you need help on transistors, SCRs, and similar devices and circuits, get in touch with the members and come to our regular meetings.

FLINT/SAGINAW VALLEY CHAPTER

Radio servicing was one of the topics at our meeting held in late November. Dennis Besser brought in a 5-transistor receiver with "no output." We used a Sencore Super Cricket transistor checker on it, and found two bad output transistors. This instrument checks transistors in or out of the circuit, making it unnecessary to disconnect a transistor for testing.

A while back, we ran into an interesting color problem in an RCA CTC25A chassis. The color would drop out of sync whenever you touched the chassis. We traced it to a rosin solder joint between the color oscillator coil and the color oscillator tube socket. The set had worked only because of a high resistance or capacitive coupling between the coil and tube pin. After applying a hot soldering iron to the solder joint, the problem was corrected. We found the circuit board had been dip-soldered and the solder did not "take" properly on that joint.

Finally, at a recent meeting we outlined our program for the first three months of 1980. The members expressed a strong desire to continue practical training exercises on home entertainment equipment and on smallto medium-sized appliances.

NEW YORK CITY CHAPTER

The election of officers was held at the December meeting. All the incumbents were reelected.

Chairman Sam Antman followed the election with a discussion on a TV set that had fallen off a table and landed on its face.

When power was applied, a flash appeared inside the set. After checking the set, Sam discovered the fuse had blown. This had caused the flash and a resulting strong, burnt odor around the tuner. The tuner shaft was also bent. After removing the barrel of the tuner a burnt resistor was exposed. It was a 1200 ohm resistor in the B+ plate supply of the 3HA5 rf amplifier. Then Sam noticed two contact springs touching – one of them was ground. This accounted for the burnt resistor. He replaced the resistor, straightened the springs and tuner shaft, put the tuner back together, and replaced the fuse.

When he applied power again, nothing happened. He then checked the filament string and everything checked OK. However, closer examination revealed a cracked 4.7 ohm, 4 watt ceramic resistor in the ac circuit. Next, he found a rectifier diode shorted. When he replaced the diode and the resistor, the set started. The shorted tuner spring in the B+ circuit caused the failure of the plate resistor, diode, fusible resistor, and ac line fuse, as all of these parts were in series – one after the other.

NORTH JERSEY CHAPTER

Al Mould presented a Zenith Sight and Sound cassette and service manual discussion on the power supply of the Zenith System-3 color TVs. In the System-3 chassis, most of the operating voltages are obtained from scan-derived power supplies. Voltage is regulated using a very complex pulse-width modulation circuit. This month's discussion covered the theoretical background of this supply. Next month we will cover troubleshooting.

Paul Howard brought in an RCA CTC85 color TV. Paul demonstrated module removal, using a tool that is attached to each set of this series. He

DIRECTORY OF ALUMNI CHAPTERS

DETROIT CHAPTER meets at 8 p.m. on the first Friday of each month at St. Andrews Hall, 431 E. Congress Street, Detroit. Chairman: James Kelly, 1140 Livernois, Detroit. Telephone 841-4972. FLINT/SAGINAW VALLEY CHAPTER meets 7:30 p.m. the second Wednesday of each month at Andy's Radio and TV Shop, G-5507 S. Saginaw Road, Flint. Chairman: Dale Keys. Telephone (313) 639-6688. Shop phone (313) 694-6773.

NEW YORK CITY CHAPTER meets at 8:30 p.m. the first Thursday of each month at 1669 45th Street, Brooklyn. Chairman: Sam Antman, 1669 45th Street, Brooklyn.

NORTH JERSEY CHAPTER meets at 8 p.m. on the second Friday of each month at the Players Club, located on Washington Square in Kearney, N.J. For information, contact Paul Howard, 950 Carteret Avenue, Union, N.J. 07083. Telephone (201) 964-8492.

PITTSBURGH CHAPTER meets at 8 p.m. on the first Thursday of each month at the home of Jim Wheeler, 1436 Riverview Drive, Verona, Pa. 15147. Chairman: George McElwain, 100 Glenfield Drive, Pittsburgh, Pa. 15235.

SAN ANTONIO CHAPTER meets at 7 p.m. on the fourth Thursday of each month at the Alamo Heights Christian Church Scout House, 350 Primrose St., 6500 block of N. New Braunfels Street, (three blocks north of Austin Hwy.), San Antonio. All San Antonio area NRI students are always welcome. A free annual chapter membership will be given to all NRI graduates attending within three months of their graduation.

SOUTHEASTERN MASSACHUSETTS CHAPTER meets at 8 p.m. on the last Wednesday of each month at the home of Chairman Daniel DeJesus, 12 Brookview Street, Fairhaven, Mass. 02719.

SPRINGFIELD (MASS.) CHAPTER meets at 7:30 p.m. on the second Saturday of each month at the shop of Norman Charest, 74 Redfern Drive, Springfield, Mass. 01109. Telephone (413) 734-2609. TORONTO CHAPTER meets at McGraw-Hill CEC, 330 Progress Ave., Scarborough, Ontario. For information, contact Stewart J. Kenmuir at (416) 293-1911. discussed the power supply in this set, which incorporates start-up circuits to power the horizontal oscillator, buffer, and driver stages. The majority of the receiver's operating voltages are then derived from flyback transformer sources, and the start-up circuits are shut down. The set uses a 150 volt supply that is not isolated from the power line. Therefore, an isolation transformer must be used.

Troubleshooting projects included a 19" Magnovox set with a sync problem brought in by Bob Morello, and a 12" Panasonic solid-state set with a raster, but no picture or sound was brought in by Harry Ala. Sam Britt brought in a 12" black-and-white GE, which Dick Wagstaff rejuvenated with his Heath IT5230. Sam also brought in a Sharp 3K-63 with no vertical deflection. Dick Wagstaff, Ted Krawczyk, and several others helped Sam isolate the trouble to the vertical oscillator stage. The base voltage of the transistor was positive instead of a negative 0.75 volt.

PITTSBURGH CHAPTER

In December we held our annual election of officers. Our new chairman is James Brugh. Past chairman, George McElwain, was elected to our Board of Directors. After the meeting, we held our Christmas Party and took some time to reflect on the importance of comradship.

During 1980, we hope to increase the range of topics covered in our meetings and to continue providing practical help and training. Primarily, we expect to work with more consumer electronics equipment and spend more time on business operations.

SPRINGFIELD, MA CHAPTER

Our November meeting featured a tour of the Springfield Telephone Switching Center. This tour was arranged by Joe Gaze, one of our members.

We started the tour at the "old cable vault" where we found literally miles of inactive cables that had been replaced. It was easy to see the technological changes, since the space required for the new cables was about one-quarter of the space taken up by the old ones. We also saw the machinery that provides pressurized dry air, which is maintained throughout the cable system to prevent the entry of moisture.

We then proceeded to another floor where the cables terminate at banks of connection terminals. Here individual lines are connected into the telephone system by the use of small plug-in coils.

Next we had a chance to see an example of troubleshooting. With the aid of a "dial hand set," the technician can test any line by a connection to the line in question. He dials in the code number and in seconds a mechanical voice calls out the number of the line being tested.

We were then taken to another floor where we were introduced to the computer that tells the technician when there is trouble and where to look for it.

Robert E. Bonge

Robert E. Bonge, past national vicepresident and past chairman and secretary of the San Antonio (Alamo) Chapter of the NRI Alumni Association, died on Nov. 25, 1979. Long-time members of the Alumni Association and of the San Antonio Chapter are saddened by the passing of this inspiring, en ergetic, and devoted friend. The computer, which is located about 90 miles away, constantly monitors the 100,000 subscriber lines in this area and monitors itself. It responds to all of the various troubles that occur on the phone lines.

Concluding our tour, we were told that this particular computerized system has eliminated the need for three floors of the older relays and associated equipment. This has permitted an increase in service without adding to the facilities.

All of the members who took the tour found it a most interesting and educational evening.

CHAPTER VISITS

The schedule of local chapter visits by the executive secretary of the NRI Alumni Association for 1980 is shown below. All NRI graduates and students are invited to attend these Alumni Chapter meetings. As the executive secretary, I will demonstrate various types of equipment and present technical information that you will find helpful and interesting. This will give you more insight into what NRI Training is all about and what lies ahead for you in various technical fields. Other NRI staff members attend some of these meetings, so you may get an opportunity to meet some of the people who participate in your training.

If you would like to attend an Alumni Chapter meeting, contact your local chapter at the address or phone number given in the "Directory of Alumni Chapters" on page 26 or contact me here at NRI. If you contact me, I will send you a reminder a few days before the meeting scheduled in your area.

Schedule of (Chapter Visits
San Antonio Chapter	Thursday, April 24
Pittsburgh Chapter	Thursday, May 1
North Jersey Chapter	Friday, May 9
Southeastern MA Chapter	Wednesday, Sept. 24
Flint/Saginaw Valley Chapter	Wednesday, Oct. 1
Detroit Chapter	Friday, Oct. 3
Philadelphia/Camden Chapter	Friday, Oct. 17 (tentative)
Springfield MA Chapter	Saturday, Nov. 8
New York City Chapter	Thursday, Dec. 4

The following ballot lists the names of those nominated to serve as officers of the NRI Alumni Association for the 1980 term. Please fill out your ballot and return it to NRI as

soon as possible. The names of those elected will be announced in the next issue of the *NRI Journal*. POLLS CLOSE AT MIDNIGHT ON TUESDAY, APRIL 15, 1980.

For President (vote for one):

Sam Antman New York City, NY Paul Howard Union, NJ

For Vice President (vote for four):

Ray Berus Detroit, MI

George McElwain Pittsburgh, PA

Richard Wagstaff Kearny, NJ Sam Dentler San Antonio, TX

Al Mould Kearny, NJ

Willie Foggie New York City, NY

Your Name_

Student Number

NRI Insulated Cups



Stock No. CU100

Perfect for cookouts, camping, your shop, and your family room. Comes to you in NRI colors of red and white. Dishwasher safe and durable. Available now from CONAR.

Number Purchased

Cost

1 2–5 6–11 12 or more \$2.25 each 1.95 each 1.75 each 1.50 each

March/April 29

CONAR, Presents...

7-Drawer Gest

\$67.50 No.CY1007

An excellent tool chest with self-storing drop front lock panel, felt-flocked replaceable drawer liners, tumbler lock and two keys, and gray baked-enamel finish.







More than an ignition tester – a diagnostic analyzer that lets you analyze the operating condition of electronic ignition systems in all American cars. When the light blinks, the component is satisfactory. If the light stays on, the component is defective. Operates with LED display to check magnetic pickup, modules, and coil circuits.

Battery Garger

Solid-State System Tester

\$23.50 No. AC472



A pocket-sized tester that hooks to a car battery. Five LEDs for diagnoses of all 12 volt auto systems, either positive or negative ground. One light tells all. Check battery voltage, charging rate, wiring, alternator, regulator, and diodes — all with one tester! All instructions are fully defined on the decal.

\$5.50 No. AC662

Gives a quick start in any weather and can't overcharge. Precision transformer keeps battery charged. Plugs into any 120 VAC outlet and includes UL listed cord and trickle charge of 12 V, 1 ampere.



Honors Program Awards

In the tradition of NRI's pursuit of excellence in training, the following graduates who earned NRI diplomas in November and December also earned unusual recognition under the NRI Honors Program. On the basis of their grades, these graduates distinguished themselves by earning the right to honors listed below, in addition to their regular NRI diploma. This distinction is made part of their permanent NRI record.

WITH HIGHEST HONDRS

Kenneth John Barr, Framingham MA Charles William Bern, Jr., Zephyrhills FL Richard M. Birt, Charlottetown PEI CANADA Norman C. Butterfield, Tacoma WA Terence M. Breen, Millville WV Skip W. F. Cadwallader, Orlando FL E. J. Chandler, Indianapolis IN William J. Conley, Titusville PA E. J. Connelly, Leavenworth KS William V. Deardoff, Philadelphia PA Randell A. Eis, Unadilla NE Clifford W. Farmer, Oak Grove KY Lynn S. Gorrell, Burlington 1A Robert Le Grand, Jr., Upper Saddle River NJ Harry James Hunt, O'Fallon MO Scott Eric Kenyon, Holley NY Donald J. Kleeberger, Perrysburg OH Robert W. Jervis, Columbus OH Bobby W. Johnson, Pasadena TX Larry Stuart Judd, Ridgefield CT John V. Labbe, Munroe Falls OH William E. Lester, Kerrville TX Lindsey S. Lewis, Delta CO Clayton Timothy Logue, Weiser ID Dennis C. Lytle, Pineville LA Thomas C. McNallan, Rochester MN Arthur Q. Oaks, Cambridge Springs PA Norman W. Reed, Lewiston NY Girard K. Russell, Elk Grove Village IL Richard E. Samborski, Buffalo NY Robert L Umholtz, Pine Bluff AR Michael A. Wilusz, South Portland ME

WITH HIGH HONORS

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The National Institute for Automotive Service Excellence (NIASE) will offer tests for certification of automobile mechanics on May 1, 6, 8, and 10; heavyduty truck (including bus) mechanics on May 1, 6, and 10; and both body repair and painting and refinishing on May 8, 1980. Test centers are located in about 260 cities across the United States. Applications must be in by March 31, 1980. For a copy of the *Bulletin of Information*, which includes a registration form, sample test questions, and detailed information about the tests, write to NIASE, Suite 515, 1825 K Street, N.W., Washington, D.C. 20006.

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This article, and related articles in later issues of the *Journal*, will be concerned primarily with the Model II Microcomputer. This is the computer offered as part of the new NRI Microcomputer course.

The purpose of this series of articles is to present programs and hardware that can be used with the Model II Microcomputer to perform a wide variety of functions. Most of these applications programs will be short, and many of them will be fully relocatable. In fact, it will be possible to run many of them on other 6800- or 6802-based microcomputer systems. The hardware will be kept as simple as possible, and will always be arranged so that it can be connected directly to the Model II. However, as with the applications programs, the hardware will be readily adaptable to other compatible computer systems.

Figure 1 shows the Model II Microcomputer as it appears when fully

assembled, at the conclusion of Training Kit 10MC. However, it is not necessary to complete the computer before using it to run programs. In fact, the student will have an operating computer after completing Training Kit 8MC (the second computer kit). At this point, the computer will appear as shown in Fig.2. Although it may not look as impressive at this stage as the completed Model II, it is already fully capable of running machine-language programs up to 4K (4096 bytes) in length, and of saving and reloading those programs using the built-in cassette interface. In its final form, the Model II can still run the same machine-language programs, but it is also capable of running programs in BASIC, using the built-in BASIC interpreter.

Because the NRI Microcomputer Course is new, no one has yet completed all four kits comprising the computer. Therefore, the remainder of this article will be devoted to a program that



FIGURE 1. THE NRI MODEL II MICROCOMPUTER.

can be run on the computer as it stands following Training Kit 8MC. As more Training Kits are completed, more complex programs and BASIC programs and routines will appear. However, we will also have additional programs that can be run directly on incomplete computers.

USING THE DOUBLE-PRECISION ARITHMETIC PACKAGE

One of the main requirements of almost any program is to perform the basic arithmetic functions of addition, subtraction, multiplication, and division. At the same time, however, a limit of 0 to 255, or -128 to +127, is often too small to be of practical use. Also, it is generally desirable not to have to move both operands to special memory locations to perform the arithmetic operations. All of these problems can be arithmetic package, such as the one shown in the listing at the end of this article.

In order to use the double-precision routines in this package, it is necessary that the operands reside in adjacent locations in memory. The exact locations in memory are unimportant, but



FIGURE 2. THE COMPUTER AT THE CONCLUSION OF TRAINING KIT 8MC.

the order in which the operands appear must be as shown in Fig.3. Furthermore, the index register (X) must contain the address of the high-order byte of the second operand. Then the loworder byte will appear at 1,X. The first operand will be located at 2,X and 3,X. This permits indexed addressing to be used throughout all operations, so that the arithmetic routines do not need to contain specific operand addresses.

The order in which the operands appear is unimportant for addition and multiplication. During subtraction and division, however, it is extremely important that the operands be in the correct sequence. In order to be sure that this requirement is met, it is best to maintain this sequence for all operations. Therefore, when using these routines, make sure that the X register points to the high-order byte of the addend, subtrahend, multiplier, or divisor, as shown in Fig.3. Then the augend, minuend, multiplicand, or dividend should appear in the next two bytes beyond. Also, the high-order byte should precede the low-order byte of each operand. This is consistent with the normal way in which 16-bit numbers are handled by the CPU.

The double-precision routines themselves are as direct and straightforward as possible. For example, the addition routine, DPADDX, first saves the contents of accumulator A on the machine stack. (This is desirable to avoid complicating the calling program, and is necessary anyway, because the multiplication and division routines use DPADDX.) The addition routine then gets the low-order byte of the augend, adds the low-order byte of the addend, and stores the sum in place of the low-order byte of the augend. The next step is to get the high-order byte of the augend and add the high-order byte of the addend. However, the carry



FIGURE 3. THE REQUIRED OPERAND FORMAT FOR THE DOUBLE-PRECISION ARITH-

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generated by the addition of the loworder bytes must be included when adding the high-order bytes. This is accomplished by using the ADC (ADd with Carry), instead of ADD. The carry flag was set or cleared by the ADD instruction, but was not affected by either the STA or LDA instruction. The resulting sum is stored in place of the high-order byte of the augend. Finally, the original contents of accumulator A are recovered from the stack, and control is returned to the calling program. The sum has replaced the augend, and the index register has not been moved.

The double-precision subtraction routine, DPSUBX, is the same as DPADDX except that in this routine, the subtrahend is subtracted from the minuend instead of being added. For this reason, it is essential that the operands appear in the order indicated in Fig.3. When the subtraction process is completed, the difference will have replaced the minuend.

PERFORMING DOUBLE-PRECISION MULTIPLICATION AND DIVISION

Double-precision multiplication is somewhat more complicated than either addition or subtraction. There are several methods that can be used to accomplish multiplication. The easiest way to visualize the process is to consider it as a series of repeated additions. Unfortunately, this process takes the greatest amount of time, and requires extra programming to keep track of any carries out of the double-precision product. This latter process is necessary because the total product of two 16-bit numbers is 32 bits long, and must be accounted for throughout the process.

A second possible method is the shift-and-add process. This is much faster than the repeated addition

method. Furthermore, if the multiplicand and product (rather than the multiplier) are shifted, the problem of outgoing carries takes care of itself. However, this method cannot handle negative numbers. Therefore, the signs of the operands must be checked to determine the final sign of the result. The operands must both be made positive (if necessary) before starting. The product might also have to be converted to negative form (if one operand were negative). It would be preferable to use a multiplication method that will work directly with either positive or negative numbers and produce the correct signed product.

The procedure that meets these requirements is known as *Booth's al*gorithm. Unlike other multiplication methods, Booth's algorithm looks for transitions between \emptyset and 1 in adjacent bits of the multiplicand. The step-wise procedure can be stated as follows:

1. Imagining a \emptyset bit to the right of the LSB of the multiplicand, compare the two rightmost bits, from right to left.

2. If the two bits in question are the same, proceed to Step 5.

3. If there is a \emptyset -to-1 transition, subtract the multiplier from the product.

4. If there is a 1-to-Ø transition, add the multiplier to the product.

5. Keeping the MSB of the product the same, shift the multiplicand and product one bit to the right.

6. If there are any bits in the multiplicand left to compare, go back to Step 1. Otherwise, stop.

While this procedure requires some thought to understand it thoroughly, it is actually very easy to implement. It runs very fast, and occupies very little memory space. This is the procedure that is used by the double-precision multiplication routine, DPMPYX.

The product generated by DPMPYX is 32 bits long. Therefore, it replaces both the multiplicand and the multiplier, with X pointing to the most significant byte. In order for the product to remain as a double-precision number, the high-order half must be $\emptyset \emptyset \emptyset \emptyset$ for a positive result, or FFFF for a negative result. Then the doubleprecision product that replaced the multiplicand will be correct and valid. If any other value appears as the highorder two bytes of the product, an overflow has occurred, so the product is no longer a correct double-precision value.

DPMPYX must actually keep track of six bytes simultaneously. These are the growing product, the diminishing multiplicand, and the complete multiplier. To do this, it assumes that the two bytes immediately below the original multiplier are unused and therefore available. It calls the subroutine DPMVOP to decrement X twice and move the multiplier down two bytes. DPMVOP then clears the original multiplier to start with a zero product, and initializes accumulator B to the shift count of 16.

When the multiplication process is complete, the index register is incremented twice to restore it to its original value, and the original contents of the two accumulators are restored before control is returned to the calling program.

Division can be performed by either a repeated subtraction method or by an alternate shift-and-subtract method. The latter method is preferred, not only because it is faster, but because it will not lock up if division by zero is attempted. In such a case, it returns a quotient of FFFF and a remainder equal to the original dividend. Such a result can easily be used to detect an illegal operation.

Unfortunately, there is no known equivalent to Booth's algorithm that will operate for division. Therefore, the double-precision divide routine, DPDIVX, uses the alternate shift-andsubtract approach. This makes the routine relatively fast, but does preclude the use of signed numbers; both dividend and divisor must be positive numbers. If they are negative, they will be treated as unsigned binary numbers, for which an unsigned binary quotient and remainder will be generated. These results will be correct, provided that the calling program treats them as unsigned binary numbers.

As with DPMPYX, DPDIVX must keep track of six bytes. These include



About the Author

Ken Bigelow joined us in 1969. Since then, Ken has served NRI in a number of capacities. Most recently, he wrote the experiments for the Microcomputer course, and is interested in expanding its capabilities as much as possible.

"This series of articles is aimed at presenting a variety of applications programs, as well as various ideas for hardware expansion. I'm eager to give new ideas a try, so be sure to drop me a line with your suggestions."

the growing quotient, the diminishing dividend (which will eventually become the remainder), and the complete divisor, Therefore, DPDIVX, like DPMPYX, calls DPMVOP as soon as the contents of the two accumulators have been saved. Then accumulator A is cleared to initialize the quotient bit. The dividend and cleared bytes are shifted one bit to the left in preparation for the first trial subtraction. DPSUBX is called to perform the trial subtraction. If it is successful, there will be no borrow bit upon return from DPSUBX. Therefore, the SBC A #\$FF instruction will leave Ø1 in accumulator A. On the other hand, if the result of the subtraction is negative, indicating a failure, the carry flag will be set to indicate a borrow. In this case, the SBC A #\$FF instruction will leave 00 in accumulator A. Thus, accumulator A will contain the correct quotient bit generated by the trial subtraction. If this bit is 0, the divisor must be added back to the dividend to cancel the subtraction

In either case, the new quotient bit is added to the growing quotient. Then the shift count is decremented. If the shift count is not zero, the partial quotient, dividend, and cleared space are again shifted left one bit, and the process is repeated.

Finally, as with DPMPYX, the index register is restored to its initial value, and the two accumulators are restored before control returns to the calling program. The quotient has replaced the dividend and the remainder has replaced the divisor. The index register points to the remainder.

APPLICATIONS

All of the double-precision routines are written using only indexed and relative addressing. No monitor or ROM routines are required at any time. As a result, this double-precision arithmetic package is totally relocatable. That is, although it is shown as starting at address $3F\emptyset\emptyset$, it can easily be moved to any other location in memory, and will run there without being modified. Furthermore, the same double-precision package can be used on any other computer that uses a 6800 or 6802 microprocessor as its CPU, without any modification. However, when this program is moved to another location or machine, it must be moved as a single block of 112 bytes. The internal sequence of routines must not be changed, or the routines will not work properly.

In order to use any of the doubleprecision routines, it is only necessary for the calling program to place the two operands, in the proper sequence, into four successive memory locations, and then set X to the first memory location. Then a JSR to the starting address of the appropriate routine will cause the desired operation to be performed. The index register will be unchanged upon return from the subroutine, so indexed addressing can immediately be used by the calling program to recover the result for use within that program.

The applications for these routines are limited only by your imagination. A few typical applications would be ordinary mathematical calculations, determining the memory space required by a memory array of any number of dimensions, or calculating memory offsets. Of course, any variation on these or any number of other applications may still call for these routines. You may also find that variations on these routines will be helpful in a given program.

In future issues of the Journal, I'll continue to discuss applications programs, as well as hardware expansions and applications for the Model II Microcomputer. Meanwhile, if you have any ideas you'd like to share, please let me know. Write to me at NRI, 3939 Wisconsin Ave., Washington, D.C. 20016.

PROGRAM DOUBLE-PRECISION ARITHMETTIC PACKAGE BY

PAGE 1

.

Location	B1	B2	B3	Label	OP	ACC	Operand	Comments
3FØØ	36			DRADDX	PSH	A		DOUBLE-PRECISION ADD.
1	Alo	\$3			LDA	A	3.X	
3	AB	ØI			ADD	A	LX	ADD LOW-ORDER BYTES.
5	AT	\$3			STA	A	3.X	
7	Ale	\$2			LDA	A	2.X	
9	A9	de			ADC	A	Ø,X	ADD HIGH-ORDER BYTES, WITTH
B	A7	\$2			STA	A	2.X	CARRY FROM LOW ORDER.
D	32				PUL	A		
E	39				RTS			SUM REPLACES AUGEND,
			-					
F	36			DPSUBX	PSH	A		DOUBLE-PRECISION SUBTRACT.
1¢	Ab	ØE			LDA	A	3, X	
2	Ad	ØI			SUB	A	1, X	SUBTRACT LOW-ORDER BYTES.
4	A	\$3			STA	A	3,X	
6	A6	Øa			LDA	A	2,X	
8	42	ØØ			SBC	A	Ø,X	SUBTRACT HIGH-CRDER BYTES,
A	AT	\$2			STA	A	2, X	WITH BORROW FROM LOW ORDER.
C	32				PUL	A		
D	39				RTS			DIFFERENCE REPLACES MINUEND.
3FIE	36			DPMPYX	PSH	A		DOUBLE-PRECISION MULTIPLY.
F.	37		_		PSH	B		USES BOOTH'S ALGORITHM.
30	8D	33	_		BSR		DAMNOP	MAKE SPACE FOR FULL PRODUCT
2	8D	42		DPMPY1	BSR		SHAR2X	SHIFT PRODUCT AND MULTIPLICAND.
4	2B	2A			BMI		DPMD9	QUIT IF LAST SHIFT.
6	24	FA			BCC		DPMPYI	C= & MEANS NO CHANGE.
8	8D	E5			BSR		DPSUBX	\$ TO 1 CHANGE: SUBTRACT.
A	80	3A		DPMPY2	BSR		SHHRAX	SHIFT PRODUCT AND MULTIPLICAND.
C	ZB	22			BMI		DPMD9	QUIT IF LAST SHIFT.
E	25	FA	_		BC.S		DPMPY2	C=1 MEANS NO CHANGE.
3¢	80	CE			BSR		DPADDX	I TO Ø CHANGE: ADD.
2	20	EE			BRA		DPMPY1	GO BACK AND SHIFT.

PROGRAM DOUBLE-PRECISION ARITHMETIC PACKAGE BY IDATE

PAGE 2

Location	81	B2	B3	Label	OP	ACC	Operand	Comments
H	36			DPDIVX	PSH	A		DOUBLE-PRECISION DIVIDE.
5	31				PSH	B		USES SHIFT-AND-SUBTRACT.
6	8D	LD			BSR		DPMYOP	MAKE SPACE FOR REMAINDER.
8	4F			DPDIYI	CLR	A		CLEAR QUOTIENT BIT.
9	68	\$5			ASL		5, X	SHIFT QUOTIENT AND
B	69	04			ROL		4.X.	DIVIDEND LEFT ONE BIT.
D	69	\$3			ROL		3, X	
F	69	92			ROL		2, X	
41	80	CC			BSR		DPSUBX	MAKE TRIAL SUBTRACTION,
3	82	FF			SBC	A	#\$FF	IF NO BORROW, IT SUCCEEDED,
5	26	\$2			BNE		DEDIVA	AND QUOTIENT BIT IS 1.
7	SD	B7			BSR		DPADDX	ELSE, ADD DIVISOR BACK.
9	AB	\$5	1	DPDIVA	ADD	A	5, X	INSERT LATEST QUOTIENT BIT.
В	A7	05			STA	A	5,X	
D	5A				DEC	B		COUNT OFF ONE CYCLE.
E	26	E8	-		BNE		DFDIVL	REPEAT UNTIL DOUE.
50	98		-	DPMD9	INX			RESET X AND
1	\$8				INX			
3	33				PUL	B		RECOVER <a> AND .
3	32	-			PUL	A		QUOTTENT REPLACES DIVIDEND,
4	39				RTS			REMAINDER REPLACES DIVISOR.
2-55		-		* 01 100				
3F55	04	-	-	DPMVOP	DEX			OPEN A CLEAR SPACE FOR
6	<u>a4</u>	47	-		DEX	1	0	EITHER THE REMAINDER
1	46	Pok			LDA	A	d,X	OR THE HIGH-ORDER HALF
9	HI	<i>\$q</i>			STA	14	φ, x	OF THE PRODUCT.
D	GF	00			CLR	4	X,X	
P	16	43	-		LDA	A	3, X	
F	1	01			SIA	A	LX	
2	65	10			CHA I DA	R	3,X 4 1/	SET SHIFT ADMIT
5	20	14			CTT.	D	#-16	SET SHIFT COUNT.
	51	-			KIS.			
			-					
6	67	07		SHARAX	ASR		2. X	SHIFT PARTIAL PRODUCT
8	66	03			ROR		3.X	AND MULTIPLICAND RIGHT
A	66	04			ROR		H,X	ONE BIT.
C	66	05			ROR		5.X	
E	5A				DEC	B	-) ~	COUNT OFF ONE SHIFT
F	39				RTS			

NRI Journal March/April 1980

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