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CONTENTS

Scanning the Issue	402
Poles and Zeros	403
Carl E. Granqvist, Vice-President, 1958	404
Microwave Antenna and Waveguide Techniques Before 1900	John F. Ramsay 405
Ghost Modes in Imperfect Waveguides	E. T. Jaynes 416
High-Frequency Crystal Filter Design Techniques and Applications	David I. Kosowsky 419
Experimental 8-MM Klystron Power Amplifiers	T. J. Bridges and H. J. Curnow 430
FM Demodulator Time-Constant Requirements for Interference Rejection	Elie J. Baghdady 432
A High-Power Periodically Focused Traveling-Wave Tube	O. T. Purl, J. R. Anderson, and G. R. Brewer 441
Index to IRE Standards on Definitions of Terms, 1942-1957	449
Measurement of the Radar Cross Section of a Man	F. V. Schultz, R. C. Burgener, and S. King 476
IRE Standards on Television: Measurement of Luminance Signal Levels, 1958	482
Theory of Networks of Linearly Variable Resistances	Harold Levenstein 486
Correspondence:	
A Parametric Electron Beam Amplifier	T. J. Bridges 494
On the Earth Geometry—A Theorem	Kurt Toman 495
Behavior of Noise Figure in Junction Transistors	W. N. Coffey 495
Electrolytic Tank Design of Electron Guns with Curved Electron Trajectories	E. J. Cook 497
Space-Charge-Balanced Hollow Beam with Uniform Charge Distribution	M. Chodorow and C. Süsskind 497
Design of Three-Resonator Dissipative Band-Pass Filters Having Minimum Insertion Loss	M. Dishal, B. Sellers, J. J. Taub, and B. F. Bogner 498
Space-Frequency Equivalence	W. E. Kock and J. L. Stone 499
Thermal Properties of Tungsten vs Copper for Electron Tube Delay Lines	Roy A. Paananen 500
Microwave Magnetic Field in Dielectric-Loaded Coaxial Line	B. J. Duncan, L. Swern, and K. Tomiyasu 500
Carrier Mobilities at Low Injection Levels	J. A. Hoerni 502
Hyperbolic Analogs	Melbourne J. Hellstrom 502
Contributors	503
IRE News and Radio Notes:	
Calendar of Coming Events	505
Obituaries	507
Professional Group News	507
1958 Transistor & Solid State Circuits Conference	508
Books:	
"Microwave Measurements," by E. L. Ginzton	Reviewed by A. B. Giordano 508
"Analytical Design of Linear Feedback Controls," by G. C. Newton, Jr., L. A. Gould, and J. F. Kaiser	Reviewed by A. M. Hopkin 508
"Nomograms of Complex Hyperbolic Functions," 2nd ed., by Jorgen Rybner	Reviewed by Martin Katzin 509
"Solid State Physics, Vol. IV," ed. by F. Seitz and D. Turnbull	Reviewed by L. T. DeVore 509
Scanning the TRANSACTIONS	510
Abstracts of IRE TRANSACTIONS	512
Abstracts and References	516

ADVERTISING SECTION

Meetings with Exhibits	6A	Section Meetings	58A	Meetings	74A
IRE People	14A	Industrial Engineering		Positions Open	118A
News—New Products	34A	Notes	68A	Positions Wanted	130A
Membership	38A	Professional Group		Advertising Index	141A

THE COVER—This reproduction of Marconi's patent specification for a 25-centimeter wavelength transmitter reveals that parabolic reflector antennas were in use as early as 1896. This is but one of a surprisingly large number of microwave antenna and waveguide techniques that were developed by early radio experimenters in the decade prior to 1900. An interesting history of these early microwave developments is presented in a paper starting on page 405 of this issue.

Scanning the Issue

Scanning the Transactions (p. 510)—A new monthly feature of the PROCEEDINGS starts in this issue which will endeavor to provide readers with an informative sample of new developments drawn from current issues of the TRANSACTIONS and other IRE publications.

Microwave Antenna and Waveguide Techniques Before 1900 (Ramsey, p. 405)—Our modern microwave technology is built largely on discoveries and developments made between 1930 and 1940. We associate with this period the beginning of the microwave era. Nevertheless, the earliest radio experimenters, in the period from Hertz's initial demonstration of radio waves in 1888 to the turn of the century, did a surprising amount of work in the microwave portion of the spectrum before it was abandoned for the then more practical and useful lower frequencies. This historical review of these many early developments in the microwave art, at wavelengths as short as 5 millimeters and high peak powers, will come as an eye-opener to most readers.

Ghost Modes in Imperfect Waveguides (Jaynes, p. 416)—This paper calls attention to the fact that imperfections in a waveguide, such as that caused by placing a dielectric in it, can cause so-called ghost modes in the immediate vicinity of the imperfection which can give rise to unexpected and troublesome resonance effects, especially in high-power applications. These spurious resonances may in fact arise just outside the pass band of any periodic structure that has a localized imperfection. Indeed, they are analogous to certain phenomena that have been observed in imperfect crystals of solid-state materials. While this phenomenon probably has no practical applications, it does improve our understanding of an effect which can in some cases cause an operational breakdown in a wide variety of wave propagating systems.

High-Frequency Crystal Filter Design Techniques and Applications (Kosowsky, p. 419)—This paper gives what is probably the first description of the use of crystals in filters at frequencies well above one megacycle. High-frequency crystal filters are now becoming commercially available in the 5 to 40 mc range which exhibit performance characteristics previously attainable only at lower frequencies, with Q 's ranging from 50,000 to as high as 1,000,000 and bandwidths from one cycle to several hundred kilocycles per second. These high-frequency filters will find a substantial number of uses in single sideband, AM and FM equipment. For example, FM receivers can now be designed with only a single frequency conversion and a high-frequency IF, instead of multiple frequency conversions and a lower IF, without impairing adjacent channel selectivity and with a resultant reduction of circuits. The discussion of crystal filter design techniques presented here will be of major interest to a large number of communication equipment designers, while the easily followed presentation and the many interesting applications cited will appeal to all readers.

Experimental 8-mm Klystron Power Amplifiers (Bridges and Curnow, p. 430)—By extending the emission capabilities of oxide cathodes to 1.5 a/sq. cm it has proven possible to produce 75 watts of cw power at 8 millimeter wavelengths. This represents a six-fold increase over previous efforts and the highest power yet reported at these high frequencies.

FM Demodulator Time-Constant Requirements for Interference Rejection (Baghdady, p. 432)—An investigation has been made of the demands imposed on FM receiver circuits in order that they may operate satisfactorily in the presence of a high level interfering signal. It is found that these demands require that ideally the time constants of the limiter and discriminator circuits must be short enough to cope with the sharp amplitude and frequency changes that are characteristic of a disturbed signal. These ideal requirements may conflict, however, with other fundamental requirements.

Some simple schemes are discussed which minimize the conflict and greatly enhance the capture performance of a FM receiver.

A High-Power Periodically Focused Traveling-Wave Tube (Purl, *et al.*, p. 441)—Periodically placed magnets have been widely used in beam focusing systems in order to reduce the weight and power requirements of low-power traveling-wave tubes to more practical values. However, as the power of tubes increases so do the problems of focusing the higher density beams. This paper describes a periodically focused tube that operates from 2 to 4 kmc at the kilowatt level. The achievement of such relatively high powers and wide bandwidths by means of this type of focusing is a significant step forward in making high power twt's a practical component in systems.

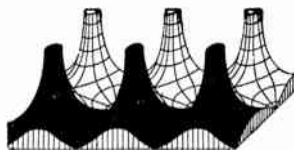
Index to IRE Standards on Definitions of Terms, 1942-1957 (p. 449)—The entire technical language of the radio engineer, from "A and R Display" to "Zoning," culled from some three dozen IRE Standards on the subject, is brought together in this one alphabetical list. Approximately 3500 terms, representing 15 years of work on the part of IRE technical committees, are listed with a reference to the Standard and the PROCEEDINGS page where the definition of each term may be found. This will be an invaluable aid to the future work of individuals and committees in this field, and stands as imposing evidence of the extent to which a still young profession has advanced.

Measurement of the Radar Cross-Section of a Man (Schultz, *et al.*, p. 476)—This is the first disclosure of quantitative measurements of how good a radar target a man is. CW Doppler measurements were performed at five frequencies ranging from 410 mc to 9375 mc, using both vertical and horizontal polarization from various angles. It was found that the side view of a man presented the smallest radar target and the back view the greatest, and that the difference between polarizations was greatest at the lowest frequency, with horizontal polarization giving the smaller value. While the authors do not go into the applications of these experiments, it is obvious that the data will be of value in the design of military equipment for the detection of the movement of small patrols.

IRE Standards on Television: Measurement of Luminance Signal Levels (p. 482)—This Standard specifies the method by which operating personnel of a television transmitter may measure the relative levels of monochrome signals or of the luminance portion of color signals by means of an oscilloscope. It is a revision of a 1950 IRE Standard covering monochrome signal levels which, because it came before the adoption of color television signal standards in the U. S., was inadequate for color signal measurements.

Theory of Networks of Linearly Variable Resistances (Levenstein, p. 486)—The design of analog devices frequently calls for the use of potentiometers whose output voltage must vary in some special nonlinear manner as the shaft is rotated. A variety of ingenious and intricate circuits have been devised to meet these requirements, designed, of necessity, by empirical methods. The guesswork that goes into the empirical approach does not, however, result in the best possible design. In this paper, the author proposes that a network consisting simply of fixed resistances and linear rheostats driven by a common shaft be used instead of nonlinear elements, and shows that such networks are very amenable to good design techniques. Moreover, he shows that these networks can be described in a mathematical form that is analogous to that of fixed RL networks. This leads to the development of a general theory of variable resistance networks that permits them to be analyzed by the more highly developed techniques of fixed RL network theory.

Poles and Zeros



Standards Story. In this issue appears an index to all IRE Standards Definitions of Terms, indicating where you can find the terms defined in standard form. This should prove useful to the membership because in the past 15 years of intense IRE activity, these definitions have become scattered throughout nearly three dozen Standards publications. You may be surprised to note that the list approximates 3500 special words or definitions required to describe conditions or things in our profession. Thirty years ago there were only 277 such terms on the books. If one assumes a continued growth of terminology at this rate for the *next* thirty years, we would have 37,000 definitions. However, one can cast considerable doubt on such prediction by noting that a typical modern abridged American dictionary contains only about 60,000 words. In fact, it might be better to bet on Madison Avenue as a source of fifty per cent of our words in the next thirty years. It is also possible to conclude that at some point one has enough words available to adequately describe his activities, and then there will be those who will say we already have too many words, or at least we use them much too often.

It is interesting to note the many cases where technical words have grown out of something which started as typical American slang. To mention a few are nonkey chatter, grass, blip, back porch, wow, and flutter. This seems to indicate a healthy down-to-earth view of our daily work, and it is to be hoped that electronics can continue to keep its feet on the ground.

The Standards Committee is certainly to be congratulated on the completion of an excellent job.

Nothing New! Immersed as we are in an industry producing things for tomorrow, it always comes as a rude shock to find that we are not nearly as modern as we had thought. Such a shock, or at least a mild thrill should come from the reading of the paper by John F. Ramsay in this issue entitled, "Microwave Antenna and Wave Guide Techniques Before 1900." To one who had the general impression that Barrow, Chu, Southworth, and a few other more or less modern investigators had discovered how to pour electromagnetic energy down the drain, this paper is deflationary. When one discovers that, prior to 1900 and Marconi, our predecessors were working in microwaves with wavelengths as short as 5 millimeters and peak powers of 70 kilowatts, one is even more hammered down in size.

When Marconi ultimately showed that the longer wavelengths seemed more suited for communication to great distances, the investigations into the microwaves of that date were dropped. We then had to wait many years for the amateurs to show the efficacy of the short waves, for radar to require development of the centi-

meter waves and microwave plumbing. Now we have come more than full circle to a realization that many valuable properties of the long waves have been overlooked.

A somewhat similar situation developed in the early 1920's. With the crowded radio broadcast spectrum of the time, investigators were looking into the possibilities of frequency modulation to reduce bandwidth. Carson published a paper which showed this was not possible, but which everyone interpreted as saying that frequency modulation had no value. Again, numerous years passed until Armstrong showed that there was value to the use of frequency modulation if we looked in exactly the opposite direction in which we had been looking in the early 1920's.

Apparently a scientific investigator is as easily bent as a twig in the wind.

Students and High Schools. One eminent engineering educator defines a vacuum tube as "something full of nothing out of which you get lots you do not expect." This might well be broadened to a definition for the whole field of electronics. Certainly the IRE STUDENT QUARTERLY, in its thorough and surprising manner, has come up with a result which was not fully expected.

While we hear much about the poor quality of our high school science educations, we actually seem to lack proof. This past fall our sister publication polled the junior and senior electrical engineering students asking their reactions towards their own high school preparations for engineering college. Many interesting comments were obtained, some of which were published in the December issue of the QUARTERLY (advertisement), but the most surprising result was that, in general, the students, about to become electronic engineers, are fairly well-satisfied with the job the high schools did on them.

To an educator interested in best utilizing the brains and intellectual man power of this country this raises a disquieting question. Are our high schools really that good, or does this mean that a student having a poor high school preparation stands no reasonable chance of reaching the junior or senior year of a modern electrical engineering curriculum? Having in the last several years talked to some hundreds of aspiring engineers who were not making it, we have a disquieting feeling that the latter conclusion may be correct. In any case, with Sputniks overhead, we have heard surprisingly little from the secondary school front as to what they are going to do about our need for better science and mathematics. As one educator has said, it is now time to start *learning* in our high schools and grade schools.—J. D. R.



C. E. Granqvist

VICE-PRESIDENT, 1958

Carl Eric Granqvist was born on March 2, 1910 in Ljungby, Sweden. He has the Master of Art degree in electrical engineering from the Royal University of Technology in Stockholm.

Mr. Granqvist holds over twenty-five patents in the field of radio air navigation systems and devices. He has written several textbooks on radio and descriptive booklets on the a-ga talking beacon and the vhf direction finder.

As Chief Engineer of Svenska Aktiebolaget

Gasaccumulator, Stockholm-Lidingo, Sweden, he was in charge of design, research and development in the electronic laboratory of that company. His present title is Director of that laboratory.

Mr. Granqvist belongs to the Swedish society, Svenska Teknologforeningen. He has also served as adviser on the Swedish Electric Committee and member of Standard Committee NK 50. He became an IRE Associate Member in 1946, and a Fellow in 1955.

Microwave Antenna and Waveguide Techniques Before 1900*

JOHN F. RAMSAY†, ASSOCIATE MEMBER, IRE

Summary—Between the years 1888, when Hertz first launched electromagnetic radiation in the radio spectrum, and 1900, when Marconi was successfully establishing communication by radio, the scientific investigators of the time turned their attention to microwaves. Later, when it was found that the longer waves were more suited to long-distance communication, interest in the microwaves waned. Between 1888 and 1900, however, microwave devices and techniques had a rich development anticipating much of present-day practice. This paper reviews the antennas and waveguides of the period, with some reference to the associated microwave techniques then developed.

Apart from Hertz's dipole, with or without a plane reflector, the principal microwave antennas evolved were the cylindrical parabola, the dielectric lens, the waveguide cavity radiator, the radiating iris, and the electromagnetic horn.

Among the waveguides produced were the round, square, and rectangular forms, the open end being used as a radiator. The experimental development of these hollow pipe radiators appears to have anticipated Rayleigh's theoretical paper on waveguides by a number of years, Lodge discovering the mode property experimentally in 1894.

Many of the associated microwave components were of the "free-space" or quasi-optical type, rather than of the constrained or bounded type as common today, since the investigators between Hertz and Marconi were interested profoundly in the representation of optical phenomena at microwave frequencies. Hertz himself was the founder of "microwave optics," a classical subject being revived today.

Thus, we find the Hertzians making and using polarized mirrors, "cutoff" metal-plate gratings, quarter-wave and half-wave plates, artificial dielectrics, microwave absorbers, prisms of wax, ice, or liquid filled, or of artificial dielectric, totally reflecting prisms, lenses of sulphur, ebonite, wax, pitch, and so on, a wealth of microwave components only partly exploited today.

In the field of systems, measuring arrangements preponderated and included microwave spectrometers, interferometers, diffraction gratings plane or curved, transmission test sets, recorders, polarimeters. With the polarimeter, Bose established microwave analog physics, with macroscopic models of molecules subjected to microwave radiation. Otherwise, representations of optical phenomena were made with the enormous scale advantage arising from the use of microwaves. The properties of dielectrics, particularly anomalous dispersion, were studied and measured extensively.

All of this microwave work was carried out using spark discharge generators, often of considerable peak power, and with surprising accuracy. For detection, many devices were investigated, the most popular being the semiconducting coherer and the gaseous discharge tube.

INTRODUCTION

IN 1888, Hertz launched decimeter-wave radiation from a parabolic mirror antenna fed by a dipole. The dipole was excited by spark discharges produced by an induction coil. The radiation was received on a

similar parabolic mirror antenna and the dipole was transmission line fed to a spark gap detector behind the mirror. The wavelength was 66 cm.

With this simple microwave apparatus Hertz conducted a series of experiments of great importance. First, he established action at a distance. Second, he showed the action was communicated to a distance by a wave motion exactly analogous to the known wave motion characterizing visible light. Third, he substantiated experimentally the theoretical predictions of James Clerk-Maxwell that the waves known to account for optical phenomena were electromagnetic, by the completeness of his experimental demonstrations and his accompanying theoretical analysis.

Hertz showed that his "electric waves" traveled in straight lines (although he surmised that diffraction would take place too). Shadows could be produced by obstacles. Different substances, whether solid, liquid, or gaseous, transmitted or absorbed the waves by different amounts. The waves could be reflected from walls or conducting metallic sheets. Standing waves were obtained which allowed the wavelength to be obtained. The shift of the pattern occasioned by the interposing of a dielectric obstacle allowed the properties of dielectrics to be investigated.

With oblique incidence on a conducting sheet, Hertz found the angle of reflection was equal to the angle of incidence. Using an opaque prism in the path of the radiation, the refracted waves were found to follow the optical law of refraction. The main features of geometrical optics were established.

The standing-wave experiments and the reinforcing action of a reflector behind a dipole radiator emphasized the wave nature of the radiation, being simple illustrations of interference. Just as Young had provided the first means of determining the wavelength of visible light by an interference experiment, so Hertz determined the first radio wavelength using the same principle.

In his experiments, Hertz observed from the start that the microwave radiation was strongly polarized. He pursued this feature making it both an experimental technique and an elucidation of the Maxwellian character of the waves. A new component that appeared, unknown to optics, was the grid of parallel wires, where the wire spacing was a small fraction of the wavelength. In one striking experiment, the transmitter and receiver antennas were cross-polarized and a grid introduced in the path with its wires at 45°. A response was obtained on the receiver previously inactive. "Clearly," wrote

* Original manuscript received by the IRE, September 9, 1957.

† Canadian Marconi Co., Montreal, Quebec, Canada; formerly with Marconi's Wireless Telegraph Co., Ltd., Chelmsford, Essex, England.

Hertz, "the screen resolves the advancing oscillation into two components and transmits only that component which is perpendicular to the direction of its wires. This component is inclined at 45° to the focal line of the second mirror, and may thus, after being again resolved by the mirror, act upon the secondary conductor. The phenomenon is exactly analogous to the brightening of the dark field of two crossed Nicols by the interposition of a crystalline plate in a suitable position."¹

Hertz was fully aware that he had discovered radio-frequency optics, where the phenomenology of optics could be represented by microwaves. "It is a fascinating idea," he wrote, "that the processes in air which we have been investigating represent to us on a million-fold larger scale the same processes which go on in the neighborhood of a Fresnel mirror or between the glass plates used for exhibiting Newton's rings."¹

It is important to notice that directive antennas played a major part in Hertz's system, providing him with a laboratory microwave link. In the path of the beam he introduced components and devices of a quasi-optical (the adjective proposed by Lodge) character which contributed to the realization of a microwave optical system as known today.

The success of Hertz's experiments attracted universal attention. Maxwell's theory was correct; light was an electromagnetic phenomenon. The scientific world, to whom electromagnetism was then the major interest, immediately took up the study of Hertz's waves and their optical implications. A school of investigators known as "the followers of Hertz," or as we may say now "the Hertzians," repeated Hertz's experiments and analytical investigations and extended the field of the work considerably. It was at this time that the divorce of optics from electromagnetism began to appear, contrary to what was expected. The electrically-minded investigators took greater interest in the generators and receivers and regarded the optical representations as well established and less important. On the other hand, physicists imbued with the long history of classical optics found in the new technique a fresh interest and the possibility of experimental verification of much that previously had been theoretical conjectures only. Of the latter group, Righi of Bologna was the most outstanding; his book, "L'Ottica delle Oscillazioni Elettriche," is a treatise on microwave optics.²

The young Marconi, inspired by Righi's work, conceived the idea of modulating the generator so that intelligence could be transmitted on the radio-frequency optical link. In an era of wire and cable telegraphy this was a major practical application of Hertz's apparatus, and of other components, notably the Branly-Lodge

coherer detector developed by the Hertzians. Using two Hertz-type parabolic reflectors separated by a range of four miles on Salisbury Plain in England in 1897, Marconi proved to the British Post Office that his system of "wireless" telegraphy on a wavelength of 25 cm was completely successful. Marconi's consummate engineering skill dwarfed Hertz's scientific virtuosity. Today, the name Marconi is a household word; Hertz is still a textbook reference.

As time went on the followers of Hertz split. The electrically-minded joined the many followers of the youthful Marconi, the optically-minded reducing to a small minority. Other contemporary scientific advances, notably the discovery of X rays and electrons, tended to remove the scientific interest from microwave optics. Until 1900, it hardly existed as a subject. When the followers of Marconi found that longer wavelengths were more suited for communication to longer distances and that unexplained vagaries in communication at these longer wavelengths existed, microwaves vanished from wireless telegraphy, and the new problems of the longer wave radio also attracted the scientists.

With the return to microwaves in our own time, it is amazing to find the extent of the development between Hertz and Marconi. This paper illustrates the development with special reference to the directive antennas that were produced. One important nonoptical type was the hollow pipe waveguide radiator. Since antenna techniques are partly optical and partly electrical, the quasi-optical components of the Hertzians are described also.

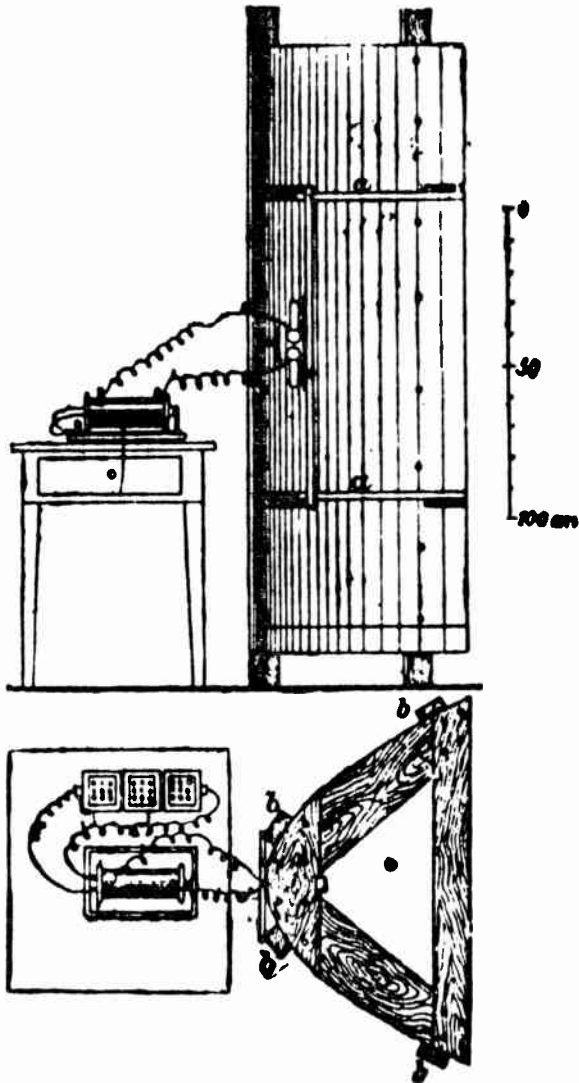
PARABOLIC CYLINDER ANTENNAS OF HERTZ, RIGHI, AND MARCONI

The optical properties of a parabolic reflector were well known to the Hertzians. A source at the focus would provide a "parallel" beam. Hence when Hertz found a dipole "source," he wrote, "As soon as I had succeeded in proving that the action of an electric oscillation spreads out as a wave into space, I planned experiments with the object of concentrating this action and making it perceptible at greater distances by putting the primary conductor (*i.e.*, *dipole*) in the focal line of a large concave parabolic mirror."¹ It is interesting to note that Hertz's need for an antenna was the same as Marconi's, *viz.*, to make the effects "perceptible at greater distances." Antenna gain was appreciated at a very early stage in radio!

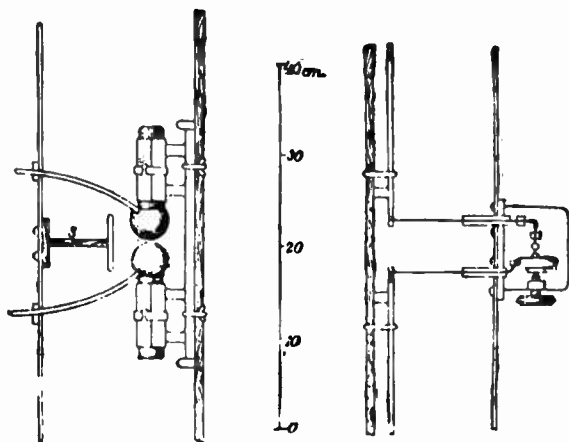
Hertz's reflector was made of sheet zinc mounted on a timber frame (Fig. 1). The horizontal aperture was 1.2 m and the vertical aperture 2 m. The focal length was only 12.5 cm, the parabola extending forward of the focal plane to make the over-all depth of the mirror 70 cm. Since the wavelength was 66 cm, it will be appreciated that this was a very small antenna when measured in wavelengths. A most optimistic estimate of the 3-db beamwidth in the horizontal plane would be 35° ;

¹ H. Hertz, "Electric Waves," Macmillan and Co., Ltd., London, Eng.; 1893.

² A Righi, "L'Ottica delle Oscillazioni Elettriche," N. Zanichelli, Bologna, Italy; 1897.



(a)

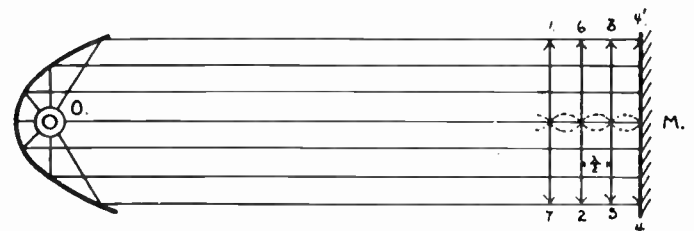


(b)

Fig. 1—(a) Hertz's parabolic reflector antenna for radiating on a wavelength of 66 cm (1888). (b) Hertz's sketches of his dipole feed arrangements for 1) transmitting and 2) receiving. (Courtesy of Macmillan and Co., Ltd., and St. Martin's Press, Inc.).

the beamwidth in the vertical plane would be around 80°. Such beamwidths resemble those used nowadays on "feeds" for parabolic antennas. It is surprising that Hertz was able to do so much fundamental work with these broad beams. He was often troubled by unwanted reflections from room surroundings, no doubt brought about by the use of the broad-beam antennas.

Righi, on the other hand, wishing to approach more closely to optics, worked on 3 cm and 10 cm (the X and S bands of today) with smaller parabolic cylinder reflectors.² Measured in wavelengths, however, the antennas were larger than those of Hertz, and very much sharper beams must have resulted. In one of Righi's illustrations he shows a parabolic cylinder used in, presumably, an X-band spectrometer. He did perform, however, many quasi-optical experiments in general, and must have used the parabolic cylinder antennas extensively, as in the Hertzian standing-wave experiment of Fig. 2.



Interference by reflection from a single mirror, M. 1, 2, 3, etc., represent wave fronts differing in phase by a half period, 1 to 4 being direct and 4' to 7 reflected and reversed in sign. The planes in which two opposite wave fronts, 4-4', 5-3, 2-6, etc., meet are interference stripe, separated by a half wavelength, $\lambda/2$. (Poincaré.)

Fig. 2—Standing waves in free space produced by a reflecting surface. (Poincaré's drawing of Hertz's experiment.) (Courtesy of Constable and Co., Ltd.)

Marconi adopted the cylindrical parabola in his early 25-cm experiments, as his first patent of 1896 shows (Fig. 3).

Instead of a single spark gap, a multiple gap due to Righi was used in the focal line. Marconi had observed the need for sizeable apertures as he stated that the aperture of the antenna should be more than two wavelengths.³

Trouton of Dublin made copies of Hertz's apparatus, including the antennas, and repeated the optical experiments, extending the polarization analysis, and investigating the propagation into water filling a large tank made of paraffin wax.⁴

Bose of Calcutta, in 1897, was using a reflector in the form of a portion of a circular cylinder for microwave optical investigations at a wavelength of 5 mm.⁵

³ G. Marconi, British Patent Specification No. 12039. Her Majesty's Stationery Office, June 2, 1896.

⁴ F. J. Trouton, "Repetition of Hertz's experiments and determination of the vibration of light," *Nature*, vol. 39, pp. 391-393; February 21, 1889.

⁵ J. C. Bose, "Collected Physical Papers," Longmans, Green and Co., New York, N. Y.; 1927.

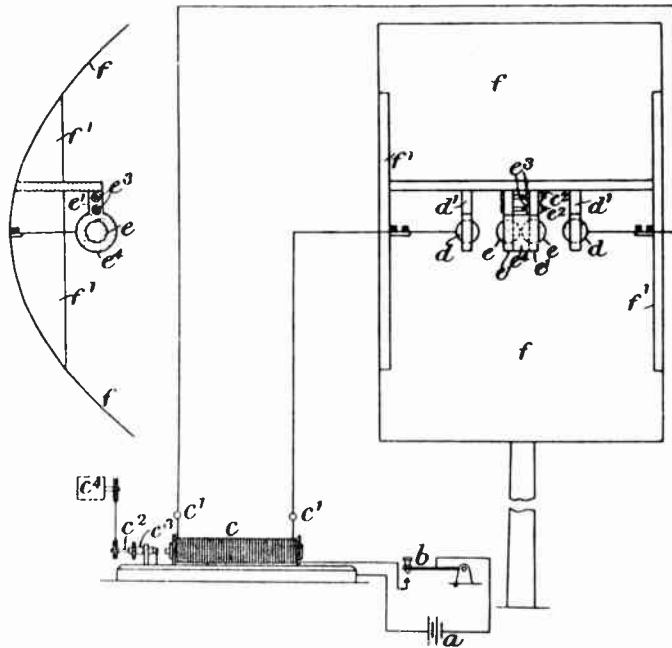


Fig. 3—Marconi's parabolic reflector antenna for transmitting information at a wavelength of 25 cm (1896). (Reproduced from Brit. Pat. Spec. No. 12039, June 2, 1896.)

The popularity of the parabolic cylinder in the 90's was no doubt due to the ease with which it could be constructed. Today in an age of improved constructional techniques, the doubly-curved paraboloidal reflector takes first place and the parallel beams the Hertzians expected but rarely obtained are now possible.

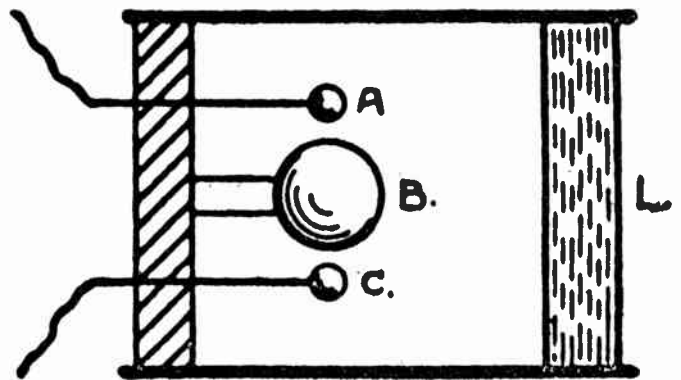
MICROWAVE LENSES OF LODGE, RIGHI, BOSE, AND FLEMING

It was natural in the early microwave optics for the investigators to consider lenses. Hertz had established refraction through a prism of pitch at radio frequencies. Lodge, who knew Hertz personally, and had translated his papers for *Nature*, in 1889 collaborated with Howard in building a cylindrical lens of pitch.⁶

Lodge's lens was 1 m square, with a focal length of 51 cm, and a thickness at the center of 21 cm. The weight was 336 pounds. As the wavelength was found to be 101 cm, this lens antenna was a very small one, measured in wavelengths. Since it was only about one wavelength square, the 3-db beamwidth would be 50° at the best. Lodge found difficulty in distinguishing any definite signs of a focus. This is not surprising, since the focal spot (or Airy disk of optics) would be nearly as large as the lens. The device was in reality a diffracting obstacle, and thus could give some antenna gain. Lodge found the received signal on a Hertzian link was increased using the "lens." Later, in 1894, he used a 9-inch-diameter glass lens on (probably) 4000 mc, where he was able to demonstrate a positive focusing action.

In Italy, Righi² made microwave lenses of paraffin and of sulphur. These lenses were 32 cm in diameter with a focal length of 50 cm. The thickness at the center was 7 cm. He claimed to have good results. As he used wavelengths down to 3 cm, it is highly likely that his results were superior to those of Lodge due to the increased aperture in wavelengths. The optical effects would be more marked.

Bose contributed to microwave lenses in a major way in originating techniques.⁵ He used 5 mm as wavelength for systematic measurements. First, using a spectrometer and the principle of total internal reflection he measured the refractive index of sulphur finding a value of 1.734.⁷ Second, he was able to calculate the profiling of a sulphur lens. Third, he put the lens at the end of a tube, *i.e.*, devised a "shielded-lens" antenna (Fig. 4). Fourth, in order to avoid unwanted reflections from the inside of the tube, he made extensive investigations of materials for coating the tube, *i.e.*, looked for a suitable "microwave absorber." He found blotting paper dipped in electrolyte to be the most satisfactory absorber.



Bose's oscillator. The platinum sphere *B*, which is insulated, is the seat of the oscillations. The spheres *A* and *C* are connected to the induction coil. *L* is a cylindrical lens for concentrating the radiation. (Bose's caption.)

Fig. 4—Shielded lens antenna of Bose for radiating on wavelengths between 5 mm and 2.5 cm (1897). (Courtesy of Longmans, Green and Co.)

The diameter of Bose's lens was only about 1 inch so that, like many of the Hertzians, he used a relatively broad beam.

Fleming (later inventor of the thermionic diode) used a cylindrical lens of paraffin wax to demonstrate microwave optical effects.⁸ As the aperture was only about 1λ at a wavelength of 20 cm the lens action was, like Lodge's large lens, indistinct. Fleming did indeed express surprise that he succeeded in obtaining quasi-optical results at all, with such small components.

Of all the experimenters, it would appear that Righi alone succeeded in building microwave lenses of ade-

⁷ J. C. Bose, "The refraction of electric waves," *Nature*, Sci. Amer. Suppl.; December 3, 1898.

⁸ J. A. Fleming, "The Principles of Electric Wave Telegraphy and Telephony," Longmans, Green and Co., New York, N. Y.; 1906.

⁶ O. J. Lodge and J. L. Howard, "On the concentration of electric radiation by lenses," *Nature*, vol. 40, p. 94; May 23, 1889.

quate enough aperture to give convincing performance.

Although artificial dielectrics were devised by the followers of Hertz, and an artificial dielectric prism was actually investigated, it would appear that no one ever considered building a lens of artificial dielectric.

HOLLOW PIPE RADIATORS OF LODGE, BOSE, AND FLEMING

The first hollow pipe or "waveguide" radiators were demonstrated at the Royal Institution in London on Friday, June 1, 1894, by Lodge in the course of his memorial lecture on "The Work of Hertz and Some of His Successors."⁹

Lodge's waveguide radiator (Fig. 5) consisted of a short length of copper tube closed at one end and open at the other. A spark gap was mounted in the tube and the leads to the induction coil were taken out through small holes in the closed end of the copper tube. Microwave radiation generated by the spark discharge was launched down the tube, and proceeded to free space from the open end. A broad radio-frequency transmitting beam was thereby obtained.

For receiving, a similar tube was used, closed at one end, a glass tube containing coarse iron filings, *i.e.*, a "coherer,"¹⁰ replacing the spark gap of the transmitter.

Lodge called his antennas "copper hats." Referring to the mounting of the coherer tube, he said:

"Sometimes the tube is put lengthways in the hat instead of crossways, which makes it less sensitive, and has also the advantage of doing away with polarizing, or rather analyzing, power of a crossway tube."⁹

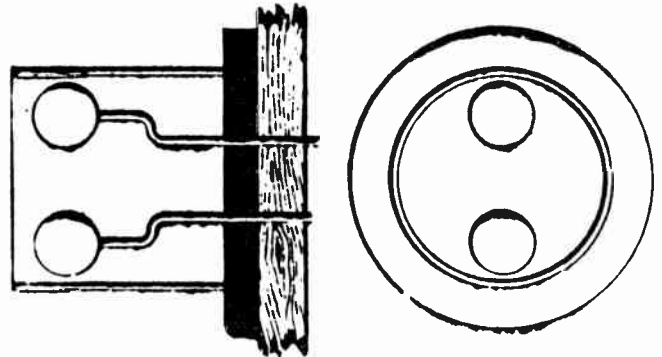
It is evident that Lodge had discovered the mode property of propagation in a hollow tube: this was to be explained later by Lord Rayleigh in 1897.¹¹ With the "crossway" disposition the coherer would be responsive to the TE_{11} mode and therefore polarization sensitive. With the coherer lying along the axis of the tube it would be sensitive to the TM_{01} mode, which has circular symmetry. The radiation pattern (for reception) for the latter mode has a null on axis. Lodge mentioned that he mounted his copper hat "with its mouth turned well askew to the source," a factor contributing to TM_{01} detection at the expense of TE_{11} detection.

In order to reduce the transmitter power radiated, the copper hat was "stopped down by a diaphragm plate with holes in it of varying size" clamped to it. By this artifice Lodge had secured a waveguide cavity subject to different amounts of radiation damping. Here too were some of the first radiating irises, used as attenuators. No doubt some narrowing of the spark spectrum

⁹ O. J. Lodge, "Signalling through Space without Wires," "The Electrician" Printing and Publishing Co., Ltd.; London, Eng., 1898.

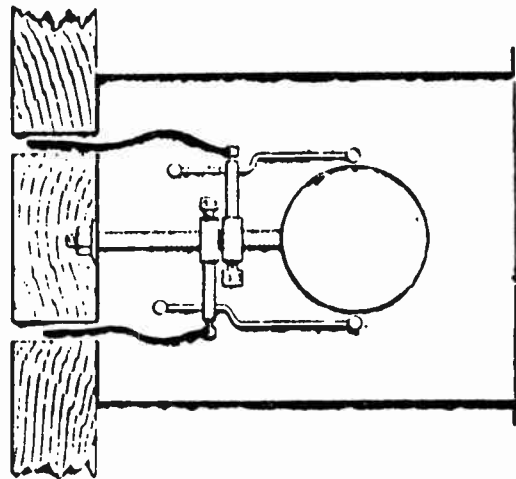
¹⁰ O. J. Lodge, "The history of the coherer principle," *Electrician*; November 12, 1897.

¹¹ Lord Rayleigh, "On the passage of electric waves through tubes, or the vibrations of dielectric cylinders," *Phil. Mag.*, vol. 43, pp. 125-132; February, 1897.



Dr. Lodge's hollow cylindrical radiator, arranged horizontally against the outside of a metal-lined box. Emitting three-inch waves. (Lodge's caption.)

(a)



Spherical radiator for emitting a horizontal beam, arranged inside a copper hat, fixed against the outside of a metal-lined box. The wires pass into the box through glass tubes not shown. (Lodge's caption.)

(b)

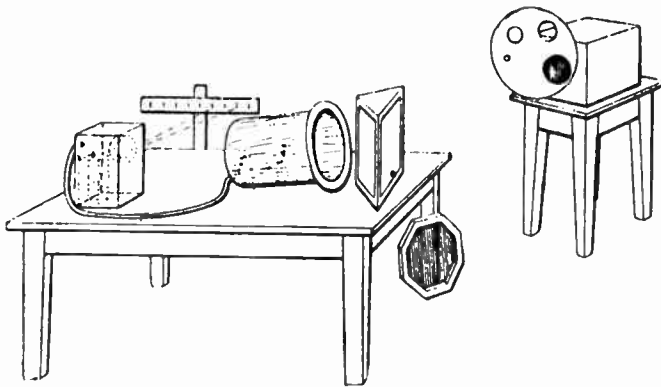
Fig. 5—Hollow pipe waveguide radiators of Lodge for transmitting on centimeter wavelengths (1894). For reception a "coherer" replaced the spark gap in the tube. ("The Electrician" Printing and Publishing Co., Ltd.)

was also obtained by their use. In all cases, it appears a TE_{11} mode was radiated from the transmitter.

Lodge used wavelengths of $7\frac{1}{2}$ cm and about 20 cm. He at one time made an estimate of 70-kw peak power as obtainable from an induction coil: this is a surprising figure. There is no doubt that power availability was not a major difficulty with the followers of Hertz. Given very good screening of the coil and all leads, microwave power was obtainable. This screening requirement may account for the appearance of waveguides.

Lodge's laboratory equipment for demonstrating microwave phenomena, using waveguide radiators for transmission and reception, is shown in Fig. 6. Note the prism of paraffin and the polarizing grid, two of Hertz's components on a much smaller scale.

Bose,⁵ in India, between 1895 and 1897, used hollow tubes of either circular or square section as waveguides



General arrangement of experiments with the copper "hat," showing metal box on a stool, inside which the radiators were fixed; the copper hat containing the coherer, with the metal box containing battery and galvanometer coil connected to it by a compo pipe conveying the wires; a paraffin prism; and a polarizing grid. (Lodge.)

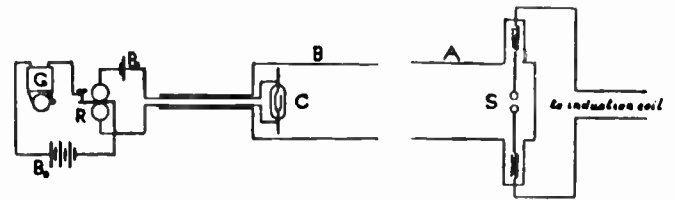
Fig. 6—Microwave equipment of 1894. Lodge's drawing of his quasi-optical bench using waveguide antennas at a wavelength of about 20 cm (June 1, 1894). (*The Electrician* Printing and Publishing Co., Ltd.)

and waveguide radiators on wavelengths between 5 mm and 2.5 cm. Sometimes a small lens was fitted to the radiating end of the tube as has been described (Fig. 4). At Bose's lowest frequencies, his tubes would behave as slightly oversize waveguides, as the width was around 1 inch. At 5 mm, however, the tube would act more as a shield, liable to produce higher order modes, whence Bose's search for absorbent material. His adoption of hollow tubes was probably based on the use of metal tubes in telescopes and microscopes.

Fleming⁸ gave lecture demonstrations on the optical features of Hertzian waves, following very closely Lodge's celebrated Royal Institution lecture of 1894. However, it is exceedingly interesting for us to find that he had replaced Lodge's round tube radiators by rectangular boxes, resembling the rectangular waveguide of the present day. Fleming used a wavelength of about 20 cm.

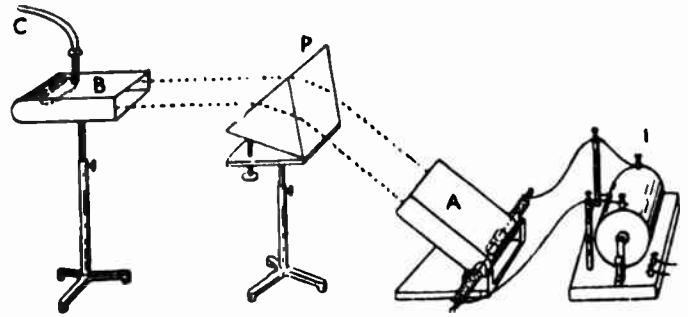
An inspection of the diagrams (Fig. 7) of Fleming's equipment indicates 1) that the polarization is parallel to the broad face instead of the narrow face as in a dominant-mode waveguide and 2) that the rectangular tubes would act more as cut-off attenuators than as waveguides. As, however, the spectrum of the spark would have many higher frequency components, it is likely that the boxes radiated significant power. Fleming's comment that the excellence of the quasi-optical demonstrations was surprising, having regard to the orders of magnitude in his system, may be explained, in fact, by his having very much shorter waves present.

Lodge, Bose, and Fleming must all have unconsciously used the high-pass filter property of waveguides, for the noisy sparks would be likely to have an enormous low-frequency spectral content. All three resorted to, and emphasized the need for screening the transmitting equipment.



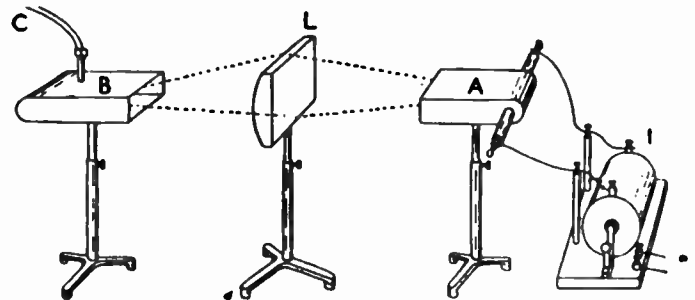
Apparatus for producing and detecting electric waves. *S*, spark balls in metal box, *A*, with open mouth; *C*, coherer in metal box; *B*, with open mouth; *R*, relay; *G*, electric bell; *B*₁, relay battery; *B*₂, electric bell battery.

(a)



Refraction of an electric beam by a paraffin prism.

(b)



Convergence of an electric beam by a paraffin lens.

(c)

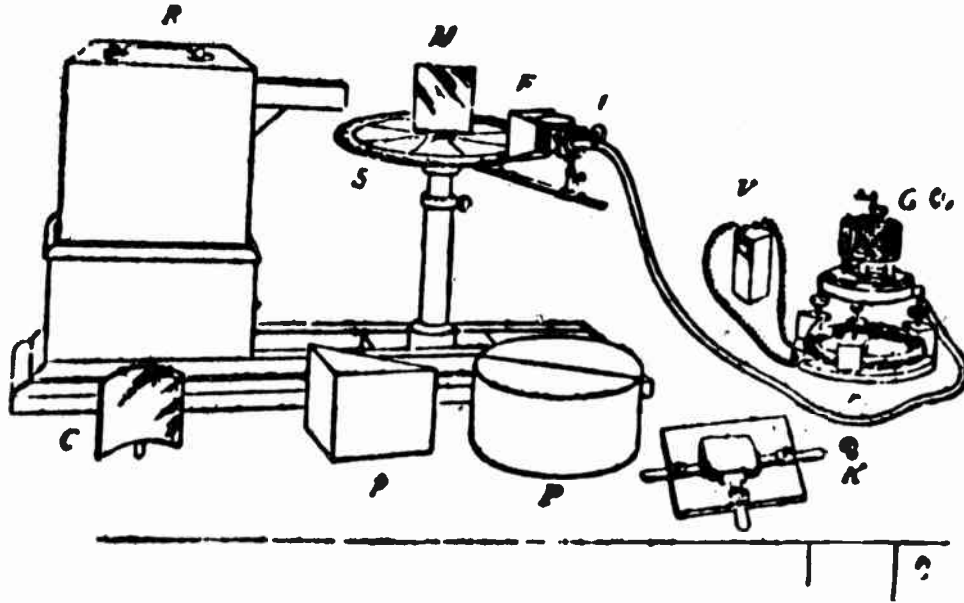
Fig. 7—Microwave-optical equipment and experiments of Fleming showing rectangular waveguide antennas used at a wavelength of 20 cm (1900). (Captions by Fleming.) (*Courtesy of Longmans, Green and Co.*)

The fact that they discovered the radiation could be led out of the transmitter box by a hollow tube represented a major step, as we now know, on the evolution of microwave transmission technique.

In radiating to free space from the open end of a hollow pipe, Lodge, Bose, and Fleming found a directive radiator unknown to optics or to Hertz. Bose was to make the next significant step.

THE ELECTROMAGNETIC HORN ANTENNA OF BOSE

In 1897, Bose gave a lecture at the Royal Institution in London on the quasi-optical researches he had been carrying out with "electric waves" at a wavelength of 5 mm.⁵ For demonstration purposes he had



Arrangement of the apparatus. *R*, radiator; *S*, spectrometer-circle; *M*, plane mirror; *C*, cylindrical mirror; *p*, totally reflecting prism; *P*, semicylinders; *K*, crystal-holder; *F*, collecting funnel attached to the spiral spring receiver; *t*, tangent screw, by which the receiver is rotated; *V*, voltaic cell; *r*, circular rheostat; *G*, galvanometer. (Bose's caption.)

Fig. 8—Electromagnetic horn receiving antenna on microwave spectrometer used for quasi-optical demonstrations by Bose (1897). Transmitting antenna is square waveguide radiator. Wavelengths 5 mm–2.5 cm. (Courtesy of Longmans, Green and Co.)

brought from India a microwave spectrometer complete with screened transmitter and a receiver that rotated around the spectrometer table. Numerous quasi-optical components were also associated with this equipment for use in the demonstrations. A diagram of the equipment still exists (Fig. 8).

An inspection of Bose's receiver arrangements shows that the receiving antenna was a pyramidal electromagnetic horn, as we now call it. Bose termed his antenna a "collecting funnel," a colloquial but more vivid description. To this funnel a semiconducting detector of a multiplicity of touching spiral springs developed by Bose was connected (Fig. 9).¹²

Bose had already used waveguiding tubes—one is shown on his transmitter—so that it is natural he would conjecture that by increasing the cross section, a receiving aperture would collect more energy. This aperture could be attached to a smaller tube by tapering it down to fit, *i.e.*, by a hollow truncated pyramid construction, whence his pyramidal funnel. Thus, Bose made the first flared waveguide or small electromagnetic horn. As with so many of the components developed by the followers of Hertz, the horn was used for investigations in microwave optics as is evident in Fig. 8.

POLARIZATION TECHNIQUES BEFORE 1900

Hertz initiated techniques on microwaves based on the polarization properties of electromagnetic waves.

¹² J. C. Bose, "On a complete apparatus for the study of the properties of electric waves," *Elec. Eng. London*; October 2, 1896.

He showed that his dipole transmitter and loop receiver were linearly polarized and that the linear polarizations were substantially unaffected on reflection from plane or parabolic mirrors. He made exact studies of the polarizations in the near fields of primary and secondary radiators. His principal invention, however, was the screen or grating, a grid of parallel wires, which he described as follows:

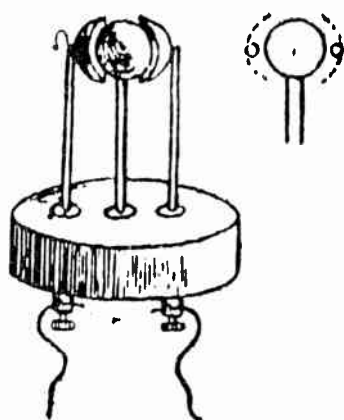
"I next had made an octagonal frame, 2 meters high and 2 meters broad; across this were stretched copper wires 1 mm thick, the wires being parallel to each other and 3 cm apart."¹

At a wavelength of 66 cm as used by Hertz, this screen would reflect 96 per cent of the incident power in a plane wave normally incident and polarized linearly parallel to the wires.

If however, the incident wave were polarized at right angles to the wires, most of its power would be transmitted *through* the screen. Such a device might have been called a "transflector," transmitting when the polarization was perpendicular and reflecting when the polarization was parallel to the wires.

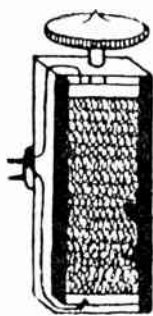
Hertz discovered the sensitivity inherent in a "cross-polarized" link, where the transmitter and receiver polarizations are perpendicular. As referred to in the Introduction, he showed that such an arrangement resembled the crossed Nicols of optics, and in fact constituted a microwave polarimeter.

This attracted the attention of Bose who built microwave polarimeters on 5-mm wavelength with crossed gratings at the transmitter and receiver (see



The radiator.

(a)



The spiral-spring receiver.

(b)

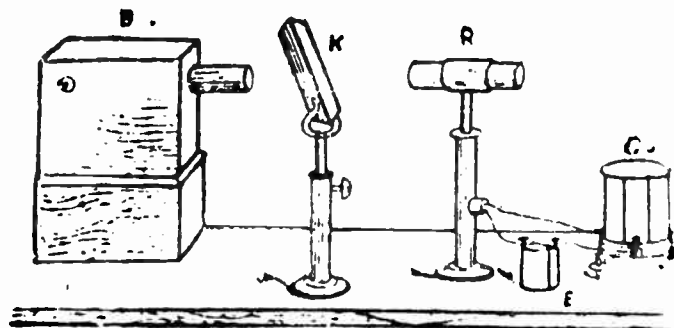
Fig. 9—(a) Spark gap arrangements for generating wavelengths down to 5 mm (Bose, 1895). Material: platinum. (b) Bose's microwave, "semi-conducting" detector consisting of rows of horizontal spiral steel springs under adjustable pressure and a small polarizing voltage (1895). (Courtesy of Longmans, Green and Co.)

Figs. 10–12).¹³ Bose's gratings, however, were not always grids of wires but sometimes consisted of parallel strips of metal (Fig. 12) as in the cut-off metal-plate grating of today. He produced these initially in a particularly simple way by interleaving the pages of a Bradshaw railway timetable with sheets of tinfoil. (Similar virtuosity was shown by Marconi on a later occasion when he inserted parallel wires into corrugated cardboard to make a Hertzian grating.)¹⁴ Bose had found that the leakage through a cut-off grating, as we term it, was much less than that occurring with a wire grid.

With the polarimeter, Bose investigated the properties of many natural substances and artificial devices. In the class of natural substances he studied crystals of many kinds, and vegetable fibers, in addition to strained

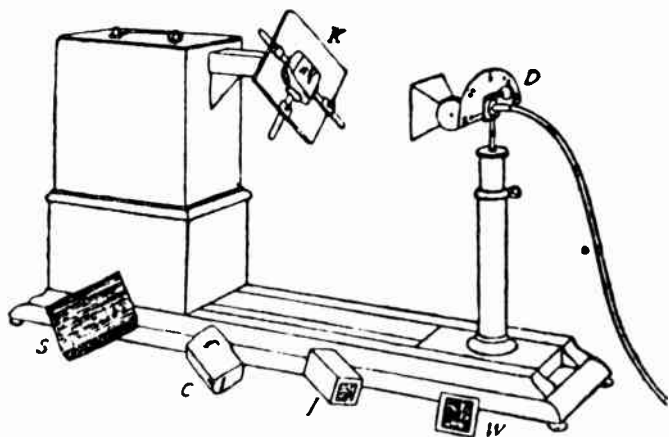
¹³ J. C. Bose, "On a new electro-polariscope," *Electrician*; December 27, 1895.

¹⁴ Described to the author by E. L. Payne, Marconi's Wireless Telegraph Co., Ltd., Baddow Res. Labs., Chelmsford, Essex, Eng.



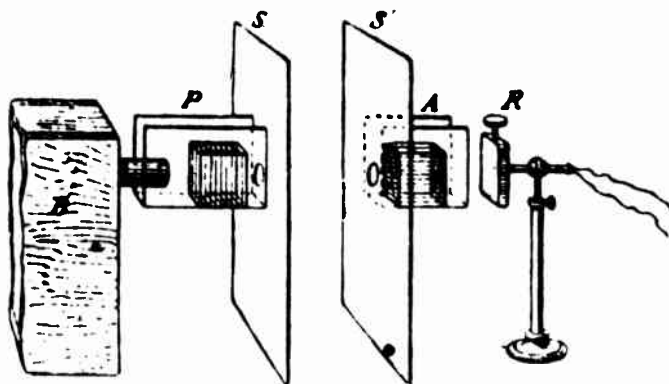
Polarization apparatus. B, metallic box enclosing the Ruhmkorff coil and radiator; K, the crystal to be examined; E, voltaic cell; G, the galvanometer; R, tube enclosing sensitive receiver. (Bose.)

Fig. 10—Microwave optical bench of Bose showing hollow-pipe waveguide antennas and polarization analyzer, R (1895). (Courtesy of Longmans, Green and Co.)



Polarization apparatus. K, crystal-holder; S, a piece of stratified rock; C, a crystal; J, jute polarizer; W, wire-grating polarizer; D, vertical graduated disk by which the rotation is measured. (Bose.)

Fig. 11—Microwave optical bench for polarization analysis. Note electromagnetic horn receiving antenna, square waveguide transmitting antenna, and Hertzian grids (Bose, 1897). (Courtesy of Longmans, Green and Co.)



Polarization apparatus. B, the radiating box; P, the polarizer; A, the analyzer; S, S', the screens; R, the receiver.

Fig. 12—"Cut-off waveguide" polarized mirrors as used in a polarimeter by Bose. (*Proc. Roy. Soc.*, vol. 63, p. 148; 1898.)

dielectrics as found in stratified rocks and fossils. Artificial polarizers of different forms he constructed from wires or jute fibers (Fig. 10).

One of the most remarkable applications of the microwave polarimeter developed by Bose was his use of it for analog physics.¹⁵ Knowing that certain sugar solutions were optically active in producing polarization rotations, he conjectured that the mechanism resided in the molecule. He therefore made macroscopic or model molecules of twisted jute fibers, some with a right-hand twist, others with a left-hand twist (Fig. 13).

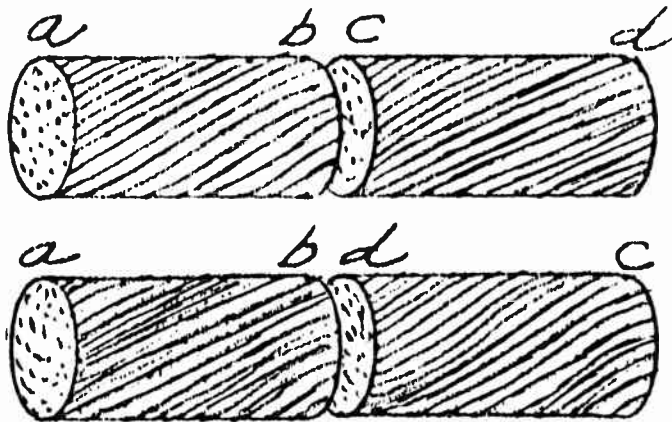


Fig. 13—Model “molecules” of twisted jute as used by Bose in 1898. (Courtesy of Longmans, Green and Co.)

Examined in a millimeter wave polarimeter these “molecules” gave either right or left-hand polarization twists, and jointly, no twist. Here, according to Bose, was an analog of the sugar rotations. The significant feature of this microwave technique was in its providing a macroscopic representation of the submicroscopic. Recently, in 1955, quasi-crystallographic reflections have been obtained from model crystal structures of macroscopic “atoms” when irradiated by millimeter waves.¹⁶ The basic technique is, however, reminiscent of Bose’s early experiments in microwave modeling.

Circular and elliptical polarizations of microwaves were familiar and well-understood phenomena to the followers of Hertz, the majority of whom had a trained optical background. Righi and Bose both observed the polarized structure of wood, Righi actually constructing a wooden quarter-wave plate or circular polarizer.² The radio half-wave plate also had its origin at this time.

Zehnder in Germany in 1894 used Hertzian grids to produce circular or elliptic polarization.¹⁷ Lodge’s de-

scription is so clear as to merit reproduction: “He takes a couple of plane polarizing grids and places them parallel to each other at a little distance apart with their wires crossed. If the two grids are close together they will act like wire-gauze, reflecting any kind of polarized radiation equally; but if the warp and woof are an eighth-wavelength apart, and the plane of the incident radiation is at 45° to the wires, the reflected radiation will be circularly polarized. A change in the circumstances will, of course, make it elliptical. Such a pair of grids acts, in fact, like a Babinet’s Compensator.”⁹ The modern form of the arrangement consists usually of one grid spaced one-eighth wavelength from a metal sheet reflector.¹⁸

Garbasso and Aschkinass, by breaking up the wires of a Hertzian grid into uniform short lengths, *i.e.*, dipoles, showed that a dispersive, or frequency-sensitive, polarized mirror then existed.¹⁹ The tuned reflector of a modern television receiving antenna is a simple case of this phenomenon. Marconi, in the first experiments in scatter communication in 1932, used parabolic mirrors of tuned elements constituting the reflectors.²⁰

The optical problem to the Hertzians was to reproduce a dispersive Newtonian prism on microwaves. Such a prism was constructed from layers of dispersive dipoles by Garbasso and Aschkinass in 1894; this prism was the first component of “artificial dielectric” as we now term such a structure. The layers consisted of tinfoil strips fixed to glass plates. The wavelength was 7.5 cm (4000 mc).

It is evident that the study of the polarization properties of microwaves in microwave optics led to considerable advances in the art before 1900.

DIELECTRICS IN THE HERTZIAN EPOCH

Hertz’s great achievement in experimentally confirming Maxwell’s electromagnetic theory of light by generating, controlling, and detecting microwave radiation, arose as a by-product of a general research into the properties of dielectrics or insulators.¹

In the years following, extensive investigations of dielectrics were carried out by the followers of Hertz. Hertz’s own dielectric researches were the basis of much of the work. He developed standing-wave measurements and evolved the nodal shift technique. He was interested in secondary reradiation from dielectric masses, not ignoring the polarization characteristics. He achieved the first dielectric constant determination by refraction, using the celebrated prism of pitch. His

¹⁵ J. C. Bose, “On the rotation of plane of polarisation of electric waves by a twisted structure,” *Proc. Roy. Soc.*, vol. 63, p. 146; 1898.

¹⁶ J. F. Ramsay and S. C. Snook, “Microwave model crystallography,” *Electronic and Radio Engr.*, pp. 165–169; May, 1957.

¹⁷ Zehnder, *Ber naturforsch. Ges. zu Freiburg i. B.*, Bd. 9, Heft 2; June 21, 1894.

¹⁸ J. F. Ramsay, “Circular polarization for cw radar,” *Marconi Rev.*, vol. 15, pp. 71–89; 2nd Quarter, 1952.

¹⁹ Garbasso and Aschkinass, “Berechnung und Dispersion elektrischer Strahlen,” *Ann. der Phys.*, vol. 53, p. 534, 1894.

²⁰ G. Marconi, “Radio communication by means of very short electric waves,” reprint, *IRE TRANS.*, vol. AP-5, pp. 90–99; January, 1957.

work is notable both for the number of substances he investigated, and in some cases for the size of the experimental samples. A list of the substances gives some idea of the thoroughness of his approach (Fig. 14).

Solids	Liquids	Gases
Metals	Water	Air
Paraffin	Sulphuric Acid	Hydrogen
Shellac	Alcohol	Carbonic Acid
Resin	Ether	Coal Gas
Ebonite	Hydrochloric Acid	Chlorine
India-Rubber	Nitric Acid	Nitrous Oxide
Glass	Ammonia (Soln)	Bromine Vapor
Porcelain	Paraffin	Iodine Vapor
Earthenware	Benzole	
Wood	Petrol	
Pasteboard	Carbon Disulphide	
Paper	Ammonium Sulphide	
Ivory	Fuchsine	
Horn	Potassium Permanganate	
Hides	Nitrate of Mercury	
Feathers	Sodium Hyposulphite	
Agate	Potassium Bromide	
Mica	Potassium Iodide	
Copper Sulphate	Iron Salts	
Crystals	Copper Salts	
Topaz	Sal-Ammoniac	
Amethyst	Zinc Sulphate	
Crystallized Sugar	Common Salt	
Alum	Potassium Sulphate	
Calc-Spar	Sodium Sulphate	
Rock-Salt	Magnesium Sulphate	
Gypsum		
Rock-Crystal		
Smoke Glass		
Quartz		

Fig. 14—List of substances investigated by Hertz. (Courtesy of Macmillan and Co., Ltd., and St. Martin's Press, Inc.)

Some of his experimental samples may be quoted.¹ His first material being paper, and the wavelength in the meter band, he "piled up books in the form of a parallelepiped 1.5 meter long, 0.5 m broad, and 1 m high." He also had cast "800 kgm of unmixed asphalt" in a block of similar size. Another block was of artificial pitch. A sulphur sample consisted of "a massive block 70 cm long, 20 cm broad and 35 cm high." As a dielectric cylinder Hertz made use of "a sandstone pillar in the building." For one liquid dielectric he used "an oak trough with 45 liters of pure paraffin."

These investigations were highly stimulating to his successors, the majority of whom used shorter waves—and smaller samples. The low-loss characteristics of paraffin and paraffin wax were known to most of the Hertzians. The liquid form was popular around the spark gap where its dielectric constant allowed greater power to be obtained. The solid form was used for components, e.g., lenses and prisms, and as an insulating support. Sulphur and ebonite were used for the same purposes.

The dielectric properties of water were examined on different frequencies, both as liquid²¹ and ice.⁸ Alcohol,

castor oil, olive oil, xylol, and petrol were also measured at microwave frequencies.²²

Anomalous dispersion was of great interest to the followers of Hertz who, realizing the truth of the electromagnetic theory, saw a solution to the optical uncertainties. Trouton in Dublin, for example, in 1889 asked, "Would the interspersing of bodies of nearly the same period in Hertz's pitch prism alter the angle of refraction?"

If so, then anomalous dispersion may yet be successfully demonstrated."⁴ Today we know that he was correct and experiment has confirmed his conjecture. Trouton may be regarded as the father of artificial dielectrics; his dipole-loaded medium was the first suggestion made in this field. To the modern it is interesting to find Trouton suggested as well that the particles need not be identical. As we have seen earlier, Garbasso and Aschkinass carried out the experiment with identical dipoles in 1894.

Trouton was also aware of the need for microwave photographs and suggested molecular dissociation and ac electrolytes as possible techniques. This problem is still unsolved today.

With the current modern interest in ferrites, germanium, and powdered artificial dielectrics at microwaves, it is relevant to mention that Birkeland in 1894 made up synthetic dielectrics from paraffin and metal filings or powders.²³ His "ferro-paraffin" consisted of iron filings or chemically obtained iron powder mixed with powdered quartz in paraffin. Birkeland desired "to demonstrate in magnetic cylinders stationary magnetic waves analogous to the electric stationary waves along metallic wires." He was unsuccessful due to losses which even then were a feature of artificial dielectrics. Birkeland did observe the detuning effect in a resonant circuit of a ferro-paraffin rod, and the excessive skin depth of the current in the rod. Control experiments were also carried out with brass filings and with zinc filings in paraffin.

Bose developed lossy artificial media in his search for a microwave absorber; the blotting paper soaked in electrolyte proved the best.⁵

It is doubtful if the Faraday rotation of the plane of polarization was ever investigated by the Hertzians. It is likely however that Lodge realized that polarization rotation by a magnetic field was possible with Hertzian waves, judging from some of his experiments and papers.

Among the classical optical phenomena that were re-investigated on centimeter and millimeter waves were total internal reflection and the evanescent field at the interface,⁵ Brewster angle,⁴ the quarter-wave and half-wave thickness feature of dielectric slabs,² polarization

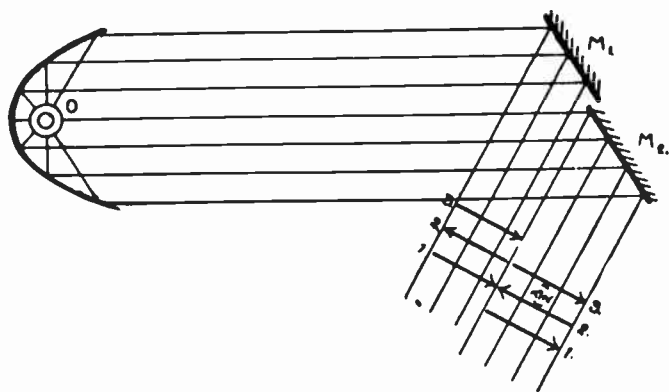
²¹ A. D. Cole, "Measurement of short electrical waves and their transmission through water cells," *Phys. Rev.*, vol. 7; November, 1898.

²² E. Branly, "The transmission of Hertz waves through liquids," *Compt. Rend.*, October 30, 1899.

²³ M. Birkeland, "On magnetisation produced by Hertzian currents; a magnetic dielectric," *Compt. Rend.*, June 11, 1894.

rotations,⁵ double refraction,²⁴ and selective absorption.⁵

For these measurements and other applications, instrumentation covered microwave spectrometers,⁵ interferometers,²⁵ diffraction gratings,²⁶ polarimeters,⁵ all used with incoherent spark generators and (usually) coherer detectors. A notable interferometer built by Hull under the direction of Prof. A. A. Michelson at Chicago University in 1897 operated on 9.12-cm wavelength and could measure wavelength and index of refraction with an accuracy of better than 1 per cent. Fig. 15 illustrates Righi's interference experiment with Fresnel mirrors as drawn by Poincaré.²⁷ The wavelength was probably in X band.



Interference between two parallel rays in the same direction. The two reflected rays have the same phase difference at all points, and the degree of interference depends upon the distance between the mirrors M_1 and M_2 .

Fig. 15—Fresnel mirror experiment modelled on 3 cm by Righi (description by Poincaré). (Courtesy of Constable and Co., Ltd.)

CONCLUSION

The above historical investigation was not written just because it provided interesting history, and to the author at least, fresh light on origins, but because in a strange way it presented a parallel with the microwave situation today.

Today, millimeter waves research is in a similar position to that existing in the 1890's. It does not know

²⁴ P. Lebedev, "Double refraction of electric rays," *Electrician*; November 15, 1895.

²⁵ G. F. Hull, "On the use of the interferometer in the study of electric waves," *Phys. Rev.*, vol. 5, p. 231; October, 1897.

²⁶ J. C. Bose, "On the determination of the wavelength of electric radiation by a diffraction grating," *Proc. Roy. Soc.*, vol. 60; 1897.

²⁷ H. Poincaré and F. K. Vreeland, "Maxwell's Theory and Wireless Telegraphy," Constable and Co., Ltd., London, Eng.; 1905.

where it is going. Any objectives it seems to have are scientific, as it was with the Hertzians. Generation of the waves presents formidable difficulties, detectors are almost as crude as those of the early experimentalists. The only positive application that may appear now is hollow-pipe waveguide communications. Radar and wireless communications are beset by propagation difficulties.

Yet, every time a region of the spectrum is developed a major practical application arises. World communications arose from the so-called short-wave region, television appeared in the very-high frequency band, radar and tropospheric scatter communications exploited the centimeter waveband. "What next?" is a natural question.

It will be observed that the major practical advances tended to arise from the development of the optical features of radio waves—beam radio, line-of-sight tv, high resolution radar, scatter communications, these descriptions are optical. The closer radio techniques approach the optical, the more likely they are to yield fruitful developments. Radio astronomy is the latest example.

Therefore, the work of the Hertzians, masters of microwave optics, then points the direction in which the new microwave radio must go.

If the signposts are correct the undeveloped millimeter waveband should see a major everyday application of radio optics.

Otherwise, the millimeter waveband remains an ideal region of the spectrum for modeling devices and phenomena from other regions of the spectrum. Antennas, for example, which are too large, can be modeled as conveniently as atoms which are too small. Particularly all wave phenomena can be reproduced with a convenience not realizable in other regions of the spectrum. Optics textbooks may yet require another chapter, one on "Microwave Optics."

ACKNOWLEDGMENT

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Ghost Modes in Imperfect Waveguides*

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Summary—Attention is called to the existence of microwave resonances which have the unusual property that they are nonradiating, and thus have high Q , in spite of the fact that the fields are not enclosed completely by metallic walls. These “ghost modes” represent fields which are derived from those of the usual waveguide modes, but are “trapped” in the vicinity of imperfections in the waveguide. Their resonant frequency is slightly lower than the corresponding cutoff frequency. If one attempts to use a waveguide in its lowest mode, over a range of frequencies which includes the ghosts of higher modes, complicated resonance effects may be observed which can cause trouble in some types of microwave circuits. The same phenomenon exists in any structure which has pass bands and rejection bands, such as periodic structures or crystals.

INTRODUCTION

THE phenomenon described herein explains certain curious and troublesome effects observed in waveguides operating close to the cutoff frequency of a propagation mode, and it may have applications for waveguide filters. In addition, it has a certain educational value because of a mathematical analogy with the phenomenon of localized bound states due to imperfections in crystals.

GHOST MODES DUE TO A DIELECTRIC

To illustrate the simplest case, and one which can be analyzed completely, consider the structure of Fig. 1. A dielectric disk of thickness d , dielectric constant ϵ , is placed in a cylindrical waveguide of radius a . Let the center of the disk be the origin of a cylindrical coordinate system ($r\theta z$). A possible electromagnetic field is one whose transverse structure is that of the TM_{01} mode, derived from the field component

$$E_z = \begin{cases} BJ_0(k_1 r) \exp [-(k_1^2 - k^2)^{1/2} z], & z > \frac{d}{2} \\ AJ_0(k_1 r) \cos [(\epsilon k^2 - k_1^2)^{1/2} z], & |z| < \frac{d}{2} \\ BJ_0(k_1 r) \exp [(k_1^2 - k^2)^{1/2} z], & z < -\frac{d}{2} \end{cases} \quad (1)$$

In (1),

$$k_1 = \frac{2.405}{a} = \frac{\omega_c}{c}, \quad k = \frac{\omega}{c},$$

where ω_c and ω are, respectively, the TM_{01} cutoff frequency and an operating frequency to be determined presently. Matching solutions across the dielectric-air interfaces, we obtain the condition

$$\tan \left[(\epsilon k^2 - k_1^2)^{1/2} \frac{d}{2} \right] = \epsilon \left[\frac{k_1^2 - k^2}{\epsilon k^2 - k_1^2} \right]^{1/2} \quad (2)$$

For any $\epsilon > 1$, (2) has at least one solution for k with $k < k_1$. If $(\epsilon - 1)^{1/2} k_1 d < 2\pi$, only one such solution exists. We consider, in particular, the case where ϵ is appreciably greater than unity and $k_1 d \ll 1$. Then k as determined from (2) is very close to k_1 , and it will be a good approximation to set

$$(\epsilon k^2 - k_1^2)^{1/2} d \simeq (\epsilon - 1)^{1/2} k_1 d \ll 1,$$

so that (2) reduces to the following formula for ω :

$$\omega^2 \simeq \omega_c^2 \left[1 - \left(\frac{\epsilon - 1}{\epsilon} \frac{k_1 d}{2} \right)^2 \right] \quad (3)$$

The field derived from (1) thus represents a resonant mode with resonant frequency slightly below the cutoff frequency of the TM_{01} mode, in which the fields are localized to the vicinity of the dielectric disk. The electric field configuration is sketched in Fig. 1. The longitudinal extension of this ghost mode is described by the “ $1/e$ distance”

$$x_0 = \frac{1}{(k_1^2 - k^2)^{1/2}} = \frac{\lambda_c}{2\pi(1 - \omega^2/\omega_c^2)^{1/2}} \quad (4)$$

where $\lambda_c = 2\pi/k_1 = 2.6a$ is the TM_{01} cutoff wavelength. Numerical values of (x_0/λ_c) are indicated in Fig. 2. It is seen that the ghost is surprisingly well localized; for example, in the case $\omega = 0.99 \omega_c$, x_0 is less than 1.5 pipe diameters. If the waveguide extends a distance three or four times x_0 on either side of the dielectric disk, this ghost will be essentially nonradiating and will have a very high Q , limited only by losses in the waveguide walls and the dielectric.

Suppose this waveguide were being operated in the TE_{11} propagating mode, at frequencies near the TM_{01} cutoff frequency. This is a rather common condition in practice, since the TM_{01} cutoff frequency is only about 30 per cent higher than that of the TE_{11} mode. In a perfect waveguide the fact that we were close to the TM_{01} propagating range would not cause any trouble. However, the disk represents an “imperfection” in what would otherwise be a smooth waveguide. The slightest asymmetry in structure near the disk, or the slightest inhomogeneity in dielectric constant of the disk, can couple the ghost to the TE_{11} mode and cause a large absorption of energy at the frequency given by (3). The field of the ghost can attain a magnitude several hundred times that of the propagating TE_{11} mode, so that

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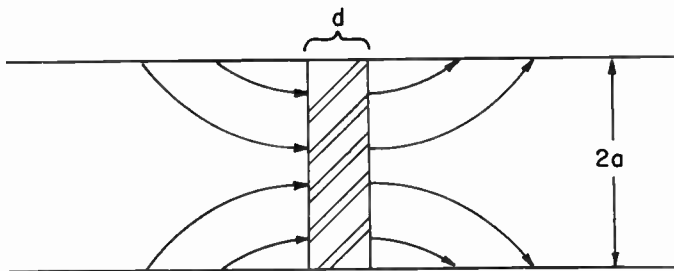


Fig. 1— TM_{01} ghost mode due to a dielectric disk.

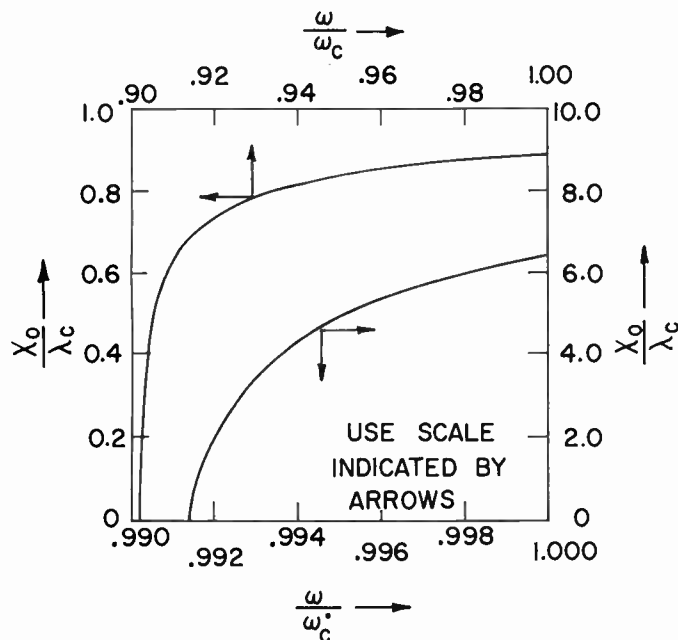


Fig. 2—“(1/e) distance” of ghost modes as a function of frequency.

in a high-power device a ghost can cause breakdown. It was, in fact, the persistent failure of ceramic windows in the output waveguides of high-powered klystrons feeding the Stanford linear electron accelerator (carrying about 20 megw at 3 kmc), which led to the recognition of ghost modes. Spurious resonances in certain ferrite devices may also be traceable to this cause.

What was said for the TM_{01} mode evidently applies in general for the structure of Fig. 1; every propagation mode of the waveguide is accompanied by a ghost with the same transverse field pattern, localized to the vicinity of the disk, with a resonant frequency slightly below the corresponding cutoff frequency.

GENERAL GHOST MODES

The presence of a dielectric is not necessary for existence of ghosts; any localized imperfection in a waveguide will cause them to appear. Consider first a perfect, infinitely long waveguide with zero loss, excited in one of the propagation mode patterns at exactly its cutoff frequency. It is thus a large resonant cavity with resonant frequency ω_c . Let the electric and magnetic fields in the vicinity of any point P on the waveguide wall be E, H . Now if $\epsilon_0 E^2 > \mu_0 H^2$, push the wall in slightly at P , while

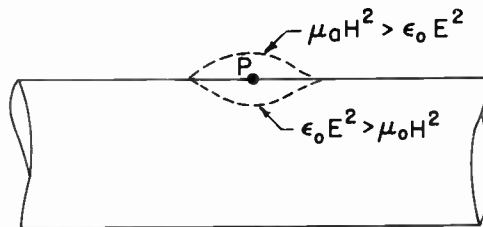


Fig. 3—Wall perturbations which create ghost modes.

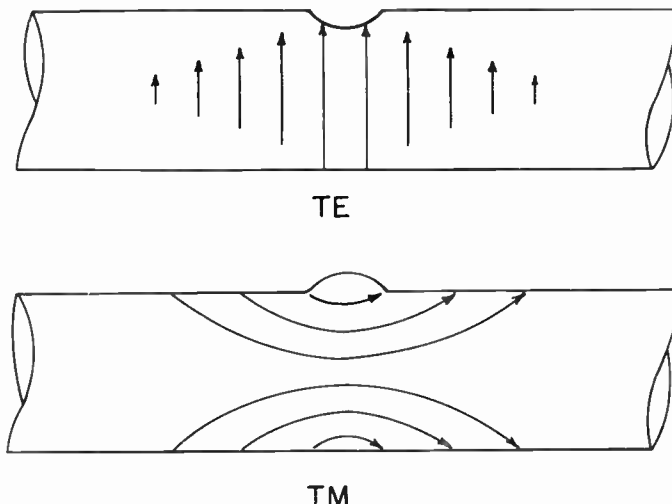


Fig. 4—Electric field lines of TE and TM ghost modes due to wall imperfections.

if $\mu_0 H^2 > \epsilon_0 E^2$, pull out a small “blister” as in Fig. 3. According to the Slater perturbation formula [1], the resonant frequency of the cavity is always lowered by this change. But at any lower frequency than ω_c the fields will be attenuated exponentially as we move away from the imperfection; thus a ghost has been created, trapped to the vicinity of the imperfection, with a resonant frequency slightly lower than ω_c . Two examples are given in Fig. 4, in which only the electric field lines are sketched.

The Q of a ghost mode due to a small imperfection as in Fig. 4 is given to order of magnitude by

$$Q \simeq \frac{a}{\delta} = \frac{\text{waveguide radius}}{\text{skin depth}}, \tag{5}$$

from which it is seen that values in excess of 10^4 are easily attained. For the ghost of any mode other than the lowest one, there also will be a “loaded Q ” involving the strength of coupling to propagating modes.

Crude estimates of the frequency and longitudinal extension of these ghosts, obtained from (4) and the Slater perturbation formula, are

$$\omega^2 \simeq \omega_c^2 \left[1 - \left(\frac{\pi a \delta V}{A \lambda_c} \right)^2 \right], \tag{6}$$

$$x_0 \simeq \frac{A \lambda_c^2}{2 \pi^2 a \delta V}. \tag{7}$$

Here A is the cross-sectional area of the waveguide, δV is the volume added or removed by the imperfection, and α a dimensionless quantity of the order of magnitude unity, given by

$$\alpha = \frac{|\mu_0 H^2 - \epsilon_0 E^2|}{\langle \mu_0 H^2 + \epsilon_0 E^2 \rangle_{\delta V}} \quad (8)$$

where the fields in the numerator are values near the imperfection, while the denominator is an average over a waveguide cross section passing through the imperfection [2].

From these formulas several general conclusions may be drawn. If the imperfection is so small that

$$\delta V < \frac{A\lambda_c}{100}, \quad (9)$$

then one may expect the ghost to be separated from the cutoff frequency by less than the bandwidth ω_c/Q , so that it does not appear as a well-resolved resonance, but only a slight broadening of the cutoff region. If, on the other hand,

$$\delta V > \frac{A\lambda_c}{100}, \quad (10)$$

the ghost will generally appear as a distinct resonance. The longitudinal extension x_0 of any well-resolved ghost will, from Fig. 2, never be more than a few times λ_c . The δV required by (10) is so large that the usual mechanical imperfections due to machining errors, inadvertent hammer blows, etc., do not cause separation of ghosts from the waveguide modes. However, installation of almost any kind of apparatus inside a waveguide will cause them to appear, as may the presence of any twist or bend.

PERIODIC STRUCTURES

What was said above for waveguides applies equally well to any periodic structure, such as those used in

linear accelerators, traveling-wave tubes, or, in fact, any lumped-constant filter composed of a cascade of identical networks. By reasoning exactly like that in the preceding section, one can show that any localized imperfection in such a structure will cause a bound resonance to appear, with resonant frequency just outside the pass band of the structure. In this case, it may lie either above or below the pass band. Once again, the imperfection has to be quite large in order to cause separation of a well-resolved resonance, so that reasonable care in construction is sufficient to avoid troubles due to these ghosts.

There is an interesting, and pedagogically useful, analogy with certain well-known features of solid-state theory. Here a crystal represents a three-dimensional periodic structure, and solutions of the Schrödinger equation, in one-electron approximation, show an almost perfect mathematical analogy with those in the corresponding electrical problem [3]. In particular, the conduction bands of the crystal correspond to pass bands of the filter, and any localized imperfection in the crystal (such as a vacancy, interstitial atom, or impurity atom), results in at least one localized bound state, with an energy just above or just below the edge of a conduction band. In this way one can understand the creation of donor or acceptor impurity levels involved in n -type and p -type conductivity in semiconductors [4].

Further work on ghost modes, by M. Forrer and the writer, is being prepared for publication. Experimental results, universal curves for predicting the occurrence of ghosts, and discussion of their possible use in waveguide filters and mode convertors will be included.

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High-Frequency Crystal Filter Design Techniques and Applications*

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Summary—High-frequency crystal filters which operate to 40 mc are now being commercially produced. These filters, with bandwidths ranging from one cycle to several hundred kilocycles per second, have been made possible by new design techniques and simplified circuitry.

Eliminating the need for multiple frequency conversion, the small rugged filters are already beginning to find wide use in many AM, SSB, and fm receivers as well as single-sideband generators.

Crystal filters are normally composed of from two to eight quartz resonators in a lattice or bridge network. The filter components are characterized by high Q and stability under extreme environmental conditions. Normal values of Q for crystal filter components in the 1 to 40 mc range are from 50,000 to 200,000; in certain filters, element Q 's exceed 1,000,000.

INTRODUCTION

WITH more and more radio communication messages crowding the radio-frequency spectrum, allotment of frequency bands to various radio and radar needs has become a serious problem. New systems have been developed to aid in the economical utilization of existing frequency space. These include schemes such as single-sideband and narrow-band frequency modulation. To be successful, each of these systems must operate within a narrow, well-defined band of frequencies. As a result, filter selectivity requirements have become increasingly stringent.

At frequencies greater than a few megacycles, equipment designers up to now have been forced to resort to systems of multiple-frequency conversion in order to obtain required equipment performance. Conventional types of filters may not perform suitably for single frequency conversion. The multiple conversion process brings about increased circuit complexity, with corresponding loss in efficiency and reliability.

The high-frequency crystal filter offers a solution to the frequency conversion problem as well as other general design problems in the higher frequency ranges.

Compact filter units employing miniature quartz crystal resonators in the 5- to 40-mc range exhibit filter performance which has previously been possible only at significantly lower frequencies. The result is that multiple frequency conversions may be eliminated. Equipment simplification and size reduction can be effected, along with improved performance and reliability.

One primary reason why crystal filters perform so well at high frequencies is the inherent high Q of the resonators. In a band-pass filter, high selectivity and low

dissipation or insertion loss require that the Q 's of the critical filter components be much greater than the ratio of center frequency to bandwidth.¹ Quartz crystal resonators used in filter networks have Q 's that range from 10,000 to 200,000 in general. Filters have been produced with crystal Q 's in excess of 1,000,000. By comparison, the Q 's normally attainable in conventional inductances may range from 50 to 200. Nickel alloy resonators commonly employed in "mechanical" filters have Q 's ranging from 2000 to 10,000.² The advantages of using crystal resonators in filter networks have been known for over 30 years,³ but not until recently have high-frequency filter units with controlled characteristics been made commercially available.

QUARTZ CRYSTAL RESONATORS

Of the hundreds of crystals that exhibit the piezoelectric effect, only the quartz crystal has been employed to any significant extent in oscillators and filters. Among other qualities, quartz crystals possess an extremely high order of stability over wide temperature variations during long time periods. In the presence of severe shock and vibration, the quartz crystal designed for filter applications does not exhibit microphonic behavior. These qualities are necessary to achieve good narrow-band filtering devices at high frequencies.

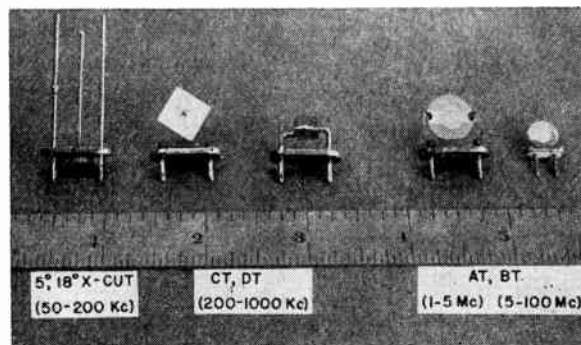


Fig. 1—Typical quartz filter crystals.

Typical quartz filter crystal resonators are shown in Fig. 1. Any plate cut from a piece of natural quartz has a number of resonant frequencies. The frequencies of resonance depend on the crystal dimensions, the vibra-

¹ E. A. Guillemin, "The effect of incidental dissipation in filters," *Electronics*, vol. 19, pp. 130-135; October, 1946.

² J. C. Hathaway and D. F. Babcock, "Survey of mechanical filters and their applications," *Proc. IRE*, vol. 45, pp. 5-16; January, 1957.

³ W. G. Cady, "The piezo-electric resonator," *Proc. IRE*, vol. 10, pp. 83-114; April, 1922.

* Original manuscript received by the IRE, September 6, 1957; revised manuscript received, October 30, 1957.

† Hycon Eastern, Inc., Cambridge, Mass.

tional mode involved, and the orientation of the cut. The AT-cut crystal, which operates in a thickness shear vibrational mode, is particularly attractive because of its extremely small size at frequencies above 5 or 6 mc. Also, the AT-cut component possesses an excellent temperature coefficient. Over the temperature range of -55°C to $+85^{\circ}\text{C}$ the resonant frequency of a typical AT crystal will shift less than ± 0.005 per cent of its nominal value.

Equivalent Circuit

In the vicinity of a resonant frequency, a crystal resonator may be represented by an equivalent electrical circuit⁴ of the type shown in Fig. 2(a). The inductance L_1 and capacitance C_1 represent the effective mass and stiffness of the crystal, respectively. C_0 is the static capacitance and includes stray-wiring and holder capacitance. The resistance R_1 represents the frictional loss of the vibrating crystal. The crystal Q is defined as the ratio of the reactance of L_1 at the resonant frequency to the resistance R_1 . Because of the extremely large value of Q , the crystal may be considered a purely reactive network for most filter applications.

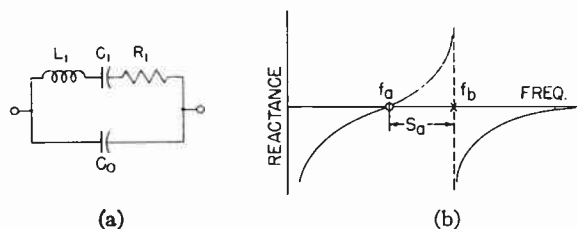


Fig. 2—Crystal resonator equivalent circuit.

The reactance curve corresponding to the lossless equivalent circuit is shown in Fig. 2(b). The resonant frequency or "zero" of the crystal unit (f_a) and the anti-resonant frequency or "pole" (f_b) are related to one another by the ratio of capacitances of the crystal defined by

$$r \equiv \frac{C_0}{C_1} \quad (1)$$

The relationship is easily seen to be:

$$f_b^2 = f_a^2 \left(1 + \frac{1}{r} \right) \quad (2)$$

Because of the coupling that exists between the electrical and mechanical stresses within the crystal, there will always be a fixed ratio of capacitances for any crystal cut.⁵ The lowest ratio found for quartz is 115, but because of stray-wiring and holder capacitance the minimum ratio for practical quartz cuts is approximately 125. At frequencies above one megacycle, the coupling factor associated with the AT-cut crystal in-

creases the minimum value of r to approximately 250. From (2), the zero-pole spacing [S_a in Fig. 2(b)] can be approximated by

$$S_a = f_b - f_a \doteq \frac{f_a}{2r} \quad (3)$$

S_a is, therefore, a very small percentage of the crystal resonant frequency, being at most 0.4 per cent of f_a at low frequencies, and 0.2 per cent of f_a at high frequencies.

A quartz crystal may have a number of vibrational modes in the vicinity of the desired response. However, by properly dimensioning the resonator and the electrodes which supply electrical excitation, it has been possible to produce crystals with essentially single-resonance characteristics at frequencies as high as 40 mc. Through the proper utilization of from 4 to 8 such resonators, filters are produced in which the level of undesirable or spurious responses is from 80 to 100 db below the mean pass band level.

Dimensioning a crystal resonator to suppress undesirable modes of vibration and to produce a given temperature coefficient generally limits the equivalent electrical parameters to a narrow range of values. This limitation, together with the existence of a fixed ratio of capacitances for the crystal resonator, places both theoretical and practical restrictions on the maximum bandwidth attainable with a given crystal filter configuration. Such restrictions apply even when inductances or resonant circuits are arranged in series or parallel with the crystal resonator in order to modify the resonator critical-frequency or zero-pole configuration.

These bandwidth restrictions make it desirable to utilize a design procedure which will rapidly and accurately indicate the range of filter characteristics obtainable with a given crystal resonator. A synthesis procedure developed for this purpose follows.

CRYSTAL FILTER CIRCUITRY

Almost all crystal filters of any significance produced in the past twenty years have been based on the symmetrical-lattice or bridge networks developed by Mason.⁶ The symmetrical lattice, which is the most general form of symmetrical network, provides analytical flexibility. In addition, practical considerations peculiar to crystal filter realization often make it necessary to employ this configuration.

Several examples of crystal lattice filter circuits are illustrated in Fig. 3. Attenuation characteristics of these filters depend completely upon the arrangement of critical frequencies or zeros and poles of the series (A) and shunt (B) arms of the lattice. Fig. 3(a) and 3(b) illustrates the crystal-capacitor lattices normally designated as narrow-band filters. The bandwidth of these filters is limited directly by the zero-pole spacings

⁴ K. S. Van Dyke, "The piezo-electric resonator and its equivalent network," *PROC. IRE*, vol. 16, pp. 742-764; June, 1928.

⁵ R. A. Heising, "Quartz Crystals for Electrical Circuits," D. Van Nostrand Co., Inc., New York, N. Y., ch. 1; 1946.

⁶ W. P. Mason, "Electric wave filters employing quartz crystals as elements," *Bell Sys. Tech. J.*, vol. 13, pp. 405-452; July, 1934.

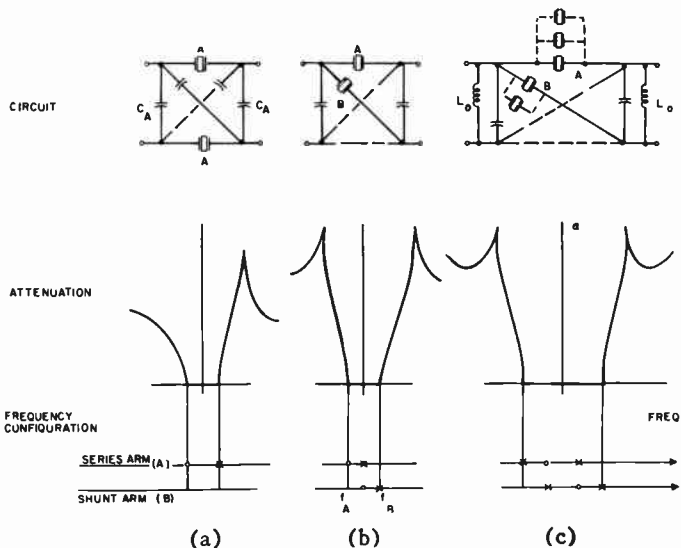


Fig. 3—Crystal lattice filter configurations.

of the associated crystals and therefore, by the ratio of capacitances (r). The ratio of capacitances must include the effects of external capacitance C_A , which may be considered to be in parallel with both series and shunt lattice arms, and will, therefore, increase the normal static capacitance C_0 . From (3) it may be seen that the upper bandwidth limit of the narrow-band crystal filter is only a few tenths of one per cent of the filter center frequency. The lower percentage bandwidth limit, which is set by crystal dissipation and frequency tolerances, may be as small as 0.01 per cent.⁷

In order to obtain wider filter bandwidths, inductances may be placed in series or in parallel with the lattice network as shown in Fig. 3(c). The inductance L_0 may be considered to resonate in the vicinity of the center frequency with all or part of the crystal effective shunt capacitance ($C_0 + C_A$). A number of the resultant critical frequencies of the series and shunt lattice arms may be so arranged as to provide a narrow pass band region. The remaining poles and zeros, far removed in frequency from the filter pass band, have negligible effect on the over-all characteristic.⁸ The width of the pass band formed in this manner is not limited directly by the crystal ratio of capacitances. This type of filter, which will be called an intermediate-band crystal filter, may have somewhat wider bandwidths than the crystal-capacitor filter. It is highly significant that the inductances associated with the intermediate-band crystal filter need not have extremely high Q 's. In general, inductor Q 's in the order of 40–60 will be sufficient to permit bandwidths up to 2 or 3 times the bandwidth of the crystal-capacitor filter, with negligible increase in filter dissipation.

The wide-band crystal filter is obtained when all the critical frequencies resulting from an inductance-crystal combination are contained within the filter bandwidth limits, as shown in Fig. 3(c). The bandwidth range for this filter type is approximately 1.5 per cent to 10 per cent of the filter center frequency. The upper limit, which is somewhat smaller at high frequencies, is set by the crystal ratio of capacitances, while the lower limit is fixed⁷ by the Q 's realizable for L_0 . The dissipation present in the external inductances may be associated directly with the filter terminating impedances, producing no effect on the network attenuation characteristics other than a constant insertion loss.

The dissipation, or midband insertion loss, introduced by the filter network is only 1 or 2 db for most narrow- and intermediate-band filters. For wide-band filters, the corresponding loss depends upon filter bandwidth and external inductance Q . For a 5 per cent filter bandwidth and a Q of 100, the filter loss is approximately 6 db.

The simple filters shown in Fig. 3 form the basic building blocks for more complicated filter networks. Greater attenuation and selectivity may be obtained either by cascading sections of the type shown, or by placing several crystals in parallel in any lattice arm as shown in Fig. 3(c) (connections shown dotted).

Unbalanced Networks

Until recently, the most significant application of crystal filters has been to low-frequency filters for carrier telephone systems. These filters, designed for use with balanced transmission lines, employ crystal resonators with divided electrodes⁹ to obtain performance equivalent to the lattice networks shown in Fig. 3.

For vacuum tube or transistor circuitry, and at frequencies above several hundred kilocycles, it is desirable to utilize an unbalanced equivalent of the symmetrical lattice network. One of the most useful lattice equivalents is the "hybrid" network shown in Fig. 4(a).¹⁰ The "hybrid" transformer has closely-balanced, tightly-coupled, secondary windings, and a primary winding which is uniformly coupled to the secondaries. Crystals 2A and 2B have twice the impedance of crystals A and B, respectively ($2L_1, C_1/2, C_0/2$). The inductance L_a may be resonated by parallel capacitance, or it may be used as one of the inductances L_0 shown in Fig. 3(c).

Fig. 4(b) and 4(c) illustrates two methods of cascading hybrid-type filter networks to achieve greater attenuation and selectivity. Hybrid leakage reactance has been neglected in these circuits. Any combination of Fig. 4(a)–4(c) may be employed to provide still better performance. Alternatively, crystals placed in parallel

⁷ D. I. Kosowsky, "Synthesis and Realization of Crystal Filters," Mass. Inst. Tech., Cambridge, Mass., Res. Lab. of Electronics, Tech. Rep. No. 298, pp. 38–42; June 1, 1955.

⁸ See, for example, Fig. 10. The frequencies f_1 and f_2 may be closely spaced and form part of a filter pass band, while f_3 may be far removed from the pass band region.

⁹ C. E. Lane, "Crystal channel filters for the cable carrier system," *Bell Sys. Tech. J.*, vol. 17, pp. 125–136; January, 1938.

¹⁰ W. P. Mason, "Resistance-compensated band-pass crystal filters for unbalanced circuits," *Bell Sys. Tech. J.*, vol. 16, pp. 423–436; October, 1937.

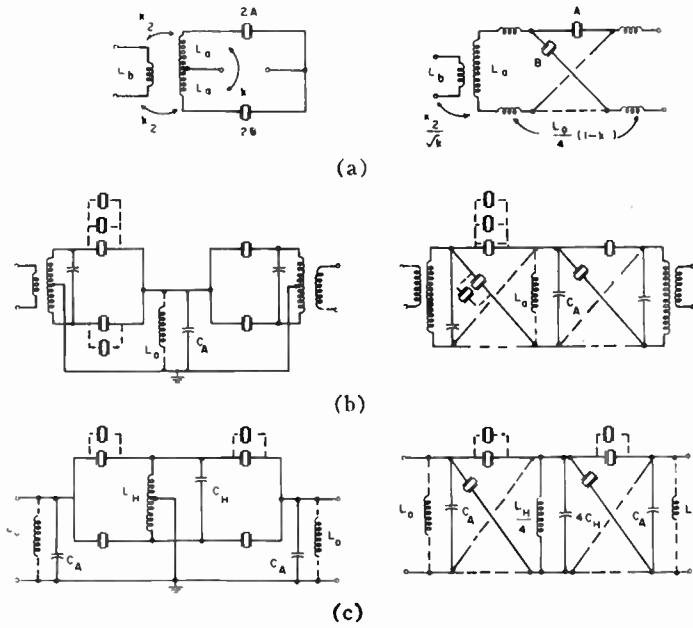


Fig. 4—"Hybrid" filter networks.

widths which are a very small percentage of the center frequency, and because of the nature of the equations involved in the image parameter synthesis of these filters, it has been possible to develop a procedure which permits the design of even the more complicated crystal filters utilizing only simple calculations and graphical aids. This procedure is based on a normalization or approximation technique which provides solutions with accuracies that are normally well within the tolerances placed on the filter components. A complete description of the synthesis procedure is given in another report⁷ and is outlined below.

As shown in Fig. 3, the pass band region of a crystal lattice filter extends from the lowest critical frequency of the series arm reactance to the highest critical frequency of the shunt arm reactance. These two frequencies, f_A and f_B , are called the cutoff frequencies. The remaining critical frequencies of the series arm coincide with those of the shunt arm to produce a continuous pass band. For a given filter, the attenuation characteristic has a number of "infinite peaks" (bridge nulls) which can be no greater than one plus the number of "coincident" frequencies in the pass band.

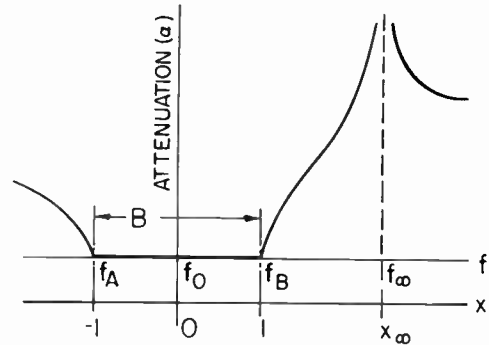


Fig. 5—"Normalized" basic section.

(shown dotted) in any lattice arm will accomplish the same result.

The inductances L_0 may be added to convert the network from the crystal-capacitor lattice [Fig. 3(b)] to the intermediate band or wide-band lattice [Fig. 3(c)]. In addition, the parallel circuit L_0-C_A in Fig. 4(c), provides a convenient means for altering the nominal impedance level of the filter. The desired impedance transformation is easily accomplished by "tapping" L_0 or C_A for the appropriate impedance level.

Utilizing the hybrid filter networks illustrated in Fig. 4, crystal filters have been produced throughout the frequency range of 10 kc to 40 mc, with bandwidths ranging from one cycle per second to several hundred kilocycles per second. The corresponding range of percentage bandwidths is 0.01 per cent to 7 per cent of center frequency.

SYNTHESIS PROCEDURE

Design of the lattice-type crystal filter network may be accomplished by utilizing classical image-parameter synthesis techniques^{6,11,12} or by considering the total insertion loss of a given filter network.¹³ However, as mentioned previously, the values of the equivalent electrical parameters of the crystal resonator are not completely within the control of the filter designer. A design procedure which rapidly indicates whether a given set of filter specifications can be realized is therefore highly desirable.

Since the crystal filter is normally restricted to band-

The simplest band-pass crystal filter [Fig. 3(a) and Fig. 5] will be referred to as the "basic" section. The characteristic of the basic section has, at most, one attenuation peak. The position of this attenuation peak may lie anywhere outside the filter pass band.

The attenuation characteristic of a filter having n infinite peaks and a bandwidth B , is equal to the sum of the characteristics of n basic sections, wherein each section has a bandwidth B and an attenuation peak corresponding to one of the n peaks of the composite filter. The degree of complexity of a crystal filter necessary to meet a given set of specifications may, therefore, be determined through the addition of basic section characteristics.

Image attenuation of the basic section is a function of the filter cut-off frequencies, f_A and f_B , and of the frequency of infinite attenuation f_∞ :

$$\alpha = \ln \left(\frac{1 + p}{1 - p} \right) = \text{attenuation loss} \quad (4)$$

¹¹ D. Indjoudjian and P. Andrieux, "Les Filtrés a Cristaux Piezo-electriques," Gauthier-Villars, Paris, France; 1953.

¹² E. A. Guillemín, "Communications Networks," John Wiley & Sons, Inc., New York, N. Y., vol. 2, ch. 10; 1935.

¹³ W. Herzog, "Siebschaltungen mit Schwingkristallen," Dieterich'sche Verlagsbuchhandlung, Wiesbaden, Germany; 1949.

where

$$p^2 = \left(\frac{f_\infty^2 - f_B^2}{f_\infty^2 - f_A^2} \right) \left(\frac{f^2 - f_A^2}{f^2 - f_B^2} \right). \tag{5}$$

Although (5) permits the calculation of all possible attenuation characteristics obtainable with the basic section, a complete set of characteristics would be necessary for each choice of filter relative bandwidth (ratio of bandwidth to center frequency). It is possible, however, to derive an approximation for p that is independent of bandwidth and center frequency and yet introduces negligible error in practice. Referring to Fig. 5, a normalization variable defined by

$$x \equiv \frac{f - f_0}{B/2} \tag{6}$$

where

$$B \equiv f_B - f_A; \quad f_0 \equiv \frac{f_A + f_B}{2} \tag{7}$$

is substituted into (5), resulting in

$$p^2 = \left[\frac{x_\infty - 1}{x_\infty + 1} \right] \left[\frac{x + 1}{x - 1} \right] \left[\frac{1 + \frac{B_r}{4}(x_\infty + 1)}{1 + \frac{B_r}{4}(x_\infty - 1)} \right] \left[\frac{1 + \frac{B_r}{4}(x - 1)}{1 + \frac{B_r}{4}(x + 1)} \right] \tag{8}$$

where

$$B_r = B/f_0 \text{ (relative bandwidth)} \tag{9}$$

and

$$x_\infty \equiv \frac{f_\infty - f_0}{B/2}.$$

Consideration of the values of B_r and x_∞ normally encountered in crystal filter design, leads to the conclusion that (8) may be closely approximated by

$$p^2 \doteq p_0^2 = \left(\frac{x_\infty - 1}{x_\infty + 1} \right) \left(\frac{x + 1}{x - 1} \right). \tag{10}$$

Normalized Characteristics

The normalized attenuation characteristic is a function only of the variable x and the position of the attenuation peak (x_∞). Since (10) contains neither f_0 nor B , the normalized attenuation expression will hold regardless of filter center frequency or filter bandwidth.

Reference to (8) indicates that (10) is an excellent approximation in cases of very small percentage bandwidths and small values of x_∞ . The set of normalized basic section characteristics shown in Fig. 6 illustrates the fact that even for the largest possible value of x_∞ and for extremely wide bandwidths (for the crystal

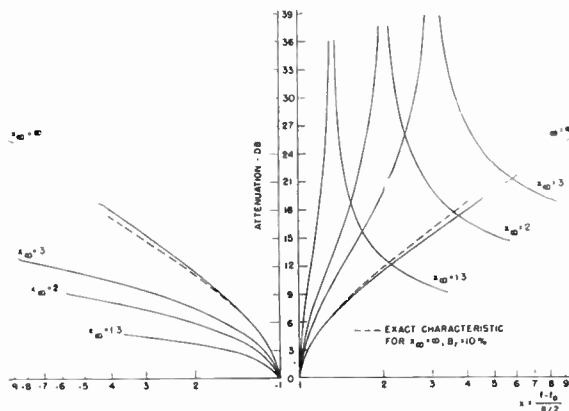


Fig. 6—"Normalized" basic section attenuation characteristics.

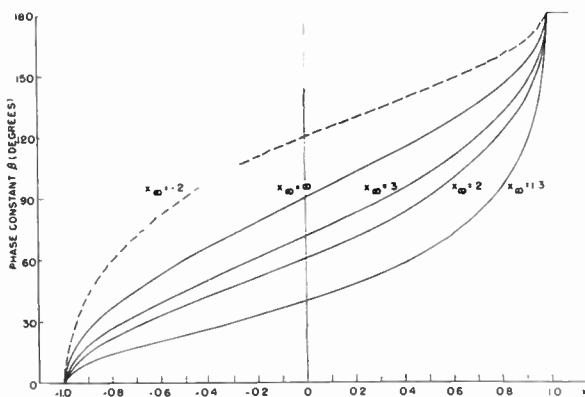


Fig. 7—Phase characteristics of basic section.

filter), the error involved in the normalization procedure is of no practical significance.

The attenuation α of a symmetrical network expresses the loss introduced by the network when it is terminated in its image or characteristic impedance. In practice the terminal impedances of a filter are generally fixed resistances. Image attenuation loss only approximately describes the performance of the filter. Filter termination effects, commonly called reflection and interaction losses, are of greatest importance in the filter pass band region. In this region, the attenuation loss is zero and the filter loss is primarily the result of mismatch.

To describe completely the filter transmission characteristic or insertion loss, it is necessary to determine the corresponding image impedance and phase characteristics. Fortunately, the same normalization technique may be applied to these characteristics to provide the complete insertion loss of any crystal filter.

The expression for a basic section normalized phase characteristic is given by

$$\beta_0 = 2 \tan^{-1} jp_0 \tag{11}$$

where

$$\beta_0 = \text{normalized image phase constant.}$$

A set of phase characteristics is shown in Fig. 7. The composite phase constant for a number of cascaded

basic sections is the sum of the phase constants for the individual sections at any value of x .

The image impedance characteristics of the crystal filters described above may be classified into three types depending on the nature of the cutoff frequencies f_A and f_B . In normalized form the three types are as follows:

Type I: Zero at f_A and pole at f_B

$$Z_{01} = R_{01} \left(\frac{1+x}{1-x} \right)^{1/2} \quad (12)$$

Type II: Zero at f_A and f_B

$$Z_{02} = R_{02}(1-x^2)^{1/2} \quad (13)$$

Type III: Pole at f_A and f_B

$$Z_{03} = R_{03}(1-x^2)^{-1/2} \quad (14)$$

where R_{01} , R_{02} , and R_{03} are resistances whose values depend on both the relative bandwidth of the filter and the equivalent circuit parameters of the crystal resonators. Eqs. (12) and (13) are plotted in Fig. 8.

In the filter pass band region ($-1 < x < +1$), the image impedance is resistive (solid line). In the attenuating region, the image impedance is reactive and the corresponding magnitude is shown by the dotted line. The Type I image impedance is characteristic of the narrow-band filter [Fig. 3(a), 3(b)], while the Type II and Type III may result when external inductances are employed in wide-band or intermediate-band filters [Fig. 3(c)].

Utilizing the data of Figs. 6-8, it is possible to construct the total insertion loss characteristic corresponding to any number of basic sections (*i.e.*, any degree of filter complexity). As an example, Fig. 9 illustrates the composite transmission characteristics of a filter consisting of 6 basic sections (peaks at $x_\infty = \pm 1.3, \pm 1.6, \infty, \infty$). These values have been chosen to provide a maximum filter attenuation of 60 db. The shape factor (ratio of 60-db bandwidth to 6-db bandwidth) is approximately 1.3:1. A Type II image impedance characteristic is assumed, and the filter is resistively terminated.

A filter of this type might be employed in a telephone carrier channel system in the vicinity of 100 kc, or in an intermediate-frequency amplifier at 10 to 15 mc where extremely high selectivity is preferred to high final attenuation. For applications requiring final attenuations of 80 to 100 db, the attenuation peaks may be placed farther from the pass band. (See Fig. 13.)

Fig. 9 illustrates the degree of approximation to "flat" pass band and linear phase characteristics which may be obtained with the crystal filter. These factors, combined with linear voltage characteristics, result in low signal distortion and contribute to good transient performance.

To complete the design of a given crystal filter, it is necessary to determine the values of the equivalent parameters of the crystal resonators from the filter insertion loss characteristic. This is accomplished first by

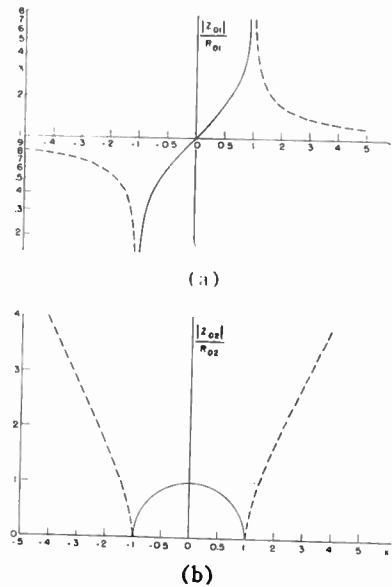


Fig. 8—Image impedance characteristics of band-pass filters. (a) Type I, (b) Type II.

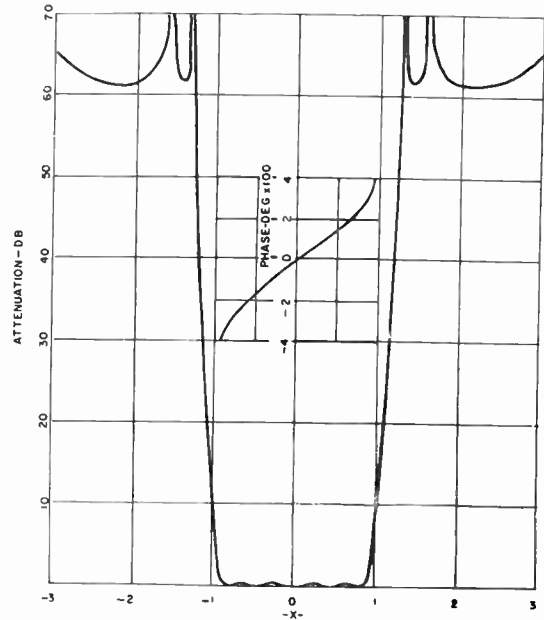


Fig. 9—Six-section transmission characteristics.

determining the locations of the pass band critical frequencies (see Fig. 3) from the attenuation peak positions, and then by calculating the element values of the filter reactances from these critical frequency configurations. It is interesting to note that even this portion of the synthesis procedure may be normalized so that the relative values of the filter elements may be determined for any given configuration without specifying filter frequency or bandwidth.

Fig. 10 illustrates the use of the normalization procedure to determine element values from zero-pole configurations. The configuration shown might represent one arm of the lattice network of Fig. 3(c). The zero and pole frequencies (f_1, f_2, f_3) can be derived from the attenuation frequencies of the filter utilizing conventional

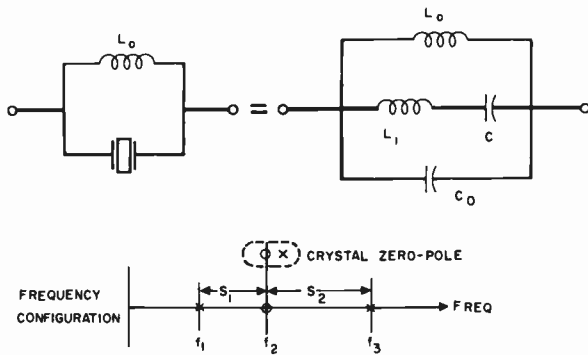


Fig. 10—Lattice-arm reactance.

synthesis techniques. On the other hand, the normalization procedure yields S_1 and S_2 directly (as functions of the filter bandwidth B).

Since f_2 is also the crystal resonant frequency, the realizability of the crystal resonator is uniquely determined by the required ratio of capacitances ($r = C_0/C_1$). If C_0 is chosen to determine the filter image impedance, or if C_1 is fixed by an available crystal unit, then the remaining element values may be determined from the ratio of capacitances and the frequency of resonance of L_0 and C_0 called f_α . That is,

$$f_\alpha \equiv \frac{1}{2\pi(L_0C_0)^{1/2}} \quad (15)$$

A comparison of the exact and normalized (approximate) values of f_α and r , for the network of Fig. 10 is given in (16) and (17).

Exact	Approximate
$f_\alpha = \frac{f_1 f_3}{f_2}$	$f_\alpha \doteq f_2 + (S_2 - S_1)$ (16)

$r = \frac{f_2^2}{(f_1^2 + f_3^2) - (f_\alpha^2 + f_2^2)}$	$r \doteq \frac{f_2^2}{4S_1S_2}$ (17)
--	---------------------------------------

Approximations such as (16) and (17) may be written for an entire filter configuration. By the proper combination of these equations, conditions of filter realizability as well as the values of all network parameters may be described in terms of filter performance characteristics. Once equations are derived for a given filter configuration, complete filter design is accomplished by simply substituting the values of center frequency, bandwidth, and impedance level. Simple manipulation of these equations provides additional important information, such as the effects parameter variations have on the filter transmission characteristic. As a result, the normalization procedure is useful not only in filter synthesis, but also in practical considerations connected with filter realization, such as the specification of tolerances and the development of alignment techniques.

APPLICATIONS AND TYPICAL CHARACTERISTICS

Without useful application, the design of high-frequency crystal filters would be to little avail. Some of

the more immediately apparent applications are explored in the following paragraphs.

Bandwidth ranges from one or two cycles to several hundred kilocycles per second represent the present-day boundaries of crystal filter technique. These ranges include the majority of channel or information bands allocated to communications and navigation equipments. The ability to produce a given bandwidth at substantially higher frequencies, together with the excellent selectivity, stability, and loss characteristics of the high-frequency crystal filter, has already resulted in many interesting applications.

Crystal filters are widely applied to intermediate frequency filtering applications in AM, SSB, and fm receivers, as well as single-sideband generators. For mobile versions of these systems, filters from 10 to 30 mc are particularly attractive, offering the advantages of small size ($\frac{1}{2}$ –2 cubic inches) and freedom from microphonic behavior.

Crystal filters are employed in data handling systems utilizing pulse techniques, where uniform time delay and smooth transient response characteristics are significant. Other important applications in which the crystal filter is utilized to select a band of frequencies or an entire bank of frequency bands include fixed-channel receivers at frequencies as high as 40 mc, carrier telephone systems, telemetering systems, Doppler radar, fire control and missile systems, and spectrum analysis.

Single-Conversion Receivers

A single-conversion crystal-filter receiver, as shown in Fig. 11, offers the advantage of a high-frequency first IF (*i.e.*, good image rejection), combined with high adjacent channel selectivity (heretofore achieved only through multiple frequency conversion). At the same time, the elimination of multiple conversions reduces cross modulation and receiver desensitization due to mixer overload, and locally generated spurious signals.

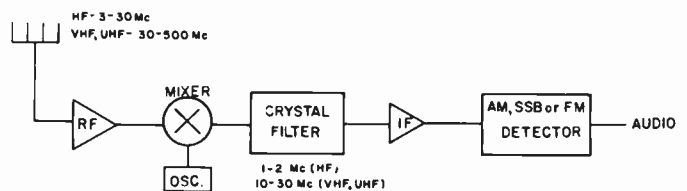


Fig. 11—Single-conversion crystal-filter receiver.

Since the frequency selection characteristics of the entire receiver are determined primarily by the crystal filter unit, it is possible to alter the receiver bandwidth and selectivity characteristics by simply changing the filter. Crystal filters designed for single conversion receivers have been produced with bandwidths ranging from 250 cps (for hf-cw telegraphy) to 50 kc (for vhf-fm or uhf-AM).

Fig. 12 illustrates the attenuation characteristics of two filters designed for single-conversion hf communica-

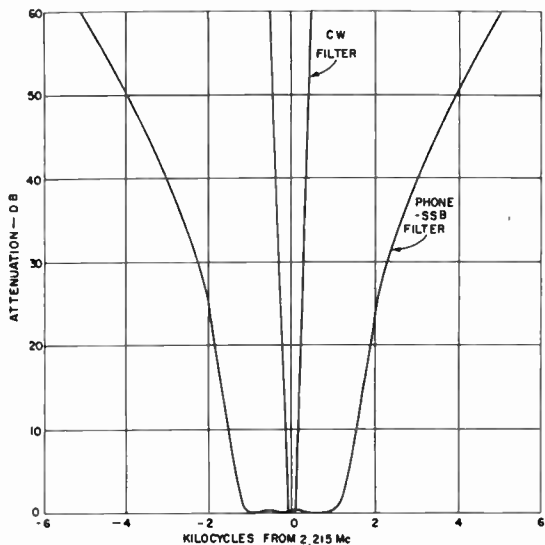


Fig. 12—Crystal filters for single conversion hf receivers.

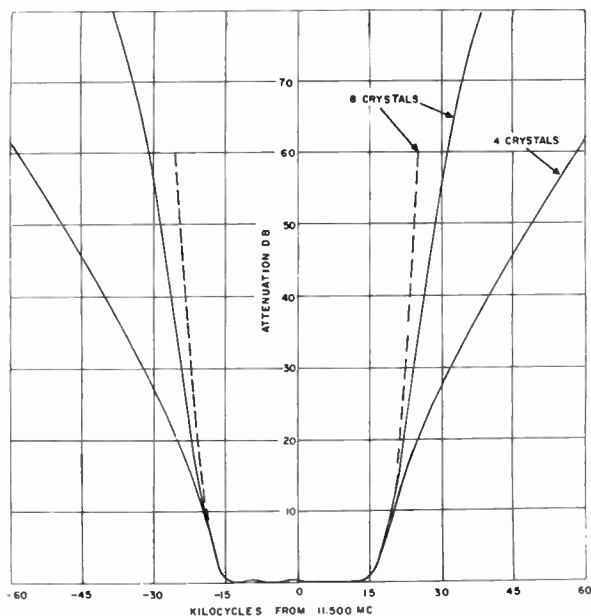


Fig. 13—Crystal filters for vhf fm receivers.

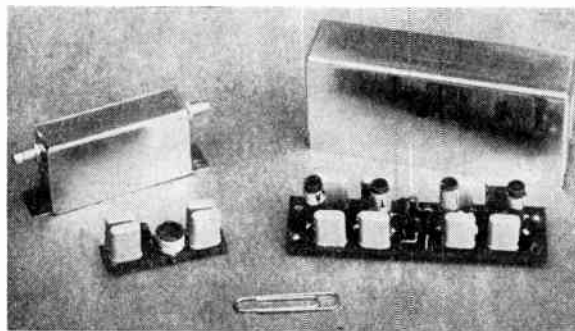


Fig. 14—Hybrid-type crystal filters.

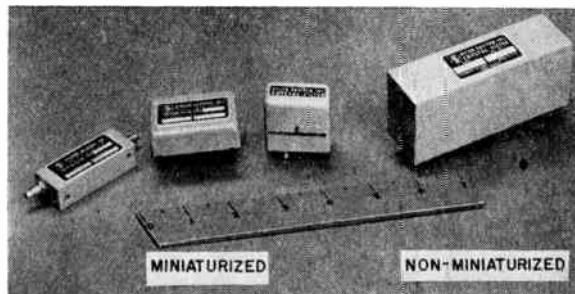


Fig. 15—High-frequency crystal filter mounting cases.

shows the attenuation characteristics of filters at 11.5 mc designed for mobile fm receivers. A comparison is made between a four-crystal filter (shape factor approximately 3.5:1) and an eight-crystal filter (shape factor approximately 1.7:1). The eight-crystal device may be made considerably more selective (*i.e.*, smaller shape factor), at the sacrifice of the final or "ultimate" attenuation reached by the filter. For example, the dotted characteristic in Fig. 13 (shape factor approximately 1.3:1) may be obtained by permitting the filter to return to an attenuation slightly greater than 60 db (see Fig. 9). The solid eight-crystal characteristic reaches an attenuation well over 80 db and represents a good compromise between final attenuation and shape factor for this application. The 6-db bandwidth for the filters shown in Fig. 13 is approximately 35 kc. For the new split-channel fm operation, filters with identical characteristics have been produced with bandwidths of 15 kc.

The filters illustrated in Fig. 13 are intermediate-band lattice networks produced in hybrid configuration. Fig. 14 shows one component arrangement for a four- and an eight-crystal filter of this type. The miniature crystal units, which occupy a volume of only 0.035 cubic inch and weigh about 1/25 of an ounce, are extremely rugged and will withstand vibration frequencies as high as 2000 cps and shock accelerations greater than 30 g.

The small size of crystal units and associated components at frequencies greater than 10 mc, makes possible extremely compact filters. Several packaging arrangements of these filters are shown in Fig. 15. The smallest of the miniaturized units (1/2 cubic inch) will accommodate a four-crystal filter. The other units may contain

tion receivers.¹⁴ The narrow filter has a 6-db bandwidth of 250 cps and is intended for cw telegraphy. The wider filter has a 6-db bandwidth of 2800 cps for phone-SSB reception. In both cases, the center frequency is 2.215 mc, and the shape factor (ratio of bandwidth at 60-db attenuation to bandwidth at 6-db attenuation) is slightly greater than 3:1. Pass band response variation or "ripple" is less than $\pm \frac{1}{2}$ db, while the insertion loss is less than 3 db. Each filter utilizes four crystal resonators in a hybrid configuration (Fig. 4) and is equivalent to two cascaded narrow-band lattices [Fig. 3(b)].

For vhf-fm applications, an intermediate frequency in the 10- to 15-mc range is normally chosen. Fig. 13

¹⁴ "A selective IF amplifier for phone and cw," in "Radio Amateur's Handbook," American Radio Relay League, Inc., 34th ed., pp. 137-140; 1957.

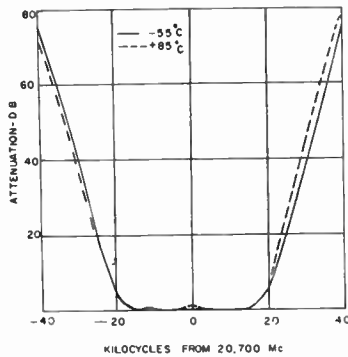


Fig. 16—Temperature performance of crystal filter.

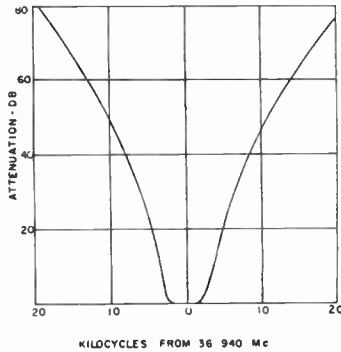


Fig. 17—Harmonic resonator filter.

up to 5 or 6 crystals, to yield characteristics lying between the 4- and 8-crystal selectivities illustrated in Fig. 13. The remaining package is nonminiaturized and accommodates the 8-crystal filter illustrated in Fig. 14.

Since the crystal filter supplies most of the selectivity of the receiver, the need for multiple-tuned interstage transformers in the IF amplifier is eliminated. Instead, the amplifier interstage networks become simple single-tuned circuits designed for maximum gain (high Q , high L/C ratio). Furthermore, as previously mentioned, the impedance level of the crystal filter may be varied over wide limits through the use of single-tuned terminating circuits.

Therefore, one filter may be employed at a high impedance level to obtain maximum gain with vacuum tube circuitry; or it may be used at lower impedance levels to obtain maximum power transfer with transistor circuitry. In either case, the same filter is used.

Fig. 16 illustrates the attenuation characteristic of a crystal filter designed for vhf-uhf AM and fm reception. The 6-db bandwidth is approximately 40 kc and the shape factor is approximately 1.7:1. The filter characteristics at -55°C and $+85^{\circ}\text{C}$ are illustrated. Even at frequencies as high as 20 mc, the extremely high stability of the crystal resonator makes possible the realization of filters which operate over wide temperature ranges with negligible degradation of performance.

At frequencies greater than approximately 30 mc, it becomes difficult to produce crystal resonators which operate in fundamental vibrational modes. At these elevated frequencies, it is common to employ crystal

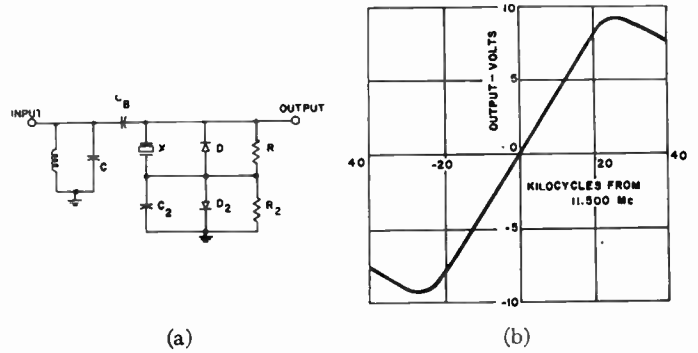


Fig. 18—Crystal discriminator.

resonators at 3rd, 5th, or 7th harmonics of their fundamental response. However, the ratio of capacitances of a harmonic resonator increases as the square of the order of the harmonic, making it difficult to obtain useful filter characteristics with such crystals. Fig. 17 shows the characteristic of a 4-crystal hybrid filter utilizing 3rd-overtone AT quartz resonators. The bandwidth of this filter is only 6 kc (0.016 per cent of center frequency).

Crystal Discriminator

In order to utilize the single conversion technique in fm receivers, it is necessary that fm detection be performed at the first IF. Since the first intermediate frequency may be too high to permit the realization of a conventional type of fm detector or discriminator, a crystal discriminator has been developed which possesses a stability comparable to that of the high-frequency crystal filter and which operates at the filter frequency. This device may be applied not only to fm receivers but also to automatic frequency control systems and frequency modulation generators.

The basic circuit diagram of the crystal discriminator is illustrated in Fig. 18(a). The voltage developed across the resonant circuit L_1-C_1 is transferred through bypass capacitor C_B , to the series crystal-capacitor circuit, $X-C_2$. The voltage developed across each element in this series combination is rectified by the diodes, D_1-D_2 . The difference between these voltages is developed across the combination R_1-R_2 , and has the form shown in Fig. 18(b). The discriminator in Fig. 18(b) is designed for use in conjunction with the filters of Fig. 13. The discriminator has a center frequency of 11.5 mc and a peak-to-peak bandwidth of approximately 50 kc. When driven from a conventional pentode limiter, which operates at a peak rf input voltage of 2 volts, the discriminator output voltage is approximately 16 volts peak-to-peak.

Single-Sideband Generators

In the generation of single-sideband signals by filtering techniques, the signal quality is largely dependent upon the ability of a filter to pass, with negligible distortion, one sideband of an amplitude modulated signal, and simultaneously to effectively eliminate the other

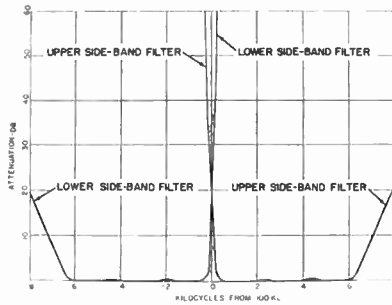


Fig. 19—Single-sideband crystal filters.

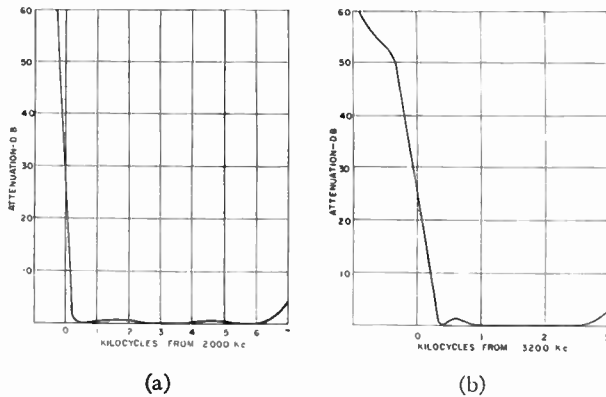


Fig. 20—High-frequency SSB crystal filters.

sideband. Fig. 19 shows the attenuation characteristics of two filters designed for single-sideband generation at a frequency of 100 kc. Each filter has a bandwidth (at 2 db) of over 6 kc, and an attenuation slope which rises from 2 db to 60 db in less than 600 cps. If either filter were produced with the same steep attenuation characteristic on both sides of its pass band, the filter would have an equivalent shape factor of less than 1.2:1.

The single-sideband signal which is generated at the filter frequency is modulated onto a high frequency carrier through processes of frequency mixing or conversion, similar to those employed in the communications receiver. As was true in the receiver case, one or more frequency conversions may be eliminated by increasing the frequency of the filtering operation. To accomplish this end, crystal filters for SSB generation have been produced at frequencies as high as 16 mc.¹⁵

Fig. 20 (a) shows the attenuation characteristic of a single-sideband filter nearly identical with the upper-sideband filter in Fig. 19, except for a center frequency of 2 mc. The 2-mc SSB crystal filter is an intermediate-band hybrid filter.

For SSB-voice operation in the hf bands, requiring audio frequencies of 300 to 3000 cps, the attenuation characteristic shown in Fig. 20(b) is generally sufficient. This filter utilizes only 4 crystal resonators in a simple narrow-band hybrid configuration.

¹⁵ W. E. Morrow, Jr., C. L. Mark, B. E. Nichols, and J. Leonhard, "Single-sideband techniques in uhf long-range communications," Proc. IRE, vol. 44, pp. 1854-1873; December, 1956.

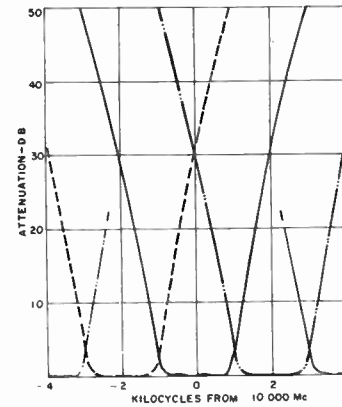


Fig. 21—"Comb" filter set.

Fixed-Channel Receivers

It is often desired to construct a receiver which operates on a fixed channel or small number of channels at some frequency below 30 mc. By producing a crystal filter at the given channel frequency and with the required bandwidth, a tuned radio frequency (trf) receiver may be constructed. This is equivalent to removing the rf, mixer, and oscillator stages from the crystal-filter receiver. (See Fig. 11.) For fixed-channel operation, the trf receiver, in addition to its simplicity, provides the maximum possible protection against adjacent channel interference. Any communications receiver may be converted to a fixed-channel receiver by inserting a crystal filter between the antenna and the first rf stage. In the presence of strong adjacent-channel interference in the hf bands, this technique materially reduces interference caused by intermodulation and desensitization.¹⁶

Frequency Multiplexing

Perhaps the best-known application of crystal filters is to frequency multiplexing systems, and more particularly to carrier-telephone systems.⁹ Filters for this application are generally wide-band lattice filters with bandwidths of 4 kc, spaced 4 kc apart, in the range of 60-108 kc. The shape factor required is approximately 1.5:1. As illustrated in Fig. 9 and Fig. 13, it is possible to produce high-frequency as well as low-frequency crystal filters with this type of characteristic.

The close tolerances which can be maintained on the shape of a crystal filter characteristic make this device particularly well suited for frequency channelizing or "comb" filter applications. Fig. 21 illustrates part of a bank of closely-spaced filters. Each filter has a bandwidth of 2 kc in the vicinity of 10 mc, utilizes 4 crystal resonators, and occupies a volume of approximately 1 cubic inch. Filter comb sets of this type have been produced at frequencies as low as 100 kc and as high as 28 mc, for application to Doppler radar and fire control and to spectrum analysis.

¹⁶ F. Raymond, "Reduction of Interference in the HF Range (2-32 MC) Through the Use of Bandpass Crystal Filter (Hycon Type 44)," Rome Air Dev. Center, Air Res. and Dev. Command, Tech. Memo, RADC-TM-56-33; 1957.

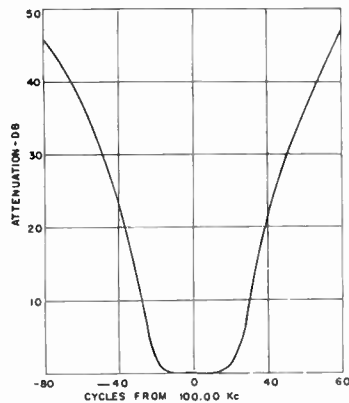


Fig. 22—Narrow-band filter for spectrum analysis.

In some types of spectrum analysis equipments, a single filter is made to cover an entire band of frequencies by employing the superheterodyne principle. Narrow-band crystal filters have been produced for this application with bandwidths as small as 1 cps (at a center frequency of 10 kc). Fig. 22 shows the attenuation characteristic of a 4-crystal hybrid filter at 100 kc. The bandwidth of this filter is approximately 50 cps and it has been employed in spectrum analysis equipment, in SSB equipment for carrier selection, and in channelizing equipment for pilot selection.

MEASUREMENT OF FILTER CHARACTERISTICS

Fig. 23 is a block diagram of the test facility which is employed for the alignment and measurement of crystal filters in the range of 10 kc to 50 mc. Basically, the filter test facility provides means of accurate frequency and attenuation-level measurements while simultaneously presenting to the operator a visual display of the entire attenuation characteristic. The attenuation display is obtained with a mechanically-swept signal generator and a logarithmic amplifier. The test circuit compresses a voltage variation of 80 db into a signal suitable for presentation on any dc oscilloscope or *X-Y* plotter. A single amplifier, using several sets of plug-in inductors, covers the entire range of 10 kc to 50 mc.

The precision attenuator is operated at its proper impedance level at all times, providing accurate attenuation-level settings. The frequency meter provides accurate frequency measurement when the sweep is stopped at some chosen attenuation point. The dc output of the logarithmic amplifier is derived from an automatic gain control (agc) circuit which provides feedback around a 3-stage amplifier.

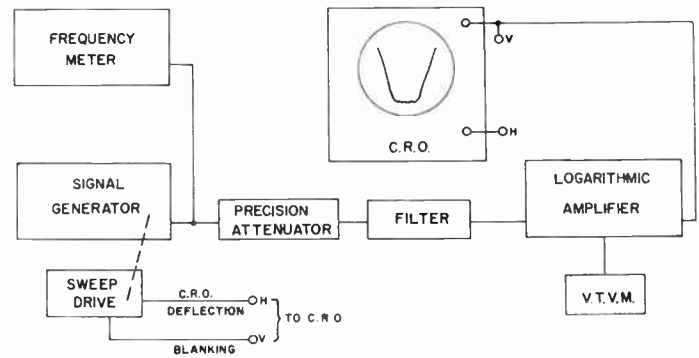


Fig. 23—Block diagram of crystal filter test facility.

Because the crystal filter is a relatively narrow-band device compared to a conventional low-*Q* tuned circuit, it is a simple matter to tailor the frequency characteristics of the logarithmic amplifier to have negligible effect on the attenuation characteristics of the filter. A blanking voltage, derived from the sweep drive, eliminates the effect of backlash in the drive by preventing the retrace of the filter characteristic when the direction of sweep is reversed.

Before a filter is inserted into the test facility, the output of the logarithmic amplifier is observed over the entire frequency band of interest and at a number of attenuation levels. The resulting oscilloscope display, which should be a series of evenly spaced horizontal lines, is used to check the level of the signal generator output and the flatness of the logarithmic amplifier characteristic over the frequency and attenuation ranges used in testing the crystal filter.

CONCLUSION

Further progress in the development of quartz resonators may make possible the extension of crystal filter ranges to frequencies approaching 100 mc. Filter bandwidths in the order of 1 to 5 mc may be achieved, permitting the application of crystal filters to wide-band systems such as pulsed radar.

High-frequency crystal filters are beginning to play an important role in the battle to expand the number of usable channels of communication in our limited frequency spectrum. The device provides a new standard of stability and selectivity. Crystal filter units are now being produced in quantity to operate at frequencies where full advantage may be derived from their unique characteristics.



Experimental 8-MM Klystron Power Amplifiers*

T. J. BRIDGES†, MEMBER, IRE, AND H. J. CURNOW‡

Summary—Experimental klystron amplifiers, which were used to investigate the cw power obtainable at a wavelength of 8 mm, are described. Working at 5000 volts with a beam current of 0.2 a, these tubes produced an output power of 75 watts cw. Operation was limited by the maximum current density of 1.5 a/cm² which could be drawn from sprayed-oxide cathodes.

INTRODUCTION

A RECENT paper¹ described a klystron oscillator of the floating-drift-tube type with a cw output of 12 watts in the 8-mm wavelength band, and a life in excess of 1000 hours. It was considered that the major limitation to the output power was the cathode emission which could be obtained. At the time the only cathode available was the standard oxide-coated type and even employing special techniques, such as a 700°C bake out, the maximum emission density which could be drawn with useful life was 0.6 a/cm². However, cathodes with superior emission capabilities are now becoming available. If these were combined with the techniques referred to, a substantial increase in the output power might be possible.

To investigate this possibility, work has been carried out on klystron power amplifiers at 8-mm wavelength. The object was to discover whether the output could be increased significantly before overheating or other limitations became prohibitive. Conventional sprayed-oxide cathodes were used in these experiments since they were readily available and it was found that current densities up to 1.5 a/cm² could be drawn from them for short periods. The same electron gun as in the oscillators was used and the dc input power was increased by raising the applied voltage. As the efficiency of a klystron increases with the applied voltage and the dc input power is proportional to the 5/2 power of the voltage, it was expected that the output power would increase very rapidly as the voltage was raised. Because a floating-drift-tube oscillator is limited to a number of discrete, narrow bands of operating voltage, the tubes were constructed so that they could be used either as amplifiers or as oscillators with a phase-shifting network in the feedback loop. They were then capable of working over a wide, continuous range of voltage, and thus of dc input power.

DESCRIPTION OF THE TUBES

The general arrangement of the tubes used in the experiments is shown in Fig. 1, while details of the reso-

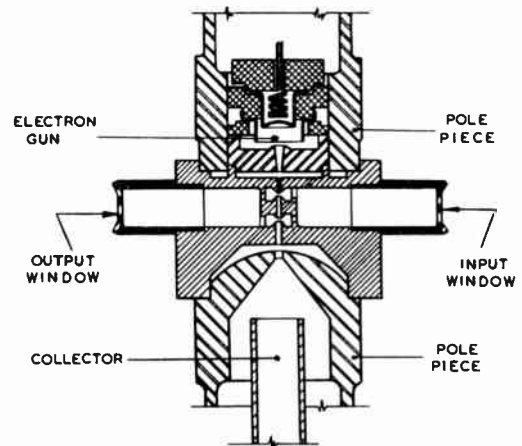


Fig. 1—General arrangement of 8-mm klystron amplifier.

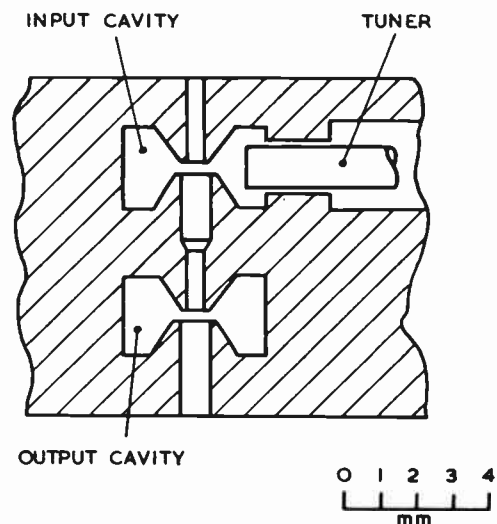


Fig. 2—Details of the resonant cavities.

nant cavities may be seen in Fig. 2. The cavities were of the doubly re-entrant type, and the gap dimensions were such that at an operating voltage of 5000 volts the gap transit angle was 2 radians and the normalized tunnel diameter 2.8 radians. The ends of the cavity cones had different diameters to avoid multipactor effects and to shield the thin cone tips from beam interception.

The drift length between the cavities was 0.15 inch, which was about 0.16 of the effective plasma wavelength for the electron beam used. A value less than the optimum 0.25-plasma wavelength was chosen in order to reduce the length over which the focusing magnetic field had to be maintained.

The method of construction of the tubes was similar to that of the oscillators.¹ There were of course, some extra features made necessary by the different cavity arrangement. With separate cavities some means had to

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¹ R. L. Bell and M. Hillier, "An 8-mm klystron power oscillator," Proc. IRE, vol. 44, pp. 1155-1159; September, 1956.

be provided of aligning them to the same resonant frequency. The cavities were approximately tuned by adjusting the lengths of the gaps during construction. Final adjustment was made during operation by tuning the input cavity. The resonant frequency of this could be varied over a 1 per cent range by means of a fine-tuning device, which consisted of a 1-mm-diameter copper wire, shown in Fig. 2, protruding through a hole in the wall of the cavity and supported by a flexible diaphragm (not shown). Each of the cavities was coupled to a separate waveguide, the coupling being arranged to be a nominal match in the absence of the electron beam. For ease of construction the waveguides inside the tubes were circular (TE₁₁ mode) and simple glass windows were used. Specially designed transitions at the windows enabled a good match to be obtained directly to standard rectangular waveguide. The windows of high-melting-point aluminosilicate glass could pass a mean power of 50 watts before forced cooling became necessary.

The electron optical system was identical with that used in the oscillators, apart from the length of the tunnel. The gun had a perveance of about 0.5×10^{-6} a/volt^{3/2}, and the current density multiplication was 100 times. A transmission efficiency of 75–80 per cent was obtained through a 0.023-inch diameter tunnel, 0.3 inch in length. The increased magnetic field required for focussing at elevated voltages was obtained with an electromagnet.

EXPERIMENTAL RESULTS

It was found that in tubes which had been baked out at 700°C, ordinary sprayed-oxide cathodes could be used at emission densities up to 1.5 a/cm². The exact conditions needed to achieve this performance were not determined, and the results varied from one cathode to another. When this emission density could be obtained it was possible to operate a tube quite consistently at 5000 volts and a beam current of 0.2 a for periods of a few hours. These conditions corresponded to a power density in the beam of 500 kw/cm².

The construction of the tubes was such that the gun could easily be replaced and satisfactory operation at 5000 volts was eventually achieved with each of four structures, with identical cavity arrangements. The low-signal gain under these conditions was 8 db. As this was so small there was no signal source available which could be used to drive the tubes to their full output. They were accordingly operated as oscillators, with an external waveguide feedback loop (see Fig. 3). The attenuation of the loop was set at about 4.5 db by the inclusion of a ring hybrid and by the loss in the waveguide components. The output power was measured with a calorimeter through a directional coupler. The phase of the feedback was adjusted with a phase shifter for optimum output. Matching stubs (not shown) were used to compensate for the mismatch caused by the presence of the electron beam across the gaps.

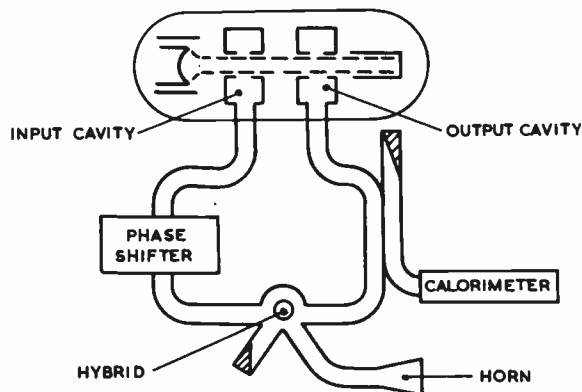


Fig. 3—Feedback loop.

Operating under the conditions described the average output power of the four tubes was 75 watts cw, corresponding to an efficiency of 7.5 per cent.

The limit to the current which could be drawn from a cathode was set by a deterioration in the transmission efficiency, causing unacceptably high dissipation on the rf structure. This was revealed by detuning the cavities, rather than by catastrophic heating effects. With better cathodes higher emission densities should be obtained before this defocusing effect occurs and the input power could then be raised even further.

COMPARISON WITH THEORY

In order to determine whether the output obtained was a fair test of the potentialities of the tubes, a comparison was made with a theoretical estimate of the power to be expected. The efficiency can be expressed in terms of the low-signal gain, the bunching angle, and the maximum rf current which can be induced in the electron stream. The low-signal gain depends on various parameters of the tube from which it can be calculated; it can also be measured directly. The maximum rf current which can be induced in an electron stream has been calculated from the theory of the bunching process. The simple theory of Webster² predicts that this will have an amplitude 1.16 times the beam current. A more elaborate analysis³ suggests that the value should be rather less than this, but for the values of the parameters for these tubes the efficiency so calculated is only slightly less.

In order to work out what low-signal gain might be expected, it was necessary to know the values of the cavity resonant conductance, and the effective gap-coupling and gap-loading coefficients. These were obtained from perturbation measurements on a scaled-up model of the cavity, and from *Q*-factor measurements on the actual cavities. From the perturbation measurements the ratio *R/Q* for the cavity was found to be 120.

² D. L. Webster, "Cathode ray bunching," *J. Appl. Phys.*, vol. 10, pp. 501–508; July, 1939.

³ M. Chodorow, E. L. Ginzton, and E. J. Nalos, "Debunching of electron beams constrained by strong magnetic fields," *Proc. IRE*, vol. 41, pp. 999–1003; August, 1953.

Q -factor measurements on the cavities used in the tubes showed that the loaded Q was 750. The cold-loaded conductance was therefore 1.11×10^{-5} mhos. The gap-coupling and gap-loading coefficients were also calculated from the shape of the gap field given by the perturbation measurements. This was preferred to calculations based on assumed field shapes, as the gap dimensions were rather larger than those for which the common assumptions are valid. The values obtained were a mean-square coupling coefficient of 0.3 and a gap-loading conductance of 0.75×10^{-5} mhos. Allowing for the effects of space-charge debunching and the mismatch introduced by the gap-loading, the low-signal gain was calculated to be 11.2 db. The experimentally observed value (8 db) was less than this. The most probable cause for this departure from theory lies in the nature of the electron stream, which certainly was not the uniform beam filling the drift tube assumed in the calculations. The effect of a smaller beam diameter would be to reduce the coupling coefficient and to increase the effect of space-charge debunching. If the observed value of the gain is used, together with the assumption of a maximum rf current 1.16 times the beam current, then the expected efficiency is 7.8 per cent, in good agreement with the observed value. Thus it may be concluded that

the observed output was that which could be expected from the tubes, and no large advantage was being lost through the lack of a powerful driving source.

CONCLUSION

The work carried out on these klystrons has shown that it is possible to obtain cw powers of at least 75 watts in the 8-mm wavelength band. A necessary condition for this is that the cathode must be capable of giving an emission density of 1.5 a/cm^2 in an electron gun with a density multiplication of 100 times. Although the power density in the beam was 500 kw/cm^2 , the limit was not set by thermal considerations, but by cathode performance.

The actual tubes used in this investigation would be of little practical use as the life was short and the gain low. In order to produce a useful tube giving this order of output power, it would be necessary to incorporate a cathode of improved performance and to increase the gain by adding extra cavities. Neither of these operations should present any major difficulties.

ACKNOWLEDGMENT

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FM Demodulator Time-Constant Requirements for Interference Rejection*

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Summary—Under conditions of high-level interference fm receiver performance is often impaired because of improper low-frequency time constants in the limiter and discriminator circuits. The computation of the upper bounds on the permissible values of these time constants is illustrated. Severe restrictions are indicated which often conflict with other fundamental requirements. The computational results of this paper demonstrate that these severe restrictions can be alleviated by means of simple schemes that will greatly enhance the capture performance of the fm receiver.

I. INTRODUCTION

A BASIC requirement in fm receiver design for suppressing multipath and cochannel disturbances is the use of the proper time constants in the low-frequency parts of the limiter and discriminator

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circuits. The presence of an undesired signal, which is weaker than the desired one, within the linear pass band of the receiver causes the resultant signal delivered to the first limiter to exhibit severe AM and fm disturbances under conditions of high-level interference. For proper amplitude-limiting operation, the limiter circuit must be capable of following the sharp changes in the envelope of the resultant impressed signal, which may recur at a rate (in cps) equivalent to the bandwidth of the IF amplifier. In the discriminator the output circuit across which the rectified voltage is taken must be capable of following the detected instantaneous-frequency disturbance pattern. This performance is necessary in order to avert diagonal clipping and leave the variational control of the operation of the rectifying diodes entirely in the hands of the envelope of the signal delivered by the fm-to-AM-conversion section of the discriminator. Here, also, the sharp changes in the detected fm disturbance waveform may recur at a maximum rate (in cps) of one IF bandwidth. In order to insure proper

operation, it is necessary, therefore, to determine the upper bounds on the time constant of the output circuit.

After discussing briefly the properties of the disturbances caused by the interference, and of the effect of narrow-band limiting upon the fm disturbance, we shall demonstrate how certain well-known principles can be applied to the determination of the upper bounds on the limiter and discriminator time constants. These upper bounds will be quite stringent if the requirements of high-capture performance are to be met, particularly because they may conflict with other fundamental requirements. To alleviate these restrictions, the disturbances must be suppressed (or minimized) before they reach the appropriate low-frequency circuits. It is believed that, more often than not, the impairment of proper performance of most available fm receivers can be traced to improper time constants in the limiters, or discriminators—particularly in the discriminators. The present study should suggest some remedies for these difficulties.

II. DISTURBANCES CAUSED BY HIGH-LEVEL INTERFERENCE

Consider the situation in which two carriers of constant relative amplitudes 1 and a ($a < 1$) and of frequencies p and $p + r$ rad/second ($r \ll p$) are passed simultaneously by the IF amplifier of an fm receiver. The AM and fm disturbances caused by the superposition of two such carriers have been extensively discussed in published work.^{1,2} The aspects of these disturbances that are of interest in the present discussion will now be summarized.

The signals are assumed to be unmodulated in amplitude and frequency or, at worst, to have frequency modulations that are so slow, relative to the frequency difference r , that the signal frequencies are not appreciably changed during a period of $2\pi/r$ seconds. It will become evident presently that the severity of the interference increases with the increase in the frequency difference r , and is greatest, therefore, when r assumes its largest possible value of one IF bandwidth (assuming, for simplicity, that this bandwidth is well defined). Thus, the assumption that r is much higher than the highest modulating frequency (if any) corresponds to the situation in which the interference causes the most troublesome amplitude and frequency disturbances. This is the situation of greatest interest in the determination of the design requirements on the limiter and discriminator circuits to insure their proper operation under all possible conditions of two-signal interference.

At the input of the first amplitude limiter the resultant signal will be

$$\begin{aligned} e_{if}(t) &= \cos pt + a \cos (p + r)t \\ &= A(t) \cos [pt + \theta(t)] \end{aligned} \quad (1)$$

if time is counted from the instant at which the two signal phasors are in phase. In this expression

$$A(t) = \sqrt{1 + 2a \cos rt + a^2} \quad (2)$$

and

$$\theta(t) = \tan^{-1} \frac{a \sin rt}{1 + a \cos rt}. \quad (3)$$

The instantaneous frequency of the resultant signal is $\omega_i(t) = p + d\theta/dt$. The presence of the weaker signal within the IF pass band causes the fm demodulator (limiter-discriminator combination) to see a resultant signal whose instantaneous frequency differs from the frequency of the stronger signal by $d\theta/dt$. Therefore, $d\theta/dt$ is the fm disturbance, while $A(t)$ contains the AM disturbance. Plots of $A(t)$ and of $d\theta/dt$ are shown in Fig. 1 and Fig. 2 (next page).

It is important to observe that the average value of $d\theta/dt$ over a period of $2\pi/r$ seconds is zero. In essence, the most important step toward achieving satisfactory capture of the stronger signal is to make the instantaneous-frequency deviation of the resultant signal from the desired frequency p average out to zero over one period of the frequency difference r , at every point in the receiver before the fm-to-AM conversion and detection process.^{3,4} The outcome of this process must then be a detected disturbance waveform that is superimposed upon the output voltage which corresponds to the frequency p and contributes a zero average deviation from this desired voltage. If r is beyond the audible range, then the preceding requirements are necessary and sufficient, since no disturbance will be passed by the de-emphasis and audio filters. If, however, r is audible, then these requirements (though necessary) will not insure complete rejection of the interference but the disturbance that gets through can be greatly reduced, if not effectively eliminated.

Two important schemes for improving the capture performance of an fm receiver will be briefly described. For the simpler scheme,^{3,4} it has been shown that limiters with bandwidths of the order of the IF bandwidth will introduce significant reductions in the effectiveness of high-level interference. The reductions result from the fact that the filter sluggishness to the violent fm disturbance can cause deformation of this disturbance into milder waveforms that maintain a zero average over a frequency-difference cycle. An extremely effective scheme for suppressing the disturbance of the weaker of two fm signals can be achieved, therefore, by cascading

¹ M. S. Corrington, "Frequency-modulation distortion caused by multipath transmission," *PROC. IRE*, vol. 33, pp. 878-891; December, 1945.

² M. S. Corrington, "Frequency-modulation distortion caused by common- and adjacent-channel interference," *RCA Rev.*, vol. 7, pp. 522-560; December, 1946.

³ E. J. Baghdady, "Frequency-modulation interference rejection with narrow-band limiters," *PROC. IRE*, vol. 43, pp. 51-61; January, 1955.

⁴ E. J. Baghdady, "Interference Rejection in FM Receivers," *Res. Lab. Electronics, M.I.T., Cambridge, Mass., Tech. Rep. 252*; September 24, 1956.

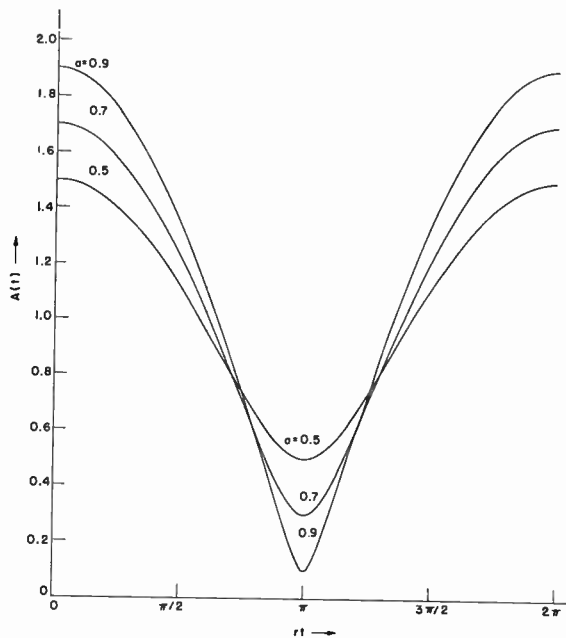


Fig. 1—Instantaneous envelope variations of the resultant of two sinusoids of relative amplitudes 1 and a , whose frequencies differ by r rad/second.

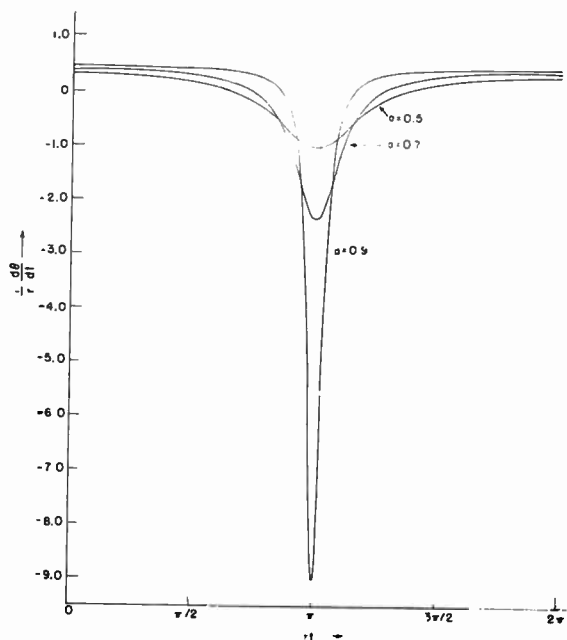


Fig. 2—Instantaneous-frequency disturbance caused by the superposition of two sinusoids of relative amplitudes 1 and a . The frequency of the stronger sinusoid is p rad/second; the frequency of the weaker sinusoid is $p+r$ rad/second.

several stages of amplitude limiting, each of which is followed by a band-pass filter of appropriate bandwidth. With such a scheme interference is effectively suppressed, by any desired amount, ahead of the discriminator rather than after it, and requirements on the performance of a satisfactory discriminator are greatly relaxed. This has been demonstrated with conventional circuits.

The mechanism by which the cascading scheme suppresses interference is based on the fact that the first

amplitude limiter spreads out the significant spectrum (which is necessary for the reproduction of the fm disturbance) over a frequency range that exceeds many times the bandwidth of the IF amplifier. The more severe the interference, the greater will be the spread of the spectrum through amplitude limiting; it will be of the order of 100 times the bandwidth of the IF amplifier if the signal strengths differ by 10 per cent of the amplitude of the stronger signal.

It follows that sizeable portions of the interference spectrum can be excluded without substantially affecting the spectrum that carries the message modulation by filtering after amplitude limiting. After one stage of limiting and filtering, a significant amount of interference will pass in a spectrum that cannot be eliminated without impairing the desired signal. Successive limiters will again spread out the interference spectrum which can be reduced further by additional filtering. As more limiter-filter units are added in cascade, more of the energy of the interference spectrum is drained off until the remaining energy is negligible. Beyond this point, the cascading of more stages of limiting and filtering is not economically justifiable.

The practical importance of the cascading scheme is enhanced significantly by the fact that the near elimination of the high-level interference (caused by undesired signals that are either delayed replicas of the desired signal, or are caused by other stations or by impulse radiation such as that from ignition systems) can be achieved with from 3 to 6 properly designed narrow-band limiters.

The greatest achievable reduction in the effective interference ratio in one stage of narrow-band limiting⁵ can reduce a to $(1/2)a$, when $a > 0.5$. The performance of one stage of ideal narrow-band limiting with only one IF bandwidth is indicated in Fig. 3. In this plot a_{out} is the output ratio of weaker-to-stronger signal amplitude (or interference ratio) and a_{in} is the corresponding input ratio. The analysis leading to this plot assumes that $r > 1/2(BW)_{if}$, and the plot only applies when $a < 0.84$. It turns out, however, that this performance can be improved by various methods. One relatively simple method (which has been tested in the laboratory) is to apply positive feedback through a bandwidth of the order of the IF bandwidth from the output of the limiter to its input.⁶ Under the more serious conditions of interference, this scheme results in pronounced improvement in the capture performance of the receiver. The positive feedback will increase the amplitudes of both signal and interference at the input of the limiter, but it will add more to the stronger signal than to the weaker signal. In this way, the predominance of the stronger signal is improved at the input of the limiter, and further improvement is effected by narrow-band limiting

⁵ E. J. Baghdady, "Theory of stronger-signal capture in fm reception," (submitted for publication); March 15, 1957.

⁶ E. J. Baghdady, "Theory of feedback around the limiter," 1957 IRE NATIONAL CONVENTION RECORD, Pt. 8, pp. 176-202.

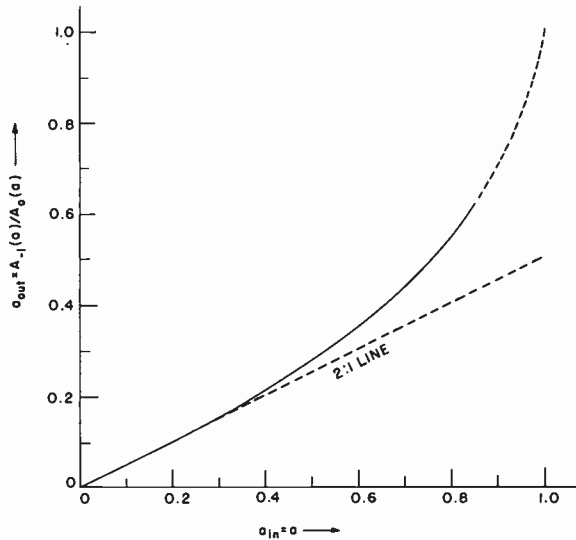


Fig. 3—Variation of the interference ratio at the output of one narrow-band limiter, whose bandwidth equals $(BW)_{if}$, with the interference ratio at the input, when the frequency difference $r = (BW)_{if}$.

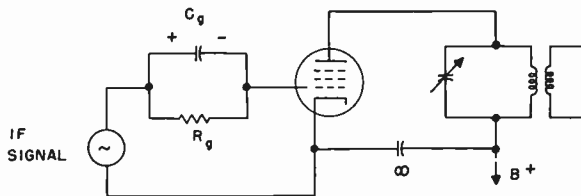


Fig. 4—Grid-circuit limiter for time-constant computation.

in the same limiter stage. The over-all improvement in one stage with band-limited positive feedback can be made equivalent to the improvement that would result from several stages that do not use feedback.

Positive feedback that causes a self-sustained oscillation in the absence of an input signal will not only cause pronounced improvement in capture performance, but it will also bring about effective interstation noise squelch, improved amplitude-limiting performance, and significant relaxation in the limiter time-constant requirements.

III. LIMITER TIME-CONSTANT REQUIREMENTS

Perhaps, the only important limiter circuit that presents a time-constant problem, at present, is the grid-bias pentode limiter circuit shown in Fig. 4. It will suffice, for our purposes, to recall⁷ that the operation of this limiter depends upon the control by the instantaneous amplitude of the input signal of an automatic self-rectified grid bias. This, in turn, controls the conduction angle and the height of the plate-current pulses, increasing the height and decreasing the angle with increasing signal amplitude so that the net charge delivered by each pulse to the plate-tank capacitor is kept approximately constant.

⁷ L. B. Arguimbau, "Vacuum-Tube Circuits," John Wiley & Sons, Inc., New York, N.Y.; 1948.

The mechanism of the operation in the grid circuit of the grid-bias limiter lends itself to a treatment that is very similar to the usual analysis of the simple diode peak detector. In our problem there are three time-constant considerations that must be taken into account if this circuit is to be used in a receiver designed to handle a specified interference ratio a .

1) The product $R_g C_g$ must be sufficiently small to enable the circuit to follow the amplitude variations of a resultant two-carrier signal, and thus keep the dynamic self-bias under the exclusive control of these amplitude variations.

2) C_g must be sufficiently large to bypass R_g at radio frequencies and offer an impedance at radio frequencies which is much lower than the input impedance of the tube in order for the IF voltage to appear effectively between the grid and the cathode of the tube when the grid potential is on the negative swing. If ω_0 is the intermediate frequency and C_{in} is the input capacitance of the stage, the present requirements can be summarized as $C_g R_g \gg 1/\omega_0$ and $C_g \gg C_{in}$.

3) R_g must be sufficiently large for the development of the necessary bias on the grid for effective smoothing of the envelope of the input wave. If the grid-to-cathode conduction resistance is r_g , then we want $R_g \gg r_g$.

Requirement 1) can be translated into an explicit condition on $R_g C_g$. Let $A(t)$ denote the instantaneous amplitude of the resultant signal impressed at the input of the grid circuit. We recognize that the magnitude of the rate at which the capacitor tends to charge (or discharge) at any instant of time must be greater than (or, at worst, equal to) the magnitude of the rate at which $A(t)$ is increasing (or decreasing), in order for the self-rectified bias on the grid to follow the amplitude variations of the input signal. For example, if $A'(t)$ is positive, the charging rate at time t must be

$$\frac{A(t)}{R_g C_g} \geq A'(t).$$

Therefore the desired condition on the RC time constant of the grid circuit can be written

$$R_g C_g \leq \left| \frac{A(t)}{A'(t)} \right|.$$

The quantity on the right-hand side will vary with time. Therefore if the most unfavorable situation is to be met, the condition should read

$$R_g C_g \leq \left| \frac{A(t)}{A'(t)} \right|_{\min}. \tag{4}$$

Under two-signal interference conditions, $A(t)$ is given by (2). With substitution in condition (4) and evaluation of the indicated minimum, we obtain

$$R_g C_g \leq \frac{1 - a^2}{ar}.$$

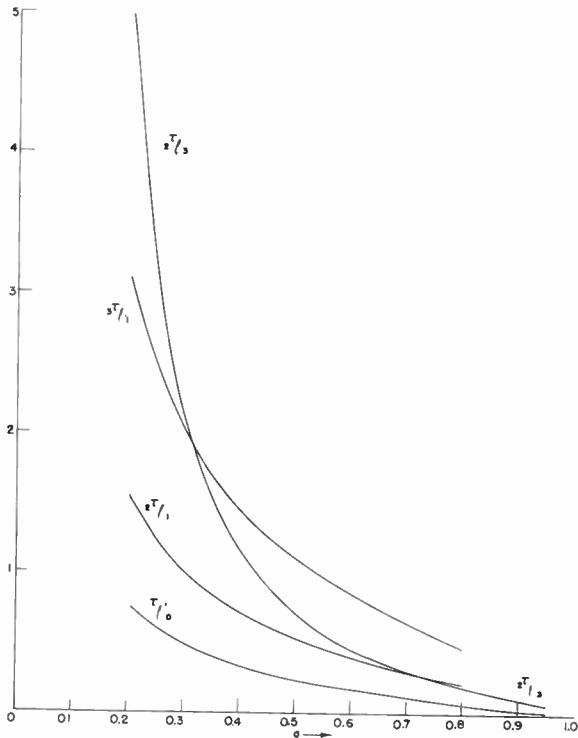


Fig. 5—Variation of the maximum permissible values of the grid-circuit time constant with the interference ratio a .

The frequency difference r can have a maximum value, $r_{max} = 2\pi W_{if}$, where W_{if} denotes the IF bandwidth in cps. Therefore, under the worst interference conditions, we must have

$$\tau_{10} = W_{if} R_g C_g \leq \frac{1 - a^2}{2\pi a} \quad (5)$$

The maximum permissible value of τ_{10} , as given by the equality sign in (5), is shown in Fig. 5 plotted against a . Multiplication by a scale factor appropriate to the value of W_{if} will convert the normalized values of time constant to microseconds.

For conditions at the input of the second-limiter stage, which immediately follows the filter of the first limiter, the problem is greatly simplified if the filter is assumed to have idealized amplitude and phase characteristics. Thus, if we consider the filter in the plate circuit of the first grid-bias pentode limiter as an ideal filter, then the input signal of the next stage is described in terms of the worst configuration of sideband components that this filter will pass. The amplitude of the resultant of these components will not be constant since, in general, not all of the components with significant amplitudes at the output of the first limiter will be passed. The spectrum of the amplitude-limited resultant of the two input signals is given by

$$\begin{aligned} e(t) &= \cos [pt + \theta(t)] \\ &= \sum_{n=-\infty}^{\infty} A_n(a) \cos (p - nr)t. \end{aligned} \quad (6)$$

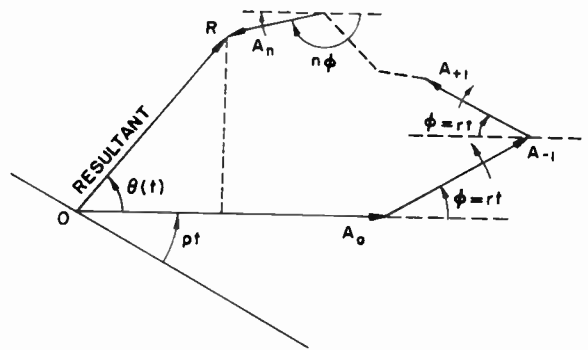


Fig. 6—Linear superposition of phasors representing the spectral components passed by the ideal-limiter filter.

This spectrum has been computed by Granlund,⁸ who presented ten-place tables of $A_n(a)$. A detailed study of the properties of this spectrum has been undertaken by the author.^{3,4}

If the bandwidth of the first-limiter filter is assumed to equal one IF bandwidth (as is permissible for all $a \leq 0.863$), then we know that the configuration A_0, A_{-1} will be the worst possible spectrum for all a 's up to approximately 0.84, and thus, for all such cases, condition (5) is directly applicable with a replaced by A_{-1}/A_0 . Fig. 3 is a plot of $A_{-1}/A_0 = a_{out}$ against $a = a_{in}$. Since $(A_{-1}/A_0) < a$, it is recognized that the highest permissible value of the time constant $R_g C_g$ is larger at the input of the second limiter than it was at the input of the first—a decided improvement in the design conditions. The extent to which improvement has been achieved is readily seen from the curve for $2\tau_{11}$, as shown in Fig. 5. Conditions at the input of the third-limiter stage are similarly computed if the second stage is assumed to be identical with the first one, and so on. Fig. 5 also shows a curve for $3\tau_{11}$ which applies to the time constant at the input of the third limiter.

When the ideal filter that follows the first limiter has three times the IF bandwidth, values of a up to 0.9807 can be considered. In the critical spectrum for this bandwidth the components whose amplitudes are given by $A_1(a), A_0(a), A_{-1}(a)$, and $A_{-2}(a)$ are passed. These have frequencies of $p - r, p, p + r$, and $p + 2r$ rad/second.

With reference to Fig. 6, we note that if the idealized limiter filter passes a spectrum made up of M lower sideband components and N upper sideband components, then the square of the amplitude of the resultant signal is

$$A^2(t) = \left[\sum_{n=-N}^M A_n \cos n\phi \right]^2 + \left[\sum_{n=N}^M A_n \sin n\phi \right]^2$$

where $\phi = rt$. When the first-limiter bandwidth is three times the IF bandwidth, the most unfavorable situation arises when $M=1, N=2$, and $r=2\pi W_{if}$. In this case, the value of ϕ that gives a minimum is a root of a fifth-degree equation in $\cos \phi$. The resultant maximum

⁸ J. Granlund, "Interference in Frequency-Modulation Reception," Res. Lab. Electronics, M.I.T., Cambridge, Mass., Tech. Rep. 42; January 20, 1949.

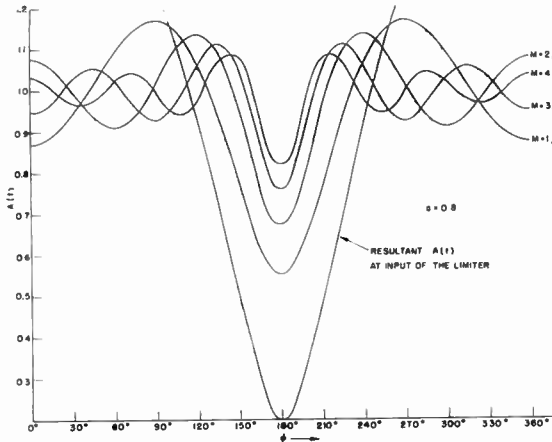


Fig. 7—Variations in the instantaneous amplitude of the resultant signal at the output of a narrow-band limiter compared with the corresponding variations at the input of the limiter.

permissible values of $2\tau_{13} \equiv W_{1f}R_0C_0$ (in the grid circuit of the second limiter when the first-limiter bandwidth is three times the IF bandwidth) are plotted in Fig. 5 for comparison with the other normalized time-constant curves.

With larger values of first-limiter bandwidth, the variations in the amplitude of the most troublesome signal delivered to the second limiter become less and less severe, and the upper bound on the permissible R_0C_0 product at the input of the second stage becomes higher and higher. The appearance of $A(t)$ for various spectral configurations is illustrated in Fig. 7.

We may now conclude that although the action of a narrow-band limiter upon the character of the resultant signal effects only a partial reduction in the severity of the amplitude variations of the signal (instead of a complete smoothing-out process), the partial abatement of the amplitude variation is sufficient, nevertheless, to show a significant increase in the upper bound on the permissible grid-circuit time constant. Eventually, with a sufficient number of cascaded narrow-band limiters, the resultant signal amplitude is smoothed out to an essentially constant value, and the upper bound on the RC product in the later stages is sufficiently high to be of no importance in the design of these stages. As for the first stage, the time-constant requirements are best relieved either by the application of regenerative feedback,⁶ or by the use of a limiter whose operation does not depend upon a low-frequency time constant.

IV. DISCRIMINATOR TIME-CONSTANT REQUIREMENTS

The time-constant requirements of two commonly encountered discriminator low-frequency output circuits will be discussed in the order of their simplicity. The low-frequency output circuit of many discriminators can be reduced to the forms shown in Fig. 8 and Fig. 9. In Fig. 8, the detected voltage, which ideally is proportional to the instantaneous-frequency variations of the signal at the discriminator input, appears across

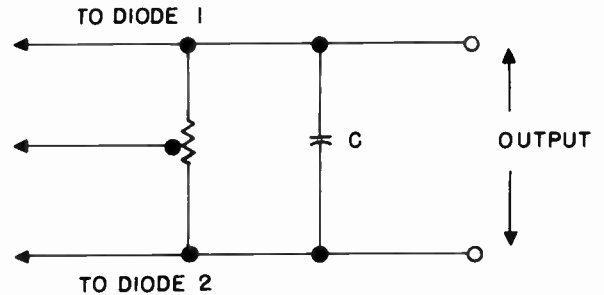


Fig. 8—Discriminator-output circuit for time-constant computation.

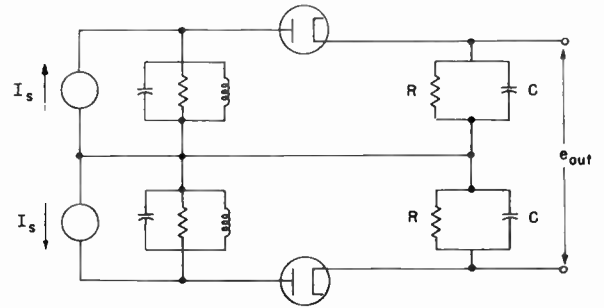


Fig. 9—Common form of balanced discriminator.

the equivalent RC combination. In some circuits this RC combination is a reduced form of a slightly more elaborate connection, in others C is the capacitor across which the output voltage of the discriminator is taken, and R either appears explicitly or consists essentially of a low equivalent output resistance that is associated with the rest of the discriminator circuit.

Let us first consider the situation in which the discriminator is either amplitude insensitive, and hence not preceded by any limiters, or amplitude sensitive but preceded by an "infinitely" wide-band ideal limiter. Assume that the discriminator has a linear over-all detection characteristic of unit slope over the whole range of the instantaneous-frequency variations of the input signal. Then, under the two-carrier interference conditions described in Section II, the voltage waveform that the output RC combination must handle is given by $E_0(p) + d\theta/dt$, where $E_0(p)$ is a direct-voltage level that is dictated by the frequency p of the stronger signal, and $\theta(t)$ is defined in (3). Since $d\theta/dt$ averages out to zero over $2\pi/\tau$ seconds, $E_0(p)$ is the only direct-voltage term that should appear at the output, inasmuch as the slow variation in this level will deliver the message of the stronger signal. If the frequency difference r lies outside the range of the desired message spectrum, subsequent de-emphasis and audio (or video) filtering will yield $E_0(p)$ with no distortion from the interference.

However, failure of the voltage across the capacitor to follow the voltage variations dictated by the instantaneous frequency of the signal at the discriminator input will cause the output low-frequency voltage to have an average value (over one frequency-difference cycle) that does not correspond to the value dictated by the frequency of the stronger signal. If the average value of

the output-capacitor voltage (over a period of $2\pi/r$ seconds) is to be maintained at the value dictated by the frequency p , the capacitor must, at every instant of time, tend to charge or discharge at a rate that is faster than (or, at worst, just as fast as) the rate at which the impressed waveform tends to change at that instant. Equivalently, the ratio of the instantaneous value of the capacitor voltage to the RC product must always exceed or, at worst, equal the time derivative of the impressed voltage evaluated at the same instant of time. This will enable the capacitor voltage to keep in step with the dictates of the instantaneous frequency of the resultant input signal, and thus ensure proper detector operation and lack of harmful diagonal clipping effects. Analogous with the problem of the limiter time constant, the restriction to be imposed on the RC product is, from condition (4),

$$RC \leq \left| \frac{e(t)}{e'(t)} \right|_{\min}, \quad e'(t) \equiv \frac{d}{dt} e(t), \quad (7)$$

where $e(t)$ is the total capacitor voltage. Evidently, $e(t)$ cannot go to zero (unless $e'(t)$ vanishes simultaneously with it). Under the aforementioned conditions,

$$e(t) = E_0(p) + \frac{1}{2} r \left[1 - \frac{1 - a^2}{1 + 2a \cos rt + a^2} \right], \quad (8)$$

where we must require that

$$E_0(p) > \frac{ar}{1 - a}. \quad (9)$$

Since $E_0(p)$ is the voltage level that corresponds to the frequency p , and p is likely to lie on either side of the center frequency of the IF pass band, it is evident that condition (7) will define a nonzero upper bound on the RC product only if the discriminator output, as seen across the RC combination of Fig. 8, is not balanced to give zero voltage at the center frequency. Furthermore, values of $E_0(p)$ that do not satisfy condition (9) will cause $e(t)/e'(t)$ to have a zero minimum magnitude, and thus require that RC be zero. The equality sign is excluded in condition (9) for the same reason.

With $e(t)$ as given by (8), we can show that the ratio

$$\frac{e(t)}{e'(t)} = \frac{[E_0(1+a^2) + a^2r + a(2E_0+r) \cos \phi][1 + 2a \cos \phi + a^2]}{ar^2(1-a^2) \sin \phi}$$

has a minimum magnitude at the negative real root of

$$\cos^3 \phi - \left[\frac{5}{2} + \frac{E_0(1+a^4) + a^4r}{2a^2(2E_0+r)} \right] \cos \phi - \left[\frac{E_0(1+a^2) + a^2r}{a(2E_0+r)} + \frac{1+a^2}{2a} \right] = 0,$$

which has a magnitude smaller than unity. An analytical expression for the resultant upper bound on the RC product is available, but it is too cumbersome to be useful.

When the discriminator is preceded by one stage of narrow-band limiting whose bandwidth equals one IF bandwidth, the formulas of the preceding computation are directly applicable to the computation of the maximum permissible discriminator RC product. Here, since the most unfavorable conditions at the limiter-filter output arise only when A_0 and A_{-1} pass and $r = 2\pi W_{if}$, it is merely necessary to replace a in the formulas by (A_{-1}/A_0) . A similar extension of the computation to the situation in which more than two limiters, each of which has a bandwidth of one $(BW)_{if}$, precede the discriminator is fairly evident.

It is of interest to observe that with a discriminator whose output across the RC combination shown in Fig. 8 is balanced, the upper bound on the RC product will be nonzero as long as the two signals lie symmetrically on opposite sides of the center frequency. For this situation, the upper bound is specified by

$$rCR \leq \frac{1 - a^2}{2a} \quad (10)$$

which is one half of the upper bound on the grid-circuit time constant of the limiter. Frequently, the capture ratio of a receiver is measured by simulating an interference situation in which the two (unmodulated) signals lie at opposite ends of the IF pass band. It is clear that, under this condition of measurement, a discriminator whose output is balanced about the intermediate frequency when it is observed across the RC combination of Fig. 8 will appear to meet the test if its RC product satisfies condition (10). Evidently, under the more general (but milder) interference conditions, it will fail.

In order to illustrate the manner in which the cascading of narrow-band limiters raises the upper bounds on the output-circuit time-constant requirements of the discriminator, we shall choose a discriminator whose characteristic goes through zero at a frequency that corresponds to a cutoff frequency of the IF amplifier. In view of condition (9), this situation is mainly of academic interest (unless the interference is effectively suppressed before it reaches the discriminator). The weaker of the two carriers will be assumed to fall at the frequency of balance. In the absence of narrow-band limiting, the voltage waveform impressed across the output capacitor is

$$e(t) = r \frac{1 + a \cos rt}{1 + 2a \cos rt + a^2}.$$

Consequently, the maximum permissible values of $\tau_{d0} = W_{if}RC$ are the values plotted in Fig. 10. If one narrow-band limiter whose bandwidth equals the IF bandwidth precedes the discriminator, the upper bounds are specified by the plotted values of τ_{d1} . The curve marked

" τ_{d1} " applies when two limiters, both of one IF bandwidth, precede the discriminator. Fig. 10 also presents a curve marked " τ_{d3} ," which applies when the discriminator is preceded by a limiter whose bandwidth equals $3(BW)_{if}$.

The plots of Fig. 10 show how the upper bound on the permissible time constant in the output circuit of the discriminator is raised when the discriminator is preceded by a process of narrow-band limiting. The effect produced by one narrow-band limiter will, clearly, be displayed by additional stages. After a sufficient number of stages has been cascaded, the upper bound on the maximum permissible time-constant values becomes sufficiently high, so that it exercises no important restraint on the design of the output circuit of the discriminator.

We shall now illustrate the computation of the maximum permissible time constant for the common type of discriminator circuit shown in Fig. 9. Alternative forms of this circuit (particularly, the one in which the AM-to-fm conversion is achieved through a double-tuned transformer, in which the top of the primary is connected to the center tap of the secondary) can be manipulated into the form of Fig. 9, and are, therefore, included in this treatment. The output voltage, e_{out} , is a superposition of the envelope of one tank-circuit response upon the other tank-circuit response with reversed polarity.

Assuming that the high- Q tank circuits have the same damping factor α , let one circuit be tuned to a frequency that is $b\alpha$ rad/second above the center frequency of operation ω_0 and the other tuned to $b\alpha$ rad/second below ω_0 . Furthermore, let the instantaneous frequency of the excitation be deviated by $\alpha x(t)$ rad/second from the center frequency of operation. Then, if the conditions for a quasi-stationary analysis of the tuned-circuit responses are satisfied, and if the RC combination of each peak detector is able to follow the envelope of the corresponding tank-circuit response, the output voltage can be normalized into the form

$$e_{out} = [1 + (x + b)^2]^{-1/2} - [1 + (x - b)^2]^{-1/2}. \quad (11)$$

For optimum linearity,⁹ b must be 1.225. Indeed, with this value of b ,

$$e_{out} = kx(t), \quad \text{for } -0.6 < x < 0.6.$$

The extent of this nearly perfect linearity is, therefore, 1.2α rad/second centered about $x=0$, while the peak-to-peak separation of the discriminator characteristic is 2.45α rad/second.

Under conditions of two-signal interference, the instantaneous frequency of the amplitude-limited resultant of the two signals is

$$\omega_i(t) = \omega_{ave} - \frac{1}{2} r \frac{1 - a^2}{1 + 2a \cos rt + a^2},$$

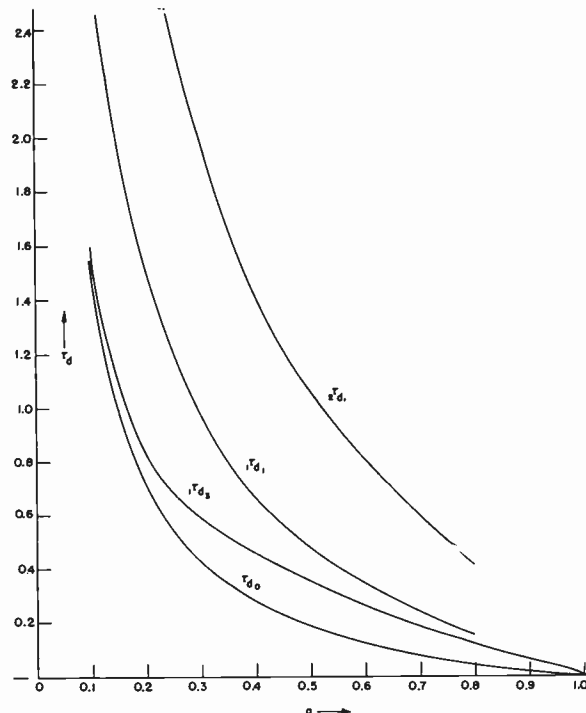


Fig. 10—Curves showing effect of cascading scheme upon the upper bounds on the time constant of Fig. 8, under the conditions of the illustrative example.

where $\omega_{ave} = p + \frac{1}{2}r$, the average of the two signal frequencies. Therefore

$$x(t) = x_{ave} - \frac{r}{2a} \frac{1 - a^2}{1 + 2a \cos rt + a^2}, \quad (12)$$

where $x_{ave} = 1/\alpha(\omega_{ave} - \omega_0)$. When the two signals are symmetrically disposed with respect to the center frequency, $x_{ave} = 0$ and

$$x(t) = - \frac{r}{2a} \frac{1 - a^2}{1 + 2a \cos rt + a^2}. \quad (13)$$

If r is given its maximum value of $(BW)_{if}$, (13) will represent the most troublesome instantaneous-frequency deviations from ω_0 , measured in units of α rad/second.

Theory¹⁰ shows that if

$$\frac{r}{2a} = \beta \frac{1 - a}{1 + a}, \quad (14)$$

then the conditions for quasi-stationary analysis, which justify use of (11), are satisfied if β is bounded by the values plotted in Fig. 11. Substitution in (13) leads to

$$x(t) = \frac{-\beta(1 - a)^2}{1 + 2a \cos rt + a^2}. \quad (15)$$

The upper bound on the RC product can now be found by requiring that the RC combination follow the voltage waveform given by

¹⁰ E. J. Baghdady, "Theory of Low-Distortion Transmission of FM Signals Through Linear Systems," Res. Lab. Electronics, M.I.T., Cambridge, Mass., Tech. Rep. 332; July 30, 1957. (To be published.)

⁹ L. B. Arguimbau, "Discriminator linearity," *Electronics*, vol. 18, pp. 142-144; March, 1945.

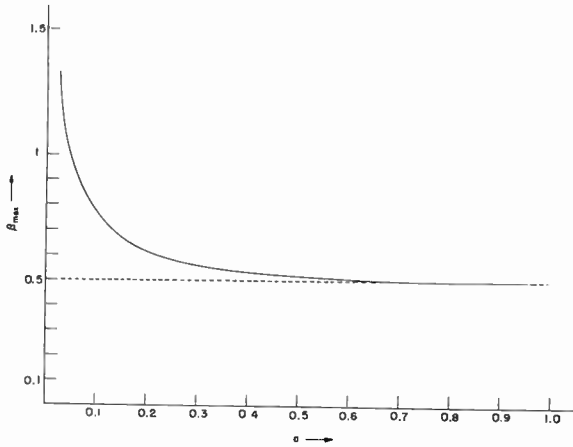


Fig. 11—The upper bounds on the value of β in (14).

$$e(t) = 1 + \{ [x(t) + 1.225]^2 \}^{-1/2} \quad (16)$$

$x(t)$ being given by (15). In Fig. 12 we present the results of a computation in which use was made of the values of $\beta = \beta_{max}$ that are plotted in Fig. 11. For all values of $a \leq 0.84$, the plot of Fig. 12 can be used in conjunction with the plot of Fig. 3 to determine the maximum permissible values of $\tau = W_{if}RC$ when any specified number of narrow-band limiters, each of one IF bandwidth, are cascaded ahead of the discriminator. Multiplication by a scale factor appropriate to the value of W_{if} that is used will convert the dimensionless vertical scale in Fig. 12 into microseconds.

Finally, we would like to emphasize the fact that any interference suppression scheme which is used to mini-

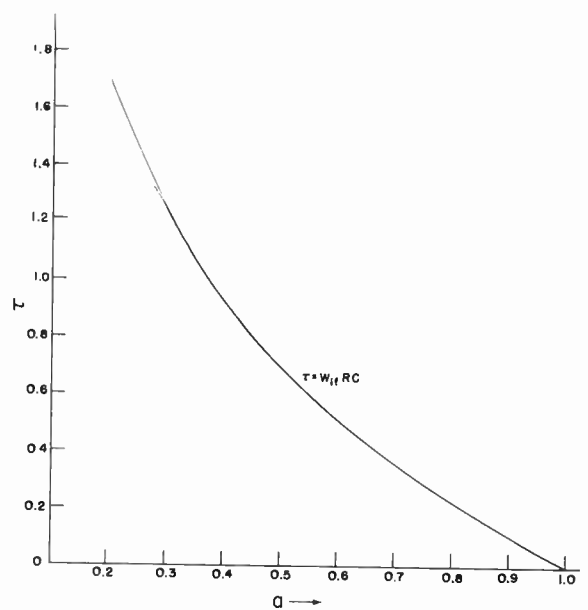


Fig. 12—Maximum permissible values of $\tau = W_{if}RC$ for each half of the balanced discriminator of Fig. 9.

mize the fm disturbance before it reaches the discriminator circuit will, by virtue of its function, alleviate the low-frequency time-constant restrictions on the discriminator circuit. The results of this paper are readily adaptable to the computation of the time-constant requirements when an interference suppressor precedes the discriminator, once the manner in which the interference ratio is decreased by the suppressor has been determined.



A High-Power Periodically Focused Traveling-Wave Tube*

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Summary—The design considerations, construction, and performance of an S-band, pulsed, kilowatt-level traveling-wave tube, focused by means of periodic permanent magnets are described. The tube exhibits saturated power gain in excess of 30 db, with a bandwidth of approximately 2–4 kmc and weighs 17 pounds or less, complete with package.

The results of studies on the electron beam defocusing effect of strong rf fields and on the effect of attenuator design on power build-up and saturation level are reported. Factors affecting the design of a high-power traveling-wave tube using periodic magnetic focusing are described in order to show the design constraints imposed by the periodic focusing system.

INTRODUCTION

A SERIOUS limitation to the extensive use of traveling-wave tubes in electronic systems has been the bulk and weight of the magnetic focusing system required to collimate the electron beam. This is particularly true for high-gain tubes, which frequently are too long to utilize uniform magnets efficiently. In the past few years, the use of periodic permanent magnets¹⁻⁴ for the beam-focusing system has allowed a considerable reduction to be made in the weight and power requirements for traveling-wave tubes. The use of periodic focusing, however, imposes some considerations and design limitations in addition to those for a tube focused with a uniform magnetic field. In many cases these limitations so influence the design as to make it almost imperative to consider the periodic focusing requirements from the outset.

The purpose of this paper is to present the results of work directed toward the design and development of a periodically focused S-band, kilowatt-level traveling-wave tube. Previous periodically focused tubes^{1, 5-7} have made use of electron beams of considerably lower density than required in high-power tubes. As the power

level is increased, in general, the beam current density and perveance is increased correspondingly, resulting in greater difficulty in obtaining the necessary field from existing magnet materials and in the formation and focusing of the beam. The aspects of the focusing problem peculiar to tubes of the kilowatt level or greater will be emphasized in this paper.

In the following sections, the design, construction, and electrical performance of this tube will be described in detail. In addition, the results of studies of the defocusing effect of the strong rf fields in the helix and of the rate of power build-up in the tube, as measured on a special traveling coupler, will be reported.

GENERAL FEATURES AND PERFORMANCE

A photograph of the tube package is shown in Fig. 1, in which a pulsed kilowatt-level traveling-wave tube for operation in immersed flow, as described by Caldwell and Iversen,⁸ is also shown for comparison. The present periodically focused tube represents a complete redesign, which incorporates coupled-helix matches, converging beam gun, external attenuator, and shrunk glass helix to provide compatibility with the periodic permanent-magnet focusing system. In addition, the power output has been increased from 1 to 2 kw in mid-band and the 3-db bandwidth has been extended to the range 2200–4000 mc.

A cross-sectional drawing of the complete tube package is shown in Fig. 2. In order to obtain maximum field amplitude, the magnet outer diameter is greater than the pole piece outer diameter. The pole pieces are aligned by means of nonmagnetic spacers and the couplers and tube are mounted concentrically with the pole piece inner diameter. The collector is connected directly to the case for good thermal conductivity and no additional cooling is required for the collector.

A typical gain-frequency curve for this tube is shown in Fig. 3, exhibiting 30 db or greater (peak power output > one kw) at one watt drive from 2200–4000 mc. The large signal gain curve is quite flat (± 0.5 db from 2500–3500 mc) in spite of operation at a low γa ($\gamma a \approx 1$). The broad-band operation is achieved by optimizing the beam voltage at the upper band edge. Operation very close to saturation also contributes to the flat gain char-

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¹ J. T. Mendel, C. F. Quate, and W. H. Yocom, "Electron beam focusing with periodic permanent magnet fields," *Proc. IRE*, vol. 42, pp. 800–810; May, 1954.

² A. M. Clogston and H. Heffner, "Focusing of an electron beam by periodic fields," *J. Appl. Phys.*, vol. 25, pp. 436–447; April, 1954.

³ K. K. N. Chang, "Beam focusing by periodic and complementary fields," *Proc. IRE*, vol. 43, pp. 62–71; January, 1955.

⁴ G. R. Brewer, "On the focusing of high-current electron beams," *J. Appl. Phys.*, vol. 25, pp. 243–251; February, 1954.

⁵ K. K. N. Chang, "Periodic magnetic field focusing for low-noise traveling-wave tubes," *RCA Rev.*, vol. 16, pp. 423–431; September, 1955.

⁶ W. W. Siekanowicz and F. Sterzer, "A developmental wide-band, 100-watt, 20-db, S-band traveling-wave amplifier utilizing periodic permanent magnets," *Proc. IRE*, vol. 44, pp. 55–61; January, 1956.

⁷ N. Nishio, T. Nemoto, and S. Yasuda, "A package type traveling-wave amplifier for 4000 mc band," *L'Onde Elec.*, vol. 37, pp. 147–152; February, 1957.

⁸ J. J. Caldwell and A. H. Iversen, "The design and performance of a kilowatt traveling-wave amplifier for pulsed operation at 3000 mc/sec," paper presented at the PGED conference, Washington, D. C.; 1955.

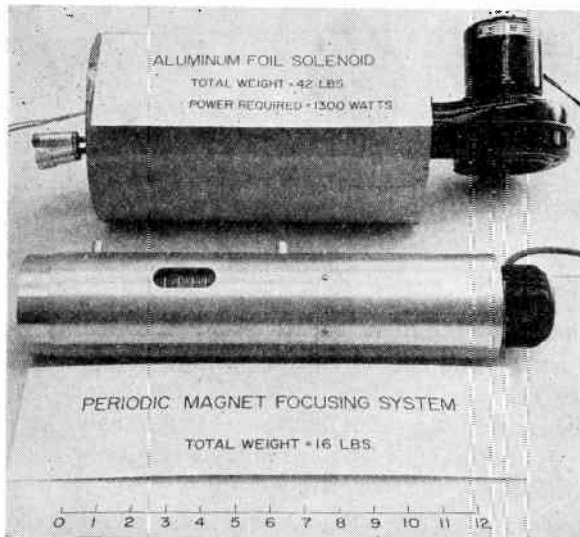


Fig. 1—Comparison of periodic-magnet and immersed-flow focusing systems for a kilowatt-level traveling-wave tube.

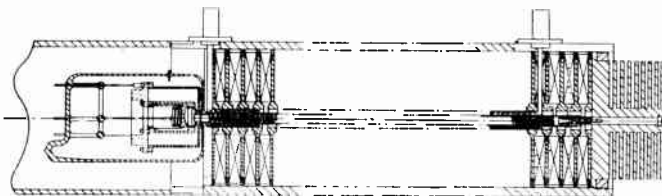


Fig. 2—Cross-sectional drawing of tube and package assembly.

acteristic. By peaking the power output at midband, 2 kw can be obtained over several hundred megacycles. The tube has operated satisfactorily at duty cycle values up to 0.006; typical values are 5- μ sec pulse length, 1000 prf, and the maximum pulse length at which the tube has been operated is 16 μ sec. A tube has been life tested for greater than 500 hours at 0.005 duty cycle without appreciable change in performance. It is believed that this duty cycle limit can be increased by a considerable factor by making use of more effective heat dissipation techniques; and since a tungsten-impregnated "L" cathode is used ($T_k \approx 1100^\circ\text{C}$ Br), the exhaustion of emission material should not occur until after a life of several times 500 hours.

Fig. 4 shows the power output as a function of power input for several frequencies. The saturation gain is 5-7 db down from that in the small signal region. This value, along with the entire shape of the curve, can be altered significantly by using different types of attenuators, as will be shown later.

The variation of power output with beam voltage is shown in Fig. 5 for both small and large signal conditions. It is seen that the optimum beam voltage is approximately 7 kv. This optimum voltage in a periodically focused tube results from a compromise between the beam transmission characteristic of the magnet system and the characteristics of the tube and is therefore more difficult to interpret than in the case of a less

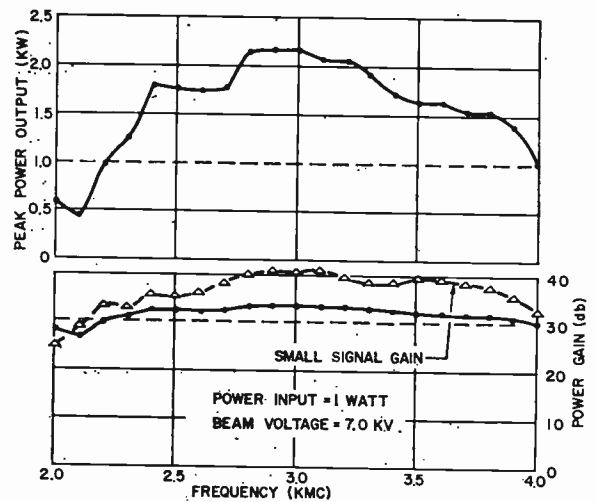


Fig. 3—Variation of power output and gain with one-watt drive power vs frequency. The small signal gain is shown also for comparison. These characteristics can be altered significantly by optimizing the attenuator to emphasize the performance feature (power output, stability, etc.) desired.

voltage-sensitive focusing system such as a uniform magnetic field.

A reproducible efficiency value of 20 per cent has been observed on various experimental tubes, and values as high as 30 per cent with an attenuator optimized for maximum power output. A slight increase in power output has been observed when using a uniform focusing field (from a solenoid), but this increase occurred at elevated beam voltages so that no increase in efficiency resulted. Fig. 6 shows comparative data taken with the same tube in a periodic focusing system and uniform magnetic field. The difference in the curves can be attributed to the different matches used. The gain in the uniform field will be slightly higher at a higher beam voltage.

The tube is short-circuit stable to the extent that no spurious output can be observed at a level 60 db or more down from the normal signal level. Two tubes have been operated in cascade (without intermediate matching or loss device) to give a gain of over 60 db (from one milliwatt to over a kilowatt) with the total weight of both tubes and focusing systems of 34 pounds.

BEAM FORMATION AND FOCUSING

The electron gun is a converging beam type (perveance 2.2×10^{-6}), and was designed according to the method outlined by Brewer.⁹ The role of the gun in successful periodic focusing should not be underestimated. It is the authors' experience that if the beam is not properly formed and injected into the periodic focusing field, no amount of magnetic field adjustment further down the tube will undo the damage. Consequently, a considerable amount of care was spent to assure correct

⁹ G. R. Brewer, "Formation of high density electron beams," *J. Appl. Phys.*, vol. 28, pp. 7-15; January, 1957.

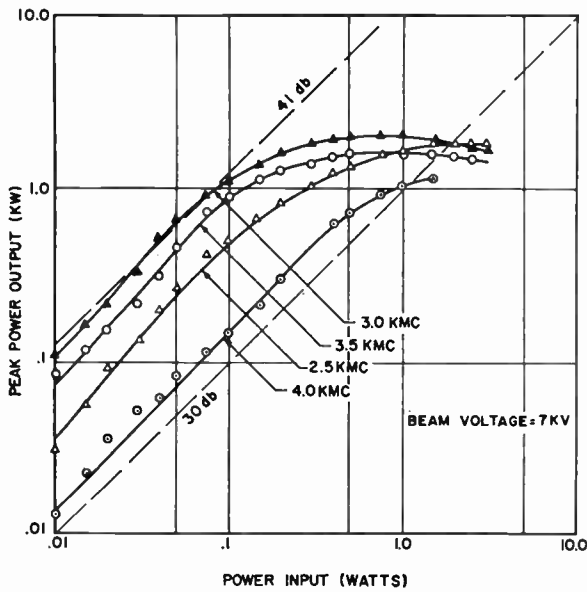


Fig. 4—Power output vs power input characteristics for several frequencies.

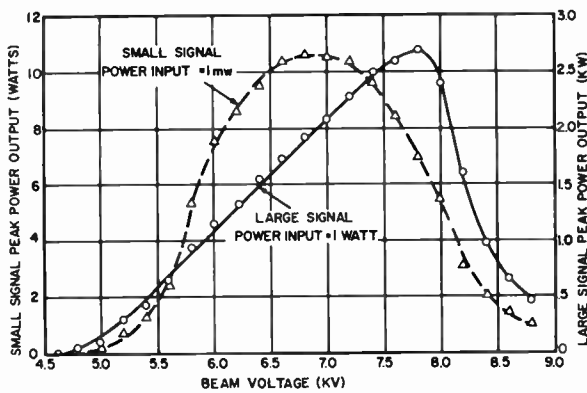


Fig. 5—Variation of output power (or gain) with beam voltage with periodic focusing and under small-signal and large-signal conditions. The equivalent curves observed in a uniform magnetic field were somewhat less peaked, and the small signal curve extended from about 6 to 9.5 kv. The beam transmission characteristic of the periodic system results in the sharp drop-off at higher voltages in these curves.

alignment of the gun parts and to shield the cathode from the stray leakage field (less than 1 per cent of the peak field has been measured at the cathode position). Entrance conditions can be designed by determining an electron trajectory from knowledge of leakage field vs axial length and matching this to the gun focusing characteristic. The use of periodic magnets, arranged with alternate polarity so that the external fields tend to cancel, results in best utilization of the magnetic material and thus corresponding compactness and light weight.

Two important focusing criteria must be satisfied for proper collimation of a periodically focused beam. First, the peak amplitude of the periodic field must be within a narrow range of values centered around that given by (1); second, the period of the field must be adjusted so that operation occurs in a "stable" region of flow.

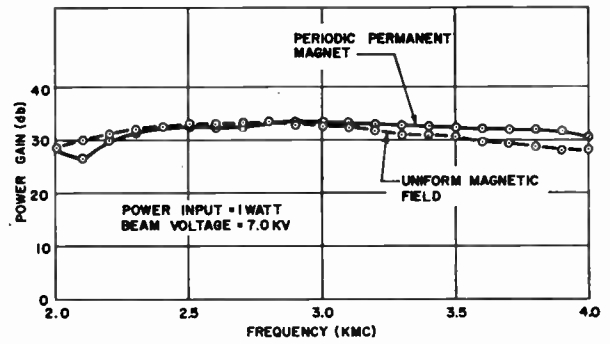


Fig. 6—Comparison of power gain for tube focused in a uniform magnetic field (Brillouin flow) and in a periodic magnetic system. Some of the difference in gain observed is due to different helix couplers used in the two tests. It is seen that the periodic focusing certainly does not degrade the tube performance.

The criterion for the amplitude of the field for minimum beam ripple is¹

$$B_0 = 925 \frac{\sqrt{PV}}{d} \tag{1}$$

where P =beam perveance in micropervs., V =beam voltage in volts, d =beam diameter in inches, and B_0 =peak amplitude of axial magnetic flux density in Gauss. Typical values for the tube are $P=2.2 \times 10^{-6}$ μpervs, $V=7 \times 10^3$ volts, $d=0.100$ inch, giving required $B_0=1150$ Gauss. This equation expresses the condition for balance, on the average, between the outward space-charge and centrifugal forces of the beam and the inward confining force of the magnetic focusing field.

It will be illuminating to express the required field value in terms of the operating parameters of the tube. In a given design the desired power output is usually specified and an estimate of the efficiency can be made so that one can write the tube output power in terms of the beam voltage:

$$P_{out} = \text{eff } V_0 I_0 = \text{eff } V_0^{5/2} P \tag{2}$$

and

$$B_0 \sim \left[\frac{P_{out}}{\text{eff} \times V_0^{5/2} d} \right]^{1/2} \tag{3}$$

It is seen from (3) that the desired field is proportional to the square root of the power output, so that as higher power tubes are required with reasonable beam voltages, the required field strength increases. There is an upper bound to the value B_0 that can be obtained in practice, arising from the maximum value of the coercive force, H_c , available in present-day magnetic materials and by the geometry of the tube and magnetic circuit.

Chang¹⁰ has computed the magnetic field that can be obtained from a set of periodic ring magnets. If we take

¹⁰ K. K. N. Chang, "Optimum design of periodic magnet structures for electron beam focusing," *RCA Rev.*, vol. 16, pp. 65-81; March, 1955.

an approximate form of his result, assuming the shim thickness is small, the peak axial flux density, B_0 , can be written

$$B_0 \approx \frac{2H_m}{I_0\left(\frac{2\pi R_1}{L}\right)} \quad (3a)$$

The notation follows that of Chang. I_0 is the zero-order modified Bessel function of the first kind.

In order to make the demagnetizing force H_m as large as possible, the ratio of magnet-to-gap area is made very large so that the operating value H_m is very nearly equal to H_c , the coercive force. However, one soon reaches a region of diminishing returns by increasing the magnet outer diameter; then one must resort to other means to increase B_0 . With the assumption that $H_m = H_c$, (3) may be written

$$B_0 \approx \frac{2H_c}{I_0\left(2\pi \frac{R_1/d}{L/d}\right)} \quad (4)$$

where R_1 = pole piece inner radius, d = beam diameter, and L = magnet period.

The maximum magnetic field that can be obtained from a given magnet depends on the coercive force of the material and also upon the R_1/L ratio. The pole piece diameter is restricted in most cases by the tube envelope or at least by the beam diameter. The period, L , is limited by the second consideration mentioned above; *i.e.*, by instability regions or "stop bands," expressed by the criterion¹

$$P\left(\frac{L}{d}\right)^2 < 4.36 \times 10^{-4} \quad (5)$$

which is the mathematical expression of the theoretical condition beyond which the periodic magnet system is no longer an effective focusing system. In practice it seems necessary to remain below about 70 per cent of this value. Since there is often only a small range of variation for the ratio L/d , (4) indicates that it is important in most cases to reduce the ratio of pole piece inner diameter to beam diameter, $2R_1/d$, in order to utilize a given size magnet efficiently. This means that one must design the tube either with the pole piece extending through the vacuum envelope or reduce to a minimum value the radial space occupied by those tube parts between the beam and pole piece. For this reason the envelope diameter was reduced from 0.400 for the immersed-flow version to 0.250 for this tube.

The magnetic field had a period of 0.660 inch, with a peak axial value of 1200 Gauss, obtained with 3-inch od Indox magnets. The uniformity of the peaks can be maintained to within ± 2 per cent by using annealed Armco iron pole pieces and selected magnets. It was found that any discontinuity in the initial part of the magnetic circuit, such as slots for couplers, etc., caused considerable decrease (10 to 15 per cent) in beam trans-

mission, so that the input coupler is inserted between the tube envelope and first pole piece. A small-diameter coaxial line is used on the input coupler to decrease the distance from the anode to the first pole piece. A slot in the magnet for the output coupler does not cause any noticeable difficulties. Beam transmission to the collector of more than 90 per cent has been attained.

RF DEFOCUSING

The beam defocusing due to the action of the intense rf electric fields is more serious in a periodically focused than in a uniform-field-focused tube and the 90-per cent beam transmission observed under zero drive conditions may drop to 75 per cent with 2 kw of output power as the beam is defocused to the point of striking the helix. This defocusing can be a serious limitation on the average power capabilities of the tube. There are two reasons for the increased sensitivity of a periodically focused beam to rf fields. First, the periodic field counterbalances the space-charge field only on the average over a period, not at every point along the beam, so that radial rf fields existing in the region of zero magnetic field will have a relatively larger effect; and second, in the process of rf interaction, the axial velocity of some of the electrons is reduced to a value for which the periodic focusing is not longer effective; *i.e.*, to a velocity which corresponds to a stop band for the periodic system.

The dependence of "rf defocusing" on power level is shown in Fig. 7, where the change in helix current expressed as a percentage of the total beam current is plotted as a function of power output for different values of the focusing field period. The increase in helix current can be plotted vs L^2 and is shown in Fig. 8 to be roughly proportional to this quantity. Since the position of the stop band depends on L^2 , this linear dependence would indicate that the presence of the stop band is undoubtedly a large contributor to the defocusing of the beam. For large periods, the defocusing is quite marked but by reducing the period, the helix current can be reduced considerably to compare reasonably well with the uniform field, as shown in Fig. 9. It is possible, as shown by the lower curve, to reduce the defocusing to a very small value by using a large uniform field over the entire circuit. It has also been shown that an increased field in the output region alone will suffice and that the amount of magnetic flux threading the cathode greatly influences the rf defocusing.¹¹

The comparison of the rf defocusing in periodic and uniform fields is complicated by the fact that the power levels along the tube length in the two cases are different for the same applied parameters such as beam voltage, power input, etc. However, the gross behavior is clearly indicated by these curves. The rf defocusing also depends on the beam voltage as shown in Fig. 10. Lower voltage operation at the same power level results in

¹¹ G. R. Brewer and O. T. Purl, "Electron beam defocusing due to high intensity rf fields," paper presented at the Conference on Electron Tube Research, Boulder, Colo.; 1956.

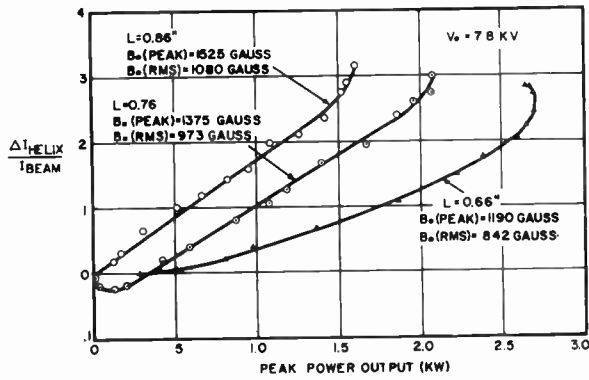


Fig. 7—Dependence of electron beam defocusing due to rf fields on power output for three values of magnet period. It is seen that the “rf defocusing” becomes greater with increase in magnet period. It is also noted that under some conditions the rf fields can focus the beam; this effect has been observed also for certain values of magnetic cathode flux with a uniform field system. (See Brewer and Purl.¹¹)

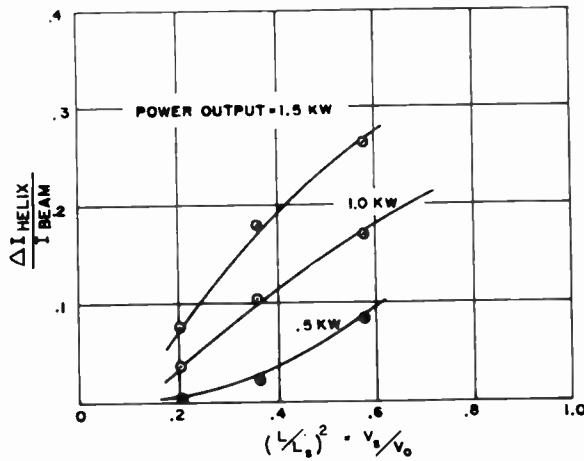


Fig. 8—Dependence of rf defocusing effect on magnet period. The abscissa scale is the square of the magnet period (data from Fig. 7) divided by the stop band period for the magnetic field used; it is also equal to the ratio of the stop band voltage to beam voltage. It is seen that the defocusing effect is roughly proportional to this quantity and that the curves appear to intersect the abscissa around 0.1.

more electrons reaching the stop-band region and becoming defocused to the helix. It is clear from the curves shown that the rf defocusing can be minimized to a great extent by operating with a smaller-period structure and at a higher beam voltage than normal. It may be worth while in certain instances to depart from maximum power output slightly by reducing the period and increasing the beam voltage in order to increase materially the possible duty cycle.

Although it is in general undesirable to collect a large percentage of the beam on the helix, the response of the beam focusing to rf fields can be utilized to provide a sensitive microwave detector tube.¹² If small duty cycle operation is permissible, the rf defocusing can be maximized and the rectified helix current will provide the detected signal. The magnitude of this effect is shown by a

¹² J. T. Mendel, “Microwave detector,” PROC. IRE, vol. 44, pp. 503-508; April, 1956.

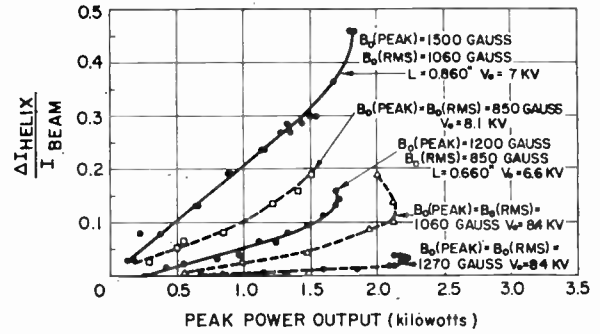


Fig. 9—Dependence of electron beam defocusing due to rf fields on power output for two values of magnet period and three values of uniform field strength. The beam voltages were adjusted for maximum power output in each case. Although the beam voltage variation slightly obscures the comparison, it is seen that periodic magnetic focusing results in considerably greater rf defocusing than use of a uniform magnetic field.

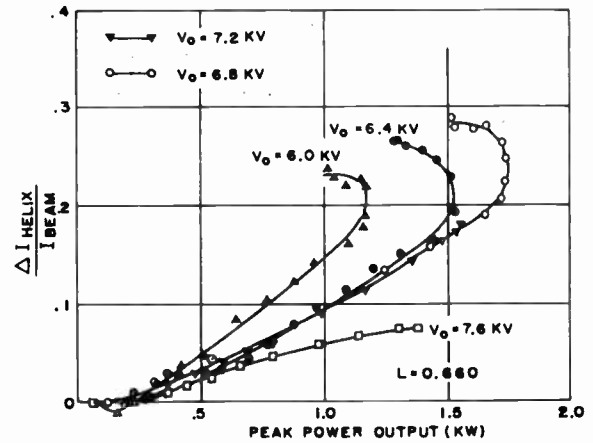


Fig. 10—Dependence of electron beam defocusing due to rf fields on power output for various values of beam voltage. As the beam voltage is reduced, the ratio V_s/V_0 becomes greater, resulting in larger rf defocusing, as shown in Fig. 8.

curve of helix current as a function of power input (Fig. 11). It is noted that the characteristic is relatively linear over a range of values of input power greater than ten to one.

COMPONENTS

The principal mechanical features of the tube are shown in Fig. 12, which is an exploded view of the tube, matches, and attenuator.

The match for a 50-Ω coax line to the slow-wave circuit is accomplished by using coupled helix transducers. No vacuum seal is required, and the outer helix unit can be made to occupy less than 0.050 inch of radial space. The vswr can be held to less than 2 to 1 over the 2-4 kmc band, and the insertion loss per coupler is less than 1 db at midband. The outer helix is moulded in Teflon for rigidity, and the perpendicular entry has been used for the coax connection. A termination is applied to both ends of the inner helix, but none is necessary on the outer helix. The helix structure is mounted in a precision-ground glass tube which is shrunk around the helix under vacuum to increase the heat dissipating

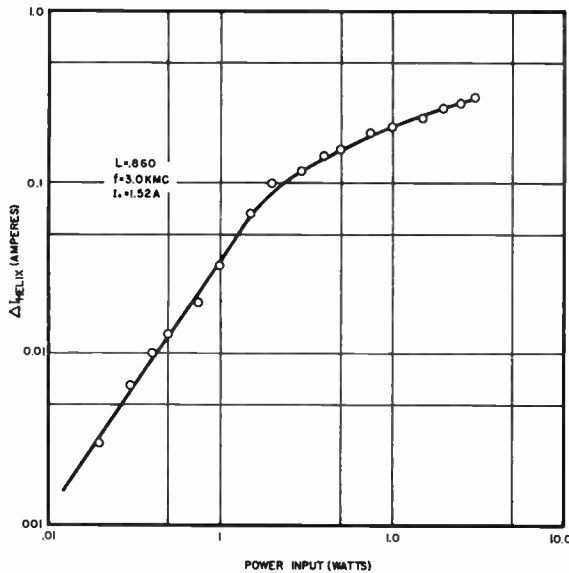


Fig. 11—Change in helix current due to rf defocusing vs input power. It is noted that the characteristic is linear up to $I_h = 0.10$ ampere so that when used as a detector, an output voltage linear up to 5 volts could be obtained with a 50- Ω load.

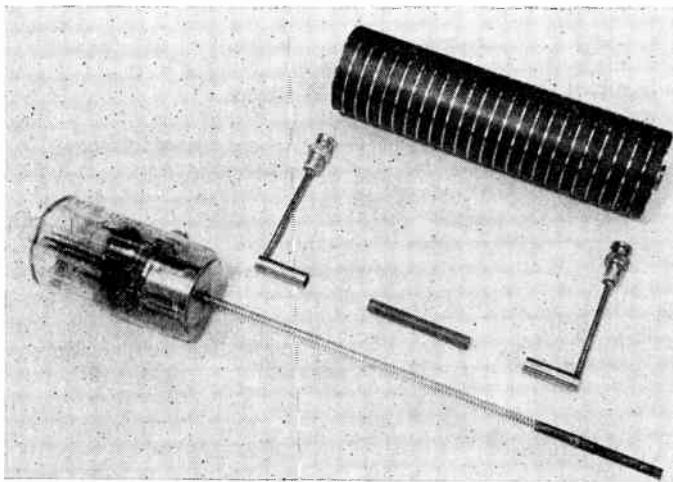


Fig. 12—Photograph of tube, coupled-helix matches, coupled-helix attenuator, and periodic-magnet stack.

quality of the circuit. Such a structure can dissipate about 9 watts per inch safely without forced air cooling. The amount of dielectric loading ($DLF = 0.8$) was measured by probing the field with a moving single-turn coil mounted on a carriage. The increase in loading after shrinking was found to be of the order of 2 per cent.

Several types of attenuators have been tested; e.g., lossy wall attenuators of Aquadag, lossy ceramic, Teledeltos paper, and other lossy plastic materials, and coupled helix attenuators with distributed loss. The cold transmission loss as a function of frequency is shown in Fig. 13 for both types. The Teledeltos paper is molded in a layer of Teflon to keep it moisture free. The 400°C temperature, required to cure the Teflon, does not deteriorate the lossy paper. This type of attenuator has been found to be more consistent from tube to tube than spraying or painting Aquadag or other commer-

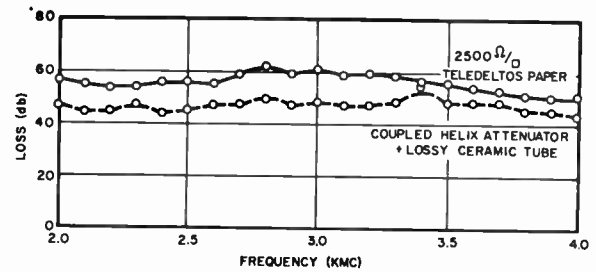


Fig. 13—Loss obtained with Teledeltos paper attenuator as compared to that with a coupled-helix plus lossy-ceramic attenuator.

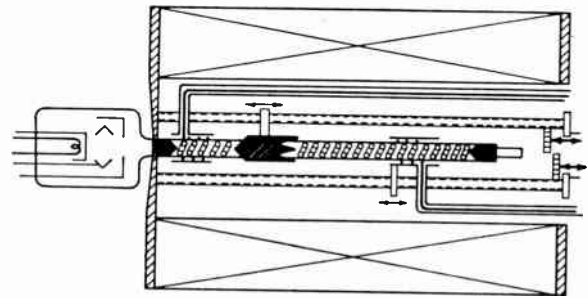


Fig. 14—Schematic drawing of movable coupler device. The input coupled-helix match is fixed in position and the attenuator and output coupled-helix match are movable independently or ganged together. The tube was operated in a uniform magnetic field for these tests.

cially available lossy materials and is capable of dissipating 12 watts of average power without any apparent damage.

A coupled helix attenuator has also been developed for this tube, consisting of a quadrifilar Kanthal wire helix moulded in Teflon in conjunction with a carbon impregnated ceramic tubing to provide additional loss. The saturation power output has consistently been 2–3 db lower than that with the lossy wall variety.¹³

The lossy wall attenuator has three sections—a slightly tapered input, a constant resistance center section, and a long tapered output section.

It was desirable for the tube to be short-circuit stable. For a high gain tube this imposes a stringent condition ($vswr \approx 1.04$) on the match looking into the attenuator from the output. A gradual taper of the lossy material in this transition region is therefore essential and this gradual transition also apparently improves the "saturation characteristic."¹⁴

A program is under way to incorporate a grid in the gun which would decrease greatly the size of modulator required for the tube.

MOVABLE COUPLER DEVICE

In order to study further the effect of the attenuator on the tube behavior, a device was built using coupled helix matches, which allows movement of both the at-

¹³ N. Rynn, "Analysis of coupled structure traveling-wave tubes," IRE TRANS., vol. ED-4, pp. 172–177; April, 1957.

¹⁴ J. J. Caldwell, "High-power traveling-wave tube gain and saturation characteristics as a function of attenuator configuration and resistivity," IRE TRANS., vol. ED-4, pp. 28–32; December, 1953.

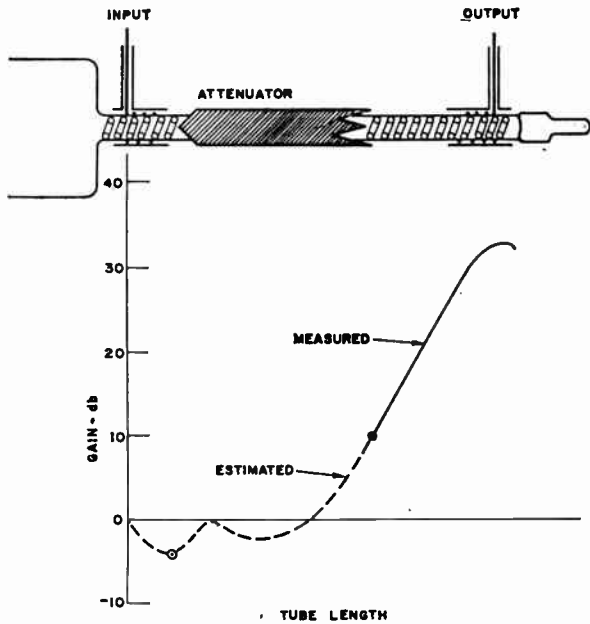


Fig. 15—Illustration of the power build-up along the tube, as determined from movable coupler measurements. The dotted parts of the curve are estimated and are therefore less accurate.

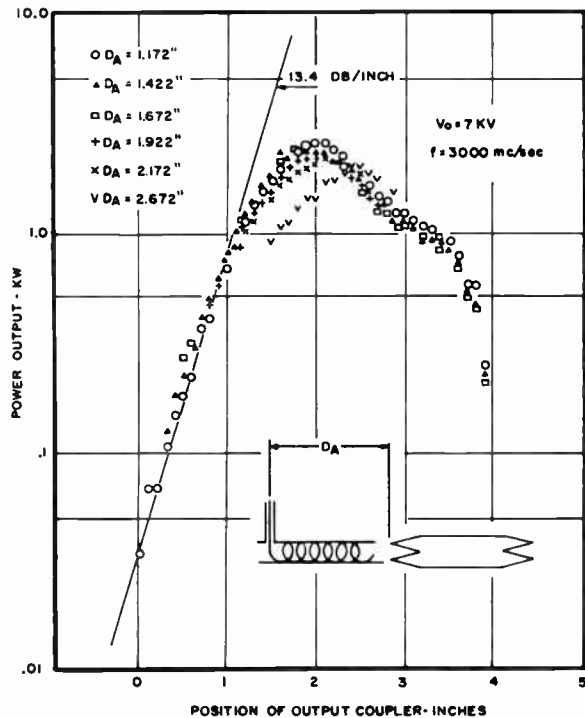


Fig. 16—Tube power output vs axial position of the output coupler for various positions of the attenuator. The zero coupler position was located at the extreme output end of the attenuator when the input end of the attenuator was $D_A = 1.172$ inches from the center line of the input coaxial line. It is seen that the power build-up after the attenuator was almost independent of attenuator position and the saturation level was highest for the attenuator in the closest position to the input.

attenuator and output match during tube operation. In contrast to probing the field, this device actually changes the electrical length of the tube during operation. A uniform field was used for focusing in these tests

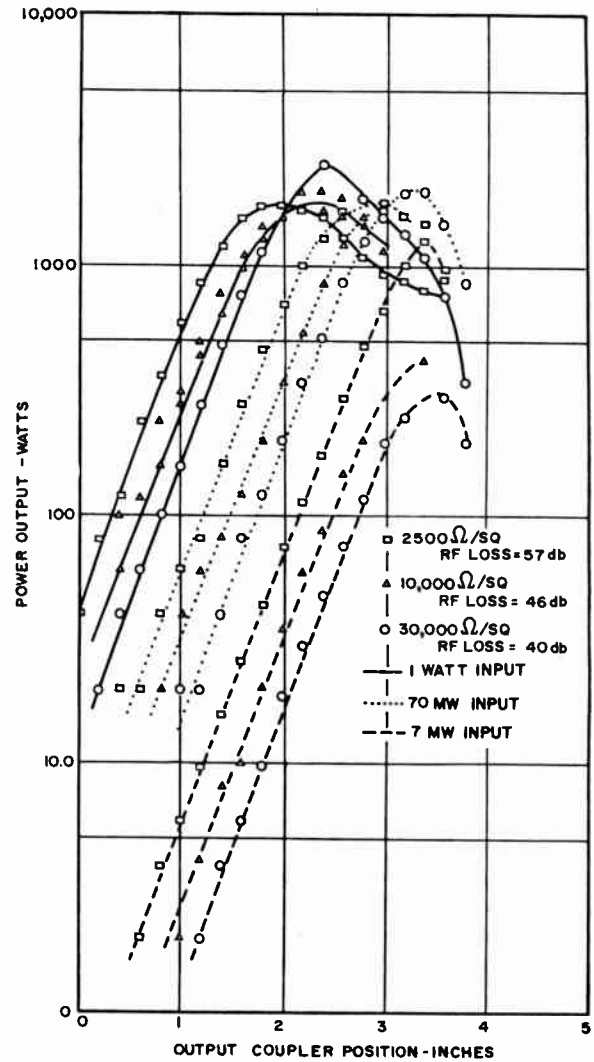


Fig. 17—Tube power output vs axial position of the output coupler for several values of attenuator resistivity and drive power levels. The attenuator was made of Teledeltos paper. $D_A = 1.172$ inches.

and the following results were observed. A schematic diagram of the apparatus is shown in Fig. 14 and an illustration of the power build-up vs position along the helix is shown in Fig. 15, as determined from these measurements. First, the position of the attenuator is not critical, as shown by the curves of Fig. 16, but for best performance should be located close to the input. The length of the input coupler is equal to $0.22 CN$, which is close to the optimum Pierce value.¹⁵ Second, the change in power build-up as a function of the Ω /square surface resistivity of the attenuator is shown in Fig. 17. Note that although the saturated output is higher with the higher Ω /square attenuator, a longer tube length is required to reach saturation.

The rate of power build-up can be measured rather accurately in the lossless region and is noted to be $5.6 \text{ db}/\lambda_g$. From a knowledge of b and c , x_1 can be computed using this experimentally obtained value of gain per

¹⁵ J. R. Pierce, "Traveling-Wave Tubes," D. Van Nostrand Co., Inc., New York, N. Y., p. 140; 1950.

wavelength. The resulting value obtained using $C=0.145$ and $b=1.0$, $N=11.9$ is $x_1=0.805$. The value of x_1 obtained by small-signal theory¹⁶ using the above values and $QC=0.2$ gives $x_1=0.79$ to 0.80 , which is within the accuracy of the curves used. The gain profile along the tube length, shown in Fig. 15, is based on the best data available from this device.

The values of the parameters $C=0.145$, $QC=0.2$, and $\gamma r_0=0.56$ are quite close to those measured by Cutler¹⁷ to yield the optimum efficiency; from his work efficiencies of 30 per cent and greater can be expected. Efficiencies of 30 per cent have been observed, but it has been found difficult to optimize the attenuator design to achieve both maximum efficiency and maximum stability (*i.e.*, short-circuit stability).

By adjusting the attenuator it is possible to optimize the tube design to meet a variety of requirements involving the gain, power output, stability, and duty cycle. For example, if the tube is not required to operate into a bad mismatch, the attenuation can be reduced with a corresponding increase in power output and efficiency. Conversely, if a lower power and efficiency can be tolerated, the gain can be made flatter over a wider band by designing the attenuator to cause premature saturation of the tube in the midband region.

¹⁶ C. K. Birdsall and G. R. Brewer, "Traveling-wave tube characteristics for finite values of C ," IRE TRANS., vol. ED-1, pp. 1-11; August, 1954. These computations in turn were based on the small-signal theory of Pierce, *op. cit.*

¹⁷ C. C. Cutler, "The nature of power saturation in traveling-wave tubes," *Bell Sys. Tech. J.*, vol. 35, pp. 841-876; July, 1956.

CONCLUSION

It has been shown that a relatively high-power electron beam for use in a broad-band (essentially 2:1) traveling-wave tube can be periodically focused. Such periodic focusing does not degrade the performance of the tube but in fact can result in a tube with more diversified operating characteristics. A total of about 25 of these tubes have been built and tested, with good reproducibility of the operating characteristics. RF defocusing becomes an important factor to consider in high-power periodically focused tubes, but the effect can be reduced by proper attention to the period of the magnetic circuit and the operating voltage.

The attenuator position is not critical, but should be located near the input of the tube for maximum saturated power output. The Ω /square value used in a lossy wall attenuator can markedly affect the saturation output, and values near 2500 Ω /square seem reasonably good. A wide variety of tube requirements can be met by changing the periodic magnet circuit, the attenuator configuration, or both. It is apparent that further extensions of periodic focusing into regions of higher power will come about by either incorporating part of the magnetic circuit inside the vacuum envelope or by obtaining magnetic materials of higher coercive force.

ACKNOWLEDGMENT

The assistance of T. Gorman, W. Perkins, T. Leonard, L. Toy, and B. Kesterson in the assembling and processing of these tubes is gratefully acknowledged.



Index to IRE Standards on Definitions of Terms 1942-1957*

(58 IRE 20.S1)

INTRODUCTION

This index covers all Standards on Definitions of Terms issued by the IRE from 1942 through July, 1957, that are still in force. It brings together in one alphabetical list approximately 3500 technical terms defined in those Standards, indicating the IRE code number of the Standard and the issue and page number of the PROCEEDINGS OF THE IRE where the definition may be found. Standards issued prior to 1949, which were published as separate reports instead of in the PROCEEDINGS, are identified by the word "separate" in the index.

In some instances the same term has been defined in more than one Standard. If the Standards are in the

same field, only the last published definition is referenced in the index; if they are in different fields, all definitions are referenced.

A list of the Standards covered in the index and their IRE code numbers is given below. Reprints may be ordered at the indicated prices from IRE headquarters. Reprints of this index are also available as indicated in the footnote below.*

The IRE is greatly indebted to Chester H. Page, Vice-Chairman and Definitions Coordinator of the Standards Committee, for the substantial task of compiling this index.

STANDARDS COVERED BY INDEX

<i>Standard No.</i>	<i>Title and Where Published</i>	<i>Reprint Price</i>	<i>Standard No.</i>	<i>Title and Where Published</i>	<i>Reprint Price</i>
48 IRE 2, 11, 15.S1	Standards on Antennas, Modulation Systems, and Transmitters: Definitions of Terms, 1948 (Separate Report)	\$0.75	42 IRE 9.S1	Standards on Facsimile: Definitions of Terms, 1942 (Separate Report)	†
53 IRE 2.S1	Standards on Antennas and Waveguides: Definitions of Terms, 1953 (December, 1953, Proc. IRE)	\$0.75	56 IRE 9.S1	Standards on Facsimile: Definitions of Terms, 1956 (June, 1956, Proc. IRE)	\$0.60
55 IRE 2.S1	Standards on Antennas and Waveguides: Definitions for Waveguide Components, 1955 (September, 1953, Proc. IRE)	\$0.25	55 IRE 10.S1	Standards on Industrial Electronics: Definitions of Industrial Electronics Terms, 1955 (September, 1955, Proc. IRE)	\$0.50
54 IRE 3.S1	Standards on Audio Techniques: Definitions of Terms, 1954 (July, 1954, Proc. IRE)	\$0.50	53 IRE 11.S1	Standards on Modulation Systems: Definitions of Terms, 1953 (May, 1953, Proc. IRE)	\$0.50
50 IRE 4.S1	Standards on Circuits: Definitions of Terms in Network Topology, 1950 (January, 1951, Proc. IRE)	\$0.50	54 IRE 12.S1	Standards on Radio Aids to Navigation: Definitions of Terms, 1954 (February, 1955, Proc. IRE)	\$1.00
53 IRE 4.S1	Standards on Circuits: Definitions of Terms in the Field of Linear Varying Parameter and Nonlinear Circuits, 1953 (March, 1954, Proc. IRE)	\$0.25	52 IRE 17.S1	Standards on Receivers: Definitions of Terms, 1952 (December, 1952, Proc. IRE)	\$0.60
51 IRE 6.S1	Standards on Electroacoustics: Definitions of Terms, 1951 (May, 1951, Proc. IRE)	\$1.00	51 IRE 20.S1	Standards on Pulses: Definitions of Terms —Part I, 1951 (June, 1951, Proc. IRE)	\$0.50
50 IRE 7.S1	Standards on Electron Tubes: Definitions of Terms, 1950 (April, 1950, Proc. IRE)	†	51 IRE 20.S2	Standards on Transducers: Definitions of Terms, 1951 (August, 1951, Proc. IRE)	\$0.50
54 IRE 7.S1	Standards on Electron Devices: Definitions of Terms Related to Phototubes, 1954 (August, 1954, Proc. IRE)	\$0.25	52 IRE 20.S1	Standards on Pulses: Definitions of Terms —Part II, 1952 (May, 1952, Proc. IRE)	\$0.50
54 IRE 7.S2	Standards on Electron Devices: Definitions of Semiconductor Terms, 1954 (October, 1954, Proc. IRE)	\$0.50	55 IRE 22.S1	Standards on Television: Definitions of Color Terms, 1955 (June, 1955, Proc. IRE)	\$0.60
56 IRE 7.S3	Standards on Electron Tubes: TR and ATR Tube Definitions, 1956 (August, 1956, Proc. IRE)	\$0.50	55 IRE 23.S1	Standards on Television: Definitions of Television Signal Measurement Terms, 1955 (May, 1955, Proc. IRE)	\$1.00
57 IRE 7.S2	Standards on Electron Tubes: Definitions of Terms, 1957 (July, 1957, Proc. IRE)	\$1.00	45 IRE 24.S1	Standards on Radio Wave Propagation: Definitions of Terms Relating to Guided Waves, 1945 (Separate Report)	\$0.20
50 IRE 8.S1	Standards on Electronic Computers: Definitions of Terms, 1950 (March, 1951, Proc. IRE)	†	50 IRE 24.S1	Standards on Wave Propagation: Definitions of Terms, 1950 (November, 1950, Proc. IRE)	\$0.60
56 IRE 8.S1	Standards on Electronic Computers: Definitions of Terms, 1956 (September, 1956, Proc. IRE)	\$0.60	55 IRE 26.S2	Standards on Terminology for Feedback Control Systems, 1955 (January, 1956, Proc. IRE)	\$0.50

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A	Standard	PROCEEDINGS		Standard	PROCEEDINGS	
		Vol	Page Mo		Vol	Page Mo
				Air Speed	54 IRE 12.S1	43 192 Feb
A and R Display	54 IRE 12.S1	43	192 Feb	Airborne Radar	49 IRE 12.S1	37 1366 Dec
Absolute Delay	54 IRE 12.S1	43	192 Feb	Airport Surveillance Radar	54 IRE 12.S1	43 192 Feb
Absorption	50 IRE 24.S1	38	1265 Nov	Alford Loop	54 IRE 12.S1	43 192 Feb
Absorption Loss	51 IRE 6.S1	39	510 May	Algebraic Adder	50 IRE 8.S1	39 272 Mar
Absorption Modulation	48 IRE 2,11,15.S1	Separate		Alternator Transmitter	48 IRE 2,11,15.S1	Separate
Accelerating Electrode	57 IRE 7.S2	45	986 Jul	Altimetric Flare-Out	54 IRE 12.S1	43 192 Feb
Acceleration	51 IRE 6.S1	39	510 May	Altitude	49 IRE 12.S1	37 1367 Dec
Access Time	56 IRE 8.S1	44	1167 Sep	AM to FS Converter	56 IRE 9.S1	44 776 Jne
Accessible Terminal	50 IRE 4.S1	39	27 Jan	Ambient Temperature	48 IRE 2,11,15.S1	Separate
Acceptor	54 IRE 7.S2	42	1506 Oct	Ambiguity	54 IRE 12.S1	43 192 Feb
Accumulator	56 IRE 8.S1	44	1167 Sep	Amplification	54 IRE 3.S1	42 1110 Jul
Accuracy	56 IRE 8.S1	44	1167 Sep	Amplification Factor	57 IRE 7.S2	45 986 Jul
AC Erasing Head	51 IRE 6.S1	39	510 May	Amplifier	57 IRE 7.S2	45 986 Jul
AC Magnetic Biasing	51 IRE 6.S1	39	510 May	Amplifier	48 IRE 2,11,15.S1	Separate
Acetate Disks	51 IRE 6.S1	39	510 May	Amplifier Torque	50 IRE 8.S1	39 272 Mar
Achromatic Locus	55 IRE 22.S1	43	742 Jne	Amplitude Balance Control	54 IRE 12.S1	43 192 Feb
Acoustic	51 IRE 6.S1	39	510 May	Amplitude Discriminator	54 IRE 12.S1	43 192 Feb
Acoustic Compliance	51 IRE 6.S1	39	510 May	Amplitude Distortion	53 IRE 4.S1	42 554 Mar
Acoustic Dispersion	51 IRE 6.S1	39	510 May	Amplitude Distortion (old usage)	48 IRE 2,11,15.S1	Separate
Acoustic Generator	51 IRE 6.S1	39	510 May	Amplitude-Frequency Distortion	53 IRE 4.S1	42 554 Mar
Acoustic Horn	51 IRE 6.S1	39	510 May	Amplitude vs Frequency Response		
Acoustic Impedance	51 IRE 6.S1	39	510 May	Characteristic	48 IRE 2,11,15.S1	Separate
Acoustic Interferometer	51 IRE 6.S1	39	510 May	Amplitude-Modulated Transmitter	48 IRE 2,11,15.S2	Separate
Acoustic Mass	51 IRE 6.S1	39	510 May	Amplitude-Modulated Noise Level	48 IRE 2,11,15.S1	Separate
Acoustic Pickup	51 IRE 6.S1	39	510 May	Amplitude Modulation	53 IRE 11.S1	41 612 May
Acoustic Radiating Element	51 IRE 6.S1	39	510 May	Amplitude Modulation	52 IRE 17.S1	40 1682 Dec
Acoustic Radiometer	51 IRE 6.S1	39	510 May	Amplitude Response (Camera		
Acoustic Reactance	51 IRE 6.S1	39	510 May	Tubes)	57 IRE 7.S2	45 986 Jul
Acoustic Refraction	51 IRE 6.S1	39	510 May	Amplitude Response Characteristic	57 IRE 7.S2	45 986 Jul
Acoustic Resistance	51 IRE 6.S1	39	510 May	A-N Radio Range	54 IRE 12.S1	43 207 Feb
Acoustic Scattering	51 IRE 6.S1	39	510 May	Analog	56 IRE 8.S1	44 1167 Sep
Acoustic Stiffness	51 IRE 6.S1	39	510 May	Analog Computer	56 IRE 8.S1	44 1167 Sep
Acoustic Transmission System	51 IRE 6.S1	39	511 May	And-Circuit	56 IRE 8.S1	44 1167 Sep
Acoustical	51 IRE 6.S1	39	511 May	And-Gate	56 IRE 8.S1	44 1167 Sep
Acoustical Ohm	51 IRE 6.S1	39	511 May	Angle	57 IRE 7.S2	45 986 Sep
Acoustical Reciprocity Theorem	51 IRE 6.S1	39	511 May	Angle, Maximum-Deflection	57 IRE 7.S2	45 986 Jul
Acoustical Units	51 IRE 6.S1	39	511 May	Angle Modulation	53 IRE 11.S1	41 612 May
Acoustics	51 IRE 6.S1	39	511 May	Angle of Elevation	49 IRE 12.S1	37 1367 Dec
Active Transducer	51 IRE 20.S2	39	898 Aug	Angle or Phase of a Sine Wave	53 IRE 11.S1	41 612 May
Active Transducer (Audio)	54 IRE 3.S1	42	1110 Jul	Angular Deviation Loss	51 IRE 6.S1	39 511 May
Actuating Transfer Function	55 IRE 26.S2	44	108 Jan	Angular Deviation Sensitivity	54 IRE 12.S1	43 192 Feb
ADF	54 IRE 12.S1	43	192 Feb	Angular Frequency	50 IRE 24.S1	38 1265 Nov
A-Display	54 IRE 12.S1	43	192 Feb	Angular Resolution	54 IRE 12.S1	43 192 Feb
Adcock Antenna	48 IRE 2,11,15.S1	Separate		Angular Width	54 IRE 12.S1	43 193 Feb
Adder	56 IRE 8.S1	44	1167 Sep	Anode (Electron Tubes)	57 IRE 7.S2	45 986 Jul
Adder, Algebraic	50 IRE 8.S1	39	272 Mar	Anode Breakdown Voltage	57 IRE 7.S2	45 986 Jul
Address	56 IRE 8.S1	44	1167 Sep	Anode Current	57 IRE 7.S2	45 986 Jul
Address Part	56 IRE 8.S1	44	1167 Sep	Anode Strap (Magnetrons)	57 IRE 7.S2	45 986 Jul
Adjacent-Channel Attenuation	52 IRE 17.S1	40	1682 Dec	Anode Voltage	57 IRE 7.S2	45 986 Jul
Adjacent-Channel Interference	52 IRE 17.S1	40	1682 Dec	Anode Voltage Drop	57 IRE 7.S2	45 986 Jul
Admittance	57 IRE 7.S2	45	986 Jul	Antenna	52 IRE 17.S1	40 1682 Dec
Advance Ball	51 IRE 6.S1	39	511 May	Antenna Array	48 IRE 2,11,15.S1	Separate
Aeolight	51 IRE 6.S1	39	511 May	Antenna Cross Talk	48 IRE 2,11,15.S1	Separate
Aerophare	54 IRE 12.S1	43	192 Feb	Antenna Effect	54 IRE 12.S1	43 193 Feb
AI Radar	54 IRE 12.S1	43	192 Feb	Antenna Resistance	48 IRE 2,11,15.S1	Separate
Aided Tracking	54 IRE 12.S1	43	192 Feb	Anti-Clutter Circuits	54 IRE 12.S1	43 193 Feb
Air Conduction	51 IRE 6.S1	39	511 May	Anti-TR Switch	54 IRE 12.S1	43 193 Feb
Airport Surface Detection Equip-				Antinoise Microphone	51 IRE 6.S1	39 511 May
ment (ASDE)	54 IRE 12.S1	43	209 Feb	Aperture	48 IRE 2,11,15.S1	Separate
Air-Position Indicator (API)	54 IRE 12.S1	43	207 Feb	Aperture Illumination	48 IRE 2,11,15.S1	Separate
				Applicator (Electrodes)	55 IRE 10.S1	43 1070 Sep
				Applicator Impedance	55 IRE 10.S1	43 1070 Sep

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Cathode Modulation	48 IRE 2,11,15.S1	Separate	Class-AB Amplifier	57 IRE 7.S2	45 988 Jul
Cathode Preheating Time	57 IRE 7.S2	45 988 Jul	Class-A Modulator	48 IRE 2,11,15.S1	Separate
Cathode Pulse Modulation	48 IRE 2,11,15.S1	Separate	Class-A Push-Pull Sound Track	51 IRE 6.S1	39 513 May
Cathode-Ray Tube	57 IRE 7.S2	45 988 Jul	Class-B Amplifier	57 IRE 7.S2	45 988 Jul
			Class-B Modulator	48 IRE 2,11,15.S1	Separate
Cathode Spot	57 IRE 7.S2	45 988 Jul	Class-B Push-Pull Sound Track	51 IRE 6.S1	39 514 May
Cavitation	51 IRE 6.S1	39 513 May	Class-C Amplifier	57 IRE 7.S2	45 989 Jul
Cavity Resonator	55 IRE 2.S1	43 1073 Sep	Clear	56 IRE 8.S1	44 1168 Sep
Cavity Resonator Frequency Meter	55 IRE 2.S1	43 1073 Sep	Clearance	54 IRE 12.S1	43 194 Feb
Cell (in Computers)	56 IRE 8.S1	44 1168 Sep	Clipper	48 IRE 2,11,15.S1	Separate
Cell, Binary	50 IRE 8.S1	39 272 Mar	Clipper Limiter	48 IRE 2,11,15.S1	Separate
Cell-Type Tube	57 IRE 7.S2	45 988 Jul	Clock	56 IRE 8.S1	44 1168 Sep
Cent (in Acoustics)	51 IRE 6.S1	39 513 May	Close-Tailing Microphone	51 IRE 6.S1	39 514 May
Center Frequency	48 IRE 2,11,15.S1	Separate	Cloud Pulse	57 IRE 7.S2	45 989 Jul
Center Line	54 IRE 12.S1	43 194 Feb	Clutter	54 IRE 12.S1	43 194 Feb
Chain	54 IRE 12.S1	43 194 Feb	Coarse Chrominance Primary	55 IRE 22.S1	43 744 Jne
Challenge	54 IRE 12.S1	43 194 Feb	Coaxial Antenna	48 IRE 2,11,15.S1	Separate
Challenger	54 IRE 12.S1	43 194 Feb	Coaxial Transmission Line	53 IRE 2.S1	41 1723 Dec
Channel (in Computers)	56 IRE 8.S1	44 1168 Sep	Co-Channel Interference	52 IRE 17.S1	40 1682 Dec
Channel, Melting	55 IRE 10.S1	43 1070 Sep	Code (in Computers)	56 IRE 8.S1	44 1168 Sep
Channel, Radio	52 IRE 17.S1	40 1682 Dec	Code Distinguishability	54 IRE 12.S1	43 194 Feb
Channeling	42 IRE 9.S1	Separate	Code, Instruction	50 IRE 8.S1	39 272 Mar
Character (in Computers)	56 IRE 8.S1	44 1168 Sep	Coded Program	50 IRE 8.S1	39 272 Mar
Characteristic	57 IRE 7.S2	45 988 Jul	Coder	49 IRE 12.S1	37 1367 Dec
Characteristic Impedance	53 IRE 2.S1	41 1722 Dec	Coder, Pulse-Duration	54 IRE 12.S1	43 194 Feb
Characteristic Telegraph Distortion	48 IRE 2,11,15.S1	Separate	Coding Delay	54 IRE 12.S1	43 194 Feb
Characteristic Wave Impedance	53 IRE 2.S1	41 1723 Dec	Cohered Video	54 IRE 12.S1	43 194 Feb
Charge (Induction Heating)	55 IRE 10.S1	43 1070 Sep	Cohherent Oscillator	54 IRE 12.S1	43 194 Feb
Charge-Storage Tube	57 IRE 7.S2	45 988 Jul	Cohherent System	54 IRE 12.S1	43 194 Feb
Chart-Comparison Unit	54 IRE 12.S1	43 194 Feb	COHO	54 IRE 12.S1	43 194 Feb
Check	56 IRE 8.S1	44 1168 Sep	Cold Cathode	57 IRE 7.S2	45 989 Jul
Check, Automatic	56 IRE 8.S1	44 1168 Sep	Cold-Cathode Tube	57 IRE 7.S2	45 989 Jul
Check Digits	56 IRE 8.S1	44 1168 Sep	Collector	57 IRE 7.S2	45 989 Jul
Check, Forbidden-Combination	56 IRE 8.S1	44 1168 Sep	Color	55 IRE 22.S1	43 744 Jne
Check Point	54 IRE 12.S1	43 194 Feb	Color Breakup	55 IRE 22.S1	43 744 Jne
Check Problem	56 IRE 8.S1	44 1168 Sep	Color Burst	55 IRE 22.S1	43 744 Jne
Check, Programmed	56 IRE 8.S1	44 1168 Sep	Color Carrier	55 IRE 22.S1	43 744 Jne
Check Routine	56 IRE 8.S1	44 1168 Sep	Color Cell	57 IRE 7.S2	45 989 Jul
Check, Selection	56 IRE 8.S1	44 1168 Sep	Color Center	57 IRE 7.S2	45 989 Jul
Check, Transfer	56 IRE 8.S1	44 1168 Sep	Color Coder	55 IRE 22.S1	43 744 Jne
Cheese Antenna	48 IRE 2,11,15.S1	Separate	Color Contamination	55 IRE 22.S1	43 744 Jne
Chip	51 IRE 6.S1	39 513 May	Color Co-ordinate Transformation	55 IRE 22.S1	43 744 Jne
Choke Joint	55 IRE 2.S1	43 1074 Sep	Color Decoder	55 IRE 22.S1	43 744 Jne
Chroma	55 IRE 22.S1	43 743 Jne	Color-Difference Signal	55 IRE 22.S1	43 744 Jne
Chromaticity	55 IRE 22.S1	43 743 Jne	Color Encoder	55 IRE 22.S1	43 744 Jne
Chromaticity Co-ordinate	55 IRE 22.S1	43 743 Jne	Color Flicker	55 IRE 22.S1	43 744 Jne
Chromaticity Diagram	55 IRE 22.S1	43 743 Jne	Color Field Corrector	57 IRE 7.S2	45 989 Jul
Chromaticity Flicker	55 IRE 22.S1	43 743 Jne	Color Fringing	55 IRE 22.S1	43 744 Jne
Chrominance	55 IRE 22.S1	43 743 Jne	Color Match	55 IRE 22.S1	43 744 Jne
Chrominance Components	55 IRE 22.S1	43 743 Jne	Color Mixture	55 IRE 22.S1	43 744 Jne
Chrominance Demodulator	55 IRE 22.S1	43 743 Jne	Color-Mixture Data	55 IRE 22.S1	43 745 Jne
Chrominance Modulator	55 IRE 22.S1	43 744 Jne	Color Picture Signal	55 IRE 22.S1	43 745 Jne
Chrominance Primary	55 IRE 22.S1	43 744 Jne	Color Picture Tube	57 IRE 7.S2	45 989 Jul
Chrominance Signal	55 IRE 22.S1	43 744 Jne	Color Plane	57 IRE 7.S2	45 989 Jul
Chrominance Subcarrier	55 IRE 22.S1	43 744 Jne	Color Purity Magnet	57 IRE 7.S2	45 989 Jul
CIE	55 IRE 22.S1	43 744 Jne	Color-Selecting-Electrode System	57 IRE 7.S2	45 989 Jul
Circuit	50 IRE 4.S1	38 27 Jan	Color-Selecting-Electrode System Transmission	57 IRE 7.S2	45 989 Jul
Circuit Efficiency	57 IRE 7.S2	45 988 Jul	Color Signal	55 IRE 22.S1	43 745 Jne
Circuit Gap Admittance	57 IRE 7.S2	45 988 Jul	Color Temperature	55 IRE 22.S1	43 745 Jne
Circular Electric Wave	53 IRE 2.S1	41 1727 Dec	Color Transmission	55 IRE 22.S1	43 745 Jne
Circular Magnetic Wave	53 IRE 2.S1	41 1727 Dec	Color Triad	57 IRE 7.S2	45 989 Jul
Circular Scanning	48 IRE 2,11,15.S1	Separate	Color Triangle	55 IRE 22.S1	43 745 Jne
Circularly Polarized Wave	50 IRE 24.S1	38 1265 Nov	Colorimetry	55 IRE 22.S1	43 745 Jne
Circulating Register (or Memory)	56 IRE 8.S1	44 1168 Sep	Colpitts Oscillator	48 IRE 2,11,15.S1	Separate
Class-A Amplifier	57 IRE 7.S2	45 988 Jul	Column	56 IRE 8.S1	44 1168 Sep

	<i>Standard</i>	<i>PROCEEDINGS</i> <i>Vol Page Mo</i>		<i>Standard</i>	<i>PROCEEDINGS</i> <i>Vol Page Mo</i>
Combination Microphone	51 IRE 6.S1	39 514 May	Control Track	51 IRE 6.S1	39 514 May
Command (in Computers)	56 IRE 8.S1	44 1168 Sep	Controlled Carrier	48 IRE 2,11,15.S1	Separate
Command (in Control Systems)	55 IRE 26.S2	44 109 Jan	Convection Current	57 IRE 7.S2	45 990 Jul
Commutation Factor	57 IRE 7.S2	45 989 Jul	Convection-Current Modulation	57 IRE 7.S2	45 990 Jul
Companding	53 IRE 11.S1	41 612 May	Convergence	57 IRE 7.S2	45 990 Jul
Comparator	50 IRE 8.S1	39 272 Mar	Convergence, Dynamic	57 IRE 7.S2	45 990 Jul
Compass Bearing	49 IRE 12.S1	37 1367 Dec	Convergence Electrode	57 IRE 7.S2	45 990 Jul
Compass Course	49 IRE 12.S1	37 1367 Dec	Convergence Magnet	57 IRE 7.S2	45 990 Jul
Compass Heading	49 IRE 12.S1	37 1367 Dec	Convergence Plane	57 IRE 7.S2	45 990 Jul
Compatibility	55 IRE 22.S1	43 745 Jne	Convergence Surface	57 IRE 7.S2	45 990 Jul
Complement	56 IRE 8.S1	44 1168 Sep	Conversion Transconductance	57 IRE 7.S2	45 990 Jul
Complementary Wavelength	55 IRE 22.S1	43 745 Jne	Conversion Transducer	57 IRE 7.S2	45 990 Jul
Complete Carry	56 IRE 8.S1	44 1168 Sep	Conversion Voltage Gain	57 IRE 7.S2	45 990 Jul
Complex Target	54 IRE 12.S1	43 194 Feb	Converter	51 IRE 20.S2	39 898 Aug
Complex Tone	51 IRE 8.S1	44 1168 Sep	Converter, Facsimile	56 IRE 9.S1	44 777 Jne
Composite Color Signal	55 IRE 22.S1	43 745 Jne	Converter, Mercury Arc, Pool Cathode	55 IRE 10.S1	43 1070 Sep
Composite Color Sync	55 IRE 22.S1	43 745 Jne	Converter, Mercury Hydrogen Spark Gap	55 IRE 10.S1	43 1070 Sep
Composite Controlling Voltage	57 IRE 7.S2	45 989 Jul	Converter Tube	57 IRE 7.S2	45 990 Jul
Composite Picture Signal	55 IRE 23.S1	43 620 May	Converter, Quenched Spark Gap	55 IRE 10.S1	43 1070 Sep
Composite Pulse	54 IRE 12.S1	43 194 Feb	Copy	56 IRE 8.S1	44 1169 Sep
Compound Horn	48 IRE 2,11,15.S1	Separate	Core	51 IRE 6.S1	39 514 May
Compound Target	54 IRE 12.S1	43 194 Feb	Core Type Induction Heater or Furnace	55 IRE 10.S1	43 1070 Sep
Compression	53 IRE 11.S1	41 612 May	Coreless Type Induction Heater or Furnace	55 IRE 10.S1	43 1070 Sep
Compression (in Television)	55 IRE 23.S1	43 620 May	Corner Reflector	54 IRE 12.S1	43 194 Feb
Compression Ratio	57 IRE 7.S2	45 989 Jul	Corrected Compass Course	54 IRE 12.S1	43 194 Feb
Compressional Wave	51 IRE 6.S1	39 514 May	Corrected Compass Heading	54 IRE 12.S1	43 195 Feb
Computer	56 IRE 8.S1	44 1168 Sep	Correction	56 IRE 8.S1	44 1169 Sep
Condensed-Mercury Temperature	57 IRE 7.S2	45 989 Jul	Corrective Network (Shaping Net- work)	42 IRE 9.S1	Separate
Conditional Jump	56 IRE 8.S1	44 1168 Sep	Cosecant-Squared Pattern	54 IRE 12.S1	43 195 Feb
Conditional Transfer of Control	56 IRE 8.S1	44 1169 Sep	Count	57 IRE 7.S2	45 990 Jul
Condor	54 IRE 12.S1	43 208 Feb	Count Down	54 IRE 12.S1	43 195 Feb
Conductance	57 IRE 7.S2	45 989 Jul	Counter	56 IRE 8.S1	44 1169 Sep
Conductance for Rectification	57 IRE 7.S2	45 989 Jul	Counterpoise	48 IRE 2,11,15.S1	Separate
Conduction Band	54 IRE 7.S2	42 1506 Oct	Counter Ring	56 IRE 8.S1	44 1169 Sep
Conductivity	54 IRE 7.S2	42 1506 Oct	Counter Tube Externally Quenched	57 IRE 7.S2	45 990 Jul
Conductivity Modulation	54 IRE 7.S2	42 1506 Oct	Counter Tube, Gas-Filled Radia- tion	57 IRE 7.S2	45 990 Jul
Conductivity, P-Type	54 IRE 7.S2	42 1506 Oct	Counter Tube, Gas-Flow	57 IRE 7.S2	45 990 Jul
Cone of Nulls	48 IRE 2,11,15.S1	Separate	Counter Tube, Geiger-Mueller	57 IRE 7.S2	45 990 Jul
Cone of Silence	54 IRE 12.S1	43 194 Feb	Counter-Tube, Proportional	57 IRE 7.S2	45 990 Jul
Conical Horn	51 IRE 6.S1	39 514 May	Counter Tube, Self-Quenched	57 IRE 7.S2	45 990 Jul
Conical Scanning	48 IRE 2,11,15.S1	Separate	Counting Efficiency	57 IRE 7.S2	45 990 Jul
Connected	50 IRE 4.S1	38 27 Jan	Counting-Rate-vs-Voltage Char- acteristic	57 IRE 7.S2	45 990 Jul
Connector Waveguide	55 IRE 2.S1	43 1074 Sep	Coupler	54 IRE 12.S1	43 195 Feb
Consol	54 IRE 12.S1	43 208 Feb	Coupling Aperture	55 IRE 2.S1	43 1074 Sep
Consolan	54 IRE 12.S1	43 208 Feb	Coupling (Induction Heating Usage)	55 IRE 10.S1	43 1070 Sep
Constant Amplitude Recording	51 IRE 6.S1	39 514 May	Coupling Coefficient, Small Signal	57 IRE 7.S2	45 990 Jul
Constant-Current Characteristic	57 IRE 7.S2	45 989 Jul	Coupling Loop	55 IRE 2.S1	43 1074 Sep
Constant-Current Modulation	48 IRE 2,11,15.S1	Separate	Coupling Probe	55 IRE 2.S1	43 1074 Sep
Constant-Delay Discriminator	54 IRE 12.S1	43 194 Feb	Course	54 IRE 12.S1	43 195 Feb
Constant Luminance Transmission	55 IRE 22.S1	43 745 Jne	Course Error	54 IRE 12.S1	43 195 Feb
Constant Velocity Recording	51 IRE 6.S1	39 514 May	Course Error, Indicated	54 IRE 12.S1	43 195 Feb
Contact, High Recombination Rate	54 IRE 7.S2	42 1506 Oct	Course Line	54 IRE 12.S1	43 195 Feb
Contact, Majority Carrier	54 IRE 7.S2	42 1506 Oct	Course Line Deviation	54 IRE 12.S1	43 195 Feb
Contact Potential Difference	57 IRE 7.S2	45 989 Jul	Course (Line) Computer	49 IRE 12.S1	37 1367 Dec
Contact Rectifier	48 IRE 2,11,15.S1	Separate	Course (Line) Selector	49 IRE 12.S1	37 1367 Dec
Contact, Load	55 IRE 10.S1	43 1070 Sep	Course Made Good	54 IRE 12.S1	43 195 Feb
Continuous-Duty Rating	48 IRE 2,11,15.S1	Separate	Course Push (or Pull)	54 IRE 12.S1	43 195 Feb
Continuous Waves or CW	48 IRE 2,11,15.S1	Separate	Course Sensitivity	54 IRE 12.S1	43 195 Feb
Control (in Computers)	56 IRE 8.S1	44 1169 Sep	Course Softening	54 IRE 12.S1	43 195 Feb
Control Characteristic	57 IRE 7.S2	45 989 Jul	Course Width	54 IRE 12.S1	43 195 Feb
Control Circuits	50 IRE 8.S1	39 273 Mar			
Control Electrode	57 IRE 7.S2	45 989 Jul			
Control-Electrode Discharge Re- covery Time	57 IRE 7.S2	45 989 Jul			
Control Grid	57 IRE 7.S2	45 990 Jul			
Control Ratio	57 IRE 7.S2	45 990 Jul			

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Coverage Diagram	54 IRE 12.S1	43 195 Feb	D Region	50 IRE 24.S1	38 1265 Nov
Crab Angle	54 IRE 12.S1	43 195 Feb	Damped Waves	48 IRE 2,11,15.S1	Separate
Crest Factor of a Pulse	51 IRE 20.S1	39 625 Jne	Dark Current	57 IRE 7.S2	45 991 Jul
Crest Factor of a Pulse Carrier	48 IRE 2,11,15.S1	Separate	Dark Trace Tube	54 IRE 12.S1	43 195 Feb
Critical Anode Voltage	57 IRE 7.S2	45 990 Jul	Data, Handling Capacity	54 IRE 12.S1	43 195 Feb
Critical Area	42 IRE 9.S1	Separate	Data Stabilization	54 IRE 12.S1	43 195 Feb
Critical Field	57 IRE 7.S2	45 990 Jul	Dead Reckoning	54 IRE 12.S1	43 195 Feb
Critical Frequency	50 IRE 24.S1	38 1265 Nov	Dead Room	51 IRE 6.S1	39 515 May
Critical Grid Current	57 IRE 7.S2	45 990 Jul	Dead Time (in Navigation Aids)	54 IRE 12.S1	43 195 Feb
Critical Grid Voltage	57 IRE 7.S2	45 990 Jul	Dead Time (Radiation Counters)	57 IRE 7.S2	45 991 Jul
Critical High-Power Level	57 IRE 7.S2	45 990 Jul	Decalescent Point (of a metal)	55 IRE 10.S1	43 1070 Sep
Critical Voltage	57 IRE 7.S2	45 990 Jul	Decay (Charge-Storage Tubes)	57 IRE 7.S2	45 991 Jul
Cross Talk	48 IRE 2,11,15.S1	Separate	Decay (Characteristic)	57 IRE 7.S2	45 991 Jul
Cross Coupling	53 IRE 2.S1	41 1723 Dec	Decay Time (Charge-Storage Tubes)	57 IRE 7.S2	45 991 Jul
Cross-Modulation (General)	52 IRE 17.S1	40 1682 Dec	Decca	54 IRE 12.S1	43 208 Feb
Cross-Modulation (in Transmitters)	48 IRE 2,11,15.S1	Separate	Decelerating Electrode (Electron-Beam Tubes)	57 IRE 7.S2	45 991 Jul
Cross Neutralization	48 IRE 2,11,15.S1	Separate	Decibel	48 IRE 2,11,15.S1	Separate
Cross Polarization	48 IRE 2,11,15.S1	Separate	Decimal Number System	56 IRE 8.S1	44 1169 Sep
Cross Section	54 IRE 12.S1	43 195 Feb	Decimal Point	56 IRE 8.S1	44 1169 Sep
Crossing Angle	54 IRE 12.S1	43 195 Feb	Decineper	48 IRE 2,11,15.S1	Separate
Crossover Characteristic Curve	54 IRE 12.S1	43 195 Feb	Decoder (in Computers)	56 IRE 8.S1	44 1169 Sep
Crossover Frequency	51 IRE 6.S1	39 514 May	Decoder (in Navigation Aids)	49 IRE 12.S1	37 1368 Dec
Crossover Region	54 IRE 12.S1	43 195 Feb	De-Emphasis	52 IRE 17.S1	40 1682 Dec
Crystal-Controlled Transmitter	48 IRE 2,11,15.S1	Separate	De-Emphasis	53 IRE 11.S1	41 612 May
Crystal Cutter	51 IRE 6.S1	39 514 May	De-Emphasis Network	48 IRE 2,11,15.S1	Separate
Crystal Loudspeaker	51 IRE 6.S1	39 514 May	Definition	56 IRE 9.S1	44 777 Jne
Crystal Microphone	51 IRE 6.S1	39 514 May	Deflecting Electrode	57 IRE 7.S2	45 991 Jul
Crystal Oscillator	48 IRE 2,11,15.S1	Separate	Deflecting Yoke	50 IRE 7.S1	38 431 Apr
Crystal Pickup	51 IRE 6.S1	39 514 May	Deflection Center	57 IRE 7.S2	45 991 Jul
Crystal Pulling	54 IRE 7.S2	42 1506 Oct	Deflection Factor	57 IRE 7.S2	45 991 Jul
Crystal-Stabilized Transmitter	48 IRE 2,11,15.S1	Separate	Deflection Plane	57 IRE 7.S2	45 991 Jul
Crystal-Video Receiver	54 IRE 12.S1	43 195 Feb	Deflection Sensitivity	57 IRE 7.S2	45 991 Jul
Curie Point	55 IRE 10.S1	43 1070 Sep	Deflection Yoke	57 IRE 7.S2	45 991 Jul
Current	57 IRE 7.S2	45 991 Jul	Deflection-Yoke Pull-Back	57 IRE 7.S2	45 991 Jul
Current Amplification	54 IRE 3.S1	42 1110 Jul	Degeneration	48 IRE 2,11,15.S1	Separate
Current Amplification	57 IRE 7.S2	45 991 Jul	Degrees of Freedom	50 IRE 4.S1	39 27 Jan
Current Attenuation	54 IRE 3.S1	42 1110 Jul	Deionization Time	57 IRE 7.S2	45 991 Jul
Current Generator	57 IRE 7.S2	45 991 Jul	Delay Distortion	56 IRE 9.S1	44 777 Jne
Cutoff Field	57 IRE 7.S2	45 991 Jul	Delay Distortion	53 IRE 4.S1	42 554 Mar
Cutoff Frequency	53 IRE 2.S1	41 1723 Dec	Delay Distortion	52 IRE 17.S1	40 1682 Dec
Cutoff Voltage (Electron Tubes)	57 IRE 7.S2	45 991 Jul	Delay Equalizer	56 IRE 9.S1	44 777 Jne
Cutoff Voltage (Magnetrons)	57 IRE 7.S2	45 991 Jul	Delay Line	56 IRE 8.S1	44 1169 Sep
Cutoff Wavelength	53 IRE 2.S1	41 1723 Dec	Delay-Line Memory	56 IRE 8.S1	44 1169 Sep
Cut Paraboloidal Reflector	48 IRE 2,11,15.S1	Separate	Delay-Line Register	50 IRE 8.S1	39 273 Mar
Cut-Set	40 IRE 4.S1	39 27 Jan	Delay-Line Storage	56 IRE 8.S1	44 1169 Sep
Cutter	51 IRE 6.S1	39 515 May	Delayed PPI	54 IRE 12.S1	43 196 Feb
Cutting Stylus	51 IRE 6.S1	39 515 May	Delta Network	50 IRE 4.S1	39 27 Jan
Cycle, Major	50 IRE 8.S1	39 273 Mar	Demodulation	53 IRE 11.S1	41 613 May
Cycle, Minor	50 IRE 8.S1	39 273 Mar	Demodulation	52 IRE 17.S1	40 1682 Dec
Cyclic Shift	56 IRE 8.S1	44 1169 Sep	Densitometer	51 IRE 6.S1	39 515 May
Cyclotron Frequency	57 IRE 7.S2	45 991 Jul	Density (in Facsimile)	56 IRE 9.S1	44 777 Jne
Cyclotron-Frequency Magnetron Oscillations	57 IRE 7.S2	45 991 Jul	Depletion Layer	54 IRE 7.S2	42 1506 Oct
Cylindrical Reflector	48 IRE 2,11,15.S1	Separate	Depth of Heating	55 IRE 10.S1	43 1070 Sep
Cylindrical Wave	50 IRE 24.S1	38 1265 Nov	Depth of Modulation	54 IRE 12.S1	43 196 Feb
D			Depth of Penetration (Induction Heating Usage)	55 IRE 10.S1	43 1070 Sep
DBM	54 IRE 3.S1	42 1110 Jul	Depth of Velocity Modulation, Small Signal	57 IRE 7.S2	45 991 Jul
DC Electron-Stream Resistance	57 IRE 7.S2	45 991 Jul	Desired Tract	54 IRE 12.S1	43 196 Feb
DC Erasing Head	51 IRE 6.S1	39 515 May	Destination	49 IRE 12.S1	37 1368 Dec
DC Magnetic Biasing	51 IRE 6.S1	39 515 May	Detail	42 IRE 9.S1	Separate
D-Display	54 IRE 12.S1	43 197 Feb	Detection	53 IRE 11.S1	41 613 May
DDM	54 IRE 12.S1	43 196 Feb	Detector	52 IRE 17.S1	40 1682 Dec
DME (Distance Measuring Equipment)	54 IRE 12.S1	43 208 Feb	Deviation Frequency	52 IRE 17.S1	40 1682 Dec

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Deviation from Pulse Flatness	54 IRE 12.S1	43 196 Feb	Discharge	57 IRE 7.S2	45 992 Jul
Deviation Distortion	52 IRE 17.S1	40 1682 Dec	Discrete Sentence Intelligibility	51 IRE 6.S1	39 515 May
Deviation Ratio	53 IRE 11.S1	41 613 May	Discrete Word Intelligibility	51 IRE 6.S1	39 516 May
Deviation Sensitivity (in FM)	52 IRE 17.S1	40 1682 Dec	Discriminator (General)	54 IRE 12.S1	43 196 Feb
Deviation Sensitivity (in Navigation Aids)	54 IRE 12.S1	43 196 Feb	Discriminator (Specific)	53 IRE 11.S1	41 613 May
Deviation Sensitivity Angular	54 IRE 12.S1	43 196 Feb	Discriminator Constant Delay	54 IRE 12.S1	43 196 Feb
Diagnostic Routine	56 IRE 8.S1	44 1169 Sep	Discriminator, Pulse Duration	54 IRE 12.S1	43 196 Feb
Dielectric Antenna	48 IRE 2,11,15.S1	Separate	Dish	54 IRE 12.S1	43 196 Feb
Dielectric Dissipation Factor	55 IRE 10.S1	43 1070 Sep	Disk Recorder	51 IRE 6.S1	39 516 May
Dielectric Heating	55 IRE 10.S1	43 1070 Sep	Dispatcher	50 IRE 8.S1	39 273 Mar
Dielectric Phase Angle	55 IRE 10.S1	43 1070 Sep	Display	54 IRE 12.S1	43 196 Feb
Dielectric Power Factor	55 IRE 10.S1	43 1070 Sep	Display Primaries	55 IRE 22.S1	43 745 Jne
Dielectric Strength	55 IRE 10.S1	43 1070 Sep	Dissector Tube	57 IRE 7.S2	45 992 Jul
Dielectric Waveguide	53 IRE 2.S1	41 1723 Dec	Dissymmetrical Transducer	51 IRE 20.S2	39 898 Aug
Difference Detector	54 IRE 12.S1	43 196 Feb	Distance Mark	54 IRE 12.S1	43 199 Feb
Difference in Depth of Modulation (DDM)	54 IRE 12.S1	43 196 Feb	Distance Measuring Equipment	54 IRE 12.S1	43 208 Feb
Difference Limen	51 IRE 6.S1	39 515 May	Distance Resolution	54 IRE 12.S1	43 199 Feb
Difference Transfer Function	55 IRE 26.S2	44 108 Jan	Distortion	53 IRE 4.S1	42 554 Mar
Differential Gain	55 IRE 23.S1	43 620 May	Distortion	52 IRE 17.S1	40 1682 Dec
Differential Gain Control	54 IRE 12.S1	43 196 Feb	Distortion Barrel	57 IRE 7.S2	45 992 Jul
Differential Phase	55 IRE 23.S1	43 620 May	Distortion, Keystone	57 IRE 7.S2	45 992 Jul
Differentiating Network	48 IRE 2,11,15.S1	Separate	Distortion, Pincushion	57 IRE 7.S2	45 992 Jul
Differentiator	53 IRE 11.S1	41 613 May	Distortion, S	57 IRE 7.S2	45 992 Jul
Differentiator (in Electronic Computers)	56 IRE 8.S1	44 1169 Sep	Distortion, Spiral	57 IRE 7.S2	45 992 Jul
Diffracted Wave	51 IRE 6.S1	39 515 May	Distributed Constant	53 IRE 2.S1	41 1723 Dec
Diffraction	51 IRE 6.S1	39 515 May	Distribution Coefficients	55 IRE 22.S1	43 745 Jne
Diffuse Sound	51 IRE 6.S1	39 515 May	Disturbance	55 IRE 26.S2	44 109 Jan
Diffuse Transmission Density	51 IRE 6.S1	39 515 May	Divergence Loss	51 IRE 6.S1	39 516 May
Diffusion Constant	54 IRE 7.S2	42 1506 Oct	Dividing Network	51 IRE 6.S1	39 516 May
Diffusion Length	54 IRE 7.S2	42 1506 Oct	Doherty Amplifier	48 IRE 2,11,15.S1	Separate
Digit	56 IRE 8.S1	44 1169 Sep	Domestic Induction Heater	55 IRE 10.S1	43 1070 Sep
Digit, Binary	50 IRE 8.S1	39 273 Mar	Dominant Mode of Propagation	53 IRE 2.S1	41 1723 Dec
Digit, Sign	50 IRE 8.S1	39 273 Mar	Dominant Wave	53 IRE 2.S1	41 1723 Dec
Digital Computer	56 IRE 8.S1	44 1169 Sep	Dominant Wavelength	55 IRE 22.S1	43 745 Jne
Diode Characteristic	57 IRE 7.S2	45 992 Jul	Donor	54 IRE 7.S2	42 1506 Oct
Diode (Electron Tube)	57 IRE 7.S2	45 991 Jul	Doping	54 IRE 7.S2	42 1506 Oct
Diode, Semiconductor	54 IRE 7.S2	42 1506 Oct	Doping Compensation	54 IRE 7.S2	42 1506 Oct
Diplex Radio Transmission	48 IRE 2,11,15.S1	Separate	Doppler Effect	51 IRE 6.S1	39 516 May
Dipole Antenna	48 IRE 2,11,15.S1	Separate	Doppler Shift	51 IRE 6.S1	39 516 May
Direct-Coupled Attenuation	57 IRE 7.S2	45 992 Jul	Doppler System	54 IRE 12.S1	43 199 Feb
Direct-Current Amplifier	48 IRE 2,11,15.S1	Separate	Doppler System, Pulsed	54 IRE 12.S1	43 199 Feb
Direct Grid Bias	57 IRE 7.S2	45 992 Jul	Dot-Sequential	55 IRE 22.S1	53 745 Jne
Direct Radiator Loudspeaker	51 IRE 6.S1	39 515 May	Double-Length Number	56 IRE 8.S1	44 1169 Sep
Direct Recording	56 IRE 9.S1	44 777 Jne	Double Pole-Piece Magnetic Head	51 IRE 6.S1	39 516 May
Direct Wave	50 IRE 24.S1	38 1265 Nov	Double-Precision Number	56 IRE 8.S1	44 1169 Sep
Directed Reference Flight	54 IRE 12.S1	43 196 Feb	Double-Sideband Transmitter	48 IRE 2,11,15.S1	Separate
Direction	54 IRE 12.S1	43 196 Feb	Downward Modulation	52 IRE 17.S1	40 1682 Dec
Direction Finder (DF)	54 IRE 12.S1	43 196 Feb	Drift Angle	54 IRE 12.S1	43 199 Feb
Direction Finder Deviation	54 IRE 12.S1	43 196 Feb	Drift Correction Angle	54 IRE 12.S1	43 199 Feb
Direction of Polarization	50 IRE 24.S1	38 1265 Nov	Drift Mobility	54 IRE 7.S2	42 1506 Oct
Direction of Propagation	53 IRE 2.S1	41 1723 Dec	Drift Rate	57 IRE 7.S2	45 992 Jul
Directional Antenna	48 IRE 2,11,15.S1	Separate	Drift Space	57 IRE 7.S2	45 992 Jul
Directional Coupler	55 IRE 2.S1	43 1074 Sep	Drive Pattern	56 IRE 9.S1	44 777 Jne
Directional Gain	55 IRE 23.S1	43 620 May	Drive Pin	51 IRE 6.S1	39 516 May
Directional Homing	54 IRE 12.S1	43 196 Feb	Drive-Pin Hole	51 IRE 6.S1	39 516 May
Directional Microphone	51 IRE 6.S1	39 515 May	Driving-Point Admittance	57 IRE 7.S2	45 992 Jul
Directive Gain	48 IRE 2,11,15.S1	Separate	Driving Signals (in Television)	55 IRE 23.S1	43 620 May
Directivity	48 IRE 2,11,15.S1	Separate	Drum Speed	56 IRE 9.S1	44 777 Jne
Directivity Factor	51 IRE 6.S1	39 515 May	Dual Frequency Induction Heater or Furnace	55 IRE 10.S1	43 1070 Sep
Directivity Index	51 IRE 6.S1	39 515 May	Dual Modulation	56 IRE 9.S1	44 777 Jne
Directivity Pattern	51 IRE 6.S1	39 515 May	Dual Networks	50 IRE 4.S1	39 27 Jan
Director	48 IRE 2,11,15.S1	Separate	Dubbing	51 IRE 6.S1	39 516 May
			Dummy Antenna	52 IRE 17.S1	40 1682 Dec
			Dummy Load	52 IRE 17.S1	40 1682 Dec

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Duplex Cavity	54 IRE 12.S1	43 199 Feb	Electrode Admittance	57 IRE 7.S2	45 992 Jul
Duplex Operation	48 IRE 2,11,15.S1	Separate	Electrode Capacitance	57 IRE 7.S2	45 993 Jul
Duplexing Assembly	54 IRE 12.S1	43 199 Feb	Electrode Characteristic	57 IRE 7.S2	45 993 Jul
Duty Cycle	48 IRE 2,11,15.S1	Separate	Electrode Conductance	57 IRE 7.S2	45 993 Jul
Duty Factor	48 IRE 2,11,15.S1	Separate	Electrode Current	57 IRE 7.S2	45 993 Jul
Duty Ratio	54 IRE 12.S1	43 199 Feb	Electrode-Current Averaging Time	57 IRE 7.S2	45 993 Jul
Dynamic Characteristic	57 IRE 7.S2	45 992 Jul	Electrode Dark Current	57 IRE 7.S2	45 993 Jul
Dynamic Sequential Control	50 IRE 8.S1	39 273 Mar	Electrode Dissipation	57 IRE 7.S2	45 993 Jul
Dynatron Oscillation	48 IRE 2,11,15.S1	Separate	Electrode Impedance	57 IRE 7.S2	45 993 Jul
Dynatron Oscillator	48 IRE 2,11,15.S1	Separate	Electrode Resistance	57 IRE 7.S2	45 993 Jul
Dynode	57 IRE 7.S2	45 992 Jul	Electrode Voltage	57 IRE 7.S2	45 993 Jul
Dynode Current	57 IRE 7.S2	45 992 Jul	Electrolytic Recording	56 IRE 9.S1	44 777 Jne
Dynode Spots	57 IRE 7.S2	45 992 Jul	Electromagnetic Wave	50 IRE 24.S1	38 1265 Nov
			Electromagnetic Wave	53 IRE 2.S1	41 1723 Dec
			Electromechanical Recording	56 IRE 9.S1	44 777 Jne
E					
E-Display	54 IRE 12.S1	43 199 Feb	Electromechanical Transducer	51 IRE 6.S1	39 517 May
E Layer	50 IRE 24.S1	38 1265 Nov	Electromechanical Transducer	51 IRE 20.S2	39 898 Aug
E-plane Bend	55 IRE 2.S1	43 1074 Sep	Electrometer Tube	57 IRE 7.S2	45 993 Jul
E-plane Tee Junction	55 IRE 2.S1	43 1074 Sep	Electron-Beam Tube	57 IRE 7.S2	45 993 Jul
E Region	50 IRE 24.S1	38 1265 Nov	Electron-Coupled Oscillator	48 IRE 2,11,15.S1	Separate
E-H Tee	55 IRE 2.S1	43 1074 Sep	Electron Device	57 IRE 7.S2	45 993 Jul
E-H Tuner	55 IRE 2.S1	43 1074 Sep	Electron Emission	57 IRE 7.S2	45 993 Jul
Earphone	51 IRE 6.S1	39 516 May	Electron Gun	57 IRE 7.S2	45 993 Jul
Earphone Coupler	51 IRE 6.S1	39 516 May	Electron-Gun Density Multiplication	57 IRE 7.S2	45 993 Jul
Eccentric Groove	51 IRE 6.S1	39 516 May	Electron Multiplier	57 IRE 7.S2	45 993 Jul
Eccentricity	51 IRE 6.S1	39 516 May			
Echo (in Electroacoustics)	51 IRE 6.S1	39 516 May	Electron-Stream Potential	57 IRE 7.S2	45 993 Jul
Echo (in Facsimile)	56 IRE 9.S1	44 777 Jne	Electron-Stream Transmission Efficiency	56 IRE 7.S1	44 347 Mar
Echo (in Navigation Aids)	54 IRE 12.S1	43 199 Feb	Electron Tube	57 IRE 7.S2	45 993 Jul
Echo Box	54 IRE 12.S1	43 199 Feb	Electron-Wave Tube	57 IRE 7.S2	45 993 Jul
Echo, Second-Time Around	54 IRE 12.S1	43 199 Feb	Electrons, Conduction	54 IRE 7.S2	42 1506 Oct
Echo Suppressor	54 IRE 12.S1	43 199 Feb			
Effective Acoustic Center	51 IRE 6.S1	39 516 May	Electronic	57 IRE 7.S2	45 993 Jul
Effective Area	48 IRE 2,11,15.S1	Separate	Electronic Efficiency	57 IRE 7.S2	45 993 Jul
Effective Band (in Facsimile)	56 IRE 9.S1	44 777 Jne	Electronic Gap Admittance	57 IRE 7.S2	45 993 Jul
Effective Bandwidth	48 IRE 2,11,15.S1	Separate	Electronic Keying	48 IRE 2,11,15.S1	Separate
Effective Bunching Angle	57 IRE 7.S2	45 992 Jul	Electronic Line Scanning	56 IRE 9.S1	44 777 Jne
Effective Height	48 IRE 2,11,15.S1	Separate	Electronic Microphone	51 IRE 6.S1	39 517 May
Effective Percentage Modulation	48 IRE 2,11,15.S1	Separate	Electronic Raster Scanning	56 IRE 9.S1	44 777 Jne
Effective Radius of the Earth	50 IRE 24.S1	38 1265 Nov	Electronics	57 IRE 7.S2	45 993 Jul
Effective Sound Pressure	51 IRE 6.S1	39 516 May	Electrophonic Effect	51 IRE 6.S1	39 517 May
Efficiency	57 IRE 7.S2	45 992 Jul	Electrostatic Actuator	51 IRE 6.S1	39 517 May
Efficiency (Radiation Counter Tubes)	57 IRE 7.S2	45 992 Jul			
Efficiency, Load Circuit	55 IRE 10.S1	43 1070 Sep	Electrostatic Focusing	57 IRE 7.S2	45 993 Jul
Efficiency, Over-all Electrical	55 IRE 10.S1	43 1070 Sep	Electrostatic Loudspeaker	51 IRE 6.S1	39 517 May
Electra	54 IRE 12.S1	43 208 Feb	Electrostatic Memory	50 IRE 8.S1	39 273 Mar
Electric Dipole	48 IRE 2,11,15.S1	Separate	Electrostatic Memory Tube	50 IRE 8.S1	39 273 Mar
Electric Displacement Density	50 IRE 24.S1	38 1265 Nov	Electrostatic Microphone	51 IRE 6.S1	39 517 May
Electric Field	50 IRE 24.S1	38 1265 Nov			
Electric Field Strength	50 IRE 24.S1	38 1265 Nov	Electrostatic Recording	56 IRE 9.S1	44 777 Jne
Electric (Magnetic) Field Strength	52 IRE 17.S1	40 1682 Dec	Electrothermal Recording	56 IRE 9.S1	44 777 Jne
Electric Field Vector	53 IRE 2.S1	41 1723 Dec	Element (of a Circuit)	50 IRE 4.S1	39 27 Jan
Electric Flux Density	50 IRE 24.S1	38 1265 Nov	Element (Semiconductor)	54 IRE 7.S2	42 1506 Oct
Electric Transducer	51 IRE 20.S2	39 898 Aug	Element (of a Tube)	57 IRE 7.S2	45 993 Jul
Electrical Distance	54 IRE 12.S1	43 199 Feb			
Electrical Function Switch	50 IRE 8.S1	39 273 Mar	Elemental Area	56 IRE 9.S1	44 777 Jne
Electrical Length	53 IRE 2.S1	41 1723 Dec	Elements of a Fix	54 IRE 12.S1	43 199 Feb
Electrical Length	50 IRE 24.S1	38 1265 Nov	Elliptically Polarized Wave	53 IRE 2.S1	41 1723 Dec
Electrical Noise	48 IRE 2,11,15.S1	Separate	Ellipticity	53 IRE 2.S1	41 1723 Dec
Electroacoustic Transducer	51 IRE 6.S1	39 516 May	Elongation	42 IRE 9.S1	Separate
Electroacoustic Transducer	51 IRE 20.S2	39 898 Aug			
Electroacoustical Reciprocity Theorem	51 IRE 6.S1	39 516 May	Embossing Stylus	51 IRE 6.S1	39 517 May
Electrochemical Recording	56 IRE 9.S1	44 777 Jne	Emission	57 IRE 7.S2	45 993 Jul
Electrode (Electron Tubes)	57 IRE 7.S2	45 992 Jul	Emission Characteristic	57 IRE 7.S2	45 994 Jul
Electrode (Semiconductor)	54 IRE 7.S2	42 1506 Oct	Emitter, Majority	54 IRE 7.S2	42 1506 Oct
			Emitter, Minority	54 IRE 7.S2	42 1506 Oct
			Enabling Pulse	54 IRE 12.S1	43 199 Feb
			Encoder	56 IRE 8.S1	44 1169 Sep
			End-Around Carry	56 IRE 8.S1	44 1169 Sep
			End-Fire Array	48 IRE 2,11,15.S1	Separate
			End-of-Copy Signal	56 IRE 9.S1	44 778 Jne

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Flux Guide	55 IRE 10.S1	43 1070 Sep	Function Switch	50 IRE 8.S1	39 274 Mar
Focusing	57 IRE 7.S2	45 995 Jul	Function Switch, Many-One	50 IRE 8.S1	39 274 Mar
Focusing and Switching Grille	57 IRE 7.S2	45 995 Jul	Function Switch, One-Many	50 IRE 8.S1	39 274 Mar
Focusing Coil or Focusing Magnet	57 IRE 7.S2	45 995 Jul	Function Unit	50 IRE 8.S1	39 274 Mar
Focusing Dynamic	57 IRE 7.S2	45 995 Jul	Fundamental Component	53 IRE 4.S1	42 554 Mar
Focusing Electrode	57 IRE 7.S2	45 995 Jul	Fundamental Frequency	53 IRE 4.S1	42 554 Mar
Focusing Magnet or Coil	57 IRE 7.S2	45 995 Jul	Fundamental Tone	51 IRE 6.S1	39 518 May
Folded Dipole Antenna	48 IRE 2,11,15.S1	Separate			
Footcandle	55 IRE 22.S1	43 746 Jne			
Footlambert	55 IRE 22.S1	43 746 Jne			
Forbidden-Combination Check	56 IRE 8.S1	44 1169 Sep			
Force Factor	56 IRE 6.S1	39 517 May			
Fork Beat	56 IRE 9.S1	44 778 Jne			
Forming	54 IRE 7.S2	42 1506 Oct			
Fortuitous Telegraph Distortion	48 IRE 2,11,15.S1	Separate			
Forward Path	56 IRE 26.S2	44 108 Jan			
Forward Transfer Function	56 IRE 26.S2	44 108 Jan			
Forward Wave	57 IRE 7.S2	45 995 Jul			
Four-Address Code	56 IRE 8.S1	44 1169 Sep			
Four-Pole	50 IRE 4.S1	39 27 Jan			
Frame (in Facsimile)	56 IRE 9.S1	44 778 Jne			
Frame (in TV)	55 IRE 23.S1	43 620 May			
Frame Frequency	55 IRE 23.S1	43 620 May			
Framer	42 IRE 9.S1	Separate			
Framing	56 IRE 9.S1	44 778 Jne			
Framing Signal	56 IRE 9.S1	44 778 Jne			
Fraunhofer Region	48 IRE 2,11,15.S1	Separate			
Free Field	51 IRE 6.S1	39 517 May			
Free-Field Current Response	51 IRE 6.S1	39 518 May			
Free-Field Voltage	51 IRE 6.S1	39 518 May			
Free Impedance	51 IRE 6.S1	39 518 May			
Free Motional Impedance	51 IRE 6.S1	39 518 May			
Free Oscillations	48 IRE 2,11,15.S1	Separate			
Free Progressive Wave	51 IRE 6.S1	39 518 May			
Free-Running Frequency	52 IRE 17.S1	40 1683 Dec			
Frequency Band	48 IRE 2,11,15.S1	Separate			
Frequency Band of Emission	48 IRE 2,11,15.S1	Separate			
Frequency Conversion Transducer	51 IRE 20.S2	39 898 Aug			
Frequency Departure	48 IRE 2,11,15.S1	Separate			
Frequency Departure	52 IRE 17.S1	40 1683 Dec			
Frequency Deviation	53 IRE 11.S1	41 613 May			
Frequency Deviation	52 IRE 17.S1	40 1683 Dec			
Frequency Distortion	53 IRE 4.S1	42 554 Mar			
Frequency Divider	51 IRE 20.S2	39 898 Aug			
Frequency-Division Multiplex	53 IRE 11.S1	41 613 May			
Frequency Doubler	48 IRE 2,11,15.S1	Separate			
Frequency Interlace	55 IRE 22.S1	43 746 Jne			
Frequency-Modulated Transmitter	48 IRE 2,11,15.S1	Separate			
Frequency Modulation	52 IRE 17.S1	40 1683 Dec			
Frequency Modulation	53 IRE 11.S1	41 613 May			
Frequency Multiplier	48 IRE 2,11,15.S1	Separate			
Frequency Multiplier	51 IRE 20.S2	39 898 Aug			
Frequency Pulling	57 IRE 7.S2	45 995 Jul			
Frequency Range (of a Device)	57 IRE 7.S2	45 995 Jul			
Frequency Record	51 IRE 6.S1	39 518 May			
Frequency-Response Equalization	51 IRE 6.S1	39 518 May			
Frequency-Shift Keying or FSK	53 IRE 11.S1	41 613 May			
Frequency Stabilization	48 IRE 2,11,15.S1	Separate			
Frequency Swing	53 IRE 11.S1	41 613 May			
Frequency Tolerance of a Radio Transmitter	48 IRE 2,11,15.S1	Separate			
Frequency Tripler	48 IRE 2,11,15.S1	Separate			
Fresnel Region	48 IRE 2,11,15.S1	Separate			
Front Porch	55 IRE 23.S1	43 620 May			
Front-to-Rear Ratio	48 IRE 2,11,15.S1	Separate			
Fruit Pulse	52 IRE 20.S1	40 553 May			
Gate	56 IRE 8.S1	44 1169 Sep			
GCA (Ground-Controlled Approach)	54 IRE 12.S1	43 208 Feb			
GCI (Ground-Controlled Interception)	54 IRE 12.S1	43 208 Feb			
G-Display	54 IRE 12.S1	43 200 Feb			
GEE	54 IRE 12.S1	43 208 Feb			
GEE-H	54 IRE 12.S1	43 208 Feb			
GPI (Ground Position Indicator)	54 IRE 12.S1	43 208 Feb			
Gain (General)	54 IRE 3.S1	42 1110 Jul			
Gain (Specific)	50 IRE 7.S1	38 433 Apr			
Gain, Available Conversion	57 IRE 7.S2	45 995 Jul			
Gain, Available-Power	57 IRE 7.S2	45 995 Jul			
Gain, Available Power Maximum	57 IRE 7.S2	45 995 Jul			
Gain-Control, Temporal	54 IRE 12.S1	43 200 Feb			
Gain Conversion Voltage	57 IRE 7.S2	45 995 Jul			
Gain, Insertion	57 IRE 7.S2	45 995 Jul			
Gain, Insertion Voltage	57 IRE 7.S2	45 995 Jul			
Gain of an Antenna	48 IRE 2,11,15.S1	Separate			
Gain Time Control	54 IRE 12.S1	43 200 Feb			
Gain, Transducer	57 IRE 7.S2	45 995 Jul			
Gain Turn Down	54 IRE 12.S1	43 200 Feb			
Galvanometer	51 IRE 6.S1	39 518 May			
Gamma (Film Recording)	51 IRE 6.S1	39 518 May			
Gamma (Picture Tube)	57 IRE 7.S2	45 995 Jul			
Gamma (TV)	55 IRE 22.S1	43 746 Jne			
Gamma Correction	55 IRE 22.S1	43 746 Jne			
Gap	57 IRE 7.S2	45 996 Jul			
Gap Admittance, Circuit	57 IRE 7.S2	45 996 Jul			
Gap Admittance, Electronic	57 IRE 7.S2	45 996 Jul			
Gap Capacitance Effective	57 IRE 7.S2	45 996 Jul			
Gap Coding	54 IRE 12.S1	43 200 Feb			
Gap Length	51 IRE 6.S1	39 518 May			
Gap Loading Multipactor	57 IRE 7.S2	45 996 Jul			
Gap Loading Primary Transit-Angle	57 IRE 7.S2	45 996 Jul			
Gap Loading, Secondary Electron	57 IRE 7.S2	45 996 Jul			
Gas Amplification	57 IRE 7.S2	45 996 Jul			
Gas Amplification Factor	57 IRE 7.S2	45 996 Jul			
Gas (Ionization) Current	57 IRE 7.S2	45 996 Jul			
Gas-Filled Radiation-Counter Tube	57 IRE 7.S2	45 996 Jul			
Gas-Flow Counter Tube	57 IRE 7.S2	45 996 Jul			
Gas Focusing	57 IRE 7.S2	45 996 Jul			
Gas Ratio	57 IRE 7.S2	45 996 Jul			
Gas Tube	57 IRE 7.S2	45 996 Jul			
Gaseous Tube Generator	55 IRE 10.S1	43 1070 Sep			
Gating	53 IRE 11.S1	41 613 May			
Gear Pattern	56 IRE 9.S1	44 778 Jne			
Geiger-Mueller Counter Tube	57 IRE 7.S2	45 996 Jul			
Geiger-Mueller Region	57 IRE 7.S2	45 996 Jul			
Geiger-Mueller Threshold	57 IRE 7.S2	45 996 Jul			
Generation Rate	54 IRE 7.S2	42 1506 Oct			
Generator	57 IRE 7.S2	45 996 Jul			
Geodesic	54 IRE 12.S1	43 200 Feb			
Geometrical Error	54 IRE 12.S1	43 200 Feb			
Geometrical Factor	54 IRE 12.S1	43 200 Feb			
Ghost Pulse	54 IRE 12.S1	43 200 Feb			
Ghost Signals	54 IRE 12.S1	43 200 Feb			

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Gill-Morrell Oscillator	48 IRE 2,11,15.S1	Separate	Half-Power Width of a Radiation	48 IRE 2,11,15.S1	Separate
Glide-Path	54 IRE 12.S1	43 200 Feb	Lobe	56 IRE 9.S1	44 778 Jne
Glide-Slope	54 IRE 12.S1	43 200 Feb	Half-tone Characteristic	54 IRE 7.S2	42 1506 Oct
Glide-Slope Angle	54 IRE 12.S1	43 200 Feb			
Glide-Slope Deviation	54 IRE 12.S1	43 200 Feb	Harmonic	53 IRE 4.S1	42 554 Mar
Glide-Slope Facility	54 IRE 12.S1	43 200 Feb	Harmonic Conversion Transducer	51 IRE 20.S2	39 898 Aug
Glide-Slope Sector	54 IRE 12.S1	43 200 Feb	Harmonic Conversion Transducer	57 IRE 7.S2	45 996 Jul
Glow Discharge	57 IRE 7.S2	45 996 Jul	Harmonic Distortion	53 IRE 4.S1	42 554 Mar
Glow-Discharge Cold-Cathode Tube	50 IRE 7.S1	38 434 Apr	Harmonic Distortion	52 IRE 17.S1	40 1683 Dec
Glow-Discharge Tube	57 IRE 7.S2	45 996 Jul	Harmonic Leakage Power	57 IRE 7.S2	45 996 Jul
Glue Line Heating	55 IRE 10.S1	43 1070 Sep	Harmonic Series of Sounds	51 IRE 6.S1	39 519 May
Gradient Microphone	51 IRE 6.S1	39 518 May	Hartley Oscillator	48 IRE 2,11,15.S1	Separate
Grain	51 IRE 6.S1	39 518 May	Heading	54 IRE 12.S1	43 201 Feb
Graininess	51 IRE 6.S1	39 518 May	Hearing Loss	51 IRE 6.S1	39 519 May
Grass	54 IRE 12.S1	43 200 Feb	Hearing Loss for Speech	51 IRE 6.S1	39 519 May
Grating Reflector	48 IRE 2,11,15.S1	Separate	Heat Loss	53 IRE 2.S1	41 1723 Dec
Grid (of a Tube)	57 IRE 7.S2	45 996 Jul	Heater	57 IRE 7.S2	45 996 Jul
Grid Bearing	49 IRE 12.S1	37 1368 Dec	Heater Coil	55 IRE 10.S1	43 1070 Sep
Grid Bias	57 IRE 7.S2	45 996 Jul	Heater Current	50 IRE 7.S1	38 434 Apr
Grid Characteristic	57 IRE 7.S2	45 996 Jul	Heater Voltage	50 IRE 7.S1	38 434 Apr
Grid-Controlled Mercury-Arc Rectifier	48 IRE 2,11,15.S1	Separate	Heater Warm-Up Time	57 IRE 7.S2	45 996 Jul
Grid Course	49 IRE 12.S1	37 1368 Dec	Heating Pattern	55 IRE 10.S1	43 1070 Sep
Grid Current	57 IRE 7.S2	45 996 Jul	Heating Station	55 IRE 10.S1	43 1070 Sep
Grid-Drive Characteristic	57 IRE 7.S2	45 996 Jul	Heating Time	57 IRE 7.S2	45 997 Jul
Grid Driving Power	57 IRE 7.S2	45 996 Jul	Height Error	54 IRE 12.S1	43 201 Feb
Grid Emission	57 IRE 7.S2	45 996 Jul	Height Error, Ionospheric	54 IRE 12.S1	43 201 Feb
Grid Heading	49 IRE 12.S1	37 1368 Dec	Height Markers (Radar)	54 IRE 12.S1	43 201 Feb
Grid Modulation	48 IRE 2,11,15.S1	Separate	Heptode	57 IRE 7.S2	45 997 Jul
Grid Neutralization	48 IRE 2,11,15.S1	Separate	Heterodyne Conversion Transducer	57 IRE 7.S2	45 997 Jul
Grid North	49 IRE 12.S1	37 1368 Dec	Heterodyne Conversion Transducer (Converter)	51 IRE 20.S2	39 898 Aug
Grid Pulse Modulation	48 IRE 2,11,15.S1	Separate	Hexadecimal	56 IRE 8.S1	44 1170 Sep
Grid Voltage	57 IRE 7.S2	45 996 Jul	Hexode	57 IRE 7.S2	45 997 Jul
Groove	51 IRE 6.S1	39 518 May	High-Frequency Induction Heater or Furnace	55 IRE 10.S1	43 1070 Sep
Groove Angle	51 IRE 6.S1	39 518 May	High-Level Firing Time	57 IRE 7.S2	45 997 Jul
Groove Shape	51 IRE 6.S1	39 518 May	High-Level Modulation	48 IRE 2,11,15.S1	Separate
Groove Speed	51 IRE 6.S1	39 518 May	High-Level Radio-Frequency Signal	57 IRE 7.S2	45 997 Jul
Ground-Controlled Approach	49 IRE 12.S1	37 1368 Dec	High-Level VSWR	57 IRE 7.S2	45 997 Jul
Ground Clutter	54 IRE 12.S1	43 200 Feb	High-Speed Carry	56 IRE 8.S1	44 1170 Sep
Ground Distance	54 IRE 12.S1	43 200 Feb	High-Velocity Scanning	57 IRE 7.S2	45 997 Jul
Ground Equalizer Inductors	48 IRE 2,11,15.S1	Separate	Hold	57 IRE 7.S2	45 997 Jul
Ground Noise	51 IRE 6.S1	39 519 May	Holding Beam	50 IRE 8.S1	39 274 Mar
Ground-Position Indicator	49 IRE 12.S1	37 1368 Dec	Hole	54 IRE 7.S2	42 1506 Oct
Ground Return (Radar)	54 IRE 12.S1	43 200 Feb	Homing	54 IRE 12.S1	43 201 Feb
Ground Speed	54 IRE 12.S1	43 200 Feb	Horizontal Ring Induction Furnace	55 IRE 10.S1	43 1071 Sep
Ground Surveillance Radar	49 IRE 12.S1	37 1368 Dec	Horizontally Polarized Wave	50 IRE 24.S1	38 1266 Nov
Ground System of an Antenna	48 IRE 2,11,15.S1	Separate	Horn Loudspeaker	51 IRE 6.S1	39 519 May
Ground Wave	50 IRE 24.S1	38 1266 Nov	Horn Mouth	51 IRE 6.S1	39 519 May
Grounded-Cathode Amplifier	48 IRE 2,11,15.S1	Separate	Horn Radiator	48 IRE 2,11,15.S1	Separate
Grounded-Grid Amplifier	48 IRE 2,11,15.S1	Separate	Horn Throat	51 IRE 6.S1	39 519 May
Grounded-Plate Amplifier	48 IRE 2,11,15.S1	Separate	Hot Cathode	57 IRE 7.S2	45 997 Jul
Grouping (in Recording)	51 IRE 6.S1	39 519 May	Hot-Cathode Tube	57 IRE 7.S2	45 997 Jul
Grouping (in Facsimile)	56 IRE 9.S1	44 778 Jne	Hot-Wire Microphone	51 IRE 6.S1	39 519 May
Group Velocity	50 IRE 24.S1	38 1266 Nov	Hue	55 IRE 22.S1	43 746 Jne
Guard Circle	51 IRE 6.S1	39 519 May	Hum	52 IRE 17.S1	40 1683 Dec
Guided Wave	50 IRE 24.S1	38 1266 Nov	Hum Modulation	52 IRE 17.S1	40 1683 Dec
	H		Hybrid Electromagnetic Wave	53 IRE 2.S1	41 1727 Dec
H	54 IRE 12.S1	43 208 Feb	Hybrid Junction	55 IRE 2.S1	43 1074 Sep
H and D Curve	51 IRE 6.S1	39 519 May	Hybrid Tee	55 IRE 2.S1	43 1074 Sep
H-Display	54 IRE 12.S1	43 201 Feb	Hydrophone	51 IRE 6.S1	39 519 May
H Network	50 IRE 4.S1	39 27 Jan	Hyperbolic Flare-Out	54 IRE 12.S1	43 201 Feb
H-plane Bend	55 IRE 2.S1	43 1074 Sep	Hysteresis (of an Oscillation)	57 IRE 7.S2	45 997 Jul
H-plane Tee Junction	55 IRE 2.S1	43 1074 Sep	Hysteresis (Radiation-Counter)	57 IRE 7.S2	45 997 Jul
Half Adder	56 IRE 8.S1	44 1170 Sep	Hysteresis Heater	55 IRE 10.S1	43 1071 Sep

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
	I		Inscriber	50 IRE 8.S1	39 274 Mar
ICI	55 IRE 22.S1	43 746 Jne	Insert Earphones	51 IRE 6.S1	39 519 May
ICW	48 IRE 2,11,15.S1	Separate	Insertion Gain	54 IRE 3.S1	42 1110 Jul
I-Display (also I-Scan or I-Scope)	54 IRE 12.S1	43 201 Feb	Insertion Gain	51 IRE 20.S2	39 899 Aug
IF	52 IRE 17.S1	40 1683 Dec	Insertion Gain	57 IRE 7.S2	45 998 Jul
I.L.S. (Instrument-Landing-System)	54 IRE 12.S1	43 208 Feb	Insertion Loss	57 IRE 7.S2	45 998 Jul
IR	54 IRE 12.S1	43 201 Feb	Insertion Loss (General)	51 IRE 20.S2	39 899 Aug
Iconoscope	57 IRE 7.S2	45 997 Jul	Insertion Loss (General)	54 IRE 3.S1	42 1111 Jul
Ideal Noise Diode	57 IRE 7.S2	45 997 Jul	Insertion Loss (Waveguide)	53 IRE 2.S1	41 1723 Dec
Ideal Transducer	51 IRE 20.S2	39 898 Aug	Insertion Power Gain	50 IRE 7.S1	38 434 Apr
Ideal Transducer	54 IRE 3.S1	42 1110 Jul	Insertion Voltage Gain	57 IRE 7.S2	45 998 Jul
Ideal Transformer	54 IRE 3.S1	42 1110 Jul	Instantaneous Automatic Gain Control	54 IRE 12.S1	43 201 Feb
Identification	54 IRE 12.S1	43 201 Feb	Instantaneous Companding	53 IRE 11.S1	41 613 May
Ignitor	57 IRE 7.S2	45 997 Jul	Instantaneous Frequency	53 IRE 11.S1	41 613 May
Ignitor Current	57 IRE 7.S2	45 997 Jul	Instantaneous Power Output	48 IRE 2,11,15.S1	Separate
Ignitor-Current Temperature Drift	57 IRE 7.S2	45 997 Jul	Instantaneous Recording	51 IRE 6.S1	39 519 May
Ignitor Discharge	57 IRE 7.S2	45 997 Jul	Instantaneous Sampling	53 IRE 11.S1	41 613 May
Ignitor Electrode	57 IRE 7.S2	45 997 Jul	Instantaneous Sound Pressure	51 IRE 6.S1	39 519 May
Ignitor Firing Time	57 IRE 7.S2	45 997 Jul	Instruction	56 IRE 8.S1	44 1170 Sep
Ignitor Interaction	57 IRE 7.S2	45 997 Jul	Instruction Code	56 IRE 8.S1	44 1170 Sep
Ignitor Leakage Resistance	57 IRE 7.S2	45 997 Jul	Instrument Approach	54 IRE 12.S1	43 201 Feb
Ignitor Oscillation	57 IRE 7.S2	45 997 Jul	Instrument Approach System	54 IRE 12.S1	43 201 Feb
Ignitor Voltage Drop	57 IRE 7.S2	45 997 Jul	Instrument Landing System	54 IRE 12.S1	43 201 Feb
Illuminance	55 IRE 22.S1	43 746 Jne	Instrumental Error (in Navigation)	54 IRE 12.S1	43 201 Feb
Image Converter Tube	57 IRE 7.S2	45 997 Jul	Integrating Network	53 IRE 11.S1	41 613 May
Image Dissector Tube	57 IRE 7.S2	45 997 Jul	Integrator	56 IRE 8.S1	44 1170 Sep
Image Frequency	52 IRE 17.S1	40 1683 Dec	Intelligence Bandwidth	48 IRE 2,11,15.S1	Separate
Image Ionoscope	57 IRE 7.S2	45 997 Jul	Intensifier Electrode	57 IRE 7.S2	45 998 Jul
Image Orthicon	57 IRE 7.S2	45 997 Jul	Intensity Level	51 IRE 6.S1	39 519 May
Image Ratio	52 IRE 17.S1	40 1683 Dec	Intensity Modulation	54 IRE 12.S1	43 201 Feb
Image Tube	57 IRE 7.S2	45 997 Jul	Interaction Circuit Phase Velocity	57 IRE 7.S2	45 998 Jul
Impedance	57 IRE 7.S2	45 997 Jul	Interaction Gap	57 IRE 7.S2	45 998 Jul
Impedance Compensator	42 IRE 9.S1	Separate	Interaction Impedance	57 IRE 7.S2	45 998 Jul
Imperfection	54 IRE 7.S2	42 1506 Oct	Interaction Space	57 IRE 7.S2	45 998 Jul
Improvement Threshold	53 IRE 11.S1	41 613 May	Intercarrier Sound	52 IRE 17.S1	40 1683 Dec
Impulse Excitation	48 IRE 2,11,15.S1	Separate	Interdigital Magnetron	57 IRE 7.S2	45 998 Jul
Impulse Noise	48 IRE 2,11,15.S1	Separate	Interelectrode Capacitance	57 IRE 7.S2	45 998 Jul
Impurity (Chemical)	54 IRE 7.S2	42 1506 Oct	Interelectrode Transadmittance	57 IRE 7.S2	45 998 Jul
Impurity, Acceptor	54 IRE 7.S2	42 1506 Oct	Interelectrode Transconductance	57 IRE 7.S2	45 998 Jul
Impurity, Donor	54 IRE 7.S2	42 1507 Oct	Interference (General)	52 IRE 17.S1	40 1683 Dec
Impurity, Stoichiometric	54 IRE 7.S2	42 1507 Oct	Interference (Induction Heating)	55 IRE 10.S1	43 1071 Sep
Incident Wave	50 IRE 24.S1	38 1266 Nov	Interference Guard Bands	48 IRE 2,11,15.S1	Separate
Incident Wave	53 IRE 2.S1	41 1723 Dec	Interlaced Scanning	55 IRE 23.S1	43 620 May
Incoherent Scattering	50 IRE 24.S1	38 1266 Nov	Intermediate Frequency	52 IRE 17.S1	40 1683 Dec
Index of Cooperation (in Facsimile)	56 IRE 9.S1	44 778 Jne	Intermediate-Frequency-Harmonic Interference	52 IRE 17.S1	40 1683 Dec
Indicated Course Error	54 IRE 12.S1	43 201 Feb	Intermediate-Frequency Interference Ratio	52 IRE 17.S1	40 1683 Dec
Indicator Tube	57 IRE 7.S2	45 997 Jul	Intermediate-Frequency Response Ratio	52 IRE 17.S1	40 1683 Dec
Indirectly Heated Cathode	57 IRE 7.S2	45 997 Jul	Intermediate Subcarrier	53 IRE 11.S1	41 613 May
Induced Current	55 IRE 10.S1	43 1071 Sep	Intermittent-Duty Rating	48 IRE 2,11,15.S1	Separate
Induction-Conduction Heater	55 IRE 10.S1	43 1071 Sep	Intermodulation	52 IRE 17.S1	40 1683 Dec
Induction Heating	55 IRE 10.S1	43 1071 Sep	Internal Correction Voltage	57 IRE 7.S2	45 998 Jul
Induction Loudspeaker	51 IRE 6.S1	39 519 May	Interrogation	54 IRE 12.S1	43 201 Feb
Induction Ring Heater	55 IRE 10.S1	43 1071 Sep	Interrogator	54 IRE 12.S1	43 201 Feb
Inductive Neutralization	48 IRE 2,11,15.S1	Separate	Interrogator-Responder	54 IRE 12.S1	43 201 Feb
Infection-Point Emission Current	57 IRE 7.S2	45 997 Jul	Interval	51 IRE 6.S1	39 519 May
Infrasonic Frequency	51 IRE 6.S1	39 519 May	Intrinsic Properties	54 IRE 7.S2	42 1507 Oct
Inhibiting Input	56 IRE 8.S1	44 1170 Sep	Intrinsic Temperature Range	54 IRE 7.S2	42 1507 Oct
Initial Ionizing Event	57 IRE 7.S2	45 998 Jul	Inverse Electrode Current	57 IRE 7.S2	45 998 Jul
Ink Vapor Recording	56 IRE 9.S1	44 778 Jne	Inverse Limiter	53 IRE 11.S1	41 613 May
Input Capacitance	57 IRE 7.S2	45 998 Jul	Ionic-Heated Cathode	57 IRE 7.S2	45 998 Jul
Input Equipment (in Computers)	50 IRE 8.S1	39 274 Mar	Ionic-Heated-Cathode Tube	57 IRE 7.S2	45 998 Jul
Input Gap	57 IRE 7.S2	45 998 Jul	Ionization Current	57 IRE 7.S2	45 998 Jul
Input Impedance	54 IRE 3.S1	42 1110 Jul			
Input Impedance (of a Transmission Line)	53 IRE 2.S1	41 1723 Dec			

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Ionization Time	57 IRE 7.S2	45 998 Jul	Leading Edge	55 IRE 23.S1	43 620 May
Ionizing Event	57 IRE 7.S2	45 998 Jul	Leading Edge Pulse Time	51 IRE 20.S1	39 625 Jne
Ionosphere	50 IRE 24.S1	38 1266 Nov	Leading Edge Pulse Time	55 IRE 23.S1	43 621 May
Ionospheric Error	54 IRE 12.S1	43 201 Feb	Leakage Power	57 IRE 7.S2	45 998 Jul
Ionospheric Height Error	54 IRE 12.S1	43 201 Feb	Leakage Radiation	48 IRE 2,11,15.S1	Separate
Ionospheric Wave	50 IRE 24.S1	38 1266 Nov	Left-Handed Polarized Wave	50 IRE 24.S1	38 1266 Nov
Ion Spot	50 IRE 7.S1	38 434 Apr	Length of Scanning Line	42 IRE 9.S1	Separate
Ion Spot (Camera Tube)	57 IRE 7.S2	45 998 Jul	Lens	48 IRE 2,11,15.S1	Separate
Ion Spot (Picture Tube)	57 IRE 7.S2	45 998 Jul	Level (in Audio)	54 IRE 3.S1	42 1111 Jul
Iris	55 IRE 2.S1	43 1074 Sep	Level (in Charge-Storage Tubes)	57 IRE 7.S2	45 998 Jul
			Level (in Television)	55 IRE 23.S1	43 621 May
			Level Above Threshold	51 IRE 6.S1	39 520 May
J			Lifetime, Volume	54 IRE 7.S2	42 1507 Oct
J Antenna	48 IRE 2,11,15.S1	Separate	Light	55 IRE 22.S1	43 746 Jne
J-Display	54 IRE 12.S1	43 201 Feb	Light-Beam Pickup	51 IRE 6.S1	39 520 May
Jitter	54 IRE 12.S1	43 201 Feb	Light Carrier Injection	56 IRE 9.S1	44 778 Jne
Jitter (in Facsimile)	56 IRE 9.S1	44 778 Jne	Light-Microsecond	54 IRE 12.S1	43 201 Feb
Johnson Noise	57 IRE 7.S2	45 998 Jul	Light Modulation	42 IRE 9.S1	Separate
Jump	56 IRE 8.S1	44 1170 Sep	Light Modulator	51 IRE 6.S1	39 520 May
Junction	54 IRE 7.S2	42 1507 Oct	Light Value	51 IRE 6.S1	39 520 May
Junction, Alloy	54 IRE 7.S2	42 1507 Oct	Limited Signal	54 IRE 12.S1	43 201 Feb
Junction, Collector	54 IRE 7.S2	42 1507 Oct	Limited Stability	53 IRE 4.S1	42 555 Mar
Junction, Diffused	54 IRE 7.S2	42 1507 Oct	Limiter	48 IRE 2,11,15.S1	Separate
Junction, Doped	54 IRE 7.S2	42 1507 Oct	Limiter	52 IRE 17.S1	40 1683 Dec
Junction Emitter	54 IRE 7.S2	42 1507 Oct	Limiting	52 IRE 17.S1	40 1683 Dec
Junction, Fused	54 IRE 7.S2	42 1507 Oct	Line Frequency	55 IRE 23.S1	43 621 May
Junction, Grown	54 IRE 7.S2	42 1507 Oct	Line Hydrophone	51 IRE 6.S1	39 520 May
Junction, N-N	54 IRE 7.S2	42 1507 Oct	Line Microphone	51 IRE 6.S1	39 520 May
Junction, P-N	54 IRE 7.S2	42 1507 Oct	Line of Position	54 IRE 12.S1	43 202 Feb
Junction, P-P	54 IRE 7.S2	42 1507 Oct	Line or Trace	57 IRE 7.S2	45 998 Jul
Junction Point	50 IRE 4.S1	38 27 Jan	Line Stretcher	55 IRE 2.S1	43 1074 Sep
Junction, Rate-Grown	54 IRE 7.S2	42 1507 Oct	Linear Array	48 IRE 2,11,15.S1	Separate
Just Scale	51 IRE 6.S1	39 519 May	Linear Power Amplifier	48 IRE 2,11,15.S1	Separate
			Linear Rectifier	48 IRE 2,11,15.S1	Separate
K			Linear Transducer	51 IRE 20.S2	39 898 Aug
K-Display	54 IRE 12.S1	43 201 Feb	Linear Varying-Parameter Network	53 IRE 4.S1	42 555 Mar
Keep-Alive	57 IRE 7.S2	45 998 Jul	Linearity Region	54 IRE 12.S1	43 202 Feb
Keep-Alive Circuit	54 IRE 12.S1	43 201 Feb	Linearly Polarized Wave	50 IRE 24.S1	38 1266 Nov
Kendall Effect	56 IRE 9.S1	44 778 Jne	Lin-Log Receiver	54 IRE 12.S1	43 202 Feb
Keyer	48 IRE 2,11,15.S1	Separate	Lip Microphone	51 IRE 6.S1	39 520 May
Keying	53 IRE 11.S1	41 613 May	Live Room	51 IRE 6.S1	39 520 May
Kink	54 IRE 12.S1	43 201 Feb	Load (General)	54 IRE 3.S1	42 1111 Jul
Knee of Transfer Characteristic	57 IRE 7.S2	45 998 Jul	Load (Induction Heating)	55 IRE 10.S1	43 1071 Sep
			Load (of a Tube)	57 IRE 7.S2	45 999 Jul
			Load (Dynamic) Characteristic	57 IRE 7.S2	45 999 Jul
L			Load Circuit (Induction Heating)	55 IRE 10.S1	43 1071 Sep
LANAC (Laminar Navigation, Anti-Collision)	54 IRE 12.S1	43 208 Feb	Load Circuit (in Transmitters)	48 IRE 2,11,15.S1	Separate
L-Display	54 IRE 12.S1	43 201 Feb	Load-Circuit Efficiency (Induction Heating)	55 IRE 10.S1	43 1071 Sep
L Network	50 IRE 4.S1	38 27 Jan	Load-Circuit Efficiency	48 IRE 2,11,15.S1	Separate
LOP	54 IRE 12.S1	43 202 Feb	Load-Circuit Power Input (Transmitters)	48 IRE 2,11,15.S1	Separate
Lacquer Disks	51 IRE 6.S1	39 520 May	Load Coil	55 IRE 10.S1	43 1071 Sep
Lacquer Original	51 IRE 6.S1	39 520 May	Load Impedance	54 IRE 3.S1	42 1111 Jul
Lacquer Recording	51 IRE 6.S1	39 520 May	Load Impedance Diagram	57 IRE 7.S2	45 999 Jul
Ladder Network	50 IRE 4.S1	38 28 Jan	Load Leads	55 IRE 10.S1	43 1071 Sep
Lag	57 IRE 7.S2	45 998 Jul	Load Matching	55 IRE 10.S1	43 1071 Sep
Lambert	55 IRE 22.S1	43 746 Jne	Load Matching Network	55 IRE 10.S1	43 1071 Sep
Laminated Record	51 IRE 6.S1	39 520 May	Load Matching Switch	55 IRE 10.S1	43 1071 Sep
Landing, Poor	57 IRE 7.S2	45 998 Jul	Load Switch	55 IRE 10.S1	43 1071 Sep
Land	51 IRE 6.S1	39 520 May	Load Transfer Switch	55 IRE 10.S1	43 1071 Sep
Lane	54 IRE 12.S1	43 201 Feb	Loaded Applicator Impedance	55 IRE 10.S1	43 1071 Sep
Language	56 IRE 8.S1	44 1170 Sep	Loaded Impedance	51 IRE 6.S1	39 520 May
Lapel Microphone	51 IRE 6.S1	39 520 May	Loaded Q	57 IRE 7.S2	45 999 Jul
Lateral Recording	51 IRE 6.S1	39 520 May	Lobe Switching	54 IRE 12.S1	43 202 Feb
Lattice	54 IRE 12.S1	43 201 Feb			
Lattice Network	50 IRE 4.S1	38 28 Jan			
Lead-In Groove	51 IRE 6.S1	39 520 May			
Lead-Out Groove	51 IRE 6.S1	39 520 May			
Lead-Over Groove	51 IRE 6.S1	39 520 May			
Leader Cable	54 IRE 12.S1	43 201 Feb			

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Maximum Keying Frequency (Facsimile)	56 IRE 9.S1	44 778 Jne	Modulating Signal	52 IRE 17.S1	40 1684 Dec
Maximum Modulating Frequency (Facsimile)	56 IRE 9.S1	44 778 Jne	Modulating Wave Modulation	53 IRE 11.S1	41 613 May
Maximum Output	52 IRE 17.S1	40 1683 Dec	Modulation Modulation	52 IRE 17.S1	40 1684 Dec
Maximum Sensitivity	52 IRE 17.S1	40 1683 Dec	Modulation Capability	48 IRE 2,11,15.S1	Separate
Maximum Sound Pressure	51 IRE 6.S1	39 521 May	Modulation Factor	53 IRE 11.S1	41 613 May
Maximum System Deviation	52 IRE 17.S1	40 1683 Dec	Modulation Factor	52 IRE 17.S1	40 1684 Dec
Maximum Usable Frequency	50 IRE 24.S1	38 1266 Nov	Modulation Index	53 IRE 11.S1	41 614 May
Maximum Undistorted Output	52 IRE 17.S1	40 1684 Dec	Modulation Noise	51 IRE 6.S1	39 522 May
MCW	48 IRE 2,11,15.S1	Separate	Modulated Amplifier	48 IRE 2,11,15.S1	Separate
M-Display	54 IRE 12.S1	43 202 Feb	Modulator	53 IRE 11.S1	41 614 May
Mean Free Path	51 IRE 6.S1	39 521 May	Moire	57 IRE 7.S2	45 999 Jul
Mean Pulse Time	51 IRE 20.S1	39 625 Jne	Moire	55 IRE 22.S1	43 747 Jne
Mechanical Phonograph Recorder	51 IRE 6.S1	39 521 May	Mold	51 IRE 6.S1	39 522 May
Mechanical Transmission System	51 IRE 6.S1	39 521 May	Monochromatic	55 IRE 22.S1	43 747 Jne
Meissner Oscillator	48 IRE 2,11,15.S1	Separate	Monochrome	55 IRE 22.S1	43 747 Jne
Mel	51 IRE 6.S1	39 522 May	Monochrome Signal	55 IRE 22.S1	43 747 Jne
Melting Channel	55 IRE 10.S1	43 1071 Sep	Monochrome Transmission	55 IRE 22.S1	43 747 Jne
Memory	56 IRE 8.S1	44 1171 Sep	Monoscope	57 IRE 7.S2	45 999 Jul
Memory Capacity	50 IRE 8.S1	39 274 Mar	Monoscope	52 IRE 17.S1	40 1684 Dec
Memory Capacity	56 IRE 8.S1	44 1171 Sep	Motional Impedance	51 IRE 6.S1	39 522 May
Memory Circulating	50 IRE 8.S1	39 274 Mar	Motor Effect	55 IRE 10.S1	43 1071 Sep
Memory, Delay-Line	50 IRE 8.S1	39 274 Mar	Motor Field Induction Heater	55 IRE 10.S1	43 1071 Sep
Memory, Electrostatic	50 IRE 8.S1	39 274 Mar	Mount	57 IRE 7.S2	45 999 Jul
Memory Tube	57 IRE 7.S2	45 999 Jul	Moving-Coil Loudspeaker	51 IRE 6.S1	39 522 May
Memory Tube, Electrostatic	50 IRE 8.S1	39 274 Mar	Moving-Coil Microphone	51 IRE 6.S1	39 522 May
Mercury Arc Converter, Pool Cathode	55 IRE 10.S1	43 1071 Sep	Moving-Coil Pickup	51 IRE 6.S1	39 522 May
Mercury Hydrogen Spark Gap Converter	55 IRE 10.S1	43 1071 Sep	Moving-Conductor Loudspeaker	51 IRE 6.S1	39 522 May
Mercury Vapor Tube	57 IRE 7.S2	45 999 Jul	Moving-Conductor Microphone	51 IRE 6.S1	39 522 May
Mesh	50 IRE 4.S1	38 28 Jan	Moving Target Indicator (MTI)	54 IRE 12.S1	43 202 Feb
MEW (Microwave Early Warning)	54 IRE 12.S1	43 208 Feb	MTI	54 IRE 12.S1	43 202 Feb
Microbar	51 IRE 6.S1	39 522 May	MTI Subclutter Visibility	54 IRE 12.S1	43 202 Feb
Microphone	51 IRE 6.S1	39 522 May	MTI Target Visibility	54 IRE 12.S1	43 202 Feb
Microphone	52 IRE 17.S1	40 1684 Dec	MTR (Multiple Track Range)	54 IRE 12.S1	43 208 Feb
Microphonism	57 IRE 7.S2	45 999 Jul	Mu-(μ) Factor	57 IRE 7.S2	45 1000 Jul
Middle Marker	54 IRE 12.S1	43 208 Feb	Multicavity Magnetron	51 IRE 7.S2	45 1000 Jul
Minimum Distance	54 IRE 12.S1	43 202 Feb	Multicellular Horn	51 IRE 6.S1	39 522 May
Minimum Firing Power	57 IRE 7.S2	45 999 Jul	Multichannel Radio Transmitter	48 IRE 2,11,15.S1	Separate
Minor Cycle	56 IRE 8.S1	44 1171 Sep	Multielectrode Tube	57 IRE 7.S2	45 1000 Jul
Minor Lobe	48 IRE 2,11,15.S1	Separate	Multifrequency Transmitter	48 IRE 2,11,15.S1	Separate
Minority Carrier	54 IRE 7.S2	42 1507 Oct	Multipath	56 IRE 9.S1	44 779 Jne
Mistake	56 IRE 8.S1	44 1171 Sep	Multipath Transmission (Multipath)	56 IRE 9.S1	44 779 Jne
Mixed Highs	55 IRE 22.S1	43 747 Jne	Multiple-Address	50 IRE 8.S1	39 274 Mar
Mixer	51 IRE 6.S1	38 522 May	Multiple-Address Code	56 IRE 8.S1	44 1171 Sep
Mixer Tube	57 IRE 7.S2	45 999 Jul	Multiple Course	54 IRE 12.S1	43 202 Feb
Mixing Point	55 IRE 26.S2	44 108 Jan	Multiple Modulation	53 IRE 11.S1	41 614 May
Mobile Transmitter	48 IRE 2,11,15.S1	Separate	Multiple Sound Track	51 IRE 6.S1	39 522 May
Mobility	54 IRE 7.S2	42 1507 Oct	Multiple Spot Scanning	56 IRE 9.S1	44 779 Jne
Mobility, Hall	54 IRE 7.S2	42 1507 Oct	Multiple Tube Counts	57 IRE 7.S2	45 1000 Jul
Mode	57 IRE 7.S2	45 999 Jul	Multiple-Tuned Antenna	48 IRE 2,11,15.S1	Separate
Mode Filter	55 IRE 2.S1	43 1074 Sep	Multiple-Unit Tube	57 IRE 7.S2	45 1000 Jul
Mode of an Oscillator	57 IRE 7.S2	45 999 Jul	Multiplex Radio Transmission	48 IRE 2,11,15.S1	Separate
Mode of Propagation	53 IRE 2.S1	41 1723 Dec	Multiplication Point	56 IRE 26.S2	44 108 Jan
Mode Purity	57 IRE 7.S2	45 999 Jul	Multiplier	56 IRE 8.S1	44 1171 Sep
Mode of Resonance	53 IRE 2.S1	41 1723 Dec	Multiplier Phototube	57 IRE 7.S2	45 1000 Jul
Mode Separation	57 IRE 7.S2	45 999 Jul	Multisegment Magnetron	57 IRE 7.S2	45 1000 Jul
Mode Transducer	53 IRE 2.S1	41 1723 Dec	Multitrack Recording System	51 IRE 6.S1	39 522 May
Mode Transducer	51 IRE 20.S2	39 898 Aug	Multivibrator	48 IRE 2,11,15.S1	Separate
Mode Transformer	51 IRE 20.S2	39 898 Aug	Musa Antenna	48 IRE 2,11,15.S1	Separate
Moder	49 IRE 12.S1	37 1369 Dec	Musical Echo	51 IRE 6.S1	39 522 May
Modes, Degenerate	57 IRE 7.S2	45 999 Jul			
Modified Index of Refraction	50 IRE 24.S1	38 1266 Nov	N		
Modulated Wave	48 IRE 2,11,15.S1	Separate	Narrow-Band Axis	55 IRE 22.S1	43 747 Jne
Modulating Electrode	50 IRE 7.S1	38 435 Apr	Navaglobe	54 IRE 12.S1	43 209 Feb
			Navar	54 IRE 12.S1	43 209 Feb

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Nava-Rho	54 IRE 12.S1	43 209 Feb	Octonary	56 IRE 8.S1	44 1171 Sep
Navigation	54 IRE 12.S1	43 202 Feb	Off Center PPI	54 IRE 12.S1	43 202 Feb
			Offset Angle	51 IRE 6.S1	39 523 May
Navigation Co-ordinate	54 IRE 12.S1	43 202 Feb			
Navigation Parameter	54 IRE 12.S1	43 202 Feb	Offset Course Computer	49 IRE 12.S1	37 1369 Dec
N-Display	54 IRE 12.S1	43 202 Feb	Offset Crossover Characteristic- Deprecated	54 IRE 12.S1	43 202 Feb
Negative Feedback	48 IRE 2,11,15.S1	Separate	Ohmic Contact	54 IRE 7.S2	42 1507 Oct
Negative Modulation	42 IRE 9.S1	Separate	Omnibearing	54 IRE 12.S1	43 202 Feb
			Omnibearing Converter	49 IRE 12.S1	37 1369 Dec
Negative-Resistance Oscillator	48 IRE 2,11,15.S1	Separate			
Negative-Transconductance Oscillator	48 IRE 2,11,15.S1	Separate	Omnibearing-Distance Facility	54 IRE 12.S1	43 203 Feb
Neper	48 IRE 2,11,15.S1	Separate	Omnibearing-Distance Navigation (OBD)	54 IRE 12.S1	43 203 Feb
Network	50 IRE 4.S1	38 28 Jan	Omnibearing Indicator	49 IRE 12.S1	37 1369 Dec
Neutralization	48 IRE 2,11,15.S1	Separate	Omnibearing Selector	49 IRE 12.S1	37 1369 Dec
			Omnidirectional Antenna	48 IRE 2,11,15.S1	Separate
Neutralizing Indicator	48 IRE 2,11,15.S1	Separate			
Neutralizing Voltage	48 IRE 2,11,15.S1	Separate	Omnidirectional Microphone	51 IRE 6.S1	39 523 May
Night Effect	54 IRE 12.S1	43 202 Feb	Omnidirectional Range (Omni- range)	54 IRE 12.S1	43 203 Feb
Node	50 IRE 4.S1	38 28 Jan	Omnidistance	49 IRE 12.S1	37 1369 Dec
Noise	56 IRE 9.S1	44 779 Jne	Omnirange	49 IRE 12.S1	37 1369 Dec
			On-Course Curvature	54 IRE 12.S1	43 203 Feb
Noise	57 IRE 7.S2	45 1000 Jul			
Noise-Current Generator	57 IRE 7.S2	45 1000 Jul	One-Address Code	56 IRE 8.S1	44 1171 Sep
Noise Diode, Ideal	57 IRE 7.S2	45 1000 Jul	Opacity	51 IRE 6.S1	39 523 May
Noise Factor	57 IRE 7.S2	45 1000 Jul	Open Center PPI	54 IRE 12.S1	43 203 Feb
Noise Factor	57 IRE 17.S1	40 1684 Dec	Operand	50 IRE 8.S1	39 274 Mar
			Operating Characteristic	57 IRE 7.S2	45 1001 Jul
Noise Factor, Average	52 IRE 17.S1	40 1684 Dec			
Noise Factor, Average	57 IRE 7.S2	45 1000 Jul	Operation	50 IRE 8.S1	39 274 Mar
Noise Factor, Spot	52 IRE 17.S1	40 1684 Dec	Operation Code	56 IRE 8.S1	44 1171 Sep
Noise Factor, Spot	57 IRE 7.S2	45 1000 Jul	Operation Part	56 IRE 8.S1	44 1171 Sep
Noise Reduction	51 IRE 6.S1	39 522 May	Operation Time	57 IRE 7.S2	45 1001 Jul
			Optical Pattern	51 IRE 6.S1	39 523 May
Noise Temperature	52 IRE 17.S1	40 1684 Dec			
Noise Temperature	57 IRE 7.S2	45 1000 Jul	Optimum Bunching	57 IRE 7.S2	45 1001 Jul
Noise Temperature, Standard	57 IRE 7.S2	45 1000 Jul	Optimum Working Frequency	50 IRE 24.S1	38 1266 Nov
Noise-Voltage Generator	57 IRE 7.S2	45 1001 Jul	Or-Circuit	56 IRE 8.S1	44 1171 Sep
Nominal Band	42 IRE 9.S1	Separate	Order	56 IRE 8.S1	44 1171 Sep
			Ordinary-Wave Component	50 IRE 24.S1	38 1266 Nov
Nominal Line Width	56 IRE 9.S1	44 779 Jne			
Nonlinear Distortion	53 IRE 4.S1	42 555 Mar	Organ	50 IRE 8.S1	39 275 Mar
Nonlinear Distortion	52 IRE 17.S1	40 1684 Dec	Or-Gate	56 IRE 8.S1	44 1171 Sep
Nonlinear Network	53 IRE 4.S1	42 555 Mar	Original Master	51 IRE 6.S1	39 523 May
Nonphysical Primary	55 IRE 22.S1	43 747 Jne	Orthicon	57 IRE 7.S2	45 1001 Jul
			Oscillator	48 IRE 2,11,15.S1	Separate
Nonplanar Network	50 IRE 4.S1	38 28 Jan			
Normalized Admittance	53 IRE 2.S1	41 1723 Dec	Oscillator	52 IRE 17.S1	40 1684 Dec
Normalized Impedance	53 IRE 2.S1	41 1723 Dec	Oscillator Starting Time, Pulsed	52 IRE 20.S1	40 553 May
Normalized Plateau Slope	57 IRE 7.S2	45 1001 Jul	Oscilloscope Tube	57 IRE 7.S2	45 1001 Jul
North-Stabilized PPI	54 IRE 12.S1	43 202 Feb	Outer Marker	54 IRE 12.S1	43 209 Feb
			Output Capacitance	57 IRE 7.S2	45 1001 Jul
Notation, Positional	50 IRE 8.S1	39 274 Mar			
Note	51 IRE 6.S1	39 522 May	Output Equipment	50 IRE 8.S1	39 274 Mar
N-Terminal Network	50 IRE 4.S1	38 28 Jan	Output Gap	57 IRE 7.S2	45 1001 Jul
N-Terminal Pair Network	50 IRE 4.S1	38 28 Jan	Output Impedance	54 IRE 3.S1	42 1111 Jul
Nth Harmonic	53 IRE 4.S1	42 555 Mar	Outscriber	50 IRE 8.S1	39 275 Mar
			Over-All Electrical Efficiency	55 IRE 10.S1	43 1071 Sep
Nullity	50 IRE 4.S1	38 28 Jan			
Number	56 IRE 8.S1	44 1171 Sep	Overbunching	57 IRE 7.S2	45 1001 Jul
Number, Double-Precision	50 IRE 8.S1	39 274 Mar	Overcutting	51 IRE 6.S1	39 523 May
Number of Loops	57 IRE 7.S2	45 1001 Jul	Overflow	56 IRE 8.S1	44 1171 Sep
Number System	56 IRE 8.S1	44 1171 Sep	Over Interrogation Control	54 IRE 12.S1	43 203 Feb
			Overlap X	56 IRE 9.S1	44 779 Jne
Nutating Feed	54 IRE 12.S1	43 202 Feb			
Nutation Field	54 IRE 12.S1	43 202 Feb	Overload Capacity	48 IRE 2,11,15.S1	Separate
No. 1 Mold	51 IRE 6.S1	39 522 May	Overthrow (or Overshoot)	42 IRE 9.S1	Separate
No. 2, No. 3, etc., Master	51 IRE 6.S1	39 522 May	Overtone	51 IRE 6.S1	39 523 May
			Overvoltage	57 IRE 7.S2	45 1001 Jul
O			O Wave	50 IRE 24.S1	38 1266 Nov
OBI (Omnibearing Selector)	54 IRE 12.S1	43 209 Feb			
Oboe	54 IRE 12.S1	43 209 Feb	P		
OBS (Omnibearing Selector)	54 IRE 12.S1	43 209 Feb	Packaged Magnetron	57 IRE 7.S2	45 1001 Jul
Octal	56 IRE 8.S1	44 1171 Sep	Pad Electrode	55 IRE 10.S1	43 1072 Sep
Octave	51 IRE 6.S1	39 522 May	PAR (Precision Approach Radar)	54 IRE 12.S1	43 209 Feb
			Parabolic-Reflector Microphone	51 IRE 6.S1	39 523 May
Octave-Band Pressure Level	51 IRE 6.S1	39 522 May			
Octode	57 IRE 7.S2	45 1001 Jul			

	Standard	PROCEEDINGS Vol Page Mo	Standard	PROCEEDINGS Vol Page Mo
Paraboloidal Reflector	48 IRE 2,11,15.S1	Separate	Phase-Recovery Time	57 IRE 7.S2 45 1001 Jne
Parallel Arithmetic Unit	50 IRE 8.S1	39 275 Mar	Phase-Shift Microphone	51 IRE 6.S1 39 523 May
Parallel Digital Computer	56 IRE 8.S1	44 1171 Sep	Phase-Shift Oscillator	48 IRE 2,11,15.S1 Separate
Parallel Elements	50 IRE 4.S1	39 28 Jan	Phase Shifter Waveguide	55 IRE 2.S1 43 1074 Sep
Parallel (in Computers)	56 IRE 8.S1	44 1171 Sep	Phase-Tuned Tube	57 IRE 7.S2 45 1001 Jul
Parallel Transmission	50 IRE 8.S1	39 275 Mar	Phaser	42 IRE 9.S1 Separate
Parallel Two-Terminal Pair Net-works	50 IRE 4.S1	39 28 Jan	Phase Velocity	50 IRE 24.S1 38 1267 Nov
Parasitic Element	48 IRE 2,11,15.S1	Separate	Phase Velocity	53 IRE 2.S1 41 1724 Dec
Parasitic Oscillations	48 IRE 2,11,15.S1	Separate	Phasing	56 IRE 9.S1 44 779 Jne
Parity Check	57 IRE 8.S1	44 1171 Sep	Phasing Line	42 IRE 9.S1 Separate
Partial	51 IRE 6.S1	39 523 May	Phasing Signal	56 IRE 9.S1 44 779 Jne
Partial Carry	56 IRE 8.S1	44 1171 Sep	Phi (Φ) Polarization	48 IRE 2,11,15.S1 Separate
Partial Velocity	51 IRE 6.S1	39 523 May	Phon	51 IRE 6.S1 39 523 May
Passive Transducer	51 IRE 20.S2	39 898 Aug	Phonograph Pickup	51 IRE 6.S1 39 524 May
Passive Transducer	54 IRE 3.S1	42 1111 Jul	Phosphor	50 IRE 7.S1 38 436 Apr
Path	54 IRE 12.S1	43 203 Feb	Photocathode	57 IRE 7.S2 45 1001 Jul
P-Display	54 IRE 12.S1	43 203 Feb	Photoelectric Emission	57 IRE 7.S2 45 1001 Jul
Peak Alternating Gap Voltage	57 IRE 7.S2	45 1001 Jul	Photographic Emulsion	51 IRE 6.S1 39 524 May
Peak Cathode Current	57 IRE 7.S2	45 1001 Jul	Photographic Recording	42 IRE 9.S1 Separate
Peak Electrode Current	57 IRE 7.S2	45 1001 Jul	Photographic Sound Recorder	51 IRE 6.S1 39 524 May
Peak Forward Anode Voltage	57 IRE 7.S2	45 1001 Jul	Photographic Sound Reproducer	51 IRE 6.S1 39 524 May
Peak Inverse Anode Voltage	57 IRE 7.S2	45 1001 Jul	Photographic Transmission Density	51 IRE 6.S1 39 524 May
Peak Power Output	48 IRE 2,11,15.S1	Separate	Photometry	55 IRE 22.S1 43 747 Jne
Peak Pulse Amplitude	56 IRE 23.S1	43 621 May	Photomultiplier	57 IRE 7.S2 45 1001 Jul
Peak Pulse Amplitude	51 IRE 20.S1	39 625 Jne	Photosensitive Recording	56 IRE 9.S1 44 779 Jne
Peak Pulse Power	52 IRE 20.S1	40 553 May	Phototube	57 IRE 7.S2 45 1001 Jul
Peak Pulse Power Carrier Fre- quency	52 IRE 20.S1	40 553 May	Photovaristor	54 IRE 7.S2 42 1507 Oct
Peak-Signal Level	42 IRE 9.S1	Separate	(Pi) π -Mode	57 IRE 7.S2 45 1002 Jul
Peak Sound Pressure	51 IRE 6.S1	39 523 May	Pi Network	50 IRE 4.S1 39 28 Jan
Pencil Beam	54 IRE 12.S1	43 203 Feb	Pickup	52 IRE 17.S1 40 1684 Dec
Pencil-Beam Antenna	48 IRE 2,11,15.S1	Separate	Pickup Arm	51 IRE 6.S1 39 524 May
Penetration Frequency	50 IRE 24.S1	38 1267 Nov	Pickup Cartridge	51 IRE 6.S1 39 524 May
Pentode	57 IRE 7.S2	45 1001 Jul	Pickup Spectral Characteristic	55 IRE 22.S1 43 747 Jne
Per Cent Hearing Loss	51 IRE 6.S1	39 523 May	Pickup Tube	57 IRE 7.S2 45 1001 Jul
Per Cent Hearing Loss	51 IRE 6.S1	39 523 May	Picture Black (or "Black")	42 IRE 9.S1 Separate
Per Cent Ripple	48 IRE 2,11,15.S1	Separate	Picture Frequencies	56 IRE 9.S1 44 779 Jne
Percentage Modulation	53 IRE 11.S1	41 614 May	Picture Inversion	56 IRE 9.S1 44 779 Jne
Percentage Modulation	52 IRE 17.S1	40 1684 Dec	Picture Signal (Facsimile)	56 IRE 9.S1 44 779 Jne
Percentage Modulation	48 IRE 2,11,15.S1	Separate	Picture Signal (TV)	55 IRE 23.S1 43 621 May
Performance Chart	57 IRE 7.S2	45 1001 Jul	Picture Tube	50 IRE 7.S1 38 436 Apr
Periodic Electromagnetic Wave	50 IRE 24.S1	38 1267 Nov	Picture White (Facsimile)	42 IRE 9.S1 Separate
Periodic Pulse Train	52 IRE 20.S1	40 553 May	Pierce Oscillator	48 IRE 2,11,15.S1 Separate
Permanent Echo	54 IRE 12.S1	43 203 Feb	Pill-Box Antenna	48 IRE 2,11,15.S1 Separate
Permanent Magnet Loudspeaker	51 IRE 6.S1	39 523 May	Pilotage	54 IRE 12.S1 43 203 Feb
Perpendicular Magnetization	51 IRE 6.S1	39 523 May	Pinch Effect	55 IRE 10.S1 43 1072 Sep
Persistence Characteristic	57 IRE 7.S2	45 1001 Jul	PIP	54 IRE 12.S1 43 203 Feb
Persistence Characteristic (Camera Tubes)	57 IRE 7.S2	45 1001 Jul	PIP Matching	54 IRE 12.S1 43 203 Feb
Perveance	57 IRE 7.S2	45 1001 Jul	PIP-Matching Display	54 IRE 12.S1 43 199 Feb
Phantom Target	54 IRE 12.S1	43 203 Feb	Pistonphone	51 IRE 6.S1 39 524 May
Phase Constant	53 IRE 2.S1	41 1724 Dec	Pitch	51 IRE 6.S1 39 524 May
Phase Delay	56 IRE 9.S1	44 779 Jne	Pitch Attitude	49 IRE 12.S1 37 1369 Dec
Phase Deviation	53 IRE 11.S1	41 614 May	Place	56 IRE 8.S1 44 1171 Sep
Phase Distortion	53 IRE 4.S1	42 555 Mar	Plan Position Indicator (PPI)	54 IRE 12.S1 43 203 Feb
Phase Distortion	56 IRE 9.S1	44 779 Jne	Planar Network	50 IRE 4.S1 39 28 Jan
Phase-Frequency Distortion	53 IRE 4.S1	42 555 Mar	Planckian Locus	55 IRE 22.S1 43 747 Jne
Phase-Frequency Distortion	56 IRE 9.S1	44 779 Jne	Plane Earth Factor	50 IRE 24.S1 38 1267 Nov
Phase-Frequency Response Char- acteristic	48 IRE 2,11,15.S1	Separate	Plane of Polarization	50 IRE 24.S1 38 1267 Nov
Phase Localizer	54 IRE 12.S1	43 203 Feb	Plane Polarized Wave	50 IRE 24.S1 38 1267 Nov
Phase-Modulated Transmitter	48 IRE 2,11,15.S1	Separate	Plane Wave	50 IRE 24.S1 38 1267 Nov
Phase Modulation (PM)	53 IRE 11.S1	41 614 May	Plan Position Indicator	49 IRE 12.S1 37 1369 Dec
Phase Modulation	52 IRE 17.S1	40 1684 Dec	Plate	57 IRE 7.S2 45 1002 Jul
Phase-Propagation Ratio	50 IRE 24.S1	38 1267 Nov	Plate Characteristic	57 IRE 7.S2 45 1002 Jul
			Plate Current	57 IRE 7.S2 45 1002 Jul
			Plate (Anode) Efficiency	48 IRE 2,11,15.S1 Separate
			Plate Keying	48 IRE 2,11,15.S1 Separate

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Plate (Anode) Load Impedance	48 IRE 2,11,15.S1	Separate	Pressing	51 IRE 6.S1	39 524 May
Plate (Anode) Modulation	48 IRE 2,11,15.S1	Separate	Pressure Microphone	51 IRE 6.S1	39 524 May
Plate Neutralization	48 IRE 2,11,15.S1	Separate	Pressure Spectrum Level	51 IRE 6.S1	39 524 May
Plate (Anode) Power Input	48 IRE 2,11,15.S1	Separate	Pre-TR Tube	57 IRE 7.S2	45 1002 Jul
Plate (Anode) Pulse Modulation	48 IRE 2,11,15.S1	Separate	PRF (Pulse Repetition Frequency)	54 IRE 12.S1	43 203 Feb
Plate Voltage	57 IRE 7.S2	45 1002 Jul	Primaries	55 IRE 22.S1	43 747 Jne
Plateau	57 IRE 7.S2	45 1002 Jul	Primary-Color Unit	57 IRE 7.S2	45 1002 Jul
Plateau Length	57 IRE 7.S2	45 1002 Jul	Primary Flow	54 IRE 7.S2	42 1507 Oct
Plateau Slope Normalized	57 IRE 7.S2	45 1002 Jul	Primary Radar	54 IRE 12.S1	43 203 Feb
Plateau Slope Relative	57 IRE 7.S2	45 1002 Jul	Prime	57 IRE 7.S2	45 1002 Jul
Playback	51 IRE 6.S1	39 524 May	Priming Speed	57 IRE 7.S2	45 1002 Jul
Plotting Board	50 IRE 8.S1	39 275 Mar	Principal Axis	51 IRE 6.S1	39 525 May
Plumbing	54 IRE 12.S1	43 203 Feb	Principal E Plane	48 IRE 2,11,15.S1	Separate
Plunger, Waveguide	55 IRE 2.S1	43 1074 Sep	Principal H Plane	48 IRE 2,11,15.S1	Separate
PM Erasing Head	51 IRE 6.S1	39 523 May	Problem, Check	50 IRE 8.S1	39 275 Mar
Pneumatic Loudspeaker	51 IRE 6.S1	39 524 May	Problem, Trouble Location	50 IRE 8.S1	39 275 Mar
Poid	51 IRE 6.S1	39 524 May	Program	56 IRE 8.S1	44 1172 Sep
Point	56 IRE 8.S1	44 1171 Sep	Program Level	54 IRE 3.S1	42 1111 Jul
Point, Binary	50 IRE 8.S1	39 275 Mar	Program Signal	54 IRE 3.S1	42 1111 Jul
Point Contact	54 IRE 7.S2	42 1507 Oct	Programmed Check	56 IRE 8.S1	44 1172 Sep
Point, Decimal	50 IRE 8.S1	39 275 Mar	Propagation Constant	53 IRE 2.S1	41 1724 Dec
Point, Radix	50 IRE 8.S1	39 275 Mar	Propagation Constant	50 IRE 24.S1	38 1267 Nov
Polar Grid	49 IRE 12.S1	37 1369 Dec	Propagation Factor	50 IRE 24.S1	38 1267 Nov
Polarization Ellipse	53 IRE 2.S1	41 1724 Dec	Propagation Ratio	50 IRE 24.S1	38 1267 Nov
Polarization Error	54 IRE 12.S1	43 203 Feb	Proportional Counter Tube	57 IRE 7.S2	45 1002 Jul
Polarization Receiving Factor	53 IRE 2.S1	41 1724 Dec	Proportional Region	57 IRE 7.S2	45 1002 Jul
Polarization Unit Vector	53 IRE 2.S1	41 1724 Dec	Proximity Effect	55 IRE 10.S1	43 1072 Sep
Polarity of Picture Signal	55 IRE 23.S1	43 621 May	Pulling Figure (of an Oscillator)	57 IRE 7.S2	45 1002 Jul
Polyplexer	54 IRE 12.S1	43 203 Feb	Pulse	55 IRE 23.S1	43 621 May
Pool Cathode Mercury Arc Converter	55 IRE 10.S1	43 1072 Sep	Pulse	51 IRE 20.S1	39 625 Jne
POPI (Post Office Position Indicator)	54 IRE 12.S1	43 209 Feb	Pulse Amplitude	51 IRE 20.S1	39 625 Jne
Port	57 IRE 7.S2	45 1002 Jul	Pulse Amplitude, Average	51 IRE 20.S1	39 625 Jne
Portable Transmitter	48 IRE 2,11,15.S1	Separate	Pulse Amplitude, Average Absolute	51 IRE 20.S1	39 625 Jne
Porthole	57 IRE 7.S2	45 1002 Jul	Pulse-Amplitude Modulation	51 IRE 20.S1	39 625 Jne
Position	54 IRE 12.S1	43 203 Feb	Pulse Amplitude, Peak	51 IRE 20.S1	39 625 Jne
Position of the Effective Short (Switching Tubes)	56 IRE 7.S3	44 1039 Aug	Pulse Amplitude, RMS	51 IRE 20.S1	39 625 Jne
Positional Crosstalk	57 IRE 7.S2	45 1002 Jul	Pulse Bandwidth	51 IRE 20.S1	39 625 Jne
Positional Notation	56 IRE 8.S1	44 1172 Sep	Pulse, Bidirectional	52 IRE 20.S1	40 553 May
Position of the Effective Short	57 IRE 7.S2	45 1002 Jul	Pulse Carrier	51 IRE 20.S1	39 625 Jne
Positive Feedback	48 IRE 2,11,15.S1	Separate	Pulse, Carrier-Frequency	52 IRE 20.S1	40 553 May
Positive Modulation (Facsimile)	42 IRE 9.S1	Separate	Pulse Code	52 IRE 20.S1	40 553 May
Post Acceleration	57 IRE 7.S2	45 1002 Jul	Pulse Code Modulation	53 IRE 11.S1	41 614 May
Post Waveguide	55 IRE 2.S1	43 1074 Sep	Pulse-Code Modulation	52 IRE 20.S1	40 553 May
Power	57 IRE 7.S2	45 1002 Jul	Pulse Coder	49 IRE 12.S1	37 1369 Dec
Power Amplification	54 IRE 3.S1	42 1111 Jul	Pulse Decay Time	51 IRE 20.S1	39 625 Jne
Power Attenuation	54 IRE 3.S1	42 1111 Jul	Pulse Decay Time	55 IRE 23.S1	43 621 May
Power Carrier-Frequency, Peak Pulse	52 IRE 20.S1	40 553 May	Pulse Delay, Receiver	52 IRE 20.S1	40 553 May
Power Gain	57 IRE 7.S2	45 1002 Jul	Pulse Delay, Transducer	52 IRE 20.S1	40 553 May
Power Gain	54 IRE 3.S1	42 1111 Jul	Pulse Delay, Transmitter	52 IRE 20.S1	40 553 May
Power Gain (of an Antenna)	48 IRE 2,11,15.S1	Separate	Pulse-Demoder (Constant-Delay Discriminator)	54 IRE 12.S1	43 203 Feb
Power Level	54 IRE 3.S1	42 1111 Jul	Pulse Droop	55 IRE 23.S1	43 621 May
Power Loss	54 IRE 3.S1	42 1111 Jul	Pulse Droop	52 IRE 20.S1	40 553 May
Power, Peak Pulse	52 IRE 20.S1	40 553 May	Pulse Duration	55 IRE 23.S1	42 621 May
PPI	54 IRE 12.S1	43 203 Feb	Pulse Duration	51 IRE 20.S1	39 625 Jne
Preamplifier	54 IRE 12.S1	43 203 Feb	Pulse Duration Coder	54 IRE 12.S1	43 203 Feb
Precision	56 IRE 8.S1	44 1172 Sep	Pulse-Duration Discriminator	54 IRE 12.S1	43 203 Feb
Preassociation	57 IRE 7.S2	45 1002 Jul	Pulse-Duration Modulation	53 IRE 11.S1	41 614 May
Pre-Emphasis	51 IRE 6.S1	39 524 May	Pulse-Duration Modulation	51 IRE 20.S1	39 625 Jne
Pre-Emphasis	53 IRE 11.S1	41 614 May	Pulse Duty Factor	51 IRE 20.S1	39 626 Jne
Pre-Emphasis	52 IRE 17.S1	40 1685 Dec	Pulse Flatness, Deviation From	54 IRE 12.S1	43 203 Feb
Pre-Emphasis Network	48 IRE 2,11,15.S1	Separate	Pulse Forming Line	54 IRE 12.S1	43 203 Feb
Preform	51 IRE 6.S1	39 524 May	Pulse Frequency Modulation	52 IRE 20.S1	40 553 May
Preoscillation Current	57 IRE 7.S2	45 1002 Jul	Pulse Frequency Modulation	53 IRE 11.S1	41 614 May

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Pulse Frequency Spectrum	51 IRE 20.S1	39 626 Jne	Purity	55 IRE 22.S1	43 747 Jne
Pulse, Ghost	54 IRE 12.S1	43 203 Feb	Purple Boundary	55 IRE 22.S1	43 747 Jne
Pulse Interleaving	51 IRE 20.S1	39 626 Jne	Push-Pull Currents (Balanced Currents)	53 IRE 2.S1	41 1724 Dec
Pulse Interrogation	52 IRE 20.S1	40 553 May	Push-Pull Microphone	51 IRE 6.S1	39 525 May
Pulse Interval	51 IRE 20.S1	39 626 Jne	Push-Pull Oscillator	48 IRE 2,11,15.S1	Separate
Pulse-Interval Modulation	51 IRE 20.S1	39 626 Jne	Push-Pull Voltages	53 IRE 2.S1	41 1724 Dec
Pulse-Interval Modulation	53 IRE 11.S1	41 614 May	Pushing Figure (of an Oscillator)	57 IRE 7.S2	45 1002 Jul
Pulse Jitter	52 IRE 20.S1	40 553 May	Push-Push Circuit	48 IRE 2,11,15.S1	Separate
Pulse-Length Modulation	51 IRE 20.S1	39 626 Jne	Push-Push Currents	53 IRE 2.S1	41 1724 Dec
Pulse Mode	52 IRE 20.S1	40 553 May	Push-Push Voltages	53 IRE 2.S1	41 1724 Dec
Pulse-Mode Multiplex	52 IRE 20.S1	40 553 May	Pyramidal Horn	48 IRE 2,11,15.S1	Separate
Pulse Mode, Spurious	52 IRE 20.S1	40 553 May	Pythagorean Scale	51 IRE 6.S1	39 525 May
Pulse-Moder	54 IRE 12.S1	43 203 Feb			
Pulse Modulation	52 IRE 20.S1	40 553 May	Q		
Pulse Modulation	53 IRE 11.S1	41 614 May	Quadripole	50 IRE 4.S1	39 28 Jan
Pulse Modulator	48 IRE 2,11,15.S1	Separate	Quadrantal Error	49 IRE 12.S1	37 1369 Dec
Pulse Multiplex	52 IRE 20.S1	40 553 May	Quantization	53 IRE 11.S1	41 614 May
Pulse Packet	54 IRE 12.S1	43 203 Feb	Quantization Distortion	53 IRE 11.S1	41 614 May
Pulse-Phase Modulation	52 IRE 20.S1	40 553 May	Quantization Level	53 IRE 11.S1	41 614 May
Pulse-Position Modulation	53 IRE 11.S1	41 614 May	Quantization Noise	53 IRE 11.S1	41 614 May
Pulse-Position Modulation	51 IRE 20.S1	39 626 Jne	Quantized Pulse Modulation	53 IRE 11.S1	41 614 May
Pulse Power, Carrier-Frequency, Peak	52 IRE 20.S1	40 553 May	Quantum Efficiency	57 IRE 7.S2	45 1002 Jul
Pulse Power, Peak	52 IRE 20.S1	40 553 May	Quenched Spark Gap Converter	55 IRE 10.S1	43 1072 Sep
Pulse, Radio-Frequency	51 IRE 20.S1	39 626 Jne	Quenching	57 IRE 7.S2	45 1002 Jul
Pulse Rate	54 IRE 12.S1	43 203 Feb	Quieting Sensitivity	52 IRE 17.S1	40 1685 Dec
Pulse Regeneration	51 IRE 20.S1	39 626 Jne			
Pulse Repeater (Transponder)	48 IRE 2,11,15.S1	Separate	R		
Pulse Repetition Frequency	54 IRE 12.S1	43 203 Feb	Racon	54 IRE 12.S1	43 209 Feb
Pulse Repetition Frequency	51 IRE 20.S1	39 626 Jne	Radar	54 IRE 12.S1	43 203 Feb
Pulse Repetition Period	51 IRE 20.S1	39 626 Jne	Radar Equation	54 IRE 12.S1	43 203 Feb
Pulse Repetition Rate	51 IRE 20.S1	39 626 Jne	Radar Performance Figure	54 IRE 12.S1	43 203 Feb
Pulse Repetition Rate (PRF)	54 IRE 12.S1	43 203 Feb	Radar Pilotage Equipment	54 IRE 12.S1	43 204 Feb
Pulse Reply	52 IRE 20.S1	40 554 May	Radar Range Equation	54 IRE 12.S1	43 204 Feb
Pulse Rise Time	51 IRE 20.S1	39 626 Jne	Radar Relay	54 IRE 12.S1	43 204 Feb
Pulse Separation	52 IRE 20.S1	40 554 May	Radar Shadow	54 IRE 12.S1	43 204 Feb
Pulse Shaper	52 IRE 20.S1	40 554 May	Radar Transmitter	48 IRE 2,11,15.S1	Separate
Pulse Shaping	52 IRE 20.S1	40 554 May	Radial	54 IRE 12.S1	43 204 Feb
Pulse, Single-Polarity	52 IRE 20.S1	40 554 May	Radial Time Base Display	54 IRE 12.S1	43 204 Feb
Pulse Spacing	51 IRE 20.S1	39 626 Jne	Radial Transmission Line	53 IRE 2.S1	41 1724 Dec
Pulse Spectrum	51 IRE 20.S1	39 626 Jne	Radiance	55 IRE 22.S1	43 747 Jne
Pulse Spike	51 IRE 20.S1	39 626 Jne	Radiant Flux	55 IRE 22.S1	43 747 Jne
Pulse Spike Amplitude	52 IRE 20.S1	40 554 May	Radiant Intensity	55 IRE 22.S1	43 747 Jne
Pulse Tilt	55 IRE 23.S1	43 621 May	Radiant Sensitivity (of a Photo- Tube)	54 IRE 7.S1	42 1277 Aug
Pulse Tilt	52 IRE 20.S1	40 554 May	Radiating Element	48 IRE 2,11,15.S1	Separate
Pulse Time, Leading Edge	51 IRE 20.S1	39 626 Jne	Radiation Counter	57 IRE 7.S2	45 1002 Jul
Pulse Time, Mean	51 IRE 20.S1	39 626 Jne	Radiation-Counter Tube	57 IRE 7.S2	45 1002 Jul
Pulse-Time Modulation	53 IRE 11.S1	41 614 May	Radiation Efficiency	48 IRE 2,11,15.S1	Separate
Pulse-Time Modulation	51 IRE 20.S1	39 626 Jne	Radiation Intensity	48 IRE 2,11,15.S1	Separate
Pulse Time, Trailing Edge	51 IRE 20.S1	39 626 Jne	Radiation Lobe	48 IRE 2,11,15.S1	Separate
Pulse Train	51 IRE 20.S1	39 626 Jne	Radiation Loss	53 IRE 2.S1	41 1724 Dec
Pulse Train, Bidirectional	52 IRE 20.S1	40 554 May	Radiation (Nuclear)	57 IRE 7.S2	45 1002 Jul
Pulse Train, Periodic	52 IRE 20.S1	40 554 May	Radiation Pattern	48 IRE 2,11,15.S1	Separate
Pulse-Train Spectrum	52 IRE 20.S1	40 554 May	Radiation Resistance	48 IRE 2,11,15.S1	Separate
Pulse Train, Undirectional	52 IRE 20.S1	40 554 May	Radio-Autopilot Coupler	49 IRE 12.S1	37 1369 Dec
Pulse Transmitter	48 IRE 2,11,15.S1	Separate	Radio Beacon	54 IRE 12.S1	43 204 Feb
Pulse Undirectional	51 IRE 20.S1	39 626 Jne	Radio Broadcasting	48 IRE 2,11,15.S1	Separate
Pulse Valley	52 IRE 20.S1	40 554 May	Radio Channel	52 IRE 17.S1	40 1685 Dec
Pulse Width	55 IRE 23.S1	43 621 May	Radio Communication Circuit	48 IRE 2,11,15.S1	Separate
Pulse Width	52 IRE 20.S1	40 554 May	Radio Direction Finding	54 IRE 12.S1	43 204 Feb
Pulse-Width Modulation	51 IRE 20.S1	39 626 Jne	Radio Field Strength	50 IRE 24.S1	38 1267 Nov
Pulsed Doppler System	54 IRE 12.S1	43 203 Feb	Radio Frequency	50 IRE 24.S1	38 1267 Nov
Pulsed Oscillator	48 IRE 2,11,15.S1	Separate	Radio Frequency	52 IRE 17.S1	40 1685 Dec
Pulsed Oscillator	52 IRE 20.S1	40 554 May	Radio-Frequency Alternator	48 IRE 2,11,15.S1	Separate
Pulsed-Oscillator Starting Time	52 IRE 20.S1	40 554 May	Radio-Frequency Converter	55 IRE 10.S1	43 1072 Sep
Pulses Equalizing	52 IRE 20.S1	40 554 May			

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Radio-Frequency Generator-Elec- tron Tube Type	55 IRE 10.S1	43 1072 Sep	Recording (in Facsimile)	56 IRE 9.S1	44 779 Jne
Radio-Frequency Pulse	51 IRE 20.S1	39 626 Jne	Recording Loss	51 IRE 6.S1	39 525 May
Radio-Frequency Signal, High Level	57 IRE 7.S2	45 1002 Jul	Recording Spot (in Facsimile)	56 IRE 9.S1	44 779 Jne
Radio-Frequency Signal, Low- Level	57 IRE 7.S2	45 1003 Jul	Recording Stylus	51 IRE 6.S1	39 525 May
Radio Horizon	50 IRE 24.S1	38 1267 Nov	Recovery Time	57 IRE 7.S2	45 1003 Jul
Radio Magnetic Indicator (RMI)	54 IRE 12.S1	43 204 Feb	Recovery Time (ATR Tubes)	56 IRE 7.S3	44 1039 Aug
Radio Navigation	49 IRE 12.S1	37 1370 Dec	Recovery Time (Gas Tubes)	57 IRE 7.S2	45 1003 Jul
Radio Proximity Fuze	48 IRE 2,11,15.S1	Separate	Recovery Time (Geiger-Mueller Counters)	57 IRE 7.S2	45 1003 Jul
Radio Range	54 IRE 12.S1	43 204 Feb	Recovery Time (TR and Pre-TR Tubes)	57 IRE 7.S2	45 1003 Jul
Radio Receiver	52 IRE 17.S1	40 1685 Dec	Rectangular Scanning	48 IRE 2,11,15.S1	Separate
Radio Transmitter	48 IRE 2,11,15.S1	Separate	Rectification Factor	57 IRE 7.S2	45 1003 Jul
Radio Wave Propagation	50 IRE 24.S1	38 1267 Nov	Rectifier	48 IRE 2,11,15.S1	Separate
Radiolocation	54 IRE 12.S1	43 204 Feb	Rectilinear Scanning	42 IRE 9.S1	Separate
Radiophare	54 IRE 12.S1	43 204 Feb	Recurrence Rate	54 IRE 12.S1	43 204 Feb
Radiosonde	48 IRE 2,11,15.S1	Separate	Redistribution	57 IRE 7.S2	45 1003 Jul
Radix	56 IRE 8.S1	44 1172 Sep	Redundancy Check	56 IRE 8.S1	44 1172 Sep
Radix Point	50 IRE 8.S1	39 276 Mar	Reference Black Level	55 IRE 23.S1	43 621 May
Radome	48 IRE 2,11,15.S1	Separate	Reference Direction	49 IRE 12.S1	37 1370 Dec
Radux	54 IRE 12.S1	43 209 Feb	Reference Line	49 IRE 12.S1	37 1370 Dec
Rain Return	54 IRE 12.S1	43 204 Feb	Reference Volume	54 IRE 3.S1	42 1111 Jul
Ramark	54 IRE 12.S1	43 209 Feb	Reference White	55 IRE 22.S1	43 748 Jne
Random Errors	54 IRE 12.S1	43 204 Feb	Reference White Level	55 IRE 23.S1	43 621 May
Random Noise	48 IRE 2,11,15.S1	Separate	Reflected Wave	53 IRE 2.S1	41 1724 Dec
Range	54 IRE 12.S1	43 204 Feb	Reflection Coefficient	53 IRE 2.S1	41 1724 Dec
Range Mark	54 IRE 12.S1	43 204 Feb	Reflection Coefficient (of Trans- mission Medium)	53 IRE 2.S1	41 1724 Dec
Range Resolution	54 IRE 12.S1	43 204 Feb	Reflection Color-Tube	57 IRE 7.S2	45 1003 Jul
Range, Visual-Aural	54 IRE 12.S1	43 204 Feb	Reflection Error	54 IRE 12.S1	43 204 Feb
Range, Visual Radio	54 IRE 12.S1	43 204 Feb	Reflection Loss	53 IRE 2.S1	41 1724 Dec
Rank	50 IRE 4.S1	39 28 Jan	Reflector (Antenna)	48 IRE 2,11,15.S1	Separate
Raster	57 IRE 7.S2	45 1003 Jul	Reflector (in Tubes)	57 IRE 7.S2	45 1003 Jul
Raster Burn	57 IRE 7.S2	45 1003 Jul	Reflex Baffle	51 IRE 6.S1	39 525 May
Rate of Decay	51 IRE 6.S1	39 525 May	Reflex Bunching	57 IRE 7.S2	45 1003 Jul
Ratio	57 IRE 7.S2	45 1003 Jul	Refracted Wave	53 IRE 2.S1	41 1724 Dec
Raydist	54 IRE 12.S1	43 209 Feb	Refracted Wave	50 IRE 24.S1	38 1267 Nov
Rayleigh Disk	51 IRE 6.S1	39 525 May	Refraction Error	54 IRE 12.S1	43 204 Feb
R-C Oscillator	48 IRE 2,11,15.S1	Separate	Refraction Loss	51 IRE 6.S1	39 525 May
RDF-Radio Direction Finding	54 IRE 12.S1	43 204 Feb	Refractive Index	50 IRE 24.S1	38 1267 Nov
Reactance Modulator	48 IRE 2,11,15.S1	Separate	Refractive Modulus	50 IRE 24.S1	38 1267 Nov
Read	56 IRE 8.S1	44 1172 Sep	Regeneration (in Charge-Storage Tubes)	57 IRE 7.S2	45 1003 Jul
Read (in Charge-Storage Tubes)	57 IRE 7.S2	45 1003 Jul	Regeneration (in Computers)	56 IRE 8.S1	44 1172 Sep
Read-Around Number	57 IRE 7.S2	45 1003 Jul	Regeneration (in Transmitters)	48 IRE 2,11,15.S1	Separate
Read-Around Ratio	57 IRE 7.S2	45 1003 Jul	Regenerative Repeater	53 IRE 11.S1	41 614 May
Read Number	57 IRE 7.S2	45 1003 Jul	Region, Geiger-Mueller	57 IRE 7.S2	45 1003 Jul
Reading Speed	57 IRE 7.S2	45 1003 Jul	Region of Limited Proportionality	57 IRE 7.S2	45 1003 Jul
Ready-To-Receive Signal	56 IRE 9.S1	44 779 Jne	Region, Proportional	57 IRE 7.S2	45 1003 Jul
Rebecca	54 IRE 12.S1	43 209 Feb	Register	56 IRE 8.S1	44 1172 Sep
Recalescent Point	55 IRE 10.S1	43 1072 Sep	Register, Delay-Line	50 IRE 8.S1	39 276 Mar
Receiver, Facsimile	56 IRE 9.S1	44 779 Jne	Register Length	56 IRE 8.S1	44 1172 Sep
Receiver Gating	54 IRE 12.S1	43 204 Feb	Register, Static	50 IRE 8.S1	39 276 Mar
Receiver Primaries	55 IRE 22.S1	43 748 Jne	Regulation (Gas Tubes)	57 IRE 7.S2	45 1003 Jul
Receiver Pulse Delay	52 IRE 20.S1	40 554 May	Reignition	57 IRE 7.S2	45 1003 Jul
Receiving Converter, Facsimile (FS to AM Converter)	56 IRE 9.S1	44 779 Jne	Rejection Band	53 IRE 2.S1	41 1724 Dec
Reciprocal Transducer	51 IRE 20.S2	39 989 Aug	Relative Bearing	54 IRE 12.S1	43 204 Feb
Recombination Rate, Surface	54 IRE 7.S2	42 1507 Oct	Relative Course	49 IRE 12.S1	37 1370 Dec
Recombination Rate, Volume	54 IRE 7.S2	42 1507 Oct	Relative Heading	49 IRE 12.S1	37 1370 Dec
Recombination Velocity	54 IRE 7.S2	42 1507 Oct	Relative Luminosity	55 IRE 22.S1	43 748 Jne
Record Medium	56 IRE 9.S1	44 779 Jne	Relative Plateau Slope	57 IRE 7.S2	45 1003 Jul
Record Sheet	56 IRE 9.S1	44 779 Jne	Relative Refractive Index	50 IRE 24.S1	38 1267 Nov
Recorded Spot	56 IRE 9.S1	44 779 Jne	Relative Response	51 IRE 6.S1	39 525 May
Recorded Spot X Dimension	56 IRE 9.S1	44 779 Jne	Relative Velocity	51 IRE 6.S1	39 525 May
Recorded Spot Y Dimension	56 IRE 9.S1	44 779 Jne	Relaxation Oscillator	48 IRE 2,11,15.S1	Separate
Recorder, Facsimile	56 IRE 9.S1	44 779 Jne	Relay Radar	54 IRE 12.S1	43 204 Feb
Recording Channel	51 IRE 6.S1	39 525 May	Remote Control	48 IRE 2,11,15.S1	Separate

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Repeatability	57 IRE 7.S2	45 1003 Jul	Rotary Generator	55 IRE 10.S1	43 1072 Sep
Repeller	57 IRE 7.S2	45 1004 Jul	Rotating Joint	55 IRE 2.S1	43 1074 Sep
Repetition Frequency	54 IRE 12.S1	43 204 Feb	Round-Off	50 IRE 8.S1	39 276 Mar
Repetition Rate	54 IRE 12.S1	43 204 Feb	Round-Off Error	50 IRE 8.S1	39 276 Mar
Repetition Rate, Basic	54 IRE 12.S1	43 204 Feb	Routine	56 IRE 8.S1	44 1172 Sep
Repetition Rate, Specific	54 IRE 12.S1	43 204 Feb	RT Box	54 IRE 12.S1	43 205 Feb
Reply	54 IRE 12.S1	43 204 Feb	Rumble	51 IRE 6.S1	39 525 May
Reply Efficiency, Transponder	54 IRE 12.S1	43 204 Feb	Rumble, Turntable	52 IRE 17.S1	40 1685 Dec
Reproducing Stylus	51 IRE 6.S1	39 525 May		S	
Reproduction Speed	56 IRE 9.S1	44 779 Jne	Sabin	51 IRE 6.S1	39 526 May
Re-Recording	51 IRE 6.S1	39 525 May	Sampling Gate	54 IRE 12.S1	43 205 Feb
Re-Recording System	51 IRE 6.S1	39 525 May	Saturated Signal	54 IRE 12.S1	43 205 Feb
Reset	56 IRE 8.S1	44 1172 Sep	Saturating Signal	54 IRE 12.S1	43 205 Feb
Residual Error	54 IRE 12.S1	43 204 Feb	Saturation	55 IRE 22.S1	43 748 Jne
Resistance	57 IRE 7.S2	45 1004 Jul	SBA (Standard Beam Approach)	54 IRE 12.S1	43 209 Feb
Resolution	49 IRE 12.S1	37 1370 Dec	Scale	51 IRE 6.S1	39 526 May
Resolution	57 IRE 7.S2	45 1004 Jul	Scale Factor	50 IRE 8.S1	39 276 Mar
Resolution, Structural	57 IRE 7.S2	45 1004 Jul	Scanner	56 IRE 9.S1	44 780 Jne
Resolver	50 IRE 8.S1	39 276 Mar	Scanning (Antenna)	48 IRE 2,11,15.S1	Separate
Resolving Power	48 IRE 2,11,15.S1	Separate	Scanning Antenna Mount	48 IRE 2,11,15.S1	Separate
Resolving Time	57 IRE 7.S2	45 1004 Jul	Scanning, High-Velocity	57 IRE 7.S2	45 1004 Jul
Resolving Time	54 IRE 12.S1	43 204 Feb	Scanning (in Facsimile)	56 IRE 9.S1	44 780 Jne
Resonant Gap	57 IRE 7.S2	45 1004 Jul	Scanning (in Navigation Aids)	49 IRE 12.S1	37 1370 Dec
Resonant-Line Oscillator	48 IRE 2,11,15.S1	Separate	Scanning Line Frequency	56 IRE 9.S1	44 780 Jne
Resonant Modes in Cylindrical Cavities	45 IRE 24.S1	Separate	Scanning Line Length	56 IRE 9.S1	44 780 Jne
Resonant Window (Switching Tubes)	56 IRE 7.S3	44 1038 Aug	Scanning Loss	48 IRE 2,11,15.S1	Separate
Resonator Mode	57 IRE 7.S2	45 1004 Jul	Scanning Low-Velocity	57 IRE 7.S2	45 1004 Jul
Resonator, Waveguide	55 IRE 2.S1	43 1074 Sep	Scanning Spot X Dimension	56 IRE 9.S1	44 780 Jne
Responder	54 IRE 12.S1	43 204 Feb	Scanning Spot Y Dimension	56 IRE 9.S1	44 780 Jne
Responder Beacon	54 IRE 12.S1	43 204 Feb	Scatterband	54 IRE 12.S1	43 205 Feb
Response	57 IRE 7.S2	45 1004 Jul	Scattering Loss	51 IRE 6.S1	39 526 May
Retained Image	57 IRE 7.S2	45 1004 Jul	Schottky Emission	57 IRE 7.S2	45 1004 Jul
Retarding-Field (Position-Grid) Oscillator	48 IRE 2,11,15.S1	Separate	Scintillation	54 IRE 12.S1	43 205 Feb
Retention Time, Maximum	57 IRE 7.S2	45 1004 Jul	Scintillation	54 IRE 12.S1	43 205 Feb
Retrace Line	52 IRE 17.S1	40 1685 Dec	Scoring System	51 IRE 6.S1	39 526 May
Return Loss	53 IRE 2.S1	41 1724 Dec	Screen	57 IRE 7.S2	45 1004 Jul
Return Transfer Function	55 IRE 26.S2	44 108 Jan	Screen Grid	57 IRE 7.S2	45 1004 Jul
Reverberation	51 IRE 6.S1	39 525 May	Screen-Grid Characteristic	57 IRE 7.S2	45 1004 Jul
Reverberation Chamber	51 IRE 6.S1	39 525 May	Screen-Grid Current	57 IRE 7.S2	45 1004 Jul
Reverberation Time	51 IRE 6.S1	39 525 May	Screen-Grid Modulation	48 IRE 2,11,15.S1	Separate
Reverberation Time Meter	51 IRE 6.S1	39 525 May	Sea Return	54 IRE 12.S1	43 205 Feb
Reverse Emission	57 IRE 7.S2	45 1004 Jul	Searchlighting	54 IRE 12.S1	43 205 Feb
Rewrite	56 IRE 8.S1	44 1172 Sep	Search Radar	54 IRE 12.S1	43 205 Feb
Rho Theta	54 IRE 12.S1	43 204 Feb	Secondary Emission	57 IRE 7.S2	45 1004 Jul
Rhombic Antenna	48 IRE 2,11,15.S1	Separate	Secondary-Emission Ratio	57 IRE 7.S2	45 1004 Jul
Ribbon Microphone	51 IRE 6.S1	39 525 May	Secondary Grid Emission	57 IRE 7.S2	45 1004 Jul
Rieke Diagram	57 IRE 7.S2	45 1004 Jul	Secondary Radar	54 IRE 12.S1	43 205 Feb
Right-Handed (Clockwise) Polarized Wave	50 IRE 24.S1	38 1267 Nov	Second-Channel Attenuation	52 IRE 17.S1	40 1685 Dec
Ring Around	54 IRE 12.S1	43 205 Feb	Second-Channel Interference	52 IRE 17.S1	40 1685 Dec
Ring Counter	56 IRE 8.S1	44 1172 Sep	Second-Time-Around Echo	54 IRE 12.S1	43 205 Feb
Ring Head	51 IRE 6.S1	39 525 May	Sectionalized Vertical Antenna	48 IRE 2,11,15.S1	Separate
Ring Oscillator	48 IRE 2,11,15.S1	Separate	Sectoral Horn	48 IRE 2,11,15.S1	Separate
Ring Time	54 IRE 12.S1	43 205 Feb	Sector Display	54 IRE 12.S1	43 205 Feb
Ringling (in Facsimile)	56 IRE 9.S1	44 780 Jne	Sector Scanning	48 IRE 2,11,15.S1	Separate
Ringling (in Receivers)	52 IRE 17.S1	40 1685 Dec	Selectance	52 IRE 17.S1	40 1685 Dec
Ripple	52 IRE 17.S1	40 1685 Dec	Selection Check	56 IRE 8.S1	44 1172 Sep
Ripple Voltage	48 IRE 2,11,15.S1	Separate	Selective Fading	50 IRE 24.S1	38 1267 Nov
Rising-Sun Magnetron	57 IRE 7.S2	45 1004 Jul	Selectivity	52 IRE 17.S1	40 1685 Dec
RMI	54 IRE 12.S1	43 205 Feb	Selector Pulse	54 IRE 12.S1	43 205 Feb
RMS (Effective) Pulse Amplitude	51 IRE 20.S1	39 626 Jne	Self-Checking Code	56 IRE 8.S1	44 1172 Sep
Roll Out	50 IRE 8.S1	39 276 Mar	Self-instructed Carry	50 IRE 8.S1	39 276 Mar
Root-Sum Square	52 IRE 17.S1	40 1685 Dec	Self-Pulse Modulation	48 IRE 2,11,15.S1	Separate
			Self-Quenched Counter Tube	57 IRE 7.S2	45 1004 Jul
			Semiconductor	54 IRE 7.S2	42 1507 Oct
			Semiconductor, Compensated	54 IRE 7.S2	42 1507 Oct

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Semiconductor Device	54 IRE 7.S2	42 1507 Oct	Short-Circuit Output Capacitance	57 IRE 7.S2	45 1005 Jul
Semiconductor Device, Multiple Unit	54 IRE 7.S2	42 1507 Oct	Short-Circuit Transfer Admittance	57 IRE 7.S2	45 1005 Jul
Semiconductor Device, Single Unit	54 IRE 7.S2	42 1507 Oct	Short-Circuit Transfer Capacitance	57 IRE 7.S2	45 1005 Jul
Semiconductor, Extrinsic	54 IRE 7.S2	42 1507 Oct	Short-Distance Navigation Aid	54 IRE 12.S1	43 205 Feb
Semiconductor, Intrinsic	54 IRE 7.S2	42 1507 Oct	Shot Noise, Full	57 IRE 7.S2	45 1005 Jul
Semiconductor, N-Type	54 IRE 7.S2	42 1507 Oct	Shot Noise, Reduced	57 IRE 7.S2	45 1005 Jul
Semiconductor P-Type	54 IRE 7.S2	42 1508 Oct	Shot Noise Reduction Factor	57 IRE 7.S2	45 1005 Jul
Semiremote Control	48 IRE 2,11,15.S1	Separate	Shunt-Fed Vertical Antenna	48 IRE 2,11,15.S1	Separate
Semitone	51 IRE 6.S1	39 526 May	Shunt Tee Junction	55 IRE 2.S1	43 1074 Sep
Semitransparent Photocathode	57 IRE 7.S2	45 1004 Jul	Sidebands	53 IRE 11.S1	41 614 May
Sending End Impedance	53 IRE 2.S1	41 1724 Dec	Sidebands	52 IRE 17.S1	40 1685 Dec
Sense	54 IRE 12.S1	43 205 Feb	Sideband Attenuation	48 IRE 2,11,15.S1	Separate
Sensing	54 IRE 12.S1	43 205 Feb	Side Frequency	53 IRE 11.S1	41 614 May
Sensitive Volume	57 IRE 7.S2	45 1004 Jul	Side Thrust	51 IRE 6.S1	39 526 May
Sensitivity	50 IRE 7.S1	38 436 Apr	Sign Digit	56 IRE 8.S1	44 1173 Sep
Sensitivity	52 IRE 17.S1	40 1685 Dec	Signal	54 IRE 3.S1	42 1111 Jul
Sensitivity, Cathode Luminous	57 IRE 7.S2	45 1004 Jul	Signal Contrast (in Facsimile)	56 IRE 9.S1	44 780 Jne
Sensitivity, Cathode Radiant	57 IRE 7.S2	45 1004 Jul	Signal Electrode	50 IRE 7.S1	38 437 Apr
Sensitivity, Illumination	57 IRE 7.S2	45 1004 Jul	Signal Electrode Capacitance	57 IRE 7.S2	45 1005 Jul
Sensitivity, Luminous	57 IRE 7.S2	45 1005 Jul	Signal Frequency Shift	56 IRE 9.S1	44 780 Jne
Sensitivity, Radiant	57 IRE 7.S2	45 1005 Jul	Signal Level	54 IRE 3.S1	42 1111 Jul
Sensitivity Time Control	54 IRE 12.S1	43 205 Feb	Signal Output Current	57 IRE 7.S2	45 1005 Jul
Sensitometry	51 IRE 6.S1	39 526 May	Signal-to-Noise Ratio	48 IRE 2,11,15.S1	Separate
Sensor	54 IRE 12.S1	43 205 Feb	Signal-to-Noise Ratio	57 IRE 7.S2	45 1006 Jul
Separate Parts of a Network	50 IRE 4.S1	38 28 Jan	Signal-Wave Envelope	42 IRE 9.S1	Separate
Separately Instructed Carry	50 IRE 8.S1	39 276 Mar	Significant Digits	50 IRE 8.S1	39 276 Mar
Serial	56 IRE 8.S1	44 1172 Sep	Simple Scanning	56 IRE 9.S1	44 780 Jne
Serial Arithmetic Unit	50 IRE 8.S1	39 276 Mar	Simple Sound Source	51 IRE 6.S1	39 526 May
Serial Digital Computer	56 IRE 8.S1	44 1172 Sep	Simple Target	54 IRE 12.S1	43 205 Feb
Serial Transmission	50 IRE 8.S1	39 276 Mar	Simple Tone	51 IRE 6.S1	39 526 May
Series Elements	50 IRE 4.S1	38 28 Jan	Simplex Operation of a Radio System	48 IRE 2,11,15.S1	Separate
Series Fed Vertical Antenna	48 IRE 2,11,15.S1	Separate	Simulation	50 IRE 8.S1	39 276 Mar
Series Tee Junction	55 IRE 2.S1	43 1074 Sep	Simultaneous Lobing	54 IRE 12.S1	43 205 Feb
Series Two-Terminal Pair Networks	50 IRE 4.S1	38 28 Jan	Sine Wave	48 IRE 2,11,15.S1	Separate
Service Area	54 IRE 12.S1	43 205 Feb	Singing	48 IRE 2,11,15.S1	Separate
Service Band	48 IRE 2,11,15.S1	Separate	Singing Point	48 IRE 2,11,15.S1	Separate
Servomechanism	55 IRE 26.S2	44 109 Jan	Single-Address Code	50 IRE 8.S1	39 276 Mar
Set	56 IRE 8.S1	44 1172 Sep	Single-Address Code	56 IRE 8.S1	44 1173 Sep
Setup	55 IRE 23.S1	43 621 May	Single-Ended Amplifier	48 IRE 2,11,15.S1	Separate
Sexadecimal	56 IRE 8.S1	44 1172 Sep	Single-Polarity Pulse	52 IRE 20.S1	40 554 May
Shading	57 IRE 7.S2	45 1005 Jul	Single Pole-Piece Magnetic Head	51 IRE 6.S1	39 526 May
Shadow Factor	50 IRE 24.S1	38 1267 Nov	Single-Sideband Modulation	53 IRE 11.S1	41 614 May
Shadow Mask	57 IRE 7.S2	45 1005 Jul	Single-Sideband Transmission	48 IRE 2,11,15.S1	Separate
Shaped-Beam Antenna (Phase-Shaped)	48 IRE 2,11,15.S1	Separate	Single-Sideband Transmitter	48 IRE 2,11,15.S1	Separate
Shaping Network	42 IRE 9.S1	Separate	Single-Tone Keying	53 IRE 11.S1	41 615 May
Shaving	51 IRE 6.S1	39 526 May	Single Track	51 IRE 6.S1	39 526 May
Shear Wave	51 IRE 6.S1	39 526 May	Sink (of an Oscillator)	57 IRE 7.S2	45 1006 Jul
Shield	55 IRE 10.S1	43 1072 Sep	Sinusoidal Electro-Magnetic Wave	50 IRE 24.S1	38 1267 Nov
Shield Grid	57 IRE 7.S2	45 1005 Jul	Site Error	54 IRE 12.S1	43 205 Feb
Shielded Pair	53 IRE 2.S1	41 1724 Dec	Skew (in Facsimile)	56 IRE 9.S1	44 780 Jne
Shielded Transmission Line	53 IRE 2.S1	41 1724 Dec	Skiatron	54 IRE 12.S1	43 205 Feb
Shift	56 IRE 8.S1	44 1172 Sep	Skin Depth	53 IRE 2.S1	41 1724 Dec
Shift, Cyclic	50 IRE 8.S1	39 276 Mar	Sky Error	54 IRE 12.S1	43 205 Feb
Shock Excitation	48 IRE 2,11,15.S1	Separate	Sky Wave	50 IRE 24.S1	38 1267 Nov
Shock Motion	51 IRE 6.S1	39 526 May	Sky-Wave Accuracy Pattern	54 IRE 12.S1	43 205 Feb
Shoran (Short Range Navigation)	54 IRE 12.S1	43 209 Feb	Sky-Wave Correction	54 IRE 12.S1	43 205 Feb
Short-Circuit Driving-Point Admittance	57 IRE 7.S2	45 1005 Jul	Sky-Wave Station-Error	54 IRE 12.S1	43 205 Feb
Short-Circuit Feedback Admittance	57 IRE 7.S2	45 1005 Jul	Slant Distance	54 IRE 12.S1	43 206 Feb
Short-Circuit Forward Admittance	57 IRE 7.S2	45 1005 Jul	Slant Range	54 IRE 12.S1	43 206 Feb
Short-Circuit Input Admittance	57 IRE 7.S2	45 1005 Jul	Slave Station	54 IRE 12.S1	43 206 Feb
Short-Circuit Input Capacitance	57 IRE 7.S2	45 1005 Jul	Slave Sweep	54 IRE 12.S1	43 206 Feb
Short-Circuit Output Admittance	57 IRE 7.S2	45 1005 Jul	Sleeve-Dipole Antenna	48 IRE 2,11,15.S1	Separate
			Sleeve Stub	48 IRE 2,11,15.S1	Separate
			Slope	54 IRE 12.S1	43 206 Feb
			Slope Angle	54 IRE 12.S1	43 206 Feb

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Slope Deviation	49 IRE 12.S1	37 1370 Dec	Spurious Radiation	48 IRE 2,11,15.S1	Separate
Slot Antenna	48 IRE 2,11,15.S1	Separate	Spurious Response Ratio	52 IRE 17.S1	40 1685 Dec
Slug Tuner	55 IRE 2.S1	43 1074 Sep	Spurious Tube Counts	57 IRE 7.S2	45 1006 Jul
Slug Tuning	48 IRE 2,11,15.S1	Separate	Sputtering	51 IRE 6.S1	39 528 May
Small-Signal Forward Transadmittance	57 IRE 7.S2	45 1006 Jul	Square Wave	52 IRE 17.S1	40 1685 Dec
Soft Spot	54 IRE 12.S1	43 206 Feb	Square-Wave Response	57 IRE 7.S2	45 1006 Jul
Sonar	54 IRE 12.S1	43 206 Feb	Square-Wave Response Characteristic	57 IRE 7.S2	45 1006 Jul
Sone	51 IRE 6.S1	39 526 May	Squeezable Waveguide	54 IRE 12.S1	43 206 Feb
Sonne	54 IRE 12.S1	43 209 Feb	Squeeze Track	51 IRE 6.S1	39 528 May
Sound	51 IRE 6.S1	39 526 May	Squelch	52 IRE 17.S1	40 1685 Dec
Sound Absorption	51 IRE 6.S1	39 526 May	Squint	54 IRE 12.S1	43 206 Feb
Sound Absorption Coefficient	51 IRE 6.S1	39 526 May	Squitter	54 IRE 12.S1	43 206 Feb
Sound Analyzer	51 IRE 6.S1	39 526 May	SRE (Surveillance Radar Element)	54 IRE 12.S1	43 209 Feb
Sound Articulation	51 IRE 6.S1	39 526 May	Stabilization	54 IRE 12.S1	43 206 Feb
Sound Energy	51 IRE 6.S1	39 526 May	Stabilized Feedback	48 IRE 2,11,15.S1	Separate
Sound-Energy Density	51 IRE 6.S1	39 526 May	Stabilized Flight	54 IRE 12.S1	43 206 Feb
Sound-Energy Flux	51 IRE 6.S1	39 527 May	Stable Element	54 IRE 12.S1	43 206 Feb
Sound Field	51 IRE 6.S1	39 527 May	Stage Efficiency	48 IRE 2,11,15.S1	Separate
Sound Intensity	51 IRE 6.S1	39 527 May	Stagger	56 IRE 9.S1	44 780 Jne
Sound Level	51 IRE 6.S1	39 527 May	Stalo	54 IRE 12.S1	43 206 Feb
Sound Level Meter	51 IRE 6.S1	39 527 May	Stamper	51 IRE 6.S1	39 528 May
Sound Power of a Source	51 IRE 6.S1	39 527 May	Standard Microphone	51 IRE 6.S1	39 528 May
Sound Pressure Level	51 IRE 6.S1	39 527 May	Standard Observer	55 IRE 22.S1	43 748 Jne
Sound Probe	51 IRE 6.S1	39 528 May	Standard Pitch	51 IRE 6.S1	39 528 May
Sound Recording System	51 IRE 6.S1	39 528 May	Standard Propagation	50 IRE 24.S1	38 1267 Nov
Sound Reflection Coefficient	51 IRE 6.S1	39 528 May	Standard Refraction	50 IRE 24.S1	38 1267 Nov
Sound Reproducing System	51 IRE 6.S1	39 528 May	Standard Sea Water Conditions	51 IRE 6.S1	39 529 May
Sound Track	51 IRE 6.S1	39 528 May	Standard Volume Indicator	54 IRE 3.S1	42 1112 Jul
Sound Transmission Coefficient	51 IRE 6.S1	39 528 May	Standing-on-Nines Carry	56 IRE 8.S1	44 1173 Sep
Source	54 IRE 3.S1	42 1112 Jul	Standing Wave	50 IRE 24.S1	38 1268 Nov
Source Impedance	54 IRE 3.S1	42 1112 Jul	Standing Wave	53 IRE 2.S1	41 1725 Dec
Space Charge	57 IRE 7.S2	45 1006 Jul	Standing-Wave Loss Factor	53 IRE 2.S1	41 1725 Dec
Space-Charge Debunching	57 IRE 7.S2	45 1006 Jul	Standing-Wave Ratio	53 IRE 2.S1	41 1725 Dec
Space-Charge Density	57 IRE 7.S2	45 1006 Jul	Star Chain	54 IRE 12.S1	43 206 Feb
Space-Charge Grid	57 IRE 7.S2	45 1006 Jul	Star Network	50 IRE 4.S1	38 28 Jan
Space-Charge-Limited Current	57 IRE 7.S2	45 1006 Jul	Start Record Signal	56 IRE 9.S1	44 780 Jne
Space-Charge Region	54 IRE 7.S2	42 1508 Oct	Start Signal	56 IRE 9.S1	44 780 Jne
Space Pattern	55 IRE 23.S1	43 621 May	Starter	57 IRE 7.S2	45 1006 Jul
Spacing Wave (Back Wave)	48 IRE 2,11,15.S1	Separate	Starter Breakdown Voltage	57 IRE 7.S2	45 1006 Jul
Spark-Gap Modulation	48 IRE 2,11,15.S1	Separate	Starter Gap	57 IRE 7.S2	45 1006 Jul
Spark Transmitter	48 IRE 2,11,15.S1	Separate	Starter Voltage Drop	57 IRE 7.S2	45 1006 Jul
Speaker	52 IRE 17.S1	40 1685 Dec	Starting Current of an Oscillator	57 IRE 7.S2	45 1006 Jul
Specific Acoustic Impedance	51 IRE 6.S1	39 528 May	Static Characteristic	57 IRE 7.S2	45 1006 Jul
Specific Acoustic Reactance	51 IRE 6.S1	39 528 May	Static Pressure	51 IRE 6.S1	39 529 May
Specific Acoustic Resistance	51 IRE 6.S1	39 528 May	Static Register	50 IRE 8.S1	39 276 Mar
Specific Repetition Rate	54 IRE 12.S1	43 206 Feb	Staticizer	56 IRE 8.S1	44 1173 Sep
Spectral Characteristic	57 IRE 7.S2	45 1006 Jul	STC	54 IRE 12.S1	43 206 Feb
Spectral Characteristic	55 IRE 22.S1	43 748 Jne	Steady-State Oscillation	51 IRE 6.S1	39 529 May
Spectral Sensitivity Characteristic	57 IRE 7.S2	45 1006 Jul	Steerable Antenna	48 IRE 2,11,15.S1	Separate
Spectrum Locus	55 IRE 22.S1	43 748 Jne	Stereophonic Sound System	51 IRE 6.S1	39 529 May
Spherical-Earth Factor	50 IRE 24.S1	38 1267 Nov	Sticking Picture	57 IRE 7.S2	45 1006 Jul
Spherical Hyperbola	54 IRE 12.S1	43 206 Feb	Stirring Effect	55 IRE 10.S1	43 1072 Sep
Spherical Wave	50 IRE 24.S1	38 1267 Nov	Stop Record Signal	56 IRE 9.S1	44 780 Jne
Spike Leakage Energy	57 IRE 7.S2	45 1006 Jul	Stop Signal	56 IRE 9.S1	44 780 Jne
Spill	57 IRE 7.S2	45 1006 Jul	Storage	56 IRE 8.S1	44 1173 Sep
Spinner	54 IRE 12.S1	43 206 Feb	Storage Capacity	56 IRE 8.S1	44 1173 Sep
Spiral Scanning	48 IRE 2,11,15.S1	Separate	Storage Element	57 IRE 7.S2	45 1006 Jul
Split-Anode Magnetron	57 IRE 7.S2	45 1006 Jul	Storage Time	57 IRE 7.S2	45 1006 Jul
Split Hydrophone	51 IRE 6.S1	39 528 May	Storage Tube	57 IRE 7.S2	45 1006 Jul
Split Projector	51 IRE 6.S1	39 528 May	Storage Tube	50 IRE 8.S1	39 277 Mar
Spot	50 IRE 7.S1	38 437 Apr	Store	56 IRE 8.S1	44 1173 Sep
Spot Projection	56 IRE 9.S1	44 780 Jne	Streaming	51 IRE 6.S1	39 529 May
Spot Speed	56 IRE 9.S1	44 780 Jne	Strength of a Sound Source	51 IRE 6.S1	39 529 May
Spurious Pulse Mode	52 IRE 20.S1	40 554 May	Striation Technique	51 IRE 6.S1	39 529 May
			Stroke Speed (Scanning or Recording Line Frequency)	56 IRE 9.S1	44 780 Jne

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Structurally Dual Networks	50 IRE 4.S1	38 28 Jan	Temporal Gain Control	54 IRE 12.S1	43 206 Feb
Structurally Symmetrical Network	50 IRE 4.S1	38 28 Jan	Tenth-Power Width	48 IRE 2,11,15.S1	Separate
Stub, Waveguide	55 IRE 2.S1	43 1074 Sep	Terminal	50 IRE 4.S1	38 29 Jan
Stylus Drag	51 IRE 6.S1	39 529 May	Terminal Pair	50 IRE 4.S1	38 29 Jan
Stylus Force	51 IRE 6.S1	39 529 May	Ternary	56 IRE 8.S1	44 1173 Sep
Subcarrier	53 IRE 11.S1	41 615 May	Terrain Clearance Indicator	49 IRE 12.S1	37 1370 Dec
Subcarrier	56 IRE 9.S1	44 780 Jne	Terrain Echoes	49 IRE 12.S1	43 206 Feb
Subharmonic	48 IRE 2,11,15.S1	Separate	Terrain Error	54 IRE 12.S1	43 206 Feb
Subject Copy	56 IRE 9.S1	44 780 Jne	Terrestrial-Reference Flight	54 IRE 12.S1	43 206 Feb
Submerged Register Induction			Test Routine	56 IRE 8.S1	44 1173 Sep
Furnace	55 IRE 10.S1	43 1072 Sep	Tetrode	57 IRE 7.S2	45 1007 Jul
Subprogram	50 IRE 8.S1	39 277 Mar	Theta (θ) Polarization	48 IRE 2,11,15.S1	Separate
Subroutine	56 IRE 8.S1	44 1173 Sep	Thermal Noise	57 IRE 7.S2	45 1007 Jul
Summing Point	55 IRE 26.S2	44 108 Jan	Thermal Tuning Time	57 IRE 7.S2	45 1007 Jul
Supersonics	51 IRE 6.S1	39 529 May	Thermal Tuning Time (Heating)	57 IRE 7.S2	45 1007 Jul
Suppressed Time Delay	54 IRE 12.S1	43 206 Feb	Thermal Tuning Time (Cooling)	57 IRE 7.S2	45 1007 Jul
Suppressor Grid	57 IRE 7.S2	45 1006 Jul	Thermionic Cathode	57 IRE 7.S2	45 1007 Jul
Surface Duct	50 IRE 24.S1	38 1268 Nov	Thermionic Emission	57 IRE 7.S2	45 1007 Jul
Surface Noise	51 IRE 6.S1	39 529 May	Thermionic Grid Emission	57 IRE 7.S2	45 1007 Jul
Surface of Position	54 IRE 12.S1	43 206 Feb	Thermionic Tube	57 IRE 7.S2	45 1007 Jul
Surge Electrode Current	50 IRE 7.S1	38 437 Apr	Thermistor	54 IRE 7.S2	42 1508 Oct
Surveillance Radar Airport	54 IRE 12.S1	43 206 Feb	Thermophone	51 IRE 6.S1	39 530 May
Syllabic Companding	53 IRE 11.S1	41 615 May	Three-Address Code	56 IRE 8.S1	44 1173 Sep
Syllable Articulation	51 IRE 6.S1	39 529 May	Threshold	51 IRE 6.S1	39 526 May
Symmetrical Network	50 IRE 4.S1	38 29 Jan	Threshold of Audibility	51 IRE 6.S1	39 530 May
Symmetrical Transducer	51 IRE 20.S1	39 898 Aug	Threshold of Feeling	51 IRE 6.S1	39 530 May
Sync Compression	55 IRE 23.S1	43 621 May	Threshold Signal	54 IRE 12.S1	43 206 Feb
Sync Level	55 IRE 23.S1	43 621 May	Throat Microphone	51 IRE 6.S1	39 530 May
Sync Signal (Synchronizing Signal)	55 IRE 23.S1	43 621 May	Through Path	55 IRE 26.S2	44 108 Jan
Synchronization Error	54 IRE 12.S1	43 206 Feb	Through Transfer Function	55 IRE 26.S2	44 108 Jan
Synchronizing (in Facsimile)	56 IRE 9.S1	44 780 Jne	Thyratron	57 IRE 7.S2	45 1007 Jul
Synchronizing (in Television)	55 IRE 23.S1	43 621 May	Tilt	49 IRE 12.S1	37 1370 Dec
Synchronizing Signal	56 IRE 9.S1	44 780 Jne	Tilt Angle	54 IRE 12.S1	43 206 Feb
Synchronous Gate	53 IRE 11.S1	41 615 May	Tilt Error	54 IRE 12.S1	43 206 Feb
Synchronous Voltage	57 IRE 7.S2	45 1006 Jul	Timbre	51 IRE 6.S1	39 530 May
Systematic Errors	54 IRE 12.S1	43 206 Feb	Time	57 IRE 7.S2	45 1007 Jul
	T		Time Discriminator	54 IRE 12.S1	43 206 Feb
Tailing (Hangover)	56 IRE 9.S1	44 780 Jne	Time-Division Multiplex	53 IRE 11.S1	41 615 May
Tailing (or Hangover)	42 IRE 9.S1	Separate	Time Gain Control	49 IRE 12.S1	37 1370 Dec
Tandem	50 IRE 4.S1	38 29 Jan	Time Gate	53 IRE 11.S1	41 615 May
Tangential Wave Path	50 IRE 24.S1	38 1268 Nov	Time Pattern	55 IRE 23.S1	43 622 May
Tank Circuit	48 IRE 2,11,15.S1	Separate	Time-Variied Gain (TVG)	54 IRE 12.S1	43 207 Feb
Tapered Transmission Line	53 IRE 2.S1	41 1725 Dec	Timer	54 IRE 12.S1	43 207 Feb
Taper, Waveguide	55 IRE 2.S1	43 1074 Sep	TM _{m,n} Wave in Circular Waveguide	53 IRE 2.S1	41 1728 Dec
Tapered Waveguide	55 IRE 2.S1	43 1074 Sep	TM _{m,n} Wave in Rectangular Waveguide	53 IRE 2.S1	41 1727 Dec
Target	54 IRE 12.S1	43 206 Feb	TM _{m,n,p} Resonant Mode in Cylindrical Cavity	53 IRE 2.S1	41 1728 Dec
Target	57 IRE 7.S2	45 1006 Jul	T-Network	50 IRE 4.S1	38 29 Jan
Target Capacitance	57 IRE 7.S2	45 1007 Jul	Toe and Shoulder	51 IRE 6.S1	39 530 May
Target Cutoff Voltage	57 IRE 7.S2	45 1007 Jul	To-From Indicator	54 IRE 12.S1	43 207 Feb
Target Glint	54 IRE 12.S1	43 206 Feb	Tone	51 IRE 6.S1	39 530 May
Target Voltage	57 IRE 7.S2	45 1007 Jul	Tone Localizer	54 IRE 12.S1	43 207 Feb
Tee Junction	55 IRE 2.S1	43 1074 Sep	Top-Loaded Vertical Antenna	48 IRE 2,11,15.S1	Separate
Telephone Receiver	51 IRE 6.S1	39 529 May	Torque Amplifier	50 IRE 8.S1	39 277 Mar
Telephone Transmitter	51 IRE 6.S1	39 530 May	Total Telegraph Distortion	48 IRE 2,11,15.S1	Separate
Teleran	49 IRE 12.S1	37 1371 Dec	Totally Unbalanced Currents	53 IRE 2.S1	41 1725 Dec
Teleran (Television and Radar Navigation System)	54 IRE 12.S1	43 209 Feb	TR Box	54 IRE 12.S1	43 207 Feb
Television Transmitter	48 IRE 2,11,15.S1	Separate	TR Cavity	54 IRE 12.S1	43 207 Feb
TE _{m,n} Wave in Circular Waveguide	53 IRE 2.S1	41 1728 Dec	TR Switch	54 IRE 12.S1	43 207 Feb
TE _{m,n} Wave in Rectangular Waveguide	53 IRE 2.S1	41 1727 Dec	TR (Transmit Receive) Tube	57 IRE 7.S2	45 1007 Jul
TE _{m,n,p} Resonant Mode in Cylindrical Cavity	53 IRE 2.S1	41 1728 Dec	Tracing Distortion	51 IRE 6.S1	39 530 May
Temperature	57 IRE 7.S2	45 1007 Jul	Track (Computers)	56 IRE 8.S1	44 1173 Sep
Temperature Coefficient of Voltage Drop	57 IRE 7.S2	45 1007 Jul	Track (navigation)	54 IRE 12.S1	43 207 Feb
			Track Homing	54 IRE 12.S1	43 207 Feb
			Tracking (antenna)	48 IRE 2,11,15.S1	Separate

	<i>Standard</i>	<i>PROCEEDINGS Vol Page Mo</i>		<i>Standard</i>	<i>PROCEEDINGS Vol Page Mo</i>
Tracking (Navigation)	49 IRE 12.S1	37 1370 Dec	Transmitted Wave	53 IRE 2.S1	41 1725 Dec
Tracking (Receivers)	52 IRE 17.S1	40 1685 Dec	Transmitted Wave	50 IRE 24.S1	38 1268 Nov
Tracking Error	51 IRE 6.S1	39 530 May	Transmitter, Facsimile	56 IRE 9.S1	44 780 Jne
Trailing Edge	55 IRE 23.S1	43 622 May	Transmitter Pulse Delay	52 IRE 20.S1	40 554 May
Trailing Edge Pulse Time	51 IRE 20.S1	39 626 Jne	Transmitting Converter, Facsimile (AM to FS Converter)	56 IRE 9.S1	44 780 Jne
Transadmittance	57 IRE 7.S2	45 1007 Jul	Transmitting Current Response	51 IRE 6.S1	39 530 May
Transadmittance Forward	57 IRE 7.S2	45 1007 Jul	Transmitting Efficiency	51 IRE 6.S1	39 531 May
Transadmittance Compression Ratio	57 IRE 7.S2	45 1007 Jul	Transmitting Power Response	51 IRE 6.S1	39 531 May
Transconductance	57 IRE 7.S2	45 1007 Jul	Transmitting Voltage Response	51 IRE 6.S1	39 531 May
Transcriber	56 IRE 8.S1	44 1173 Sep	Trans-u Factor	57 IRE 7.S2	45 1008 Jul
Transducer	54 IRE 3.S1	42 1112 Jul	Transponder	54 IRE 12.S1	43 207 Feb
Transducer	57 IRE 7.S2	45 1007 Jul	Transponder Beacon	54 IRE 12.S1	43 207 Feb
Transducer	51 IRE 20.S2	39 898 Aug	Transponder Crossband	54 IRE 12.S1	43 207 Feb
Transducer Equivalent Noise Pressure	51 IRE 6.S1	39 530 May	Transponder Reply Efficiency	54 IRE 12.S1	43 207 Feb
Transducer Gain	54 IRE 3.S1	42 1112 Jul	Transportable Transmitter	48 IRE 2,11,15.S1	Separate
Transducer Gain	51 IRE 20.S2	39 899 Aug	Transrectification Factor	57 IRE 7.S2	45 1008 Jul
Transducer Gain	57 IRE 7.S2	45 1008 Jul	Transverse-Beam Traveling-Wave Tube	57 IRE 7.S2	45 1008 Jul
Transducer Loss	54 IRE 3.S1	42 1112 Jul	Transverse Electric Wave	53 IRE 2.S1	41 1725 Dec
Transducer Loss	51 IRE 20.S2	39 899 Aug	Transverse Electric Wave	50 IRE 24.S1	38 1268 Nov
Transducer Pulse Delay	52 IRE 20.S1	40 554 May	Transverse Electromagnetic Wave	50 IRE 24.S1	38 1268 Nov
Transfer	56 IRE 8.S1	44 1173 Sep	Transverse Electromagnetic Wave Transverse-Field Traveling Wave Tube	53 IRE 2.S1	41 1725 Dec
Transfer Admittance	42 IRE 9.S1	Separate	Transverse Magnetic Wave	57 IRE 7.S2	45 1008 Jul
Transfer Admittance	57 IRE 7.S2	45 1008 Jul	Transverse Magnetic Wave	53 IRE 2.S1	41 1725 Dec
Transfer Characteristic	57 IRE 7.S2	45 1008 Jul	Transverse Magnetic Wave	50 IRE 24.S1	38 1268 Nov
Transfer Characteristic	52 IRE 17.S1	40 1685 Dec	Transverse Magnetization	51 IRE 6.S1	39 531 May
Transfer Check	56 IRE 8.S1	44 1173 Sep	Traveling Plane Wave	53 IRE 2.S1	41 1725 Dec
Transfer, Conditional	50 IRE 8.S1	39 277 Mar	Traveling Plane Wave	50 IRE 24.S1	38 1268 Nov
Transfer Control	56 IRE 8.S1	44 1173 Sep	Traveling-Wave Magnetron	57 IRE 7.S2	45 1008 Jul
Transfer Current	57 IRE 7.S2	45 1008 Jul	Traveling-Wave Magnetron Os- cillations	57 IRE 7.S2	45 1008 Jul
Transfer Function	55 IRE 26.S2	44 108 Jan	Traveling-Wave Tube	57 IRE 7.S2	45 1008 Jul
Transfer Ratio	42 IRE 9.S1	Separate	Traveling-Wave Tube Interaction Circuit	57 IRE 7.S2	45 1008 Jul
Transfer Ratio	55 IRE 26.S2	44 108 Jan	Tree	50 IRE 4.S1	38 29 Jan
Transfer, Unconditional	50 IRE 8.S1	39 277 Mar	Triad	54 IRE 12.S1	43 207 Feb
Transformer Loss	54 IRE 3.S1	42 1112 Jul	Tricon	54 IRE 12.S1	43 209 Feb
Transformer, Waveguide	55 IRE 2.S1	43 1074 Sep	Trigatron	54 IRE 12.S1	43 207 Feb
Transient Motion	51 IRE 6.S1	39 530 May	Trigger Level	54 IRE 12.S1	43 207 Feb
Transistor	54 IRE 7.S2	42 1508 Oct	Triode	57 IRE 7.S2	45 1008 Jul
Transistor, Conductivity Modula- tion	54 IRE 7.S2	42 1508 Oct	Triplet	54 IRE 12.S1	43 207 Feb
Transistor, Filamentary	54 IRE 7.S2	42 1508 Oct	Tristimulus Values	55 IRE 22.S1	43 748 Jne
Transistor, Junction	54 IRE 7.S2	42 1508 Oct	Troposphere	50 IRE 24.S1	38 1268 Nov
Transistor, Point-Contact	54 IRE 7.S2	42 1508 Oct	Tropospheric Wave	50 IRE 24.S1	38 1268 Nov
Transistor, Point-Junction	54 IRE 7.S2	42 1508 Oct	Trouble-Location Problem	50 IRE 8.S1	39 277 Mar
Transistor, Unipolar	54 IRE 7.S2	42 1508 Oct	True Bearing	49 IRE 12.S1	37 1370 Dec
Transit Angle	57 IRE 7.S2	45 1008 Jul	True Course	49 IRE 12.S1	37 1370 Dec
Transit-Time Mode	57 IRE 7.S2	45 1008 Jul	True Heading	49 IRE 12.S1	37 1370 Dec
Transition Frequency	51 IRE 6.S1	39 530 May	True Homing	49 IRE 12.S1	37 1370 Dec
Transition Loss (in Audio Systems and Components)	54 IRE 3.S1	42 1112 Jul	Truncation Error	50 IRE 8.S1	39 277 Mar
Transition Region	54 IRE 7.S2	42 1508 Oct	Tube	57 IRE 7.S2	45 1008 Jul
Transitron Oscillator	48 IRE 2,11,15.S1	Separate	Tube	52 IRE 17.S1	40 1685 Dec
Translation Loss	51 IRE 6.S1	39 530 May	Tube Count	57 IRE 7.S2	45 1009 Jul
Translator	56 IRE 8.S1	44 1173 Sep	Tube Heating Time	57 IRE 7.S2	45 1009 Jul
Transmission	51 IRE 6.S1	39 530 May	Tube, Vacuum	52 IRE 17.S1	40 1685 Dec
Transmission Band	53 IRE 2.S1	41 1725 Dec	Tube Voltage Drop	57 IRE 7.S2	45 1009 Jul
Transmission Coefficient	53 IRE 2.S1	41 1725 Dec	Tuned-Grid Oscillator	48 IRE 2,11,15.S1	Separate
Transmission Gain	42 IRE 9.S1	Separate	Tuned-Grid Tuned-Plate Oscillator	48 IRE 2,11,15.S1	Separate
Transmission Level	48 IRE 2,11,15.S1	Separate	Tuned-Plate Oscillator	48 IRE 2,11,15.S1	Separate
Transmission Level	42 IRE 9.S1	Separate	Tuner, Waveguide	55 IRE 2.S1	43 1074 Sep
Transmission Line	53 IRE 2.S1	41 1725 Dec	Tuning, Electronic	57 IRE 7.S2	45 1009 Jul
Transmission Loss	53 IRE 2.S1	41 1725 Dec	Tuning Probe	55 IRE 2.S1	43 1074 Sep
Transmission Loss (or "Loss")	42 IRE 9.S1	Separate	Tuning Range	57 IRE 7.S2	45 1009 Jul
Transmission Primaries	55 IRE 22.S1	43 748 Jne	Tuning Range, Electronic	57 IRE 7.S2	45 1009 Jul

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Tuning Rate Thermal	57 IRE 7.S2	45 1009 Jul	Variable-u Tube	57 IRE 7.S2	45 1010 Jul
Tuning Sensitivity, Electronic	57 IRE 7.S2	45 1009 Jul	Variable-Reluctance Microphone	51 IRE 6.S1	39 532 May
Tuning Sensitivity Thermal	57 IRE 7.S2	45 1009 Jul	Variable-Reluctance Pickup	51 IRE 6.S1	39 532 May
Tuning Susceptance	57 IRE 7.S2	45 1009 Jul	Variable-Resistance Pickup	51 IRE 6.S1	39 532 May
Tuning Thermal	57 IRE 7.S2	45 1009 Jul	Variation	49 IRE 12.S1	37 1371 Dec
Tuning Time Constant, Thermal	57 IRE 7.S2	45 1009 Jul	Varistor	54 IRE 7.S2	42 1508 Oct
Turntable Rumble	52 IRE 17.S1	40 1685 Dec	V-Beam Radar	54 IRE 12.S1	43 207 Feb
Turnstile Antenna	48 IRE 2,11,15.S1	Separate	Vehicle	54 IRE 12.S1	43 207 Feb
TVG (Time-Variied Gain)	54 IRE 12.S1	43 207 Feb	Velocity	51 IRE 6.S1	39 532 May
Twist, Waveguide	55 IRE 2.S1	43 1074 Sep	Velocity Level	51 IRE 6.S1	39 532 May
Two-Source Frequency Keying	53 IRE 11.S1	41 615 May	Velocity Microphone	51 IRE 6.S1	39 532 May
Two-Terminal Pair Network	50 IRE 4.S1	38 29 Jan	Velocity Modulation	57 IRE 7.S2	45 1010 Jul
Two-Tone Keying	53 IRE 11.S1	41 615 May	Velocity-Modulated Oscillator	48 IRE 2,11,15.S1	Separate
	U		Velocity Sorting	57 IRE 7.S2	45 1010 Jul
Ultrasonic Coagulation	51 IRE 6.S1	39 531 May	Verification	56 IRE 8.S1	44 1173 Sep
Ultrasonic Cross Grating	51 IRE 6.S1	39 531 May	Vertex	50 IRE 4.S1	39 29 Jan
Ultrasonic Delay Line	51 IRE 6.S1	39 531 May	Vertical Recording	51 IRE 6.S1	39 532 May
Ultrasonic Detector	51 IRE 6.S1	39 531 May	Vertically Polarized Wave	50 IRE 24.S1	38 1268 Nov
Ultrasonic Frequency	51 IRE 6.S1	39 531 May	Vestigial Sideband	56 IRE 9.S1	44 781 Jne
Ultrasonic Generator	51 IRE 6.S1	39 531 May	Vestigial Sideband Transmission	56 IRE 9.S1	44 781 Jne
Ultrasonic Grating Constant	51 IRE 6.S1	39 531 May	Vestigial-Sideband Transmitter	48 IRE 2,11,15.S1	Separate
Ultrasonic Light Diffraction	51 IRE 6.S1	39 531 May	VHF Omnidrange	54 IRE 12.S1	43 209 Dec
Ultrasonic Material Dispersion	51 IRE 6.S1	39 531 May	Vibration Meter	51 IRE 6.S1	39 532 May
Ultrasonic Space Grating	51 IRE 6.S1	39 531 May	Vibrato	51 IRE 6.S1	39 532 May
Ultrasonic Stroboscope	51 IRE 6.S1	39 531 May	Video	55 IRE 23.S1	43 622 May
Ultrasonics	51 IRE 6.S1	39 531 May	Video	52 IRE 17.S1	40 1685 Dec
Unconditional Jump	56 IRE 8.S1	44 1173 Sep	Video-Frequency Amplifier	48 IRE 2,11,15.S1	Separate
Unconditional Transfer of Control	56 IRE 8.S1	44 1173 Sep	Video Integration	54 IRE 12.S1	43 207 Feb
Underbunching	57 IRE 7.S2	45 1009 Jul	Video Mapping	54 IRE 12.S1	43 207 Feb
Underlap	52 IRE 9.S1	Separate	Video Stretching	54 IRE 12.S1	43 207 Feb
Underlap X	56 IRE 9.S1	44 780 Jne	Vidicon	57 IRE 7.S2	45 1010 Jul
Underlap Y	56 IRE 9.S1	44 780 Jne	Virtual Cathode	57 IRE 7.S2	45 1010 Jul
Underthrow Distortion	42 IRE 9.S1	Separate	Virtual Height	50 IRE 24.S1	38 1286 Nov
Underwater Sound Projector	51 IRE 6.S1	39 531 May	Visibility Factor (Display Loss)	54 IRE 12.S1	43 207 Feb
Undirectional Microphone	51 IRE 6.S1	39 531 May	Visual-Aural Range	54 IRE 12.S1	43 207 Feb
Undirectional Pulse	51 IRE 20.S1	39 626 Jne	Visual-Aural Radio Range	49 IRE 12.S1	37 1371 Dec
Undirectional Pulse Train	52 IRE 20.S1	40 554 May	Visual Radio Range	49 IRE 12.S1	37 1371 Dec
Unfired Tube	57 IRE 7.S2	45 1009 Jul	Visual Transmitter	48 IRE 2,11,15.S1	Separate
Uniconductor Waveguide	53 IRE 2.S1	41 1725 Dec	Volatile	56 IRE 8.S1	44 1173 Sep
Unidirectional Antenna	48 IRE 2,11,15.S1	Separate	Voltage	57 IRE 7.S2	45 1010 Jul
Unidirectional Pulses	48 IRE 2,11,15.S1	Separate	Voltage Amplification	54 IRE 3.S1	42 1112 Jul
Uniform Plane Wave	50 IRE 24.S1	38 1268 Nov	Voltage Amplification	51 IRE 20.S2	39 899 Aug
Uniform Waveguide	53 IRE 2.S1	41 1725 Dec	Voltage Amplification	48 IRE 2,11,15.S1	Separate
Unilateral Area Track	51 IRE 6.S1	39 531 May	Voltage Attenuation	51 IRE 20.S2	39 899 Aug
Unilateral Transducer	51 IRE 20.S2	39 898 Aug	Voltage Attenuation	54 IRE 3.S1	42 1112 Jul
Unipole	48 IRE 2,11,15.S1	Separate	Voltage Generator	57 IRE 7.S2	45 1010 Jul
Unipotential Cathode	57 IRE 7.S2	45 1009 Jul	Voltage Jump	57 IRE 7.S2	45 1010 Jul
Unit	56 IRE 8.S1	44 1173 Sep	Voltage Reference Tube	57 IRE 7.S2	45 1010 Jul
Unloaded Applicator Impedance	55 IRE 10.S1	43 1072 Sep	Voltage Regulator Tube	57 IRE 7.S2	45 1010 Jul
Unloaded (Intrinsic) Q	57 IRE 7.S2	45 1009 Jul	Volume	54 IRE 3.S1	42 1112 Jul
Unmodulated Groove	51 IRE 6.S1	39 532 May	Volume Indicator	51 IRE 6.S1	39 532 May
Useful Line	56 IRE 9.S1	44 781 Jne	Volume-Limiting Amplifier	48 IRE 2,11,15.S1	Separate
	V		Volume Velocity	51 IRE 6.S1	39 532 May
Vacuum Tube	57 IRE 7.S2	45 1009 Jul	Volumetric Radar	54 IRE 12.S1	43 207 Feb
Vacuum Tube	52 IRE 17.S1	40 1685 Dec	VOR (VHF Omnidrange)	54 IRE 12.S1	43 209 Feb
Vacuum-Tube Amplifier	48 IRE 2,11,15.S1	Separate	Vowel Articulation	51 IRE 6.S1	39 532 May
Vacuum-Tube Transmitter	48 IRE 2,11,15.S1	Separate	VSWR, High-Level	57 IRE 7.S2	45 1010 Jul
Valence Band	54 IRE 7.S2	42 1508 Oct	vu	54 IRE 3.S1	42 1112 Jul
Value, Munsell	55 IRE 22.S1	43 748 Jne		W	
V-Antenna	48 IRE 2,11,15.S1	Separate	Wander	54 IRE 12.S1	43 207 Feb
VAR (VHF Aural-Visual Range)	54 IRE 12.S1	43 209 Feb	Wave	48 IRE 2,11,15.S1	Separate
Variable Area Track	51 IRE 6.S1	39 532 May	Wave	50 IRE 24.S1	38 1268 Nov
Variable Density Track	51 IRE 6.S1	39 532 May	Wave	57 IRE 7.S2	45 1010 Jul
Variable-Induction Pickup	51 IRE 6.S1	39 532 May	Wave Antenna	48 IRE 2,11,15.S1	Separate
			Waveform-Amplitude Distortion	53 IRE 4.S1	42 555 Mar

	Standard	PROCEEDINGS Vol Page Mo		Standard	PROCEEDINGS Vol Page Mo
Wave Front	42 IRE 9.S1	Separate	Wide-Band Ratio	48 IRE 2,11,15.S1	Separate
Waveguide	50 IRE 24.S1	38 1268 Nov	Williams-Tube Storage	56 IRE 8.S1	44 1173 Sep
Waveguide	53 IRE 2.S1	41 1725 Dec	Word	56 IRE 8.S1	44 1173 Sep
Waveguide Wavelength	53 IRE 2.S1	41 1725 Dec			
Wave Heating	55 IRE 10.S1	43 1072 Sep	Word Time	56 IRE 8.S1	44 1173 Sep
Wave Interference	50 IRE 24.S1	38 1268 Nov	Work Coil	55 IRE 10.S1	43 1072 Sep
Wavelength	50 IRE 24.S1	38 1268 Nov	Work Function	57 IRE 7.S2	45 1010 Jul
Wave Normal	53 IRE 2.S1	41 1725 Dec	Wow	52 IRE 17.S1	40 1685 Dec
Wave Normal	50 IRE 24.S1	38 1268 Nov	Write	56 IRE 8.S1	44 1173 Sep
			Write	57 IRE 7.S2	45 1010 Jul
Wave Tail	42 IRE 9.S1	Separate	Writing Speed	57 IRE 7.S2	45 1010 Jul
Wax	51 IRE 6.S1	39 532 May	Wye Junction	55 IRE 2.S1	43 1074 Sep
Wax Original	51 IRE 6.S1	39 532 May			
Way Point	54 IRE 12.S1	43 207 Feb			
Weighting	48 IRE 2,11,15.S1	Separate	X		
			X Wave	50 IRE 24.S1	38 1268 Nov
White	55 IRE 22.S1	43 748 Jne			
White Compression (White Saturation)	55 IRE 23.S1	43 622 May	Y		
White Object	55 IRE 22.S1	43 748 Jne	Y Network	51 IRE 4.S1	39 29 Jan
White Peak	55 IRE 23.S1	43 622 May			
White Recording	56 IRE 9.S1	44 781 Jne	Z		
			Z (Zone) Marker	54 IRE 12.S1	43 209 Feb
White Signal	56 IRE 9.S1	44 781 Jne	Zero-Subcarrier Chromaticity	55 IRE 22.S1	43 748 Jne
White-to-Black Frequency Swing	42 IRE 9.S1	Separate	Zero Time Reference	54 IRE 12.S1	43 207 Feb
White-to-Black Amplitude Range	42 IRE 9.S1	Separate	Zone (Z) Marker	49 IRE 12.S1	37 1371 Dec
White Transmission	56 IRE 9.S1	44 781 Jne	Zone Leveling	54 IRE 7.S2	42 1508 Oct
Whole Tone	51 IRE 6.S1	39 532 May			
			Zone Purification	54 IRE 7.S2	42 1508 Oct
Wide-Band Axis	55 IRE 22.S1	43 748 Jne	Zoning	48 IRE 2,11,15.S1	Separate
Wide-Band Improvement	48 IRE 2,11,15.S1	Separate			

Measurement of the Radar Cross Section of a Man*

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Summary—Both the monostatic and the bistatic radar cross sections¹ of a man were measured at the five frequencies 410, 1120, 2890, 4800, and 9375 mc. The measurements were made using both horizontal and vertical polarizations, and for various directions of facing, or aspects, of the man being used as a target. The cw Doppler

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¹ The bistatic radar cross section is measured when the transmitter and receiver are not located on the same radial from the target. The monostatic cross section is a special case of the bistatic cross section. The monostatic value is obtained when the transmitter and receiver are at the same location, and thus on the same radial.

method² was used in making the measurements. The man whose cross section was measured weighed about 200 pounds and he was six feet tall.

It was found that the man's cross section varied as follows, depending primarily upon polarization of the incident wave and aspect of the man:

410 mc	0.033 to 2.33 square meters
1120 mc	0.098 to 0.997 square meters
2890 mc	0.140 to 1.05 square meters
4800 mc	0.368 to 1.88 square meters
9375 mc	0.495 to 1.22 square meters.

A few measurements were made with men of different sizes, and these indicate that the cross section is approximately proportional to the weight of the man.

² D. D. King and H. Scharfman, "Antenna scattering measurements by modulation of the scatterer," Proc. IRE, vol. 42, pp. 854-858; May, 1954.

I. INTRODUCTION

OFTEN in making radar cross section measurements indicated above, it is desirable to utilize modeling techniques which make possible the use of indoor laboratory facilities for carrying out the measurements. Since a human being is neither a perfect conductor nor a perfect dielectric, it was considered unwise to attempt to use a modeling technique which would involve a modeling of the electrical properties of the target as well as of its size. Consequently full-scale measuring techniques were used.

II. EXPERIMENTAL PROCEDURE

Since a cw Doppler system was used in making the measurements, it was necessary to impart radial motion (relative to the Doppler transmitter and receiver) to the target in order to obtain a Doppler signal. This was accomplished by constructing a test stand consisting of a wooden A frame that supported a swinging platform on which the man stood. A 16-inch sphere and one with a diameter of 10 inches served as standard targets for calibration purposes, and these were hung from the cross member of the test stand. Nylon cord, with a diameter of about $3/32$ inch and a test strength of 190 pounds, supported the swinging platform as well as the standard spheres. No detectable Doppler signal was generated by the motion of these nylon supporting cords.

In order to reduce satisfactorily the Doppler return signal from the swinging platform on which the man stood, it was necessary to erect in front of the platform a barrier of microwave absorbing material. A block of Styrofoam was placed on top of the swinging wooden platform in order that a full view of the man standing thereon would be seen by the Doppler measuring system. The unwanted Doppler return was satisfactorily reduced by these techniques. The test stand was sufficiently rigid that no detectable Doppler return was generated by it. Multiple reflections involving various stationary objects and the swinging targets were believed to be of no consequence since cross checks on the measured cross sections obtained for the two different spheres, used as standards, were very satisfactory.

Each of the transmitters used consisted of a suitable cw generator coupled to an appropriate antenna, which could be rotated about a horizontal axis. This made possible the emission of either horizontally or vertically polarized waves. At the receiver an antenna identical to the transmitting antenna was coupled to a superheterodyne-type receiver. During operation the Doppler-shifted signal from the target and the leakage signal from the transmitter passed through the receiver and produced a Doppler beat signal at the output of the second detector of the receiver. This signal was fed through a variable band-pass audio filter to reduce the noise, and then finally used to drive the pen of a record-

ing oscillograph. The pen deflections were proportional to the voltage of the Doppler signal returned by the target, the linearity of the system having been verified over the operating range. Typical tape records taken on the oscillograph are illustrated in Fig. 1(a) and 1(b).

A series of measurements commenced with setting the transmitter and receiver side by side at the correct distance from the test stand and directly in front of the test stand. Measurements were first made of the Doppler signals returned by each of the two spheres used as standards. After these calibration recordings the man was placed on the movable platform of the test stand and the Doppler signal returned by the swinging man was recorded with the man facing the Doppler transmitter and receiver. Further measurements were made of the signal returned by the man after he was rotated 45° about a vertical axis, then a 90° rotation (side view), next 135° , and finally 180° (rear view). Returns for five different aspects of the man were thus obtained. Following the recordings of the man's returns, calibration recordings of the two standards were made again. The entire process was then repeated, so that at least two series of records were obtained for each set of conditions. These measurements yielded the monostatic radar cross section of the man for one particular frequency and polarization.

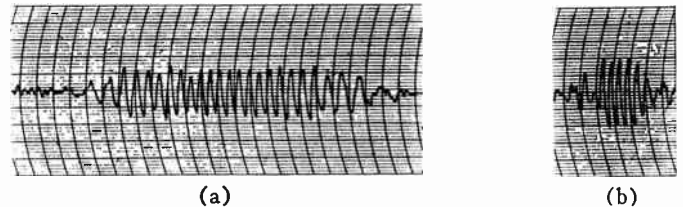


Fig. 1—(a) Recording of the 16-inch standard sphere made at 9375 mc, a bistatic angle of 30° , and horizontal polarization. The voltage scale is 10 mv per mm, and the recording speed was 125 mm per second. (b) Recording of man's return at 45° front aspect with all conditions as above, except that the recording tape speed was 25 mm per second.

In order to measure the bistatic cross section, the transmitter was first moved 15° clockwise, considering the test stand and the line of motion of the swinging target platform as references, and the Doppler receiver was moved 15° counterclockwise. The measuring process described in the preceding paragraph was repeated and thus the 30° bistatic-angle radar cross section of the man was obtained. In the same way the 60° and 90° bistatic-angle cross sections were measured.

Since it was not feasible to elevate the Doppler system and the target sufficiently above the ground to eliminate the ground-reflected waves, it was necessary to take steps to reduce sufficiently the variation of field intensity over the surface of the man, this variation being caused by the interference between the direct wave from the transmitter and the ground-reflected wave. A similar phenomenon existed, of course, for the

propagation path from the target to the receiving antenna. The most satisfactory means of reducing this effect proved to be the use of diffracting screens^{3,4} placed on the ground between the transmitter and target and between the target and receiver. By this method it was possible to reduce the measured field variation in the area occupied by the target to approximately plus or minus 1 db.

Since the cw Doppler system employed for the measurements detects all moving objects, noise caused by moving vegetation and insects entered the system along with the return from the desired target. The effect of this noise was satisfactorily reduced by taking three steps. First, a band-pass filter centered at the frequency of the target return was connected to the output of the second detector of the receiver to eliminate the portion of the clutter return that was not at the target frequency. Second, vegetation was removed as much as possible. Third, the transmitter and receiver were moved as close as allowable to the target so that a return of sufficient magnitude to override the clutter might be received from the target.

The third step mentioned above could not be carried to an extreme because of the requirement that the phase-front curvature of the rf wave over the target be satisfactorily small. A number of workers in the microwave measurements field have developed experimental and theoretical criteria for the minimum range necessary in radar cross section measurements in order to minimize the errors resulting from the curvature of the wave phase front at the target.²⁻⁵ For the present measurements the criterion for allowable phase-front curvature was set at $\pi/16$ radian. The minimum range for the measurements as developed from this criterion is $R=4D^2/\lambda$, where R is the minimum permissible range, D is the major dimension of the target, and λ is the wavelength at which the measurements are being made. Computations from the above equation, with D equal to six feet, give the results shown in Table I. No allowance was made here for phase shifts introduced by the ground-reflected wave.

At 4800 mc and 9375 mc, it was not possible to obtain adequately large return signals from the target for target-transmitter separations of greater than 400 feet because of extraneous signal return from moving vegetation. The phase-front curvature over the target for this separation of 400 feet and for 4800 and 9375 mc is of course greater than $\pi/16$ radian, selected as the maximum allowable. Consequently it was necessary to determine as well as possible the results of this condition. In order to do this, an experiment was undertaken

³ H. E. Bussey, "Reflected ray suppression," *Proc. IRE*, vol. 38, p. 1453; December, 1950.

⁴ C. C. Cutler, A. P. King, and W. E. Kock, "Microwave antenna measurements," *Proc. IRE*, vol. 35, pp. 1469-1470; December, 1947.

⁵ D. R. Rhodes, "On minimum range for radiation patterns," *Proc. IRE*, vol. 42, pp. 1408-1410; September, 1954.

TABLE I
MINIMUM ALLOWABLE SEPARATION (R) BETWEEN TRANSMITTER AND TARGET FOR A MAXIMUM PHASE-FRONT VARIATION OVER THE TARGET OF $\pi/16$ RADIAN. TARGET HEIGHT IS 6 FEET

Frequency	R
410 mc	60 feet
1120 mc	164 feet
2890 mc	422 feet
4800 mc	702 feet
9375 mc	1370 feet

to evaluate this effect of phase-front curvature on the measured cross section of a man. This experiment was conducted at a frequency of 1120 mc and consisted of identical measurements made at three different ranges. The first range used (71 feet) was chosen because it produced the same phase variation over the target as occurred during the 9375-mc measurements made at a range of 400 feet. The second range (104 feet) simulated the conditions of phase variation during the 4800-mc measurements, while the third range (200 feet) insured a phase variation of less than the $\pi/16$ -radian criterion. In all three measurements the diffracting screens were used to make the signal strength over the target uniform. It was not possible to scale the target, so the measurements were not completely definitive, but the results did indicate that an error of probably not more than about 20 per cent was introduced in the 9375-mc measurements, and one of probably not more than about 5 per cent in the 4800-mc results.

III. DATA REDUCTION

As mentioned previously, the Doppler beat signal generated by the moving target was traced on paper tape by a recording oscillograph. Sample tape recordings are shown in Fig. 1(a) and 1(b), and, as stated before, the deflections are proportional to the voltage of the Doppler beat signal. The measurement procedure has also been described earlier in the paper; this consisted of first obtaining calibration recordings of the two standard spheres, then recordings of the human target, and finally check recordings of the two spheres. The entire procedure was then repeated once or twice.

The first step in the data reduction consisted of reading the deflections recorded on the tapes. This was done by drawing straight lines through the average peak values and the average through values attained by the deflections, after the Doppler beat signal had settled down to a fairly steady tone. The averaging process was done visually. These total swings on the tapes were read and recorded for both the human target and the spheres. The two sets of values obtained on the spheres, one set at the beginning of an experiment and the other at the end, were averaged. In no case were these two sets of values sufficiently different to indicate a systematic drift in the characteristics of the complete measurement system.

TABLE II
CALCULATED RADAR CROSS SECTIONS IN SQUARE METERS OF THE STANDARD SPHERES

Sphere	Frequency	Horizontal Polarization				Vertical Polarization			
		Bistatic Angle in Degrees				Bistatic Angle in Degrees			
		0°	30°	60°	90°	0°	30°	60°	90°
10 inches	410 mc	0.17886	0.15720	0.10073	0.04017	0.17886	0.17915	0.17162	0.15300
16 inches	1120 mc	0.16911	0.09064	0.17965	0.11448	0.16911	0.14704	0.20315	0.23490
16 inches	2890 mc	0.12901	0.12901	0.12901	0.12901	0.12901	0.12901	0.12901	0.12901
16 inches	4800 mc	0.12888	0.12888	0.12888	0.12888	0.12888	0.12888	0.12888	0.12888
16 inches	9375 mc	0.12888	0.12888	0.12888	0.12888	0.12888	0.12888	0.12888	0.12888

Since the targets were swung through a distance of never less than about two wavelengths, the error due to changing target velocity, as discussed by Ruze,⁶ should never exceed about 10 per cent.

After all the tape deflection readings for the signal return from the human target were recorded, they were smoothed by the use of a least-squares technique and these final regression values were used for calculating the radar cross sections.

The radar cross section of the human target, corresponding to each final regression value of tape deflection, was calculated by using the following:

$$\sigma_m = \left[\frac{R_m}{R_s} \right]^2 \sigma_s.$$

Here

σ_m = radar cross section, in square meters, of the man.

R_m = tape deflection, in millimeters, corresponding to Doppler signal generated by human target.

R_s = tape deflection, in millimeters, corresponding to Doppler signal generated by sphere used as standard for calibration.

σ_s = calculated radar cross section, in square meters, of the sphere used as a standard.

In all cases, except at 410 mc, the 16-inch sphere was used as a standard and the readings obtained on the 10-inch sphere were used as a check of the system accuracy. The calculated and the measured values of the cross section of this 10-inch sphere differed by an average of about 0.5 db, or about 12 per cent.

The radar cross sections of the spheres at the lower frequencies were calculated by using the exact electromagnetic solution.⁷ At the higher frequencies the geo-

metrical optics values were used. The calculated cross sections of the spheres are listed in Table II. It should be mentioned that the average diameter of the 16-inch sphere was 15.95 inches and that of the 10-inch sphere was 9.88 inches. The sphericity of both spheres was excellent, various diameters differing by only 3/32 inch, or less.

IV. RESULTS OBTAINED

The values of the radar cross section of the man are listed in Tables III–VII, inclusive, for the various frequencies, polarizations, bistatic angles, and aspect angles used in the experiment. It is an easy matter to see from the tables how the radar cross section of the man varies with aspect angle and with bistatic angle for a given frequency and a given polarization, but the variations with frequency and with polarization are somewhat more difficult to observe. For this reason Fig. 2–Fig. 6 have been prepared. Values of the cross section, averaged over bistatic angle, are shown in Fig. 2 and in normalized form in Fig. 3. For Fig. 4 and Fig. 5 the values of cross section were averaged over target aspect for given values of polarization, frequency, and bistatic angle. The curves then give indications of how, for a given polarization and frequency, the man's cross section varies with bistatic angle. In order to obtain Fig. 6, the cross section values corresponding to a given polarization and frequency were averaged over bistatic angle and aspect of the target. Fig. 6 then indicates how these average values of cross section vary with frequency for each of the two polarizations.

V. CONCLUSION

As shown in the Summary, the measured radar cross section of the man used varies from 0.033 square meter to 2.33 square meters. These extreme values were obtained at 410 mc, the smaller for horizontal polarization and a side view of the man, the larger for vertical polarization and a rear view of the man. These results might be expected for a quasi-cylindrical target such as a man. As the frequency was increased the cross section differed less and less between the two polarizations.

Examination of Tables III–VII reveals that, in general, the cross section is least for a side view of the man and

⁶ J. Ruze, "Errors in Radar Cross-Section Reflection Measurements," Air Force Cambridge Field Station, Cambridge, Mass., Rep. No. 4-24; July 30, 1947.

⁷ D. E. Kerr, "Propagation of Short Radio Waves," McGraw-Hill Book Co., New York, N. Y., pp. 445–454; 1951.

TABLE III
RADAR CROSS SECTIONS IN SQUARE METERS FOR 410 MC

Target Aspect	Horizontal Polarization				Vertical Polarization			
	Bistatic Angle in Degrees				Bistatic Angle in Degrees			
	0°	30°	60°	90°	0°	30°	60°	90°
Front	0.897	0.641	0.795	0.464	1.127	0.939	1.628	2.163
45° Front	0.197	0.108	0.264	0.196	0.312	0.217	0.613	0.941
Side	0.083	0.033	0.157	0.136	0.161	0.095	0.397	0.681
45° Rear	0.321	0.197	0.367	0.251	0.464	0.346	0.816	1.174
Rear	1.091	0.796	0.931	0.529	1.343	1.138	1.880	2.327

TABLE IV
RADAR CROSS SECTIONS IN SQUARE METERS FOR 1120 MC

Target Aspect	Horizontal Polarization				Vertical Polarization			
	Bistatic Angle in Degrees				Bistatic Angle in Degrees			
	0°	30°	60°	90°	0°	30°	60°	90°
Front	0.718	0.359	0.410	0.388	0.879	0.718	0.608	0.997
45° Front	0.322	0.156	0.124	0.154	0.433	0.344	0.224	0.447
Side	0.281	0.135	0.098	0.131	0.386	0.305	0.187	0.391
45° Rear	0.518	0.256	0.259	0.268	0.656	0.531	0.410	0.719
Rear	0.718	0.359	0.410	0.388	0.879	0.718	0.608	0.997

TABLE V
RADAR CROSS SECTIONS IN SQUARE METERS FOR 2890 MC

Target Aspect	Horizontal Polarization				Vertical Polarization			
	Bistatic Angle in Degrees				Bistatic Angle in Degrees			
	0°	30°	60°	90°	0°	30°	60°	90°
Front	0.409	0.665	0.471	0.322	0.496	0.774	0.564	0.400
45° Front	0.228	0.427	0.275	0.165	0.294	0.516	0.347	0.221
Side	0.198	0.386	0.242	0.140	0.260	0.471	0.310	0.192
45° Rear	0.268	0.481	0.318	0.198	0.339	0.574	0.395	0.260
Rear	0.613	0.920	0.688	0.506	0.719	1.048	0.800	0.602

TABLE VI
RADAR CROSS SECTIONS IN SQUARE METERS FOR 4800 MC

Target Aspect	Horizontal Polarization				Vertical Polarization			
	Bistatic Angle in Degrees				Bistatic Angle in Degrees			
	0°	30°	60°	90°	0°	30°	60°	90°
Front	1.499	1.404	1.320	1.039	1.745	1.643	1.552	1.247
45° Front	0.858	0.786	0.724	0.521	1.047	0.968	0.898	0.670
Side	0.658	0.596	0.542	0.368	0.825	0.755	0.694	0.495
45° Rear	0.940	0.865	0.799	0.585	1.137	1.054	0.982	0.742
Rear	1.624	1.525	1.438	1.144	1.881	1.774	1.680	1.361

TABLE VII
RADAR CROSS SECTIONS IN SQUARE METERS FOR 9375 MC

Target Aspect	Horizontal Polarization				Vertical Polarization			
	Bistatic Angle in Degrees				Bistatic Angle in Degrees			
	0°	30°	60°	60°	0°	30°	60°	90°
Front	1.018	0.749	0.933	0.799	1.003	0.736	0.919	0.786
45° Front	0.858	0.612	0.780	0.658	0.845	0.601	0.767	0.647
Side	0.730	0.505	0.658	0.547	0.718	0.495	0.647	0.536
45° Rear	0.905	0.652	0.825	0.700	0.891	0.641	0.812	0.688
Rear	1.215	0.919	1.122	0.975	1.199	0.905	1.106	0.961

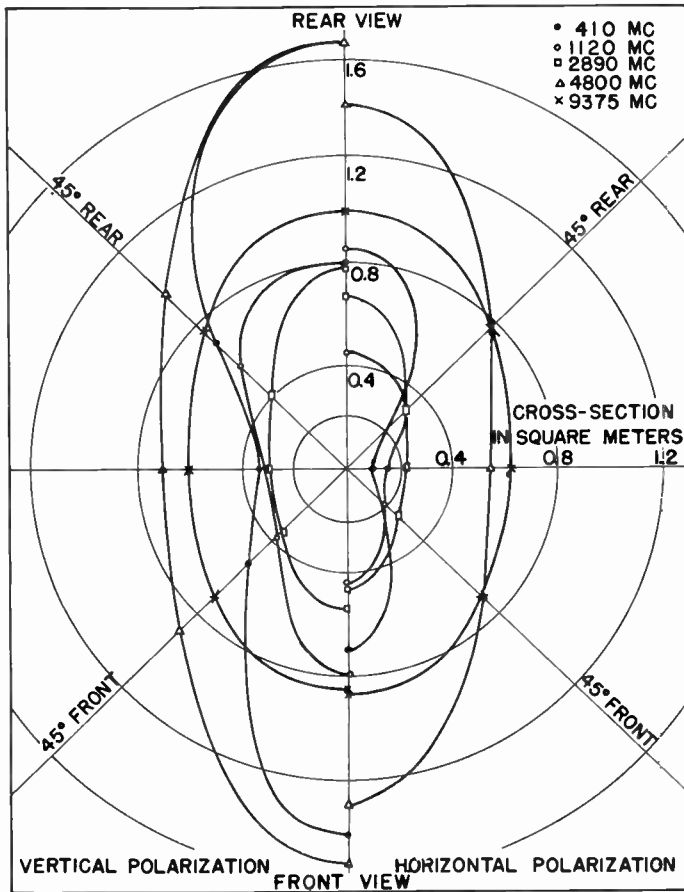


Fig. 2—Average bistatic radar cross section of a man as a function of target aspect angle, with frequency and polarization as parameters.

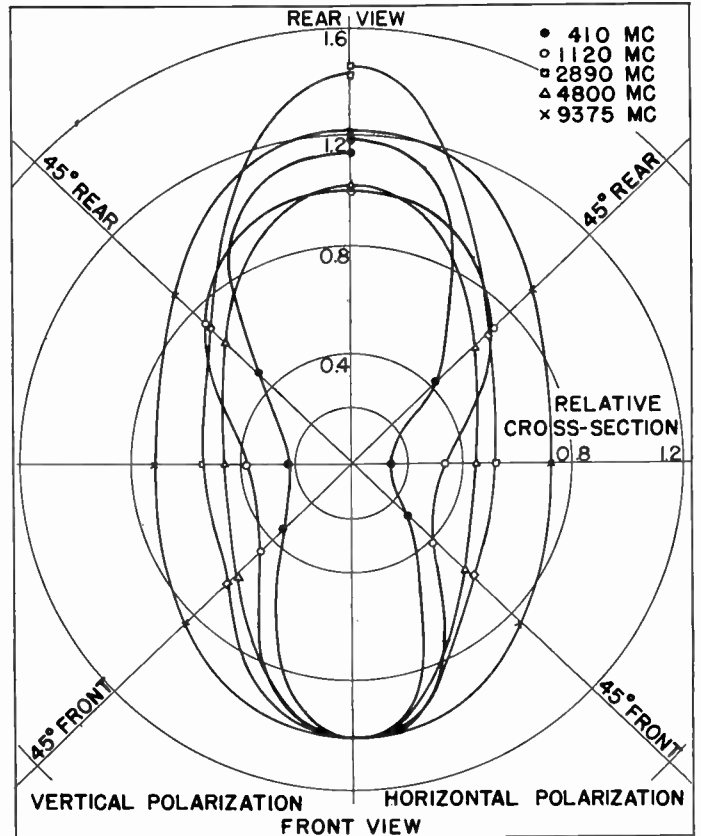


Fig. 3—Average relative bistatic radar cross section of a man as a function of target aspect angle, with frequency and polarization as parameters. (The curves are normalized with respect to the radar cross section of the front aspect.)

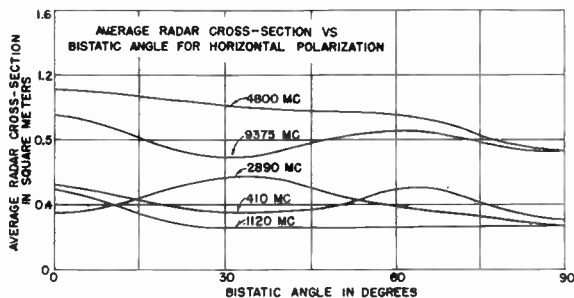


Fig. 4—Average bistatic radar cross section of a man as a function of bistatic angle, for horizontal polarization with frequency as a parameter.

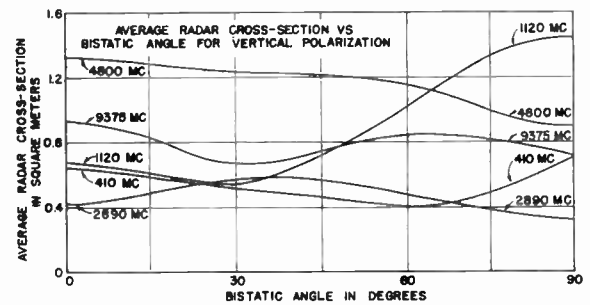


Fig. 5—Average bistatic radar cross section of a man as a function of bistatic angle, for vertical polarization with frequency as a parameter.

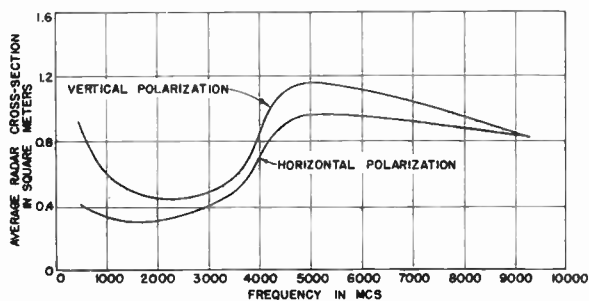


Fig. 6—Average radar cross section of a man as a function of frequency, with polarization as a parameter.

somewhat greater for a rear view than a front view. Fig. 4 and Fig. 5 show that the cross section varies but little with bistatic angle, except for vertical polarization at 410 mc, where the cross section increases about twice as the bistatic angle goes from 0° to 90°. These are not unexpected results.

Fig. 6 illustrates the over-all variation of the cross section with frequency. The general decrease in polarization dependence as the frequency is increased is, of course, to be anticipated. Because of the complex nature of the object being measured, however, no explanation is offered for the other characteristics of the two curves contained in this figure.

IRE Standards on Television: Measurement of Luminance Signal Levels, 1958*

(58 IRE 23. S1)

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* Approved by IRE Standards Committee, September 12, 1957. Reprints of this Standard, 58 IRE 23. S1, may be purchased while available from the Institute of Radio Engineers, 1 East 79th Street, New York, N. Y., at \$0.60 per copy. A 20 per cent discount will be allowed for 100 or more copies mailed to one address.

1.0 INTRODUCTION

This Standard is a revision of Part 1 of Standard 50 IRE 23. S1 and replaces in all respects this previously issued part of the Standard. The need for the revision stems from the standardization of color television signals in the USA, and the inadequacy of the earlier Standard in providing methods of measuring the luminance component of the color signal. The revision consists primarily of a change in the response characteristics of the oscilloscopes to insure adequate suppression of the color subcarrier. Other minor changes in wording and in the associated figures have been made to bring the standard into accord with present terminology and practice.

1.1 Description

This Standard describes methods of measuring the significant amplitude levels of a monochrome or color television signal, either composite or noncomposite. It is concerned with measurements at points in transmission systems where the signals are at video frequency. The methods described in this Standard are limited to those involving the use of oscilloscopes, and are primarily directed to specifying means of measuring television signal levels for operating purposes.

For the purposes of this Standard, the levels which are significant are the levels of monochrome signals or the levels of the luminance portion of color signals. The peak amplitude excursion of a color signal may exceed, by substantial amounts, the peak amplitude excursions of the luminance portion of the signal, but since subjective brightness is more nearly proportional to the luminance signal than to any other quantity, it is most desirable from the operating standpoint to control and adjust levels using the luminance signal as a gauge. When this is done, monochrome and color signals, interspersed in a given program sequence, will produce approximately the same brightness and contrast when viewed on color or monochrome monitors without supplementary adjustments.

In the succeeding paragraphs of this Standard, the words "luminance signal" will refer to either a monochrome signal or to the luminance portion of a color signal.

Six significant amplitude levels of a composite luminance signal have been defined as follows.¹ These are shown in the right-hand portion of Fig. 1.

Reference White Level. The picture signal level corresponding to a specified maximum limit for *White Peaks*.

White Peak. A peak excursion of the picture signal in the white direction.

Black Peak. A peak excursion of the picture signal in the black direction.

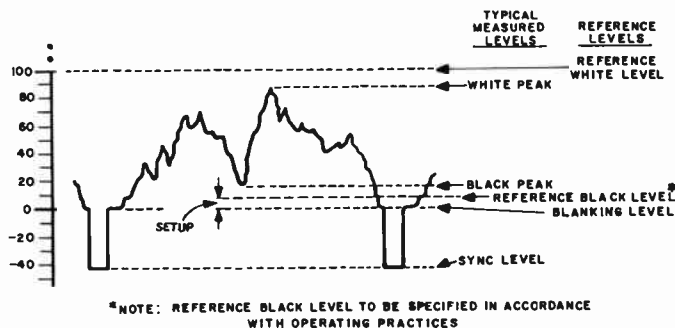


Fig. 1—Significant levels and details of IRE standard scale.

Reference Black Level. The picture signal level corresponding to a specified maximum limit for *Black Peaks*.

Blanking Level. That level of a composite picture signal which separates the range containing picture information from the range containing synchronizing information.

Note: The setup region is regarded as picture information.

Sync Level. The level of the peaks of the sync signal.

This Standard specifies a method of measuring the differences between these levels in a manner permitting ready correlation between the measurements at different parts of a system, regardless of the nominal voltages at the points of measurement.

1.2 Theory of Measurements

1.2.1 General: The method of level measurement prescribed in this Standard is based on the provision of oscilloscopes of standardized characteristics, with a linear scale for indicating the various levels. The scale is the same on all oscilloscopes, but each oscilloscope is calibrated with a voltage related to the nominal signal level at the point where the measurements are to be made. If the gains or losses between two measuring points on a system are normal, therefore, similar scale readings should be obtained for all the significant levels on oscilloscopes at both points regardless of differences in the voltages at the two points.

1.2.2 Scale: The standard scale is shown in the left-hand portion of Fig. 1, together with an illustrative luminance signal to show the relation between the scale and the oscilloscope presentation. It will be observed that the zero or reference point of the scale is placed at the blanking level. The upper part of this scale is marked from 0 to 100 with 100 corresponding to the reference white level. The scale is linear and two additional points (at 110 and 120) are provided to permit reading abnormally high *White Peaks*. The various levels of the picture signal are read on this scale above zero. The lower part of the scale is marked in linear steps from 0 to -50 and on it are read the levels of the sync signal.

Where other scales are used for specific purposes,

¹ Cf. "IRE standards on television: Definitions of television signal measurement terms, 1955 (55 IRE 23. S1)," PROC. IRE, vol. 43, pp. 619-622; May, 1955.

such as modulation monitoring at broadcast transmitters, the standard scale should be added to any existing scales to permit correlation with measurements at other points in the system. The standard level scale should be placed with the 0 and 100 markings corresponding to the normal *Blanking* and *Reference White Levels*, respectively, of the other scale.

2.0 APPARATUS REQUIRED

2.1 List of Equipment

A suitable oscilloscope is required for these measurements. Its specifications are given below and form a part of this Standard.

2.2 Specifications of Standard Oscilloscope for Level Measurements

2.2.1 *Measurement Accuracy:* An oscilloscope which is suitable for this application should be capable of television level measurements with errors not exceeding 2.5 units on the scale. Factors which contribute to error include:

- Spot size and brightness,
- Deflection amplitude,
- Amplifier linearity,
- Readability of scales or markers, including a reasonable allowance for parallax,
- Calibration accuracy, and stability of calibration.

2.2.2 *Bandwidth:* The oscilloscope response characteristic should be such as to introduce negligible measurement errors due to low-frequency distortion or overshoot. The response characteristics should be standardized so that uniform measurements are obtained with different oscilloscopes. The bandwidth should be great enough to yield satisfactory luminance signal level readings and narrow enough that the readings are negligibly affected by the subcarrier portion of a color signal. To meet these requirements, this Standard prescribes that the response shall be monotonic and within the limits indicated in Fig. 2. This provides 20-db attenuation (-3 db or +5 db) at 3.58 mc with respect to the low frequencies and a rise time on the order of 0.3 μsec.

The specified characteristic may be obtained by adding a suitable network to an oscilloscope of wider bandwidth. For example, Fig. 3 shows a one-stage four-terminal network that may be used for this purpose with an oscilloscope having a bandwidth much wider than the specified characteristic. By arranging to remove the network, the oscilloscope can be made available for other uses where its full bandwidth is needed, such as 1) to measure color burst amplitude in terms of IRE scale units or 2) to check the amplitude of chrominance signal peaks on a color test signal. Fig. 3 also shows the circuit constants of an idealized three-stage amplifier having the specified nominal characteristics. For oscilloscopes having intermediate bandwidth, the pre-

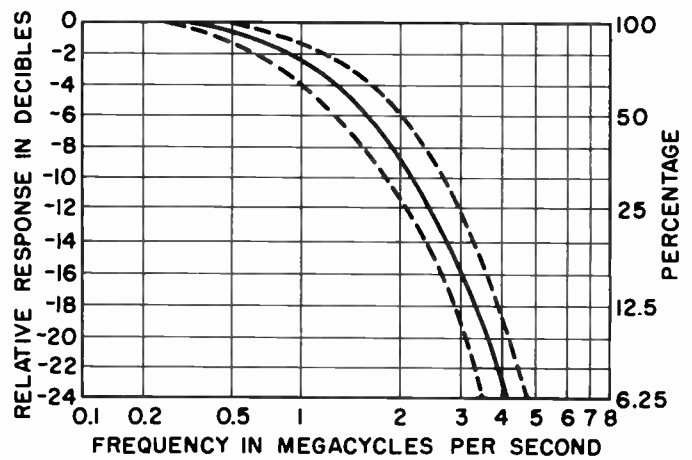


Fig. 2—Frequency response for standard oscilloscope (IRE roll-off).

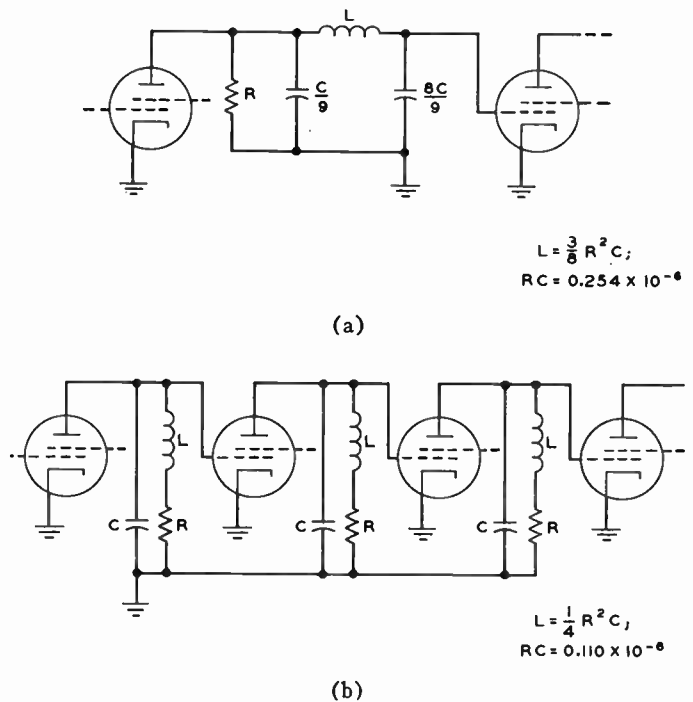


Fig. 3—Idealized networks for standard oscilloscope, R in ohms, L in henrys, and C in farads. (a) One-stage four-terminal network and (b) three-stage RCL network.

scribed responses may be attained with a smaller number of interstage networks or with different constants in the three networks.

There should be no sudden break in the response curve above 3.58 mc and the maximum response above 5 mc should be at least 20 db down with respect to that of 100 kc. The oscilloscope should indicate less than 2 per cent tilt in a 60-cps symmetrical square wave.

2.2.3 *Scale:* The oscilloscope shall be provided with the standard scale shown in Fig. 1 and described in 1.2.2 of this Standard.

2.2.4 *Calibration:* A suitable voltage calibration means shall be provided.

2.2.5 *DC Restoration:* It is highly desirable that dc

restoration at the deflection plates of the oscilloscope be employed for operational measurements on signals having changing picture content in order to prevent shifts of the trace with variations in average value of the signal. It is desirable that the time constants of such dc restoration circuits be shorter than the equivalent time constants of the ac portions of the oscilloscope amplifier to avoid shift and bounce of the base line with picture changes. At the same time, it is desirable that the time constants of the restoration circuits be as long as the above limitation allows, in order that the true low-frequency content of the signal may be exhibited.

2.2.6 Vertical and Horizontal Centering: Means shall be provided for adjusting the relative position of the scale and the oscilloscope image. This may consist either of electrical centering controls on the oscilloscope or of a movable scale.

3.0 METHOD OF MEASUREMENT

3.1 Application

Whether the oscilloscope is permanently connected to the circuit to be measured, as is the case in many operational systems, or is connected only periodically, care must be taken that the oscilloscope input circuit and the manner of connection have no adverse effect upon the signal circuit. It is essential that the circuit being measured operate with its normal source and the load impedances during the measurements.

In a transmission system the terminations may often be complex impedances, which cause the waveform to appear severely distorted when observed on an oscilloscope bridged across such a circuit. In measuring signal levels at such points, care must be exercised to properly interpret the indications. For example, where a constant-current source is used to drive a transmission system through a coupling transformer, the waveform measured directly across the transformer terminals may be so distorted as to be unusable for level measurements. It is usually preferable to connect the oscilloscope across a constant resistance point in the circuit, to which transmission from the signal origin is constant with frequency.

Low-frequency interference or distortion may seriously impair the accuracy of observation unless effective clamping means are employed. It is therefore recommended that such devices be employed wherever possible.

3.2 Adjustment

In using the oscilloscope the usual precautions must be taken to insure adequate brightness, sharp non-astigmatic beam focus, and gain-control settings which allow the necessary deflection without amplifier overload.

The oscilloscope time base should normally be synchronized at either the line rate or at one half of the line

rate when making level measurements, providing a convenient display of the longer duration *Blanking* and *Sync Levels* which occur during the vertical blanking interval. The oscilloscope brightness and focus should be adjusted to make these portions of the signal wave form visible and well defined.

3.3 Calibration

Since, in general, the measurements will be made on a video bus or line in which the signal is to be maintained at a predetermined voltage chosen for that point in the system, it shall be standard practice to maintain an oscilloscope deflection within the appropriate calibrated boundaries of the standard scale.

In using the oscilloscope method of level measurement, accurate calibration of the oscilloscope amplifier gain is a very important aspect of the technique. Calibration is concerned with adjustment of the oscilloscope amplifier gain so that a normal signal will produce a standard oscilloscope deflection. This may conveniently be done by introducing a known calibrating voltage to the input of the oscilloscope in place of the normal input signal. The calibrating signal should be one whose principal frequency components lie within the band of uniform response of the oscilloscope. If such a calibrating signal has a peak-to-peak deflection equivalent to, for example, the *Blanking-to-Reference-White Level* of the standard signal, the oscilloscope gain would be adjusted so its calibrating voltage produces a deflection from 0 to 100 on the standard scale. Experience will indicate how often calibration checks should be made to maintain the desired accuracy of level measurement.

3.4 Interpretation

Standardizing the response characteristic of the oscilloscope serves to minimize possible differences in interpretation of signal levels. To further insure uniformity in interpreting the oscilloscope indication, the measurement of *Sync* and *Blanking Levels* should be observed at a point in the waveform where the voltages representing these levels are substantially at their steady-state value. The longer duration signals of both *Sync* and *Blanking Levels* which occur during the vertical sync interval are suitable. A representation of the appearance of these portions is shown in Fig. 4, the measurements being made as indicated to minimize errors due to transmission distortion. For noncomposite picture signals, *Blanking Level* may be observed similarly during the vertical blanking interval. In setting picture signal levels, important information-bearing signal peaks will be normally held within the 0 to 100 scale range. Certain highlight signals may occasionally exceed this range. Where comparison measurements are being made at different points in a transmission system, it is important to insure that identical peaks are being considered.

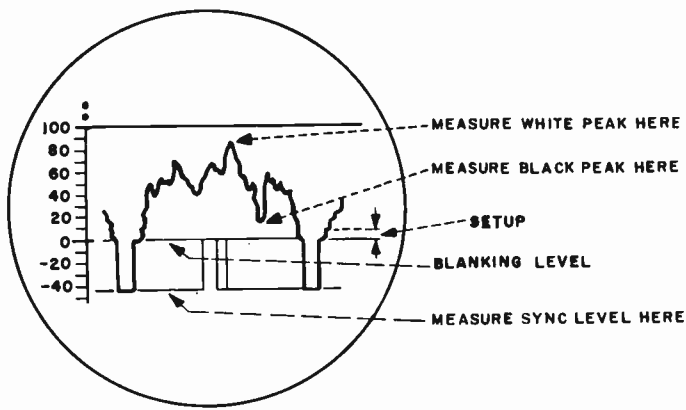


Fig. 4—Use and interpretation of IRE standard scale.

Measurements made with the IRE standard scale may be expressed as follows:

- White Peak.** 86 (meaning 86 IRE scale units or 86 per cent of the range between *Blanking* and *Reference-White Levels*).
- Black Peak.** 13 (meaning 13 IRE scale units or 13 per cent of the range between *Blanking* and *Reference-White Levels*).
- Sync Level.** -43 (meaning 43 IRE scale units or 43 per cent of the range between *Blanking* and *Reference-White Levels* but negative with respect to *Blanking Level*).

Theory of Networks of Linearly Variable Resistances*

HAROLD LEVENSTEIN†, MEMBER, IRE

Summary—A network theory is derived for circuits constructed of linear rheostats driven from a common input shaft. A correspondence between these networks and *RL* networks is used to demonstrate that driving point impedances and transfer functions are real rational fractions in a real variable, the input shaft rotation. Requirements on the pole-zero characteristics of these functions are established. Methods for developing functions approximating a given input-output relation in physically realizable form are discussed. Modern methods of transfer-function realization can be applied to these fractions to synthesize the physical networks. Networks for sine and log transfer functions obtained by the technique are presented.

BACKGROUND

IN the design of analog computers, the engineer often makes use of potentiometers whose output voltage is required to vary in a prescribed manner as the shaft of the potentiometer is rotated. To meet these requirements a variety of ingenious techniques and special circuits have been advised. Special potentiometers may be employed whose variation in resistance is obtained by winding on nonlinear cards, by winding different wire sizes along the length of the card, or by varying the spacing between wires. Taps may be distributed along the winding and connected to appropriate voltages from a voltage divider. The potentiometer may be loaded by connecting resistances from the slider to some reference potential.^{1,2}

These and more intricate circuits all have been employed widely. It is characteristic of loading methods that a wholly empirical approach is used most often. In such methods the designer "guesses" at an appropriate circuit, takes literal values for the circuit elements, and then, by more or less sophisticated mathematics, attempts to discover numbers for the literal quantities which cause the circuit to approximate best the original prescription.

Such a technique is inefficient. It provides no basis for establishing an economical design, nor does it provide any suggestion for the improvement of the design if this is required.

From a practical point of view, the use of linear potentiometers as the basis for generating prescribed nonlinear functions of shaft rotation has considerable importance. There are several reasons for this. Linear potentiometers are considerably less expensive than nonlinear components of the same precision. They are manufactured more easily. Finally, they can be obtained commercially with an extremely high degree of linearity; at present, they can be obtained with linearity tolerances of 0.015 per cent. In this paper we present derivations of some of the significant properties of networks constructed of linearly varying rheostats. Methods for reducing data to a form appropriate to such networks are described, and some of the aspects of network synthesis are considered.

STATEMENT OF THE PROBLEM

The problem will be formulated in the following way. Given a network with two input terminals and two out-

* Original manuscript received by the IRE, January 30, 1957; revised manuscript received, November 6, 1957.

† W. L. Maxson Corp., New York, N. Y.

¹ I. Greenwood, J. Holdam, and D. Mackae, "Electronic Instruments," McGraw-Hill Book Co., Inc., New York, N. Y.; 1946.

² H. Levenstein, "Generating Non-Linear Functions with Linear Potentiometers," *Trans. 1953 Natl. Conf. on Airborne Electronics*.

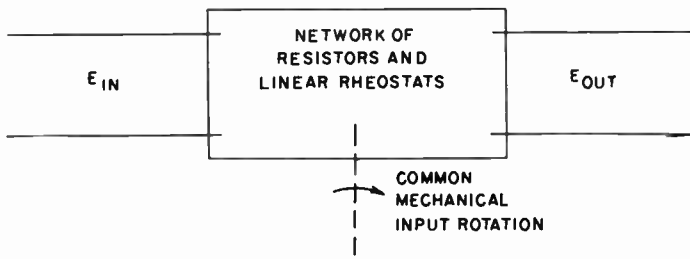


Fig. 1—The general problem.

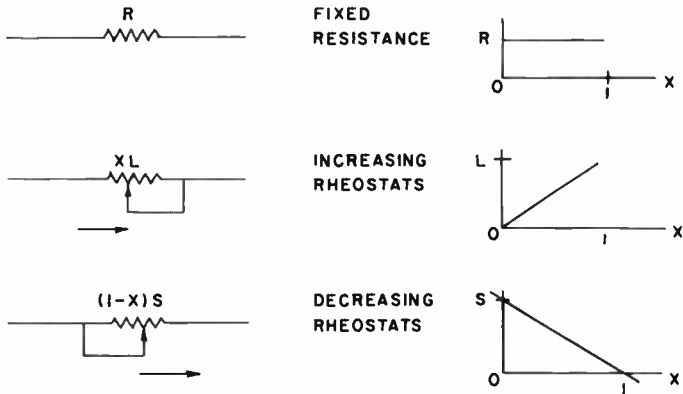


Fig. 2—The three types of elements.

put terminals and containing only fixed resistances and linear rheostats, the latter driven by a common shaft accessible from the outside, what is the relationship of the output voltage to the input voltage as a function of shaft rotation?

Note that rheostat has replaced potentiometer in this statement. Since any potentiometer can be replaced by a series connection of two rheostats, we may regard this as a more general statement of the problem.

When we have solved this problem we then can consider the problems of synthesizing networks and the problem of approximating prescribed functions. A graphic description of the problem is shown in Fig. 1.

BASIC DESCRIPTIONS OF NETWORK ELEMENTS

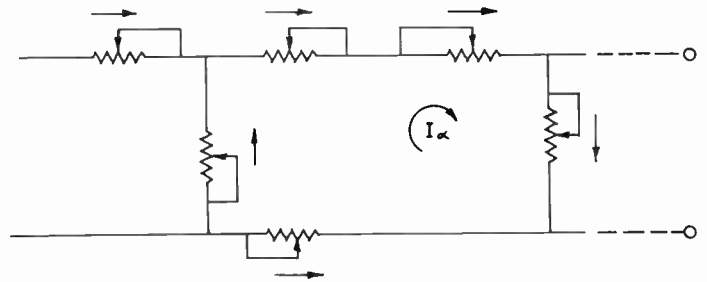
The three types of elements which must be considered are shown schematically in Fig. 2. R denotes a fixed resistance of value R . We take x , the shaft rotation, to be a variable running from zero to one, so that x represents fractional shaft rotation. There are two possible connections for rheostats: resistance increasing with x and resistance decreasing with x . If the rheostat resistance increases with x , its "instantaneous" resistance is xL , where L is the total resistance. If the start and end of the winding are reversed, the resistance decreases with x and can be denoted $(1-x)S$, where S is the total resistance. These three cases are schematically distinguished as Fig. 2(a), 2(b), and 2(c).

AN EQUIVALENT CIRCUIT THEOREM

So far we have described a network containing three types of elements. The present state of electric circuit



Fig. 3—Equivalent circuit for fixed resistor.



$$|Z_{\alpha\beta}| \cdot |I_{\alpha}| = |E_{\beta}|$$

WHERE

$$Z_{\alpha\beta} = xL_{\alpha\beta} + (1-x)S_{\alpha\beta}$$

Fig. 4—Circuit relationships.

theory does not permit the complete treatment of circuits of more than two mathematically independent elements. Accordingly, we shall make note of a superficially trivial relation which permits a complete treatment of this problem. We observe that every fixed resistance R can be replaced by a series connection of two rheostats of values xR and $(1-x)R$. (See Fig. 3.) Thus, if we replace each fixed resistance by its equivalent circuit of two series rheostats, the network is reduced to one containing only two types of elements.

We may now refer to the general theory of such networks for a solution.

PROPERTIES OF NETWORKS CONTAINING TWO TYPES OF ELEMENTS

While it is not necessary to do so, we shall find it most convenient from the viewpoint of exposition to draw a close analogy between the networks we have hypothesized and networks consisting of resistors and inductors (with no mutual coupling), and to make use of the analogy to arrive at the properties of the networks.

To arrive at this analogy, we may begin by considering Fig. 4, which illustrates a typical network. Each element is either of the x type or $(1-x)$ type. If we assume mesh currents and write mesh equations, we find the customary matrix relation:

$$|Z_{\alpha\beta}| \times |I_{\alpha}| = |E_{\beta}| \tag{1}$$

Each term of $Z_{\alpha\beta}$ is generally of the form:

$$Z_{\alpha\beta} = xL_{\alpha\beta} + (1-x)S_{\alpha\beta} \tag{2}$$

Now, if we divide every term of $Z_{\alpha\beta}$ by x and multiply every current by x , we will have modified the elements of the matrices without modifying the matrix equation. Formally let us define

$$Z_{\alpha\beta}^* = Z_{\alpha\beta}/x \tag{3}$$

and

$$I_{\alpha}^* = xI_{\alpha} \tag{4}$$

Then the matrix equation becomes:

$$|Z_{\alpha\beta}^*| \times |I_{\alpha}^*| = |E_{\beta}| \tag{5}$$

The elements of the Z^* matrix will now have the form:

$$Z_{\alpha\beta}^* = L + \frac{1-x}{x} S \tag{6}$$

If we introduce a new parameter p defined by (7)

$$p = \frac{1-x}{x} \tag{7}$$

these elements become:

$$Z_{\alpha\beta}^* = L + pS \tag{8}$$

Thus, the relations between the starred mesh currents and the voltages have the same mathematical structure as the relations which exist in a network constructed of resistances and inductances. Since the theory of these circuits has been highly developed, we may adopt it and use it to predict the properties of variable resistance networks.³

Accordingly, we may now make the following statements:

1) The driving-point impedance of the starred networks, the ratio of voltage to starred current, is a rational fraction in p . The degree of the numerator is equal to or one more than the degree of the denominator. The roots of the numerator and the denominator must be simple, real, negative, and must alternate with the least (magnitude) root of the numerator less than the least root of the denominator.

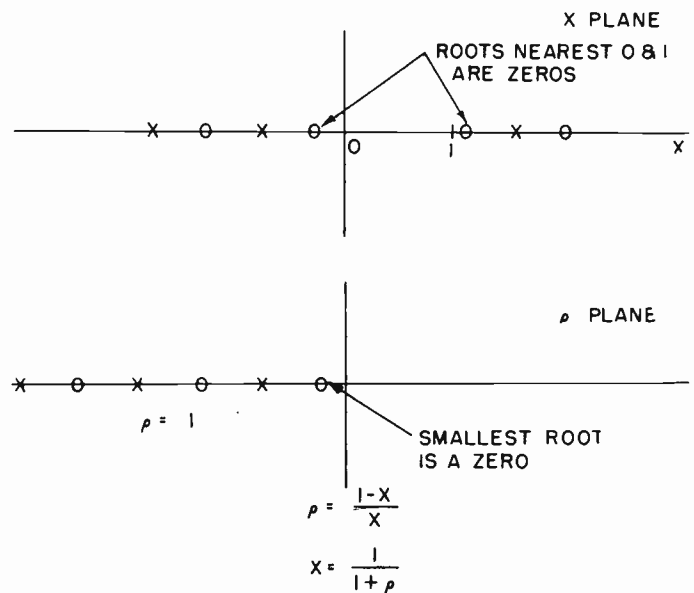
2) The transfer function of the starred network, the ratio of voltage across the load to input voltage, is a rational fraction in p . The order of the numerator is equal to or less than the order of the denominator. The roots of the numerator may lie anywhere in the complex p plane, with the restriction that complex roots must occur in conjugate pairs. The roots of the denominator must be simple, real, and negative.

When we introduce the inverse transformation from p to x we can restate 1) and 2) as follows:

3) The driving point impedance of the variable resistance networks is a rational fraction in x . The order of the numerator may be equal to, or one, or two more than the order of the denominator. The roots of the numerator and the denominator must be simple, real, and lie outside the range of $0 < x < 1$.

Within the ranges $-\infty < x < 0$ and $1 < x < \infty$ the alternation property of the poles and zeros still holds, with the zeros of the numerator closer to 0 and 1 than the

³ E. Guillemin, "A Summary of Modern Methods of Network Synthesis" in "Advances in Electronics," Academic Press, New York, N. Y., vol. 3, pp. 261-301; 1951.



POLES AND ZEROS OF THE x FUNCTIONS AND THE p FUNCTIONS MUST ALTERNATE.

Fig. 5—Typical pole-zero distribution of driving-point impedance in p plane and x plane.

corresponding zeros of the denominator. A picture of the zero-pole distribution in the p and x planes is shown in Fig. 5.

4) The transfer function of the variable resistance networks is a rational fraction in x . The order of the numerator may be equal to or less than the order of the denominator plus one. The roots of the numerator may lie anywhere in the complex plane. The roots of the denominator must be simple and real and may lie anywhere except in the range $0 \leq x \leq 1$.

In all cases, complex roots appear in complex conjugate pairs.

The derivations of the above relations appear in Appendix I.

While it is possible to deduce other related properties, these are sufficient to characterize the next phase of the problem, the approximation problem. We shall derive additional information where we require it (for example, in the synthesis phase).

It may be informative to note that the transformation of p to x is a mapping of the p plane into the x plane. While we are most often concerned with the real axes, the general character of the mapping, a bilinear transformation, is of interest when we are dealing with the complex roots of the numerator of the transfer function. Fig. 6 shows the nature of the mapping performed.

THE APPROXIMATION PROBLEM

Since for the most part these networks are not used as impedances, we shall concern ourselves primarily with methods of approximating prescribed data by functions characteristic of the transfer function. In any event, there is no serious difficulty in extending these methods to specification of impedance function.

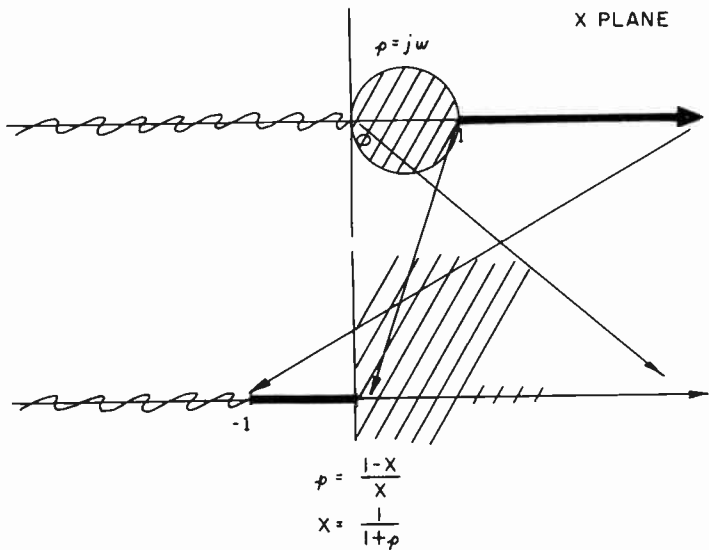


Fig. 6—Mapping between p and x planes.

The approximation problem usually is presented as follows: the desired output function y shall vary with an independent parameter z in a certain functional, graphical, or tabular manner. What rational fraction in x shall we select to best approximate this relation between z and y ? This fraction must have the properties stated as 3).

Since the range of variation of x is zero to one, we must first establish a scale factor between z and x ; sometimes, as in the case of the log function, we must shift the origin. While it is conceivable that we may select a nonlinear transformation from z to x (for example, in the case where the x shaft carries a calibrated dial displaying the inverse transformation), we ordinarily employ a linear transformation. In any event we must first establish a relation between y and x over the range $0 \leq x \leq 1$.

It is not necessary to modify the scale of y at this time, although it is likely that this will be necessary in synthesizing the network.

An answer to this approximation problem has been found in standard interpolation theory.^{4,5} Formally, if we select n values of y : $y_0, y_1, \dots, y_i, \dots, y_{n-1}$ corresponding to $x_0, x_1, \dots, x_i, \dots, x_{n-1}$, values at which we wish to make our approximation exact, we merely need to substitute them in the determinant of Fig. 7 and solve for y to find an approximating rational fraction.

Unfortunately, there is no guarantee that the roots of the denominator will be of the proper nature. There is every likelihood that they will be complex.

One recourse we have is to manufacture a rational fraction with the proper denominator. An effective technique is the following:

1) Fit a polynomial in x to y by any suitable technique; for example, by least squares. Call it $Q(x)$.

⁴ W. E. Milne, "Numerical Calculus," Princeton Univ. Press, Princeton, N. J., 1949.

⁵ L. M. Milne-Thompson, "Calculus of Finite Differences," Macmillan & Co. Ltd., London, Eng., pp. 106-108; 1951.

GIVEN: $y = y_0, y_1, \dots, y_n, \dots, y_N$
CORRESPONDING TO
 $x = x_0, x_1, \dots, x_n, \dots, x_N$

FIND: $Z = N(x) / D(x)$ SUCH THAT $Z = y$ AT THE SELECTED POINTS

SOLUTION: FORM THE FOLLOWING DETERMINANT, SET EQUAL TO ZERO, AND SOLVE FOR Z .

$$\begin{vmatrix} 1 & y_0 & x_0 & x_0 y_0 & x_0^2 & x_0^2 y_0^2 & \dots & \dots \\ 1 & y_1 & x_1 & x_1 y_1 & x_1^2 & x_1^2 y_1^2 & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ 1 & y_n & x_n & x_n y_n & x_n^2 & x_n^2 y_n^2 & \dots & \dots \\ 1 & Z & x & x Z & x^2 & x^2 Z^2 & \dots & \dots \end{vmatrix} = 0$$

Fig. 7—Milne's method for finding rational fraction approximation. (Milne, *op. cit.*, ch. VIII.)

2) Divide this by a polynomial in x , denoted $P(x)$, constructed of pairs of factors of the form $(x-a)$ $(x+a-1)$. That is,

$$P(x) = \prod_{i=1}^n (x - a_i)(x + a_i - 1). \tag{9}$$

The order of $P(x)$ is $2n$ and is selected to be equal to or greater than one plus the order of $Q(x)$. The a_i are all different and chosen remote from the range of interpolation. Accordingly, $P(x)$ approximates a constant over $0 \leq x \leq 1$. It is often convenient to factor $Q(x)$ first since, if it possesses a root b_i which is real and outside the range of interpolation, we may make one of the a_i identical with b_i and thus reduce the order of $Q(x)$ and $P(x)$.

3) $Q(x)/P(x)$ is an acceptable transfer function which is physically realizable.

A further refinement of this process consists of forming the product $P(x)Y$ and fitting a polynomial $Q^*(x)$ to this modified datum. Generally, if $Q(x)$ and $Q^*(x)$ are of the same order, $Q^*(x)/P(x)$ more accurately fits the data than $Q(x)/P(x)$.

Another method for finding a rational fraction approximation which provides some control of the denominator is presented in Appendix II.

For the purposes of this paper, we may consider the approximation problem solved.

THE SYNTHESIS PROBLEM

Since network synthesis is an ever changing art with the personal preference or experience of the engineer often the dominating factor in the solution, we shall merely show how the problem is reduced to a form suitable for synthesis by any acceptable technique. Some post-synthesis considerations will be introduced.

At the conclusion of the approximation stage we

$$\text{SINH } \theta \approx K \frac{X(X+4.3503)}{(X-3.1312)(X+1.5474)}$$

$$\gamma = K \frac{X(X+0.64436)}{(X+1.5618)(X+0.28629)}$$

$$\sim \text{LOG}(10X+1) \quad 0 < X < 1$$

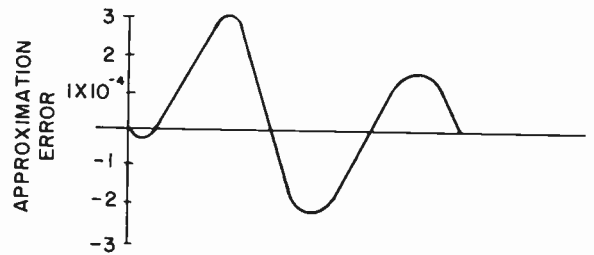
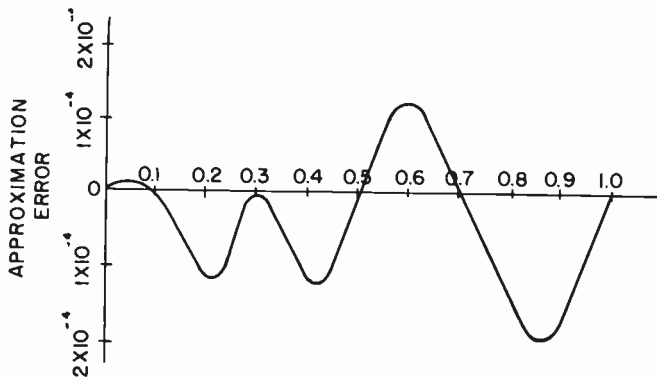
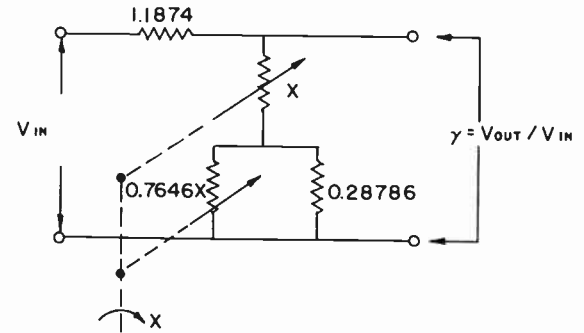
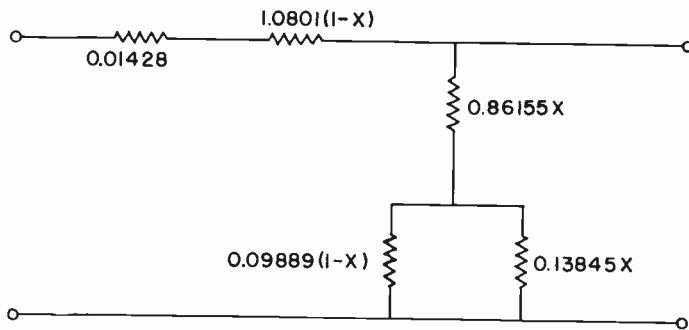


Fig. 8—Network for sinh θ .

Fig. 9—Log function network.

TWO EXAMPLES

possessed a function Y

$$Y = Q(x)/P(x) \tag{10}$$

which approximates $y=y(x)$ in a satisfactory manner over the range of x .

The substitution of $x=1/(1+p)$ into (10) provides a relation between Y and p identical with the transfer function of an RL network. Accordingly, using the methods of Guillemin^{3,6,7} or Bower and Ordnung,⁸ we can arrive at a network configuration and component values for this equivalent RL network.

We next replace p by $(1-x)/x$ in the circuit impedances. This, of course, leaves us with nothing recognizable. We must recall that the transformation into the RL network also included the scaling of every component value by division by x . Accordingly, we multiply every component by x and find that we can now interpret the network as a combination of x -type rheostats and $(1-x)$ -type rheostats. By use of equivalent circuits we may be able to replace some of the rheostats by fixed resistors or potentiometers. Some of these equivalences are shown below (Figs. 10 and 11).

Figs. 8 and 9 show two examples of the application of the theory. In both cases it happened that it was not necessary to force the approximating functions into appropriate form. Fig. 8 shows a network for generating the hyperbolic sine over the range zero to one. Fig. 9 is a circuit for generating log x ; it is notable for its simplicity. In each figure the error is plotted as a function of shaft rotation. The extraordinary quality of the approximating function coupled with the simplicity of the circuits is indicative of what can be accomplished when the properties of these networks are properly used.

SOME EQUIVALENT CIRCUITS

In Fig. 10 we have tabulated some equivalent circuits and their impedance representations in the x and p variables. They are intended primarily for use in recognizing standard configurations and in simplifications of the synthesized networks.

FIELDS FOR EXTENSION OF THE THEORY

Several questions can be raised which indicate possible directions for extension of the theory. One important question is: what are the properties of networks in which the rheostats are turned by several independent variables? Perhaps this can be answered partly by considering what the possibilities are for networks whose driving point impedances are substantially constant over a considerable range, while possessing prescribed transfer functions. Such networks could be cascaded to obtain products of functions of independent variables.

⁶ J. G. Truxal, "Control System Synthesis," McGraw-Hill Book Co., Inc., New York, N. Y., ch. 3, pp. 161-220; 1955.

⁷ P. M. Lewis, "The Synthesis of Voltage Transfer Functions," M.I.T., Res. Lab. of Electronics, Cambridge, Mass., Tech. Rep. 314; June, 1956.

⁸ J. L. Bower and P. F. Ordnung, "The synthesis of resistor capacitor networks," Proc. IRE, vol. 38, pp. 263-269; March, 1950.

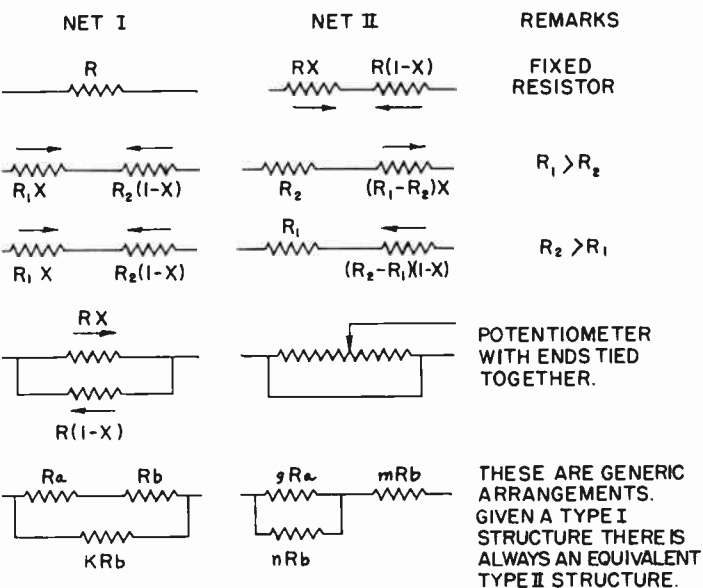


Fig. 10—Equivalent two-terminal nets.

While the discussion has been limited to linear rheostats, it is obvious that it is applicable to similar networks made up of adjustable capacitors or inductors. There may be special advantages to these circuits.

Finally, there may be some advantage in range of application to circuits constructed of some special functional rheostats which are not so readily obtained commercially. As an example, the use of sine-cosine elements may simplify some of the elaborate trigonometric relations associated with changes of coordinate reference systems in gimbal structures.

APPENDIX I

DERIVATION OF DRIVING-POINT IMPEDANCE AND TRANSFER-FUNCTION RELATIONS IN THE X PLANE

Driving-Point Impedance

In the text it is shown that the driving-point impedance can be written by means of suitable transformations in the form

$$Z = xZ^*(p). \tag{11}$$

Where $Z^*(p)$ has the form of an RL network driving point impedance

$$Z^*(p) = K \frac{(p - p_1)(p - p_3) \dots}{(p - p_2)(p - p_4) \dots} \tag{12}$$

In this form the p_i 's are negative, real, and alternate and p_1 is closest to the origin. The degree of the numerator may be equal to or one greater than the degree of the denominator.

By definition

$$p = \frac{1 - x}{x} \tag{13}$$

Substituting in (12) and rationalizing we have

$$Z^* = \bar{K}x^{m-n} \frac{\left(x - \frac{1}{1+p_1}\right)\left(x - \frac{1}{1+p_3}\right) \dots}{\left(x - \frac{1}{1+p_2}\right)\left(x - \frac{1}{1+p_4}\right) \dots} \tag{14}$$

m = the degree of the denominator,
 n = the degree of the numerator,
 \bar{K}^* = a new value of K appropriate to the rearranged form. Then

$$Z = xZ^* = \bar{K}x^{m-n+1} \frac{\left(x - \frac{1}{1+p_1}\right)\left(x - \frac{1}{1+p_3}\right) \dots}{\left(x - \frac{1}{1+p_2}\right)\left(x - \frac{1}{1+p_4}\right) \dots} \tag{15}$$

We can now evaluate the polynomial relationships under the following possible conditions:

$$n = m$$

and

$$n = m + 1$$

If $n = m$, there are the same number of roots in numerator and denominator and

$$Z = \bar{K}x \frac{N(x, n)}{D(x, n)} \tag{16}$$

In this form the total numerator is one degree higher than the denominator.

If $n = m + 1$, then

$$Z = \bar{K} \frac{N(x, n)}{D(x, n - 1)} \tag{17}$$

The numerator is again one degree higher than the denominator.

We must add to this the special case in which one of the p_i 's is (-1) . We handle all of the factors except this one as before. This factor disappears. To see this we evaluate the factor explicitly:

$$F = (p + 1) = \left(\frac{1 - x}{x} + 1\right) = \frac{1}{x} \tag{18}$$

Thus the contribution to x^{m-n+1} appears as before but the factor disappears from N or D , depending upon where it appeared.

Since the poles and zeros are simple, this situation can happen only once. But it can occur in either the numerator or the denominator.

In summary, the degree of the numerator may be equal to or one or two greater than the degree of the denominator.

Transfer Function

We may develop the transfer function relationship in

much the same manner that we have handled the driving point impedance.

We are concerned with the ratio here of an output voltage to the input voltage as a function of p first, and then x .

Starting with the RL equivalent of the resistance network we can describe the voltage transfer function as a ratio of polynomials in p

$$T = K \frac{N(p)}{D(p)} \quad (19)$$

The roots of $D(p)$ must be simple, negative, and real. The roots of $N(p)$ may be anywhere in the complex plane provided that for every complex root a conjugate root appears.

The degree of the numerator may be equal to or less than the degree of the denominator.

Note that x does not appear explicitly since we are dealing with a voltage ratio only, not an impedance.

Now rewrite (19) in the form

$$T = K \frac{(p - p_1)(p - p_3) \cdots}{(p - p_2)(p - p_4) \cdots} \quad (20)$$

No special ordering is implied here by the subscripts. Letting $p = (1 - x)/x$, and rationalizing

$$T = \bar{K} x^{m-n} \frac{\left(x - \frac{1}{1+p_1}\right) \left(x - \frac{1}{1+p_3}\right) \cdots}{\left(x - \frac{1}{1+p_2}\right) \left(x - \frac{1}{1+p_4}\right) \cdots} \quad (21)$$

We are interested in the cases, $m = n$ and $m > n$. We must also consider the effects of a root at $p = (-1)$ which may occur simply in the denominator or multiply in the numerator.

Let $m = n$. Then the leading terms in the numerator and the denominator are both x^m ; their degree is the same.

Let $m > n$; the leading terms are x^m in both polynomials and the degree is the same, again.

Now let a simple root occur at $p = -1$ in the denominator. As before this factor will disappear from the denominator. The leading term in the numerator will be x^m , in the denominator x^{m-1} . The degree of the numerator is one higher than the degree of the denominator.

Let a multiple root of order k appear at $p = -1$ in the numerator. The leading term in the numerator will be x^{m-k} , in the denominator x^m , k higher than the numerator.

In summary, the degree of the numerator may be equal to or less than one plus the degree of the denominator.

Ordering Property of the Poles and Zeros of a Driving-Point Impedance

Poles and zeros of $Z^*(p)$ alternate on the real negative axis. A detailed examination of the way in which these roots map into the x axis shows the following:

1) The alternation property is preserved. However if these roots lie outside the range $(-1 < P < 0)$, the relationship occurs over two regions.

The poles and zeros lying between $(-1 < P < 0)$ map into the corresponding range $(0 < x < 1)$. The root closest to $x = 1$ is a zero and the poles and zeros alternate along the axis out to infinity. The ordering relationship then continues in along the negative real x axis from $-\infty$ to zero.

If $m = n$ in $Z^*(p)$ there will be a zero at the origin in the x plane due to the relationship

$$Z = xZ^*$$

If $m = n - 1$, the root closest to the origin in the x plane along the negative x axis will be a zero. Thus, in general, the alternation property holds, starting with a zero at or to the right of $x = 1$, continuing to infinity and returning along the negative axis, and concluding with a zero at or to the left of the x origin.

APPENDIX II

CONSTRUCTION OF A RATIONAL FRACTION TO FIT ASSIGNED DATA

Milne-Thompson⁵ describes a method due to Thiele for constructing a continued fraction approximation to data. By terminating the fraction we obtain a rational fraction fitting the data at n specified points. A minor modification of this method gives additional freedom to adjust the roots of the denominator so that frequently they can be made to lie in the desired ranges without increasing the complexity of the network or changing the points of fit. Since the method is direct and reasonably simple it is usually worth trying.

The continued fraction proposed has the form

$$\bar{y} = a_0 + \frac{(x - x_0)}{a_1 + \frac{(x - x_2)}{a_2 + \frac{(x - x_2)}{a_3 + \cdots}}} \quad (22)$$

The x_i 's are the points of fit, \bar{y} is the approximation to y , the given data, and the a_i 's are initially unknown.

Inspection of the above equation shows that the a 's are readily determined in sequence.

If we set $x = x_0$, and $y = y_0$, we compute a_0 . Then set $x = x_1$, $y = y_1$, and compute a_1 . Setting $x = x_n$ makes the portion of the succeeding fraction identically zero, so that we can terminate the fraction at $x = x_n$ without changing the previous points of fit. The fraction can then be written in the form:

$$\bar{y} = a_0 + \frac{(x - x_0)}{a_1 + \frac{(x - x_1)}{a_2 + \cdots + \frac{(x - x_{n-2})}{a_{n-1} + \frac{(x - x_{n-1})}{a_n}}} \quad (23)$$

As we noted \bar{y} is identical with y at the points $x = x_0, x_1 \dots x_{n-1}$. In addition, they are identical at $x = x_n$, since at that point the quantity $(x - x_n)$ is zero and would contribute nothing to the function in this form. Thus the $n+1$ coefficients characterize the function.

It is merely a matter of some algebra to rearrange this function as a rational fraction, which now approximates the data over the range $x_0 \leq x \leq x_n$.

$$\bar{y} = \frac{P(x)}{Q(x)} \tag{24}$$

However, the roots of Q may not be properly placed for y to be a realizable function. So, instead of terminating the function with a_n we add the term $K(x - x_n)$ where K is an arbitrary parameter to be determined. Since when $x = x_n$ this term is zero, we have not changed the points of fitting.

Rearrangement of the function into a rational fraction now yields

$$\bar{y} = \frac{P(x) + K(x - x_n)P_1(x)}{Q(x) + K(x - x_n)Q_1(x)} \tag{25}$$

This is a function which has the same points of fit as (24), but by adjustment of K we have some freedom to adjust the roots of the denominator. At the most this increases the complexity of the network by one degree.

It is clear that the functions P_1 and Q_1 must be proportional to P and Q at all points of fit except X_n , where this is unnecessary.

When $Q(x)$ is of reasonable degree, say 3 or 4, the numerical work associated with finding suitable values of K so that the roots of Q are real, simple, and do not lie inside the $0 \leq x \leq 1$ range is not usually prohibitive.

When a suitable selection has been made, it is necessary of course to check performance between the points of fit to determine the magnitude of errors; increasing the number of points of fit will, in general, permit reduction of errors.

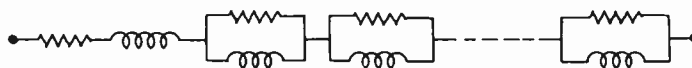
APPENDIX III

CHARACTERISTICS OF DRIVING-POINT IMPEDANCES

Shannon and Hargelbarger⁹ show the driving-point impedance of a variable resistance network must always be a convex upward function of rotation. This is ac-

⁹ C. E. Shannon and D. W. Hargelbarger, "Concavity of resistance functions," *J. Appl. Phys.*, vol. 27, pp. 42-43; January, 1956.

CANONICAL FOSTER FORM FOR RL NET



CANONICAL FOSTER FORM FOR VARIABLE RESISTANCE NETWORK

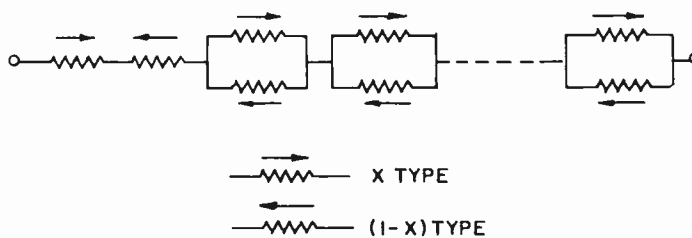


Fig. 11.

complished through investigation of hypothetical experimental connections of the network. In the following paragraphs, we wish to prove this relation using the network theory developed in the body of this paper.

Every variable resistance network has an analog in the form of an *RL* network. Cauer's investigation of two terminal *RL* nets displays as one general canonical configuration a Foster form in which the network can be drawn as a series connection of parallel *RL* nets in series with a resistance and inductance. The series resistor and inductor may be identically zero.

The variable resistance analog of this is shown in Fig. 11.

The equation for the driving-point impedance can be written

$$Z(x) = R_{10}(x) + R_{20}(1 - x) + \sum \frac{R_{1i}R_{2i}(1 - x)x}{xR_{1i} + R_{2i}(1 - x)}$$

Double differentiation of $Z(x)$ shows that

$$\frac{d^2Z(x)}{dx^2} \leq 0.$$

This can be verified very simply by sketching the $Z(x)$ curve of any of typical sections.

ACKNOWLEDGMENT

The author is indebted to Dr. H. Hochstadt for working out the two illustrative approximating functions and to Miss M. Whitfield and Mrs. R. Waldmann for the calculations associated with them.



Correspondence

A Parametric Electron Beam Amplifier*

A new type of solid state microwave amplifier has recently been proposed by Suhl.¹ Amplification of the signal occurs by transfer of power from a local rf source at a frequency higher than the signal and can be achieved by using certain properties of ferrites.

The purpose of this note is to show that a similar amplifier can be devised using an electron beam instead of the ferrite. Such an amplifier has the possibility of very-low-noise operation. The fundamental limitations² of the noise performance of conventional microwave amplifiers do not apply to it. An amplifier of this type has been built and some initial experimental results are given. The term "parametric amplifier" has been used because the device works by a variation in a circuit parameter.

In the simplest form of parametric amplifier the local source of power (usually called the pump) operates at exactly twice the signal frequency. The arrangement is shown in Fig. 1, where a parallel tuned circuit is reso-

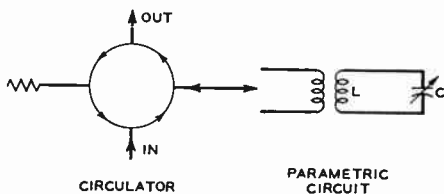


Fig. 1—Simple parametric circuit.

nant to the signal. The capacity (or inductance) is modulated at twice the signal frequency $\omega/2\pi$;

$$e.g., C = C_0[1 + \epsilon \sin(2\omega t + \phi)]. \quad (1)$$

ϵ is a modulation coefficient with maximum value of 1.

If a signal at ω is applied to the circuit, then it can be shown that the capacity variation will inject, or extract power from the signal, depending on the value of the phase angle ϕ . The effect is equivalent to shunting a conductance G_p across the capacity where

$$G_p = -\frac{\omega C_0 \epsilon}{2} \cos \phi. \quad (2)$$

When $\phi=0$, G_p has a maximum negative value and conditions are best for feeding power into the circuit.

If ϵ is then increased until $-G_p$ equals the loaded shunt conductance G_L of the circuit, oscillations will occur at frequency ω without the presence of the external signal. This condition is given by

$$G_L = -G_p = \frac{\omega C_0 \epsilon}{2}$$

or

$$\epsilon = \frac{2G_L}{\omega C_0} = \frac{2}{Q_L}, \quad (3)$$

where Q_L = loaded Q of circuit.

At a value of ϵ slightly less than that for oscillation, the circuit is stable and amplification can be obtained. The device acts as a regenerative amplifier like the maser and the regenerative reflex klystron amplifier. The operation of such an amplifier has been described by Gordon and White.³ A single line is coupled to the circuit and the input and output signals are separated in a circulator. (See Fig. 1.) As well as preventing the loss of some of the output power into the input line, the circulator isolates the cavity from external load variations and enables stable operation much closer to the oscillation point with correspondingly higher gain.

Operating in this way the power gain is simply the square of the reflection coefficient (Γ) of the resonant circuit.

Power gain

$$= \Gamma^2 = \left[\frac{2}{1 + Q_E \left(\frac{1}{Q_0} - \frac{\epsilon}{2} \cos \phi \right)} - 1 \right]^2, \quad (4)$$

where Q_E is the external Q of the loaded circuit and Q_0 is the unloaded Q of the circuit. It will be noticed that the gain cannot exceed 1 (assuming $\cos \phi=1$) unless $\epsilon/2 > 1/Q_0$; i.e., unless the parametric variation is sufficient to make the unloaded circuit oscillate.

If the signal frequency differs slightly from half the pump frequency ($\omega_p/2\pi$), then the result can be described by a variation of the phase angle with time.

$$\phi = 2 \left(\omega - \frac{\omega_p}{2} \right) t. \quad (5)$$

This causes a periodic amplification and attenuation of the signal at the frequency $(\omega - \omega_p/2)/\pi$. Essentially the output signal is modulated at twice the beat between the signal and half the pump frequency, giving rise to sidebands. The actual bandwidth of the amplifier is determined by the loaded Q .

An electron beam can be used to produce an electronic admittance in a microwave cavity, and one way of doing this is used in klystron oscillators. Take for example the "floating drift tube" klystron. There are two equal gaps in a single cavity separated by a field free drift space. A beam of electrons passes through the cavity and is arranged to have a drift angle between gaps given by

$$\alpha = (2n + 3/2)\pi \text{ radians,}$$

where α = drift angle

$$n = 0, 1, 2, 3 \dots$$

An electronic admittance is produced across the cavity which is a pure negative conductance. This can overcome the positive conductance of the cavity and give rise to oscillation.

If, however, the drift angle is made a quarter cycle greater or smaller than this, the electronic admittance becomes a pure susceptance shunted across the cavity. This occurs when

$$\alpha = (2n + 1)\pi \text{ for a positive susceptance,}$$

$$\alpha = (2n + 2)\pi \text{ for a negative susceptance.}$$

This susceptance will change the resonant frequency of the cavity without altering the effective losses. As seen above, however, by modulating this susceptance at twice the signal frequency, a negative conductance will be produced which can overcome the cavity losses and give oscillation or amplification of the signal.

To modulate the susceptance, the beam must be modulated. This can be done by means of a preceding cavity resonant to the pumping frequency. If this is supplied with pumping power, any degree of beam modulation up to 100 per cent can be obtained at the signal cavity. The optimum spacing between cavities is a quarter of the effective plasma wavelength. The arrangement is shown in Fig. 2.

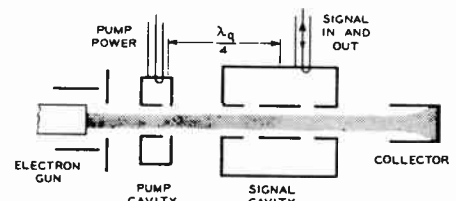


Fig. 2—Parametric beam amplifier.

The rf current (at the pump frequency) in the beam necessary to start parametric oscillations is given by

$$I_{rt} = \frac{4G_L V_0}{M^2 \alpha}, \quad (6)$$

where

- V_0 = beam voltage;
- M = signal cavity gap coupling factor;
- I_{rt} = peak rf current on the beam.

If the beam is 100 per cent modulated,

$$I_{rt} = I_0,$$

where I_0 = dc beam current. It will be recognized that I_{rt} is just twice the start oscillation current of a floating drift tube klystron. A parametric beam amplifier should therefore operate with reasonable values of voltage and current.

Now, consider noise currents in the beam at the signal frequency. If the drift angle between gaps is $(2n + 1)\pi$ radians (corresponding to a positive susceptance) and is short

* Received by the IRE, November 8, 1957.

¹ H. Suhl, "Proposal for a ferro-magnetic amplifier in the microwave range," *Phys. Rev.*, vol. 106, p. 384; April 15, 1957.

² H. A. Haus and F. N. H. Robinson, "The minimum noise figure of microwave beam amplifiers," *Proc. IRE*, vol. 43, pp. 981-991; August, 1955.

³ J. P. Gordon and L. D. White, "Experimental determination of the noise figure of an ammonia maser," *Phys. Rev.*, vol. 107, pp. 1728-1729; September 15, 1957.

in terms of the plasma wavelength, the currents at the two gaps are essentially equal in amplitude and are in antiphase. No noise currents will be induced into the cavity. In other words, by choosing the drift cycle to be π , 3π , 5π , etc., it is possible to excite a cavity to produce amplification without coupling to the noise current in the beam, at least to a first order of approximation.

A demountable tube based on Fig. 2 has been built. This operated, as far as gain and oscillation, substantially as expected. No noise measurements have yet been made. Table I shows the measured characteristics

TABLE I

Signal Cavity Resonant Frequency Drift Angle	4150 mc 3π radians
Pump frequency	8300 mc
Beam voltage	2450 v
Beam current	18 ma
Pump power	140 mw
Maximum observed gain	20 db

of the device. Fig. 3 demonstrates amplification obtained as a function of pumping power. In this figure cw power at constant frequency was used for the pump and the signal frequency was swept through the resonance of the signal cavity. In Fig. 3(a) the pumping power was zero, and the oscillation mode of the signal source klystron is seen with the resonance absorption of the signal cavity in the center (critically coupled). By increasing the pumping power to 35 mw and tuning in to twice the signal cavity frequency, some reduction in cavity loss was obtained [Fig. 3(b)]. Fig. 3(c)–3(e) shows gain with 56, 82, 140 mw of pumping power, respectively.

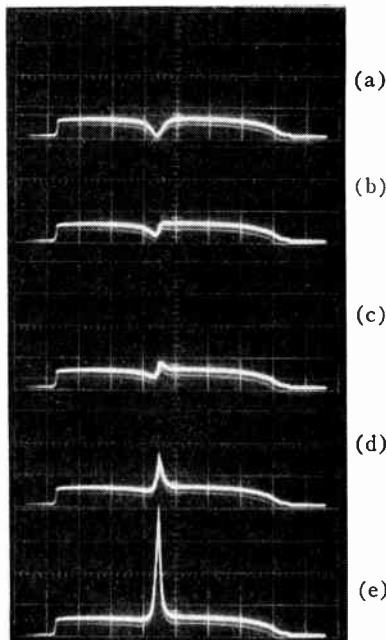


Fig. 3—Parametric amplification as function of pumping power.

Fig. 4 shows an enlarged section of the gain region. During the sweep, the phase changes periodically from that giving amplification to that giving attenuation, and this

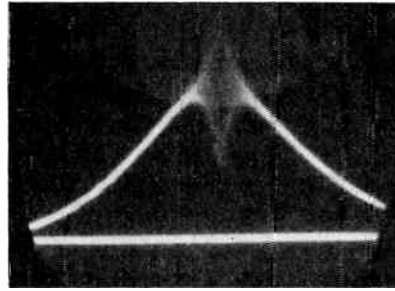


Fig. 4—Enlarged portion of Fig. 3(e).

accounts for the pattern seen in the center of the picture. The width of the pattern depends on the bandwidth of the video amplifiers used.

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**On the Earth Geometry—
A Theorem***

If one chooses an arbitrary point P inside of a circle other than its center, a normal s upon the diameter, both through P , intersects the circle with ψ , which is the angle between s and the tangent to the circle through the intersection point (Fig. 1). It can be shown analytically that ψ increases if s is rotated on P in either sense. For the conditions stated above ψ must be a minimum.

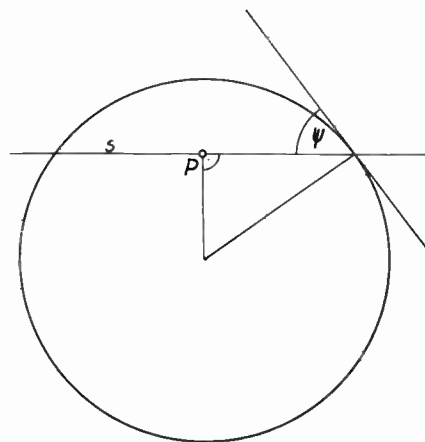


Fig. 1.

Applied to the earth geometry and to propagating radio waves which are reflected by the ionosphere, one arrives at the following conclusion: if the antenna height is zero and a radio beam is moved progressively from the zenith to the horizon, ψ , the angle of incidence at the reflecting layer, diminishes monotonously and reaches a minimum for zero elevation angle Δ of the beam, provided earth and ionosphere are concentric

* Received by the IRE, August 30, 1957.

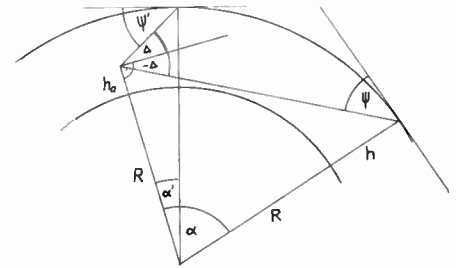


Fig. 2—The earth geometry.

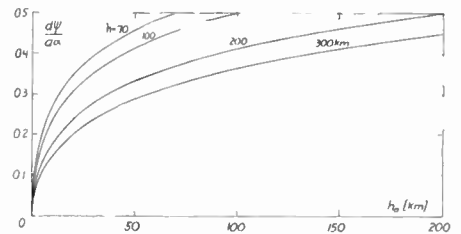


Fig. 3— $d\psi/d\alpha$ for negative elevation angles Δ as a function of antenna h_a and layer height h .

spheres (Fig. 2). Applying the same procedure to finite antenna heights, it can be shown that ψ passes through this minimum before the beam becomes tangent to the earth, i.e., for a negative elevation angle Δ of the beam $d\psi/d\alpha$ is positive. For an earth whose radius is modified so as to include uniform refraction in the atmosphere $k=1.25$ and for negative values of Δ , $d\psi/d\alpha$ was calculated as a function of antenna elevation h_a for various heights of the reflecting layer h (Fig. 3). $d\psi/d\alpha$ is less than one half for all practical cases of $h_a < h$.¹

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¹ Negative values of Δ correspond to the beam grazing the earth.

**Behavior of Noise Figure in
Junction Transistors***

Nielsen¹ has presented a well-organized treatise on a timely subject. He has simplified van der Ziel's circuit by assuming the emitter and collector noise generators are uncorrelated. It may be of interest to see how the noise figure expressions may be modified to include the effect of partial correlation of the emitter and collector noise generators.

Van der Ziel^{2,3} has determined the magnitudes of the noise generators to be

* Received by the IRE, September 13, 1957.
¹ E. G. Nielsen, Proc. IRE, vol. 45, pp. 957-963; July, 1957.
² A. van der Ziel, "Theory of shot noise in junction diodes and junction transistors," Proc. IRE, vol. 43, pp. 1639-1646; November, 1955.
³ "Theory of shot noise in junction diodes and junction transistors," Proc. IRE, vol. 45, pp. 1011; July, 1957.

$$\overline{e_s^2} = \frac{2kTdf(2g_0 - g_0)}{g_0^2 + b_s^2} \quad (1)$$

$$\overline{i_p^2} = 4kTG_n d = 2kTdf\alpha_0 g_0 \left(1 - \frac{|\alpha|^2}{\alpha_0}\right) + 2eI_{c_{sat}} df \quad (2)$$

or

$$G_n = \frac{\alpha_0 g_0}{2} \left(1 - \frac{|\alpha|^2}{\alpha_0}\right) + 20I_{c_{sat}}$$

$$e_s^* i_p = 2kTdf\alpha \left(1 - \frac{g_0}{Y_s^*}\right) \quad (3)$$

Van der Ziel sets $e_s = e_s'' + e_s'$ where e_s'' is uncorrelated with i_p , and e_s' is completely correlated with i_p .⁴

He also sets

$$\overline{e_s'^2} = 4kTR_n df, \quad (4)$$

where $R_n = r_e/2$ at low frequencies.

$$e_s' = \frac{Z_1 i_p}{\alpha} \text{ where } Z_1 = \pm R_1 \pm jX_1 \quad (5)$$

$$\begin{aligned} \therefore e_s^* i_p &= \left(e_s''^* + \frac{Z_1^* i_p^*}{\alpha^*}\right) i_p \\ &= e_s''^* i_p + \frac{Z_1^* i_p^{*2}}{\alpha^*} \end{aligned} \quad (6)$$

Since $e_s''^* i_p = 0$ then, neglecting effects of collector saturated current, $I_{c_{sat}}$,

$$Z_1^* = \frac{e_s^* i_p \alpha^*}{i_p^2} = \frac{2kTdf\alpha \left(1 - \frac{g_0}{Y_s^*}\right) \alpha^*}{2kTdf\alpha_0 g_0 \left(1 - \frac{|\alpha|^2}{\alpha_0}\right)} \quad (7)$$

$$\begin{aligned} Z_1^* &= \frac{|\alpha|^2 \left(1 - \frac{g_0}{Y_s^*}\right)}{\alpha_0 g_0 \left(1 - \frac{|\alpha|^2}{\alpha_0}\right)} \\ &= \frac{|\alpha|^2 \left(\frac{1}{g_0} - \frac{1}{Y_s^*}\right)}{\alpha_0 - |\alpha|^2} \end{aligned} \quad (8)$$

Thus at very low frequencies $Y_s^* \rightarrow g_0$ and $Z_1 \rightarrow 0$ in the absence of lf noise, and at very high frequencies $|\alpha| \rightarrow 0$ and $Z_1 \rightarrow 0$. At some intermediate frequency Z_1 will reach a maximum value. To find that approximate maximum value and the approximate frequency at which it occurs, the expressions for Y_s and α derived by Pritchard⁵ may be substituted into (8). Y_s is the diffusion admittance of the emitter-base junction.

$$Y_s \approx \frac{qI_s}{kT} \frac{[(1 + 0.25x^2) + j0.8x]}{1 + 0.06x^2} \quad (9)$$

where

$$\frac{qI_s}{kT} = g_0, \quad x = \frac{f}{f_\alpha}$$

f_α = inherent alpha cutoff frequency.

$$\alpha \approx \alpha_0 \frac{[(1 - 0.25x^2) - j1.2x]}{(1 + x^2)} \quad (10)$$

At this time (9) and (10) will be simplified to

$$Y_s \approx g_0(1 + jx) \quad (11)$$

$$\alpha \approx \frac{\alpha_0}{1 + jx} \quad (12)$$

The magnitude of alpha in (12) should be within 10 per cent of the value in (10) up to twice f_α . The magnitude of Y_s in (11) is within 15 per cent of the value of (9) up to $f = 2f_\alpha$. However, there is an excess angle in (11) of 12° at f_α and 25° at $2f_\alpha$. With the emitter-base transition capacity assumed small compared to the diffusion capacity, then

$$Z_1 \approx \frac{\alpha_0 \left(1 - \frac{1}{1 + jx}\right)}{(1 - \alpha_0 + x^2)}, \quad (13)$$

$$R_1 \approx \frac{\alpha_0}{g_0} \frac{x^2}{(1 + x^2)(1 - \alpha_0 + x^2)}, \quad (14)$$

$$X_1 \approx \frac{\alpha_0}{g_0} \frac{x}{(1 + x^2)(1 - \alpha_0 + x^2)}, \quad (15)$$

$$|Z_1| \approx \frac{\alpha_0}{g_0} \frac{x}{\sqrt{1 + x^2}(1 - \alpha_0 + x^2)} \quad (16)$$

Using values of $\alpha_0 = 0.98$, $r_{e0} = 1/g_0 = 26\Omega$ at $I_\xi = 1$ ma, (14), (15), and (16) reach maximum values at the indicated frequencies below:

$$R_{1,max} \approx 19.5\Omega f \approx 0.38f_\alpha$$

$$X_{1,max} \approx 88.0\Omega f \approx 0.14f_\alpha$$

$$|Z_1|_{max} \approx 90.0\Omega f \approx 0.14f_\alpha$$

Under those conditions of transistor amplifier operation where Z_L (the load impedance across which is obtained the output signal) contains a source of thermal noise $\overline{e_{nL}^2} = 4kTR_L df$, and provided $\alpha Z_c \gg Z_e$, $\alpha Z_c \gg Z_b + Z_b$, $\alpha Z_c \gg R_L$, the common-base and common-emitter noise figures then become

$$\begin{aligned} F_b = F_e = 1 + \frac{r_b'}{R_g} + \frac{R_n}{R_g} \\ + \frac{G_n}{R_g |\alpha|^2} | (R_g + r_b' + r_e - R_1)^2 \\ + (x_g - x_b' - x_e - X_1)^2 |, \end{aligned} \quad (17)$$

where the complex base impedance $Z_b' = r_b' - jx_b'$. In alloy transistors $Z_b' = r_b'$.

The common collector noise figure is

$$\begin{aligned} F_c = 1 + \frac{r_b'}{R_g} + \frac{R_n + R_L}{R_g} \\ + \frac{G_n}{R_g} \left[\left(R_g + r_b' - R_e \left[\frac{Z_1}{\alpha} \right] \right)^2 \right. \\ \left. + \left(x_g - x_b' - I_m \left[\frac{Z_1}{\alpha} \right] \right)^2 \right]. \end{aligned} \quad (18)$$

It is interesting to observe that the noise figures for the common-emitter and common-base configurations are independent of Z_L to the extent that the above conditions are satisfied. However, it should be noted that the common collector amplifier noise figure is degraded as R_L is increased. Decreasing R_L in this case to improve the noise

figure will also decrease the dynamic input impedance to the stage, which may be undesirable.

Nielsen points out the noise figure of the common collector becomes fairly constant at high frequencies. However, lest one be tempted to use this configuration at frequencies above f_α , it should be pointed out that the available power gain must inevitably decrease to zero so that the device becomes useless as a signal amplifier in spite of its lower noise figure.

The contribution to the noise figure of the correlation impedance Z_1 is probably negligible in Nielsen's measurements in view of the moderate value of emitter current used (1-3 ma) and the magnitude of the source resistance (around 500Ω). However, under conditions of low emitter current and low source resistance the contribution may have to be included. Also, the contribution to the noise figure from the reactive term multiplying $G_n/R_g |\alpha|^2$ may also become important when R_g becomes smaller.

Finally, to those interested in the design of transistor amplifiers with the ultimate in sensitivity (hence minimum noise figure), it may be well to show how an unbypassed emitter resistance or a partially bypassed emitter resistance in the common-emitter configuration may degrade the noise figure. Let the net effective external emitter impedance be represented in the series impedance form of $Z_0 = R_0 - jx_0$. Then

$$\begin{aligned} F_e = 1 + \frac{r_b'}{R_g} + \frac{R_n + R_0}{R_g} \\ + \frac{G_n}{|\alpha|^2 R_g} | (R_g + r_b' + r_e + R_0 - R_1) \\ + (x_g + x_b' + x_e + x_0 - x_1)^2 |. \end{aligned} \quad (19)$$

At audio frequencies in the shot noise region $Z_1 \rightarrow 0$, $X_b' \rightarrow 0$, $x_e \rightarrow 0$. Let us assume the actual generator driving the stage is purely resistive, but let us lump the reactance of the input coupling capacitor x_c into x_g so that $x_g = x_c$. Then

$$\begin{aligned} F_e = 1 + \frac{r_b'}{R_g} + \frac{R_n + R_0}{R_g} + \frac{G_n}{|\alpha|^2 R_g} \\ \cdot | (R_g + r_b' + r_e + R_0)^2 + (x_c + x_0)^2 |. \end{aligned} \quad (20)$$

Not only does R_0 degrade the noise figure but so does X_0 and x_c as well. If possible, one should ground the emitter directly. Otherwise, if an external resistance is employed, use a large capacitance to reduce R_0 and x_0 to a small value. Also, x_c should be made small compared to R_g for minimum noise figure.

This may be a new criterion for some who have been used to making x_{c1} at some low frequency f_i small, compared to generator resistance plus the input resistance to the particular stage, to help insure adequate low-frequency response down to f_i .

The writer would like to acknowledge helpful discussions with R. L. Watters and K. E. Mortenson of this Laboratory and with Prof. A. van der Ziel, University of Minnesota.

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⁴ G. N. Hanson and A. van der Ziel, "Noise in transistors," to be published.

⁵ R. L. Pritchard, "Frequency response of theoretical models of junction transistors," IRE TRANS., vol. CT-2, pp. 183-191; June, 1955.

Electrolytic Tank Design of Electron Guns with Curved Electron Trajectories*

The general problem in electron gun design is to find a set of electrode shapes which approximate along the beam edge a theoretically determined gradient and potential distribution. For guns employing rectilinear flow, the problem is relatively simple, for the equipotentials are normal to the electron trajectories and the beam edge may be simulated in an electrolytic tank by an insulating strip, a method due to Pierce.¹ Of increasing interest, however, are types of motion in which the equipotentials are not normal to the beam edge as, for example, the curved trajectory flows discussed by Meltzer² and Walker³ and more recently reported on by Kirstein and Kino.⁴ If an electrolytic tank is to be used for gun design in these more general cases, an alternative to the insulating strip method must be employed.

Since it is no longer practical to fix the direction of the gradient at the beam edge, the potential distribution is the logical function to specify. For the general case then, the beam edge is simulated in an electrolytic tank by a resistance card cut so that a current caused to flow from one end to the other will establish along the card a potential distribution which will match the potential distribution required along the edge electron trajectory. After cutting, the card is placed in the tank and curved so as to duplicate the electron path. With the proper voltage applied across the card, the electrode shapes and positions are adjusted until the correct angles are established between the resistance card and the equipotentials. This operation is facilitated by placing immediately adjacent to the resistance card a series of probe pairs oriented so that the direction each pair defines is appropriate to the correct equipotential at that point (see Fig. 1). Proper

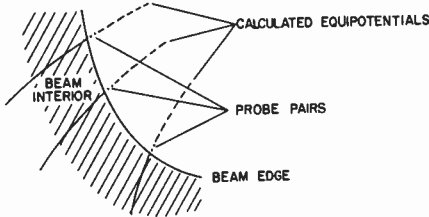


Fig. 1.

electrode design will then make the potential difference between the two probes of a given pair zero. In practice, it suffices to calculate for each pair the potential difference resulting from some allowable error in the angle of the equipotential and then settle for a design where the measured potential difference is less than or equal to this value.

To simplify the cutting of the resistance card, the potential distribution may be approximated by a series of chords and the resistance card cut, as in Fig. 2. The dotted lines indicate strands of fine wire which are



Fig. 2.

woven into the card at each discontinuity in order to keep the equipotentials on the card parallel. The conductivity of the card should be much greater than that of the electrolyte so that the current flowing into the tank from the card will not appreciably alter the potential distribution.

The device used to measure the probe pair potential differences must present identical high input impedances to each probe. In addition, each probe should be etched and coated with aqua-dag before use, in order to minimize surface effects.

The method of design just described generally is applicable to any flow which requires that a given potential and gradient be matched along a path. It has been used here quite successfully in connection with the design of electron guns which operate in the presence of a transverse magnetic field and should find additional application with the curved trajectory flows mentioned.

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Space-Charge-Balanced Hollow Beam with Uniform Charge Distribution*

In 1949, Samuel¹ proposed a convergent hollow-beam electron gun with an external conductor and a special shielding magnet, which is used to divide the magnetic flux at the mouth of a focusing solenoid in such a way that the flux threading through the hole in the cathode is the flux contained within the inner beam radius. In a subsequent investigation carried out by Harris,² this configuration was shown to be one of a class of electron beams utilizing what has since been called *space-charge-balanced flow*; i.e., the type of beam focusing in which electrons are caused to rotate about the axis in an axial magnetic field in such a way that the outward space-charge-spreading plus centrifugal forces are just balanced by the inward Lorentz force. (The well-known Brillouin-flow focusing is a special case, in which the magnetic field drops off to zero at the cathode.) The hollow beam in space-charge-balanced flow requires a specific radial charge distribution, given by¹

$$\rho = 2\epsilon_0\eta A_0^2 \left[1 + \left(\frac{r_0}{r} \right)^4 \right] \quad (1)$$

where A_0 is the normalized magnetic vector potential and r_0 is the inner beam radius. If the radial charge distribution deviates from the form of (1), individual electrons follow stable oscillating trajectories; but as Harris has shown,² the angular frequency of oscillation is *not* independent of radius, so that adjacent electrons at different initial radial positions oscillate with different frequencies. Under this condition adjacent electron paths ultimately must cross, and the important laminar-flow assumption of space-charge-balanced flow analysis is violated.

The present note is a report on an analysis and experimental investigation of the case in which a deliberate deviation from the distribution of (1) is made by making ρ independent of radius. The uniform charge distribution is of obvious practical interest since it would be extremely difficult to obtain any other distribution from a conventional cathode without an elaborate design of the transition region between the gun and the interaction regions.

The equation of motion for this case can be derived quite simply if it is assumed that adjacent electrons do *not* cross radially—an assumption that will be shown below to be satisfied if beam lengths are restricted to a certain range (which is, nevertheless, of considerable practical interest).

$$\ddot{r} = r_0^2 \frac{\omega_p^2}{2r} \left(1 - \frac{r_0^2}{r^2} \right) - \omega_L^2 r \left(1 - \frac{r_0^4}{r^4} \right) \quad (2)$$

where $\omega_L \equiv \eta B/2$ is the Larmor frequency, $\omega_p^2 \equiv -\eta\rho_0/\epsilon_0$ is the plasma frequency, and ρ_0 is the charge density inside the radius r_0 of a given electron. Again, (2) can be readily solved if it is assumed that electron trajectories deviate only slightly from straight paths (an assumption that likewise is justified by the results of the analysis). Then $r = r_0 + \Delta$, where $\Delta \ll r_0$; $\dot{r} = \dot{\Delta}$; and

$$\frac{1}{r} \approx \frac{1}{r_0} \left(1 - \frac{\Delta}{r_0} \right); \quad \frac{1}{r^2} \approx \frac{1}{r_0^2} \left(1 - 3 \frac{\Delta}{r_0} \right).$$

Thus

$$\ddot{\Delta} = \alpha - \beta^2 \Delta \quad (3)$$

where

$$\alpha \equiv r_0 \left[\frac{\omega_p^2}{2} \left(1 - \frac{r_0^2}{r_0^2} \right) - \omega_L^2 \left(1 - \frac{r_0^4}{r_0^4} \right) \right] \quad (4)$$

$$\beta^2 \equiv \frac{\omega_p^2}{2} \left(1 - \frac{r_0^2}{r_0^2} \right) + \omega_L^2 \left(1 + 3 \frac{r_0^4}{r_0^4} \right).$$

Eq. (3) has the solution

$$\Delta = \gamma \cos(\beta t - \delta) + \frac{\alpha}{\beta^2} \quad (5)$$

and the constants γ and δ can be evaluated from the entrance conditions $\Delta=0$ and $\dot{\Delta}=\dot{r}_a$ at $t=0$, where \dot{r}_a is the slope at entrance, so that finally

$$\Delta = \frac{\alpha}{\beta^2} (1 - \cos \beta t) + \frac{\dot{r}_a}{\beta} \sin \beta t. \quad (5a)$$

The value of α/β^2 may be adjusted in accordance with the boundary conditions that one chooses to impose on the configuration; e.g., the specification of a nonoscillating outer beam boundary ($\dot{r}=0$ at $r_0=r_b$, the equilibrium radius of the outermost electron) leads to a generalized form of the familiar Brillouin flow equilibrium condition

* Received by the IRE, September 23, 1957.
 1 J. R. Pierce, *J. Appl. Phys.*, vol. 11, pp. 548-554; August, 1940.
 2 B. Meltzer, *Proc. Phys. Soc.*, vol. B62, pp. 813-817; December, 1949.
 3 G. B. Walker, *Proc. Phys. Soc.*, vol. B63, pp. 1017-1027; December, 1950.
 4 Kirstein and Kino, paper presented at the IRE Tube Conference, Berkeley, Calif., June, 1957.

* Received by the IRE, July 29, 1957; revised manuscript received, September 26, 1957. Much of this work was carried out under the sponsorship of the U. S. Navy, Army, and Air Force under Contracts N6onr 25132 and DA36-039-sc-63189.
 1 A. L. Samuel, "On the theory of axially symmetric electron beams in an axial magnetic field," *Proc. IRE*, vol. 37, pp. 1252-1258; November, 1949.
 2 L. A. Harris, "Axially symmetric electron beam and magnetic-field systems," *Proc. IRE*, vol. 40, pp. 700-708; June, 1952.

$$\frac{\omega_p^2}{2} = \omega_L^2 \left(1 + \frac{r_a^2}{r_b^2} \right). \quad (6)$$

It is obvious from (4) that the angular frequency of oscillation β is not independent of r_0 , and hence adjacent trajectories must cross, as mentioned previously. However, in the first few oscillation wavelengths, the electrons merely begin to slip past one another, and relatively little crossing takes place. As an example, consider trajectories of a hollow beam for which $\dot{r}_a = 0$ (beam parallel to the axis at entrance), and the outer boundary is held at constant radius. (The inner boundary is automatically parallel to the axis, since $\alpha = 0$ at $r_0 = r_a$.) Two adjacent paths at radii r_1 and r_2 ($r_1 < r_2$) will not cross if at all times $r_2 + \Delta_2 \geq r_1 + \Delta_1$; i.e., if $\Delta_2 - \Delta_1 \geq -(r_2 - r_1)$, which in the limit becomes

$$\frac{d\Delta}{dr_0} \geq -1. \quad (7)$$

But from (5a), for the case $\dot{r}_a = 0$,

$$\begin{aligned} \frac{d\Delta}{dr_0} &= (1 - \cos \beta t) \frac{d}{dr_0} \left(\frac{\alpha}{\beta^2} \right) \\ &+ t \frac{\alpha}{\beta^2} \sin \beta t \frac{d\beta}{dr_0}. \end{aligned}$$

It can be shown (perhaps most readily by means of a plot, as described below) that the

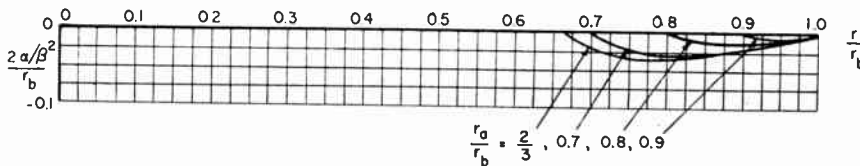


Fig. 2—Maximum deviation from initial radius (as a function of radius) for several beam thicknesses.

term α/β^2 has its maximum negative slope at $r_0 = r_a$ (the equilibrium radius of the innermost electron), and that the first term of (8) consequently always is greater than -1 , so that only the second term invalidates the inequality (7). Since this term is proportional to t , it is possible that the assumption of noncrossing trajectories may be satisfied if t remains small (i.e., if the time necessary to pass through the interaction region is small). A graphical representation of the case $r_a = \frac{2}{3}r_b$ (Fig. 1) shows that such is indeed the case. The change in angular oscillation frequency β over the beam width is so small that virtually no crossing takes place within the first few oscillation cycles.

The amplitude of the oscillation for the present case varies with r_0 as α/β^2 (5a) and is zero at the inner and outer edges. The maximum amplitude $2\alpha/\beta^2$ is plotted as a function of radius r in Fig. 2, both normalized with regard to the outer beam radius r_b . The graphs show that the greatest deviation occurs near the middle between inner and outer boundary, and that the relative deviation becomes quite small for thin beams. The graphs also clearly illustrate the above statement that α/β^2 has its maximum negative slope at $r = r_a$.

The angular frequency of oscillation varies from $\beta_a = 2\omega_L$ (i.e., a "wavelength" of $2\pi v_0/2\omega_L$ where v_0 is the dc beam velocity and ω_L is the Larmor frequency) at the inner boundary to $\beta_b = \omega_L \sqrt{2[1 + (r_a/r_b)^4]}^{1/2}$ (i.e., a

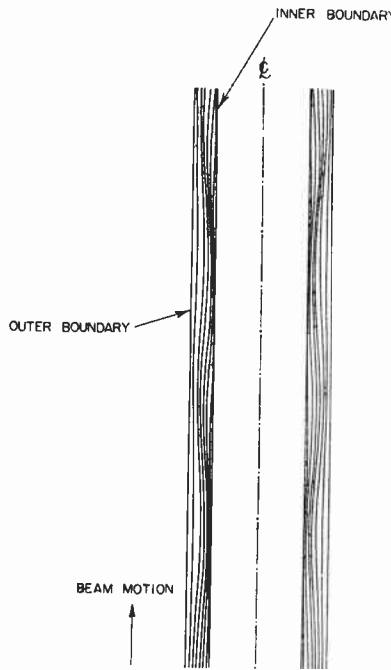


Fig. 1—Electron trajectories in a hollow beam initially parallel to the axis with uniform charge distribution under space-charge-balanced flow for $r_a = \frac{2}{3}r_b$.

wavelength of just under $2\pi v_0/\sqrt{2}\omega_L$) at the outer boundary). These values can be readily related by means of (6) to the plasma wavelength $\lambda_p = 2\pi v_0/\omega_p$, where ω_p is the plasma frequency. For the present example, for instance, the oscillation "wavelength" varies from $0.423\lambda_p$ at the inner boundary to $0.556\lambda_p$ at the outer boundary.

The oscillation wavelength is thus of the order of half a plasma wavelength, and we may conclude that, even though an analysis of a hollow beam (with a uniform charge distribution) based on (2), and assuming noncrossing trajectories cannot be rigorously said to hold for arbitrary beam lengths, in practice the assumption is likely to be satisfied in a large number of actual applications in which the length of the beam is of the order of a few plasma wavelengths (e.g., klystrons and most high-power traveling-wave tubes). A previously described and executed design³ of a hollow-beam electron gun appears to bear out this conclusion.

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C. Süsskind, "A Convergent Hollow-Beam Electron Gun for Microwave Tubes," Stanford Electronics Labs. and Microwave Lab., Stanford University, Stanford, Calif., Tech. Rep. No. 450-1; June 29, 1956.

Design of Three-Resonator Dissipative Band-Pass Filters Having Minimum Insertion Loss*

In the above paper¹ Taub and Bogner have presented a great deal of useful design information for uniformly dissipative three-resonator filters which are to be driven by a resistive generator and work into a resistive load. The desire is to maximize the ratio of the power delivered to the load to that available from the generator.

We recently have had need to design such a filter for the Butterworth response shape and took this opportunity to compare our design equations with the analytical solution developed by Dr. E. G. Fubini and given as (5) and (6) in the above paper. Unfortunately, we find the presented equations to be incorrect and, in fact, simple numerical substitution in them shows that (5d) calls for imaginary values for k_{23} for even such a low-normalized decrement as 0.1.

The correct equations, arrived at by B. Sellers of the Federal Telecommunication Laboratories, Nutley, N. J., are given below:

$$\delta_1 = \frac{U_2 - V_2}{2} + \delta_2 \quad (1a)$$

$$\delta_3 = \frac{U_2 + V_2}{2} + \delta_2 \quad (1b)$$

$$k_{12} = \frac{U_0 + V_0}{U_2 + V_2} \quad (1c)$$

$$k_{23}^2 = \frac{U_0 - V_0}{U_2 - V_2} \quad (1d)$$

$$(P_1/P_a) = \frac{(U_0 + V_0)(U_0 - V_0)}{C_0^2} \quad (1e)$$

where

$$U_2 = (2 - 3\delta_2) \quad (2a)$$

$$U_0 = (1 - 2\delta_2 + 2\delta_2^2 - \delta_2^3) \quad (2b)$$

$$V_2 = \sqrt{2B - A} \quad (2c)$$

$$V_0 = (B + A)\sqrt{(2B - A)} \quad (2d)$$

where

$$A = 1/3(4\delta_2 - 3\delta_2^2) \quad (2e)$$

$$B = 1/3\sqrt{(6\delta_2 - 8\delta_2^2)} \quad (2f)$$

$$C_0 = 1.0.$$

These solutions were obtained by using the twelve synthesis steps detailed in a previous paper.² These steps are one way of expressing the Darlington procedure. When performing the steps all quantities were kept literal; i.e., no numerical values were used, and the following two basic points were included:

- 1) It was realized that, for the specific case wherein the numeric 1.0 is used in step 6 (in order that minimum insertion loss result), the resulting cubic polynomial in $(\omega/\omega_{3db})^2$ must have a positive real double root. Thus when step 7 is performed, we may use

* Received by the IRE, August 26, 1957.

¹ J. J. Taub and B. F. Bogner, "Design of three-resonator dissipative band-pass filters having minimum insertion loss," Proc. IRE, vol. 45, pp. 681-687; May, 1957.

² M. Dishal, "Two new equations for the design of filters," Elec. Commun., vol. 30, pp. 324-337; December, 1953. Addendum, vol. 32, p. 178; September, 1955.

the explicit (and quite simple) closed form expressions for the roots of a cubic which is known to have a double root. Having the roots of step 7 in closed literal form enables the following steps 8 through 12 also to be performed in a literal manner.

- 2) The continued fraction expansion of steps 9 and 10 produces the so-called ladder-network coefficients (a_1, a_2 , and a_3) in terms of the left-hand termination. To obtain the left-hand end decrement and the coefficients of coupling, it is necessary to realize that the simple relationship between the above two forms of circuit constants is as follows:³

$$\delta_1 = \left(\frac{1}{a_1} + \delta_0 \right), \quad k_{12}^2 = \frac{1}{a_1 a_2},$$

$$k_{23}^2 = \frac{1}{a_2 a_3}, \text{ etc.}$$

Similarly, the continued fraction expansion of steps 11 and 12 produces a different set of a 's (a_{111}, a_{11}, a_1) in terms of the right-hand termination. This set then gives the right-hand end decrement and the coefficient of couplings as:

$$\delta_3 = \left(\frac{1}{a_{111}} + \delta_0 \right), \quad k_{23}^2 = \frac{1}{a_{11} a_{111}},$$

$$k_{12}^2 = \frac{1}{a_1 a_{11}}, \text{ etc.}$$

The simplest resulting expressions then were picked to provide the design equations (1a) through (1e) of this letter.

Incidentally, as pointed out in the Taub and Bogner paper, the important (Butterworth) design chart Fig. 4(a) was obtained by "graphical" methods and not by the analytical solutions, (5), presented by them. We do agree with the values called for in Fig. 4(a), except in the region to the left of 0.2 of the abscissa. In this region of low loss the graphical solution is rather inaccurate and the design equations presented in this letter show that even with such a low-normalized decrement as 0.05 the required network values have changed from their "lossless" values more rapidly than as given in Fig. 4(a); e.g., at $(\delta_2/\delta_{2\max}) = 0.05$, $\delta_1 = 0.765$, $k_{12} = 0.655$, $k_{23} = 0.780$, and $\delta_3 = 1.225$. This rapid change from the symmetrical values, called for with lossless resonators, stresses the fact that optimum filters (with respect to insertion loss) are markedly unsymmetrical—as can be seen, this is particularly true of the required end resonator decrements.

Incidentally, by comparing our solutions with those given in the Taub and Bogner paper, Sellers has found the error in the latter solutions; when corrected, they should read as follows:

$$k_{12}^2 = \delta_2^2 \left[\frac{\gamma + (\beta - 2\rho)\sqrt{\alpha^2 - 4\rho}}{\alpha + \sqrt{\alpha^2 - 4\rho}} \right]$$

$$k_{23}^2 = \delta_2^2 \left[\frac{\gamma - (\beta - 2\rho)\sqrt{\alpha^2 - 4\rho}}{\alpha - \sqrt{\alpha^2 - 4\rho}} \right].$$

³ "Filters, Modern-Network-Theory Design," in "Reference Data for Radio Engineers," International Telephone and Telegraph Corp., 4th ed., pp. 187-235; 1956.

It is straightforward to obtain the closed form solutions for the end decrements and the coefficients of couplings required when uniformly lossy resonators are used and the general Tchebycheff response shape with minimum insertion loss is desired—(1) of this letter applies to this case also, but the U 's and V 's must be defined more generally as follows:

$$U_2 = (C_2 - 3d_0) \quad (3a)$$

$$U_1 = (C_1 - 2C_2 d_0 + 3d_0^2) \quad (3b)$$

$$U_0 = (C_0 - C_1 d_0 + C_2 d_0^2 - d_0^3) \quad (3c)$$

and again

$$V_2 = \sqrt{2B - A} \quad (3d)$$

$$V_0 = (B + A)\sqrt{2B - A} \quad (3e)$$

where now

$$A = 1/3(2U_1 - U_2^2) \quad (3f)$$

$$B = 1/3\sqrt{(2U_1 - U_2^2)^2 - 3(U_1^2 - 2U_2 U_0)} \quad (3g)$$

and

$$C_2 = \left(\frac{S_2}{C_3} \right) (2) \quad (3h)$$

$$C_1 = \left(\frac{S_2}{C_3} \right)^2 \left(2 + \frac{0.75}{S_2^2} \right) \quad (3i)$$

$$C_0 = \left(\frac{S_2}{C_3} \right)^3 \left(1 + \frac{0.75}{S_2^2} \right) \quad (3j)$$

where

$$S_2 = \sinh [1/3 \sinh^{-1} \{ (V_\rho/V_\nu)^2 - 1 \}^{-1/2}] \quad (3k)$$

$$C_3 = \cosh [1/3 \cosh^{-1} \{ (V_\rho/V_\nu)^2 - 1 \}^{-1/2}]. \quad (3l)$$

In the above equations, all decrements and coefficients of coupling are normalized to the 3-db down fractional bandwidth.

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Authors' Comments⁴

We appreciate Dishal and Sellers pointing out an error in our paper. Upon rechecking the solution, it was found that an error was made in (5c) and (5d). The error was not in Dr. Fubini's solution. It came about in transcribing it from his notation to that used in our paper. The corrected expressions for (5c) and (5d) should read:

$$k_{12}^2 = \delta_2^2 \left[\frac{-\frac{1}{2}(\alpha - \sqrt{\alpha^2 - 4\rho})(\beta - \rho) + \gamma}{\sqrt{\alpha^2 - 4\rho}} \right] \quad (5c)$$

$$k_{23}^2 = \delta_2^2 \left[\frac{\frac{1}{2}(\beta - \rho)(\alpha + \sqrt{\alpha^2 - 4\rho}) - \gamma}{\sqrt{\alpha^2 - 4\rho}} \right]. \quad (5d)$$

Although not apparent, a check of these expressions and those given by Dishal and Sellers reveals that they are identical. This identity of the two solutions demonstrates that either the Darlington procedure or the direct minimization of the insertion loss, in conjunction with the three design equations, are equally valid approaches for obtaining the set of circuit constants which yield minimum midband insertion loss.

The nature of the numerical computations used in obtaining the graphical solution for the Butterworth response gave rise to

errors (in the low-loss region— $\delta_2 < 0.1$) of 0.2-db maximum in the filter midband insertion loss. A recheck of the design chart, Fig. 4(a), showed agreement with the closed form solution. It therefore is recommended that the closed form solution be used in obtaining the correct design parameters for $\delta_2 < 0.1$.

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Space-Frequency Equivalence*

Correlation systems comprising a pair of widely separated antennas have been suggested for the detection of signals encompassing a wide frequency band.¹⁻³ The purpose of this note is twofold: 1) to observe that such wide-band correlation systems will operate equally well if the source consists of a number of discrete frequencies, and 2) to discuss the correspondence which exists between the spatial complexity of the usual single-frequency antenna system and the frequency complexity of the antenna-pair multifrequency correlation system.

Directional patterns of the two-receiver cross-correlation system are easily calculated from a consideration of the power spectrum employed and the use of Wiener's theorem which states that the correlation function is the Fourier transform of the power spectrum of the original wave. A noise band extending from zero frequency has a Fourier transform represented by $\sin x/x$ and the output of a cross-correlator at the two receivers therefore will follow a $\sin x/x$ pattern as a noise source passes through the plane equidistant from the two receivers. The Fourier transform of a limited noise band (say an octave of noise) is a $\sin x/x$ function multiplied by a cosine term. Directional patterns for noise sources of other frequency extent can be similarly determined. For the discrete frequency case, the space-frequency plot shown in Fig. 1 is of interest. The conventional single-frequency space array of discrete elements is indicated as the horizontal line of circles. The directional pattern of any radiator pair is maintained if the product of frequency and spacing is kept constant; i.e., if the pair is moved along the hyperbolas shown. In this way the horizontal row of radiators is converted to a radiator pair functioning at the frequencies indicated on the two vertical rows of circles. The process can, of course, be generalized to more than two elements. Because of squaring of the cosine terms which is inherent in the cor-

* Received by the IRE, October 7, 1957.

¹ M. Ryle, "A new radio interferometer audits application to the observation of weak radio stars," *Proc. Roy. Soc. A.*, vol. 211, pp. 351-375; March 6, 1952.

² R. Hanbury Brown, R. C. Jennison, and M. K. DasGupta, "Apparent angular sizes of discrete radio sources—observations at Jodrell Bank, Manchester," *Nature*, vol. 170, pp. 1061-1063; December 20, 1952.

³ J. J. Faran, Jr. and R. Hills, Jr., Acoustics Res. Lab., Harvard Univ., Cambridge, Mass., Tech. Memo Nos. 27 and 28; 1952.

⁴ Received by the IRE, September 26, 1957.

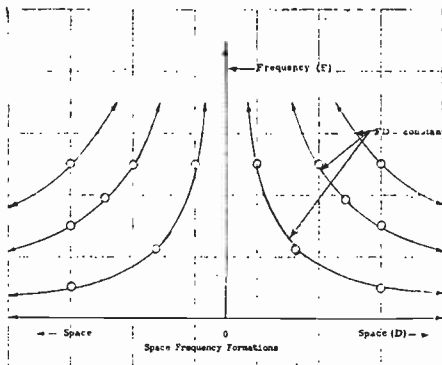


Fig. 1—The 6-element linear array operating at one frequency (top row of circles) has the same beam pattern as the correlation receiver pair detecting a source of three frequencies (two vertical rows of circles).

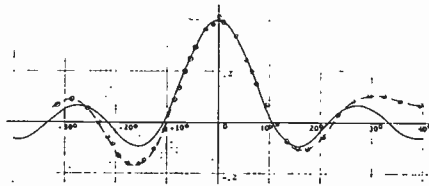


Fig. 2—Experimental test of the space-frequency equivalence indicated in Fig. 1. Dotted curve, an experimental beam pattern of the correlated outputs of two isotropic receivers spaced 21.5 inches apart against a source comprising frequencies 300, 900, and 1500 cps. Solid curve, the calculated pattern for a 6-element linear array 43 inches long against a 1500-cps source.

relation process, the pair spacing obtained by the method described must be divided by two.

Experimental verification of the concept was accomplished using sound waves. In Fig. 2 the solid curve is calculated for a 6-element array 5 wavelengths long; the dotted curve is a measured correlation pattern of a pair-array receiving three audio frequencies: 300, 900, and 1500 cps. The pair spacing was $2\frac{1}{2}$ wavelengths at 1500 cps. It is observed that the correlation array is half the length of the conventional array.

We conclude that in a detection system, the space complexity and size of an antenna could be reduced by increasing the frequency complexity of the system. Such a process requires that the antennas be effective at several frequencies; however, the saving in antenna size and extent may outweigh this difficulty in certain applications. Either continuous noise bands or multiple discrete frequencies can be used to produce narrow directional patterns having low side lobes. Extensions of the concept could include 1) tapering of the intensity of the higher frequency components to reduce side lobes, 2) manipulation of the phases of individual frequencies to create shaped beams (e.g., cosecant-squared beams) from a receiver pair, 3) alternate reversing of the polarity of discrete frequencies to achieve a super-directive multifrequency detection system,⁴ and 4) the use of three or four receivers located in a plane with double cross-correlation to form a pencil beam.

This note has discussed mostly receiving aspects, applications of which would include

radio astronomy, microwave radiometry, passive acoustic detection, and beacon tracking of moving objects. Signal-to-noise considerations, power gain evaluation, and the use of the concept in active systems will be discussed in a later paper.

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Thermal Properties of Tungsten vs Copper for Electron Tube Delay Lines*

A calculational comparison has been made of the thermal load capacity of copper as against tungsten fingers in an interdigital delay line of particular, but not unrepresentative, dimensions for use in an electron tube. The finger was assumed to be a right circular cylinder of 0.050-inch diameter with a length of 10 diameters, or 0.500 inch, and was assumed to be heated uniformly along its length by electron bombardment, such as exists in tubes with a ribbon beam.

The choice of finger extremity temperatures can be made in several ways. A finger base temperature of 300°K was chosen for the problem as indicative of what can be obtained with the finger base in intimate contact with coolants at temperatures near 280°K. For the free end extremity temperature, three options are possible: 1) temperature adjusted so that the copper and tungsten delay lines have equal vapor pressures, 2) temperature adjusted so that rate of finger reduction due to evaporation is the same for the two metals, and 3) operation at the melting temperature of the metal involved. One can eliminate the third choice since the comparison ought to be made on a normal operation basis rather than on a condition tantamount to destruction of the delay line. The extremity temperatures were chosen according to option 2) based on a 1000-hour evaporation of 10 per cent of the finger mass. These values are 2680°K for tungsten and 1160°K for copper. In this case the calculated¹ vapor pressures are reasonable, $5.7 \cdot 10^{-7}$ mm Hg for copper and $1.1 \cdot 10^{-6}$ mm Hg for tungsten. Actually, options 1) and 2) give closely related extremity temperatures.

The differential equation governing the steady-state temperature distribution along the finger in the presence of radiation is,

$$Kc \frac{d^2T}{dz^2} = - [Pi - Kr(T^4 - C)] \quad (1)$$

where Kc and Kr are conduction and radiation "constants" (actually functions of temperature) and Pi is the incident power per unit length. For tungsten, the absolute value and variation of Kc have some spread in the

literature, but what appeared to be the most reliable values were chosen.^{2,3} Also, in the Kr for tungsten, the effective radiating area is approximately 0.80 of the actual area since there is some radiation exchange between adjacent hot fingers. For copper, radiation is ineffective at the temperature achieved.

A numerical solution of (1) then yielded a permissible power input of 73 w per finger for tungsten, while the value for copper was 61 w per finger. Without radiation the tungsten value would be about 48 w.

For fingers of other diameters and length/diameter ratios, estimates can be made of their relative thermal capabilities keeping in mind that the conduction/radiation ratio is proportional to diameter/length.³ An additional point is that increased diameters permit increased temperatures for a 1000-hour evaporation life.

Because tungsten at the chosen finger terminal temperature is an excellent thermionic emitter, some extra heating could be expected due to finger-to-finger electronic currents caused where rf power is transmitted along the delay line. Also, the average resistance of the tungsten under the assumed conditions of the problem is about 8 times that of hot copper, causing a $\sqrt{8}$ ratio of attenuation for the two lines. For tubes working at the higher microwave frequencies, a particular case shows that due to this cause about 3 extra watts/finger must be subtracted from the permissible thermal load of tungsten as against copper for a basic finger thermal load of about 36 w. Plating of the tungsten fingers with copper or silver to increase their surface conductivity is ineffective against this latter effect because of the high temperatures attained.

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² Forsythe and Worthing, "The properties of tungsten and characteristics of tungsten lamps," *Astrophys. J.*, vol. 61, pp. 146-185; 1925.

³ Langmuir and Taylor, "Heat conductivity of tungsten and cooling effect of leads upon filaments at low temperatures," *Phys. Rev.*, vol. 50, pp. 68-87; 1936.

Microwave Magnetic Field in Dielectric-Loaded Coaxial Line*

In a recent publication,¹ the authors described a probable mode configuration for a coaxial line one-half filled with a low-loss high dielectric constant material. This mode picture was based on the initial experimental results reported in that article. By additional experimental work and by subsequent theoretical considerations, it has been determined that this suggested picture should be rotated by 180° relative to the dielectric. The corrected picture is shown in Fig. 1, but this does not affect the previously re-

* Received by the IRE, April 26, 1957.

¹ B. J. Duncan, L. Swern, K. Tomiyasu, and J. Hannwacker, "Design considerations for broadband ferrite coaxial line isolators," *Proc. IRE*, vol. 45, pp. 483-490; April, 1957.

⁴ Comparable to the single-frequency technique discussed by R. L. Pritchard, "Optimum directivity patterns for linear point arrays," *J. Acoust. Soc. Amer.*, vol. 25, pp. 879-891; September, 1953.

* Received by the IRE, September 30, 1957.

¹ L. B. Loeb, "Kinetic Theory of Gases," McGraw-Hill Book Co., Inc., New York, N. Y., 2nd ed., p. 106; 1934.

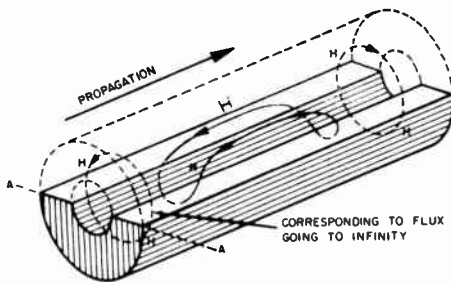
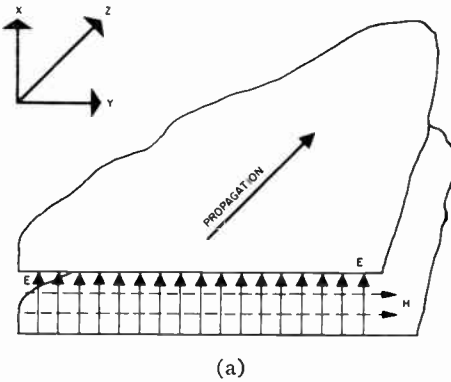
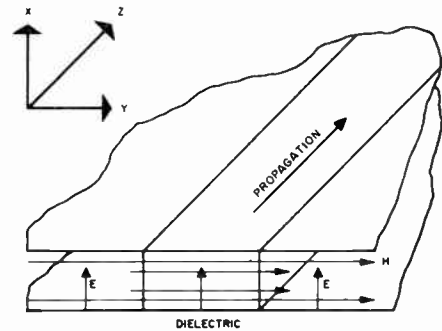


Fig. 1—Microwave H -field configuration in partially dielectric-loaded coaxial line.



(a)



(b)

Fig. 2—(a) Microwave E and H fields in an air-filled plane parallel transmission line propagating the TEM mode. (b) Microwave E and H fields in a partially dielectric-loaded plane parallel transmission line—cross-sectional view.

ported experimental data. That the latter picture is indeed the correct one will be demonstrated in this paper from a qualitative analysis using Maxwell's equations and by describing the additional experimental work.

An approach, to show that the strongest component of longitudinal magnetic field (Fig. 1) is in the air-filled one-half of the coax, starts with a parallel plane transmission line propagating the TEM mode [Fig. 2(a)]. As shown, only a transverse component of the microwave magnetic field H exists for the air filled transmission line. Next, consider a dielectric wedge ($\epsilon' > 1$) located in the parallel plane line as depicted in Fig. 2(b). Under these conditions it will be shown that the instantaneous microwave magnetic field is as depicted in Fig. 2(b) (cross-sectional view) and Fig. 3 (top view).

The reasoning leading to this mode picture is based on several considerations. The dielectric is transparent to the microwave

magnetic field due to the permeability (μ) of the dielectric being unity. Also, in this region of the dielectric it can be assumed to a first-order approximation that the potential difference between the top and bottom plates [Fig. 2(b)] is a constant; *i.e.*,

$$\int E_x dx = \text{constant} \quad (1)$$

and is independent of y . In this equation, E_x represents the x component of the microwave electric field. This means that since the displacement vector (D) is defined by

$$D = \epsilon_0 \epsilon_m E, \quad (2)$$

where ϵ_0 is the dielectric constant of free space and ϵ_m is the dielectric constant of the medium and satisfies Maxwell's divergence equation,

$$\nabla \cdot D = \rho, \quad (3)$$

where ρ represents surface charge density, there must be more surface charge at the dielectric-conductor interface than at the air-conductor interface on either side. Because of the greater moving charge ρ_m under the dielectric, there is a greater longitudinal current here and, hence, greater transverse field (H_y) as shown in Fig. 2(b) and Fig. 3. That is

$$\frac{\partial H_y}{\partial y} \neq 0.$$

Now, since away from the dielectric the longitudinal current, and hence H_y , becomes smaller, and since $\nabla \cdot B$ or $\nabla \cdot H$ must equal zero, there must be a longitudinal component of B_x or H_x near the dielectric-air interfaces to cancel out the nonzero derivative of H_y .

It has been demonstrated previously² that the change in charge distribution is not abrupt at the interface and it is reasonable to expect this for the parallel-plane case as well. This would lead, at microwave frequencies, to the picture given in Fig. 4. The kink in E lines becomes essential to permit $\int E_x dx$ to remain constant, and to account for the increase in surface charge on the conductor in the region slightly removed in the transverse direction from the dielectric. This increase in surface charge and its consequent longitudinal current permits the change in H -flux lines shown in Fig. 3 to be gradual in the immediate vicinity of the dielectric. Since there is a kink in E , there is a curl of E . On the left side of the dielectric the curl is in the positive z direction and since

$$\nabla \times E = -\frac{1}{c} \dot{B}, \quad (4)$$

this means that B is increasing in the negative z direction with increasing time. This result is compatible with the mode configuration of Fig. 3. Curl E is oppositely oriented on opposite sides of the dielectric which also is consistent with the picture of Fig. 3.

A TEM mode coaxial line is, to a first approximation, a wrapped around version of the parallel-plane line of Fig. 2(a). Similarly, the structure of Fig. 2(b) and Fig. 3

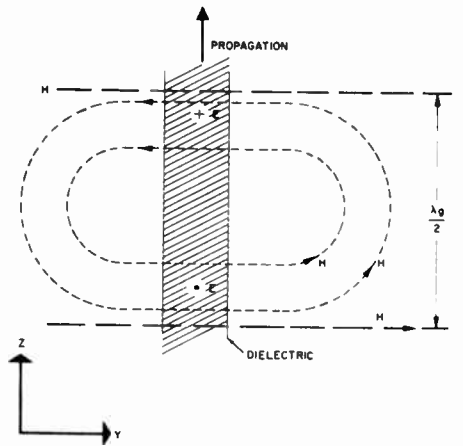


Fig. 3—Microwave E and H fields in a partially dielectric-loaded plane parallel transmission line—top view.

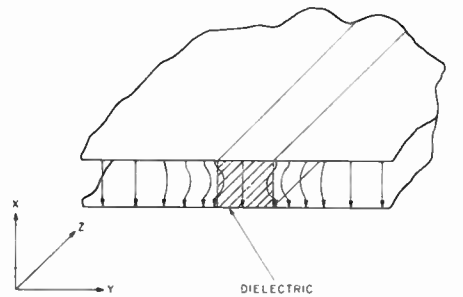


Fig. 4—Microwave E -field configuration in a partially dielectric-loaded plane parallel transmission line.

can be wrapped around to form the coax structure of Fig. 1, thus giving rise to the TE mode configuration depicted in this same figure.

A similar argument can be given to show that a TM mode can, if excited, be propagated in the dielectric loaded structure. However, if a TM mode were generated it would exhibit no appreciable H -vector circular polarization on the dielectric surfaces and, hence, would not give rise to appreciable nonreciprocity of ferrite characteristics for the field orientation and other conditions under consideration. Since a very large nonreciprocity has been experimentally observed, most of the TEM energy incident on the dielectric loaded structure must be converted into the desired TE mode with only negligible conversion to the TM mode.

An experimental verification of the correctness of the mode picture of Fig. 1 over that previously reported can be achieved quite simply by checking the sense of circular polarization which exists on the dielectric surface under a known set of conditions.³ This is readily apparent if it is realized that for a given direction of propagation and of transversely applied dc magnetic field along the dielectric surfaces, a 180° rotation of the mode polarization changes the sense of circular polarization which exists on these surfaces.

In line with these considerations, a small diameter ferrite rod was placed on one and

² D. J. Angelakos, "A coaxial line filled with two nonconcentric dielectrics," IRE TRANS., vol. MTT-2, pp. 39-44; July, 1954.

³ R. Mangiaracina and B. J. Duncan, "Nonreciprocal Ferrite Devices in TEM Mode Transmission Lines," presented at the Annual PGMTT Meeting, New York, N. Y., May 9-10, 1957.

then on the remaining flat dielectric surface of Fig. 1. The direction of propagation is as shown in the figure and a dc magnetic field of sufficient strength to produce ferrite resonance is applied along the direction from A to A' . Under these conditions, no appreciable resonance attenuation is encountered with the ferrite located on either of the dielectric surfaces. However, when either the direction of applied magnetic field or propagation are reversed a large resonance absorption is encountered for location of the ferrite on either of the two surfaces. Therefore, it is apparent that these results are those which would be expected only for the mode configuration of Fig. 1.

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Carrier Mobilities at Low Injection Levels*

In a recent paper,¹ Sah, Noyce, and Shockley have derived expressions for the diffusion currents flowing across a p - n junction. They take into consideration the existence of an electric field, E , outside the transition layer, but they assume that the space charge due to the divergence of this field is negligible. The resulting mobility of minority carriers for any injection level is the ambipolar mobility, $\bar{\mu} = 2\mu_n\mu_p / (\mu_n + \mu_p)$. The conclusion reached is that even at low injection levels the hole current injected in n -type material differs from the usual relation,² by a factor $\sqrt{\frac{1}{2}(\mu_n + \mu_p) / \mu_n}$, and implies that, under equal conditions, transit times across the bases of n - p - n and p - n - p transistors should be identical. We wish to point out here that the approximation used by Sah, Noyce, and Shockley is not justified.

Consider the steady-state equations:

$$J_p = q\mu_p p E - kT\mu_p \text{grad } p, \quad (1)$$

$$J_n = q\mu_n n E + kT\mu_n \text{grad } n, \quad (2)$$

$$\text{div } J_p = -\text{div } J_n = -qU,$$

$$(J_p + J_n = J = \text{const}), \quad (3)$$

where the symbols have their usual meaning. Since space charge neutrality very nearly holds, $n \approx p + N$, and $\text{grad } n \approx \text{grad } p$. We obtain the result of Sah, Noyce, and

Shockley by adding the divergences of (1) and (2) (multiplied respectively by $-\mu_n$ and μ_p) and neglecting terms containing $\text{div } E$. We shall check the validity of this procedure by computing the terms appearing in $\text{div } J_n$ in the case of low-level injection of holes in n -type material ($p \ll n \approx N$). From (1) and (2), using $\text{grad } n \approx \text{grad } p_n$,

$$E = \frac{J - kT(\mu_n - \mu_p) \text{grad } p}{q(\mu_p p + \mu_n n)} \approx \frac{J - kT(\mu_n - \mu_p) \text{grad } p}{q\mu_n N} \quad (4)$$

In the expression for $\text{div } J_n$, the terms $q\mu_n n \text{div } E = -kT(\mu_n - \mu_p)\nabla^2 p$ and $kT\mu_n \nabla^2 p$ are comparable in magnitude, so that there is no justification in dropping the former term. This comes from the fact that the small factor $\text{div } E$ is multiplied by the majority carrier density. We then have

$$-\mu_n \text{div } J_p + \mu_p \text{div } J_n = (\mu_n + \mu_p)U = kT(\mu_n + \mu_p)\mu_p \nabla^2 p, \quad (5)$$

which leads to the correct low-level approximation.

In the same way, it can be shown that the ambipolar mobility, $\bar{\mu}$, is involved at very high-injection levels only ($n \approx p \gg N$). At intermediate levels, the effective mobility is a complicated function of the carrier densities and their gradients, as shown by Rittner.³

The author is indebted to Dr. R. N. Noyce and Dr. C. T. Sah for helpful discussions on this subject.

J. A. HOERNI
Fairchild Semiconductor Corp.
Palo Alto, Calif.

³ E. S. Rittner, "Extension of the theory of the junction transistor," *Phys. Rev.*, vol. 94, pp. 1161-1171; June 1, 1954.

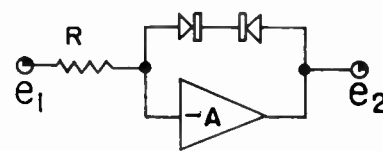
Hyperbolic Analogs*

To the extent to which the voltage (V), current (I), and reverse saturation current (I_s) of a semiconductor diode are related by the expression $I = I_s [\exp(qV/kT) - 1]$, it is possible to construct circuits which provide hyperbolic relations between electrical quantities therein.

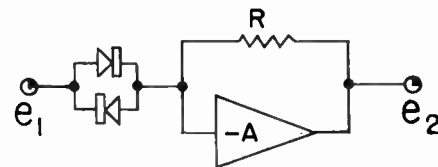
For example, if two identical semiconductor diodes are connected in series and poled to conduct in opposite directions, it is easily shown that the terminal voltage and current are related by $I = I_s \tanh(qV/2kT)$.

Two such diodes connected in parallel and oppositely poled will provide a dependence between terminal voltage and current given by $I = 2I_s \sinh(qV/kT)$.

There are variations or extensions of



$$e_2 = \frac{2kT}{q} \tanh^{-1}(e_1 / I_s R)$$



$$e_2 = 2 I_s R \sinh(qe_1 / kT)$$

Fig. 1.

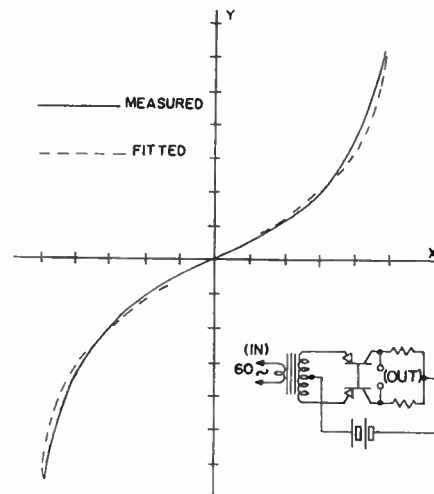


Fig. 2.

these circuits which can be used to provide hyperbolic analog devices. For example, the diode pairs might be used as input or feedback elements in a standard operational amplifier (Fig. 1).

In another incorporation of these principles transistors provide both the necessary exponential characteristic and gain. A transfer characteristic measured for such a circuit is shown in Fig. 2, along with a fitted curve,

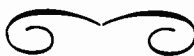
$$y = 2.9 \tanh^{-1} x.$$

It is also possible, although somewhat more complicated, to obtain hyperbolic cosine analogs.

MELBOURNE J. HELLSTROM
Westinghouse Electric Corp.
Metuchen, N. J.

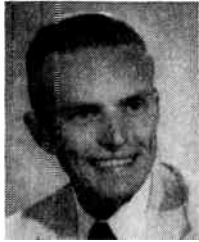
* Received by the IRE, October 15, 1957.
C. T. Sah, R. N. Noyce and W. Shockley, "Carrier generation and recombination in p - n junctions and p - n junction characteristics," *Proc. IRE*, vol. 45, pp. 1228-1243; September, 1957.
W. Shockley, "Electrons and Holes in Semiconductors," D. Van Nostrand Co., Inc., New York, N. Y., sec. 12.5; 1950.

* Received by the IRE, September 24, 1957.



Contributors

J. Robert Anderson (S'53-M'57) was born in New York, N. Y. on December 31, 1932. He received the B.S. degree in engineering physics from



J. R. ANDERSON

New York University in 1954. From 1954 to 1957, he was a member of the technical staff at the Electron Tube Laboratory of Hughes Aircraft Company. During part of this time, he received graduate training in physics at U.C.L.A. under a Howard

Hughes Cooperative Fellowship.

Mr. Anderson presently is continuing his graduate training in electrical engineering, while holding an appointment as a research engineer in the Electron Tube Laboratory at the University of California, Berkeley, Calif.

He is a member of Tau Beta Pi, Sigma Pi Sigma, and AAAS.



Elie J. Baghdady (A'52-M'57) was born in Zahleh, Lebanon, on November 10, 1930. Between 1949 and 1951, he was a British



E. J. BAGHDADY

Council Scholar and recipient of the university first prize scholarship at the American University of Beirut. He received the B.A. degree with high distinction in physics in 1951.

In the summer of 1951, he came to the United States on a Georgia Institute of

Technology World Student Fund Fellowship and enrolled in the Institute's graduate division of electrical engineering. In June, 1952, he joined the electrical engineering staff of the Massachusetts Institute of Technology as a graduate student and research assistant in the Research Laboratory of Electronics. He became an instructor in electrical engineering in 1955 and assistant professor in 1956. He received the M.S. and D.Sc. degrees in electrical engineering from M.I.T. in 1954 and 1956, respectively.

Dr. Baghdady's research has been mainly concerned with frequency-modulation studies, including problems of improving reception in the presence of high-level noise and interference and the analysis of network response to fm waves. Since 1954, he has taught advanced courses in radio engineering and modulation theory, mathematical methods in electrical engineering, network analysis and synthesis, electronic circuits, and transient analysis of linear electro-mechanical systems. Presently, he is in charge of a graduate course on modulation theory and a research project on fm.

George R. Brewer (A'43-M'49-SM'54) was born in New Albany, Ind., on September 10, 1922. He received the B.E.E. degree



G. R. BREWER

from the University of Louisville in 1943, and the Ph.D. degree in electrical engineering from the University of Michigan in 1952.

Dr. Brewer has been principally engaged in research and development of electron tubes from 1943 to 1944, at the Radiation Laboratory, Massachusetts Institute of Technology; from 1944 to 1947, at the Naval Research Laboratory; and from 1947 to 1951, at the Engineering Research Institute of the University of Michigan. He now is a member of the Electron Tube Laboratory of Hughes Research Laboratories.

He is a member of the American Physical Society, Sigma Xi, and Phi Kappa Phi.



T. J. Bridges (M'57) was born at Gillingham, Kent, Eng., in December, 1923. He attended London University, London, Eng.,



T. J. BRIDGES

where he received the Bachelor of Science degree in engineering in 1944.

He joined the Admiralty in 1945 and is a member of the Royal Naval Scientific Service at the Services Electronics Research Laboratory, Baldock, Eng. Since November, 1956, he has been on leave of absence from the Admiralty and is engaged in microwave tube research at Bell Telephone Laboratories, Murray Hill, N. J.



R. C. Burgener (A'54) was born October 10, 1921 in Galion, Ohio. He received the B.S.E.E. degree from Case Institute of Technology in 1950.



R. C. BURGNER

After graduation he was engaged in relay development at the North Electric Mfg. Co., Galion, Ohio until September, 1951. At that time he joined the Department of Electrical Engineering of The University of Tennessee as research engineer, where he

was primarily concerned with development in the field of radar. He received the

M.S.E.E. degree from The University of Tennessee in June, 1956. He is presently employed at Battelle Memorial Institute as a research engineer and he also is attending Ohio State University as a candidate for the Ph.D. degree.

He has a professional engineering license in Tennessee.



Harold J. Curnow was born at Birmingham, Eng., in November, 1930. He was educated at Solihull School, Warwickshire, Eng.



H. J. CURNOW

He also attended Birmingham University, Birmingham, Eng. He received the degree of Bachelor of Science with honors in mathematical physics from Birmingham University in 1951.

Since then, he has been a member of the Royal Naval Scientific Service, and at the present time is employed at the Services Electronics Research Laboratory, Baldock, Hertfordshire, Eng.



E. T. Jaynes (SM'54) was born in Waterloo, Iowa, on July 5, 1922. He attended Cornell College and Iowa State University,



E. T. JAYNES

receiving the B.A. degree in physics from the latter in 1942. He studied in the graduate school of the University of California in Berkeley and at Princeton University from which he received the M.A. degree in 1948 and the Ph.D. degree in theoretical physics in 1950.

From 1942 to 1946, he was engaged in microwave research and development as a project engineer at the Sperry Gyroscope Co., Garden City, N. Y., and in the combined research group of the Naval Research Laboratory.

Since 1950, he has been on the faculty of Stanford University and at present holds the titles of associate professor in the microwave laboratory and lecturer in physics.



Sherwood King (S'40-A'41-SM'53) was born in Schenectady, N. Y. on August 5, 1917. He received the B.S. degree in engineering sciences from Harvard University in 1938 and the M.S.E.E. degree from Lafayette College in 1940. From 1940 until

1947, he was a member of the technical staff of Bell Telephone Laboratories, engaged in the development of sonar and radar test equipment and of mobile radio telephone systems. In 1947, he joined the staff of the Department of Electrical Engineering of the University of Tennessee as assistant professor. He became associate professor of electrical engineering in 1955. At Tennessee he was in charge



S. KING

of the electronics laboratories and supervisor of a research group engaged in radar development. In 1956 Mr. King became a member of the technical staff in the Ground Systems Division, Hughes Aircraft Company, and at present is head of the Studies and Analysis Section of that Division's Radar Laboratory.

Mr. King is a member of Sigma Xi and Eta Kappa Nu.



David I. Kosowsky (S'50-A'53-M'57) was born in New York, N. Y., in 1930. He received the B.E.E. degree from the College of the City of New York in 1951 and the S.M. and Sc.D. degrees from Massachusetts Institute of Technology in 1952 and 1955. He was a staff member of the Research Laboratory of Electronics (M.I.T.) from 1951 to 1955 and was engaged in research on missile systems, applications of statistical communication theory, and filter theory. He was responsible for the development of techniques for the synthesis and realization of crystal filters.



D. I. KOSOWSKY

He is presently employed by Hycon Eastern, Inc., as Director of the Crystal Filter Division. He is a member of Eta Kappa Nu, Tau Beta Pi, and Sigma Xi.



Harold Levenstein (A'46-M'55) was born on June 28, 1923, in Philadelphia, Pa. He received the B.E.E. degree from Cooper Union, New York, N. Y., in 1943, and the M.E.E. degree from the Polytechnic Institute of Brooklyn in 1949. In addition to course work for the doctorate, he has been a special student in fire control systems and communications theory at Massachusetts Institute of Technology in 1949, 1953, and 1955.



H. LEVENSTEIN

Mr. Levenstein joined Western Electric in 1943 as a test planning engineer on radar systems. In 1946, he was a member of the Sight Laboratory, Fairchild Camera and Instrument Co., working in fire control systems. From 1947 to 1950, he was employed by Fairchild Guided Missiles Division as an electronics engineer on telemetering and guidance systems for the Lark Missile. In 1950, he joined the W. L. Maxson Corp. as a senior engineer, responsible for fire control and bombing and navigation systems. He has been manager of the analysis group and the systems engineering department. In 1955, he took a leave of absence to work as a member of the M.I.T. Instrumentation Laboratory on inertial navigation systems. Since June, 1956, he has been research assistant to the Vice-President of the R&D Division of the W. L. Maxson Corp., acting as consultant in systems and control engineering and is responsible for preliminary system planning.

Mr. Levenstein is a member of Tau Beta Pi, Sigma Xi, the American Physical Society, and the American Mathematical Society.



O. Thomas Purl (S'50-A'54) was born on June 5, 1924 in East St. Louis, Ill. He received the B.S. degree in general engineering from the University of Illinois in 1948. Prior to that, he was a meteorologist with the Air Force from 1943 to 1946. He was engaged in microwave tube work at the Collins Radio Co. from 1948 to 1949. In 1949, he returned to the University of Illinois, where he received the B.S.E.E., M.S.E.E., and Ph.D. degrees in 1951, 1952, and 1955, respectively. During part of this time, he was a research associate in the Electrical Engineering Research Laboratory.



O. T. PURL

Since 1955, he has been a member of the technical staff at the Hughes Electron Tube Laboratory, where he has been engaged in research and development on microwave tubes.

Dr. Purl is a member of Sigma Xi, Eta Kappa Nu, Phi Kappa Phi, and Sigma Tau.



J. F. Ramsay (A'56) was born at Milngavie, Dunbartonshire, Scotland, in 1908. He received the M.A. degree in mathematics and physics from the University of Glasgow in 1934. From 1933 to 1935, he was employed by the Cosmos Lamp Works, Enfield, Eng., as assistant engineer engaged on circuit applications of receiving tubes. In 1935, he was employed by the Gen-



J. F. RAMSAY

eral Electric Co., Ltd., Coventry, Eng., as radio circuit engineer on broadcast receiver problems.

In 1936, Mr. Ramsay joined the research staff of Marconi's Wireless Telegraph Co., Ltd., Chelmsford, Eng., as assistant engineer on broadcast receiver investigational work. From 1938 to 1940, he was attached to the Air Division on transmitter drive development. In 1941, he returned to research in the development of superregenerative radar: seconded to the Admiralty in the same year, Mr. Ramsay took part in war-time microwave antenna research both with Marconi's Wireless Telegraph Co., Ltd., and at Admiralty establishments. Among the antenna types with which he was associated were metal-plate lens, mirror-connected horn, squintless linear array, polyrod, channel-guide antenna, and circularly polarizing mirrors. Returning to Marconi's in 1946, he published papers on Fourier transform theory for antennas based on G. A. Campbell's memoir for circuit theory. In further antenna work, he was associated with antennas for marine radar, VOR, tv broadcasting, fm broadcasting, microwave relay, and millimetric techniques. The problems encountered in the millimeter field led to the discovery of the old microwave techniques of the 1890's. Since 1956, Mr. Ramsay has been employed by Canadian Marconi Company, Montreal, Canada.

He is a member of the IEE, London.



F. V. Schultz (A'32-SM'45) was born on November 7, 1910 in Petersburg, Mich. He received the B.S.E.E. degree in 1932, the M.S.E.E. degree in 1939, and the Ph.D. degree in 1950, all from the University of Michigan. After five years in industry, primarily as a receiver development engineer, he joined the Department of Electrical Engineering of Michigan State University East Lansing, Mich., where



F. V. SCHULTZ

he remained from 1937 until 1941.

During World War II, Dr. Schultz was a group leader in the Radar Laboratory of the Wright Air Development Center, where he was concerned with the development of antennas and radar beacons. From 1946 to 1950, he was research engineer in the Engineering Research Institute of the University of Michigan. During this time, Dr. Schultz was engaged in research studies on missile guidance systems and on electromagnetic wave scattering problems. From 1950 until 1956, he was professor of electrical engineering at the University of Tennessee, in charge of instruction and research in electronics. Since 1956, he has been professor of electrical engineering at Purdue University, Lafayette, Ind.

He is a member of Sigma Xi, Tau Beta Pi, Phi Kappa Phi, Eta Kappa Nu, the American Physical Society, and the American Society for Engineering Education.

IRE News and Radio Notes

EARLY RESERVATIONS URGED FOR IRE NATIONAL CONVENTION

Plans are all but completed for the forty-sixth annual national convention of the IRE, scheduled for the Waldorf-Astoria Hotel and the New York Coliseum, March 24-27. Fifty-five technical sessions are being set up by the Technical Program Committee with the aid of all IRE Professional Groups. Thirty-three sessions will be held at the Waldorf; the remainder, at the Coliseum. The program will feature two special symposia on the evening of March 25 in which the nation's leading experts will discuss "Electronics in Space" and "Electronics in Industry." Full program details will be published in the March issue of the PROCEEDINGS OF THE IRE.

The popular social events will open with a "get-together" cocktail party on the afternoon of March 24. The annual banquet, to be held in the Grand Ballroom of the Waldorf during the evening of March 26, will feature Robert C. Sprague, Chairman of the Board of Sprague Electric Co. and of the Federal Reserve Bank of Boston, who will speak on "The Federal Reserve and the Electronics Industry."

Since a convention attendance of 55,000 is anticipated, all members are urged to place their reservations for cocktail party tickets at \$4.30 each, and banquet tickets at \$15.00 with IRE Headquarters quickly.

The annual Single Sideband Dinner will be held March 25 at the Hotel New Yorker. Tickets can be obtained for \$7.50 each at Single Sideband Amateur Radio Assn., 261 Madison Ave., N. Y. 16, N. Y.

I. J. KAAR IS RECIPIENT OF IRE-EIA FALL MEETING PLAQUE

I. J. Kaar (J'22-M'29-F'41), Vice-President of Hoffman Electronics, received the Radio Fall Meeting Plaque at the 29th meeting in Toronto, Canada. He received the award for "his many contributions to the broadcast and television receiver industry."



I. J. KAAR

Mr. Kaar was former head of the General Electric Color System Technical Project. For the previous thirty years he had been closely associated with the organization of the General Electric radio and television engineering developments.

He also served as panel chairman on receiver-transmitter coordination for the first National Television System Committee and vice-chairman of the panel on coordination for the second NTSC.

Alois W. Graf 1901-1957

The following resolution was adopted by the IRE Board of Directors at a meeting on November 20, 1957.

RESOLUTION

With profound sorrow the Directors of The Institute of Radio Engineers record the death of one of their friends and associates—Alois W. Graf. Mr. Graf was an IRE member for over thirty years, having joined as an Associate in 1926, advancing to Member grade in 1944, Senior Member in 1945, and Fellow in 1955. He served as a Director in 1952, 1953, and 1957.

Perhaps his most important contributions to IRE nationally were the time and effort taken from his personal law practice to devote to legal matters for IRE. A great deal of his time was spent on trade-mark applications to safeguard the IRE name, symbol, and publication titles.

Having served as the Chairman of the Constitution and Laws Committee since 1954, he believed that the Constitution and Bylaws were in need of modernization, and he undertook the tremendous task of drafting a proposal for a new Constitution and Bylaws.

Mr. Graf was very active in Professional Group administration, serving as Central Division Vice-Chairman since 1954.

He contributed vastly to the welfare of IRE on the Section level, serving as Chairman of the Chicago Section in 1946-47, and continuing thereafter, as an elder statesman, to guide the destinies of a large and flourishing Section.

The Board of Directors of The Institute of Radio Engineers desires to spread upon its records its keen sense of personal loss in Mr. Graf's death and its deep sympathy for the members of his family.

Calendar of Coming Events and Authors' Deadlines*

1958

- Cleveland Elec. Conf. Masonic Audit., Cleveland, Ohio, Feb. 14-15
- Transistor-Solid State Circuits Conf., Phil., Pa., Feb. 20-21
- Nuclear Eng. and Science Congress, Palmer House, Chicago, Ill., Mar. 16-21
- IRE Nat'l Convention, N. Y. Coliseum and Waldorf-Astoria Hotel, New York City, Mar. 24-27 (DL*: Nov. 1, G. L. Haller, IRE Headquarters, New York City)
- Single Sideband Dinner, Hotel New Yorker, New York City, Mar. 25
- Instruments & Regulators Conf., Univ. of Del., Newark, Del., March 31-Apr. 2
- Conf. on Automatic Optimization, Univ. of Del., Apr. 2-4
- Symp. on Electronic Waveguides, Eng. Soc. Bldg., New York City, Apr. 8-10
- SW Regional Conf. & Show, Mun. Audit, San Antonio, Tex., Apr. 10-12
- Conf. on Automatic Techniques, Statler Hotel, Detroit, Mich., Apr. 14-16
- Spring Tech. Conf. on TV and Transistors, Eng. Soc. Bldg., Cincinnati, Ohio, Apr. 18-19
- Elec. Components Symp., Ambassador Hotel, Los Angeles, Calif., Apr. 22-24 (DL*: Nov. 15, E. E. Brewer, Convair, Pomona, Calif.)
- URSI Spring Mtg., Willard Hotel, Wash., D. C., Apr. 24-26
- Semiconductor Symposium of Electrochemical Society, Statler Hotel, New York City, Apr. 27-May 1
- Seventh Region Conf. & Show, Sacramento, Calif., Apr. 30-May 2
- PGMTT Symp., Stanford Univ., Stanford, Calif., May 5-7 (DL*: Jan. 15, K. Tomiyasu, G. E. Microwave Lab., 601 California Ave., Palo Alto, Calif.)
- Western Joint Computer Conf., Ambassador Hotel, Los Angeles, Calif., May 6-8 (DL*: Jan. 15, Tech. Program, Chairman, P. O. Box 213, Claremont, Calif.)
- Nat'l Aero. & Nav. Elec. Conf., Dayton, Ohio, May 12-14
- IEE Convention on Microwave Values Savoy Place, London, England, May, 10-23
- PGME Mtg., Wash., D. C., May

*DL = Deadline for submitting abstracts.

(Continued on page 506)

Calendar of Coming Events and Authors' Deadlines*

(Continued)

- PGPT Symp., Hotel New Yorker, New York City, June 5-6
- PGMIL Convention, Sheraton-Park Hotel, Wash., D. C., June 16-18
- Spec. Tech. Conf. on Nonlinear Mag. and Mag. Amplifiers, Los Angeles, Calif., Aug. 6-8
- Elec. Radio & Standards Conf., Univ. of Colo. and NBS, Boulder, Colo., Aug. 13-15
- WESCON, Ambassador Hotel and Pan-Pacific Audit., Los Angeles, Calif., Aug. 19-22 (DL*: May 1)
- Nat'l Symp. on Telemetering Americana Hotel, Miami Beach, Fla., Sept. 22-24
- Indus. Elec. Conf., Detroit, Mich., Sept. 24-25
- Nat'l Electronics Conf., Hotel Sherman, Chicago, Ill., Oct. 13-15
- IRE Canadian Convention, Toronto, Can., Oct. 15-17
- PGCS Symp. on Aero. Communications, Hotel Utica, Utica, N. Y., Oct. 20-22
- Nat'l Simulation Conf., Dallas, Tex., Oct. 23-25
- EIA-IRE Radio Fall Meeting, Sheraton Hotel, Rochester, N. Y., Oct. 27-29
- East Coast Aero. & Nav. Elec. Conf., Lord Baltimore Hotel and 7th Regiment Armory, Baltimore, Md., Oct. 27-29
- PGED Meeting, Shoreham Hotel, Washington, D. C., Oct. 30-Nov. 1
- Atlanta Section Conf., Atlanta-Biltmore Hotel, Atlanta, Ga., Nov. 17-19
- Elect. Computer Exhibition, Olympia, London, Eng., Nov. 29-Dec. 4
- Eastern Joint Computer Conf., Bellevue-Stratford Hotel, Philadelphia, Pa., Dec. 3-5
- Nat'l Symp. on Global Comm., St. Petersburg, Fla., Dec. 3-5
- PGVC Annual Mfg., Hotel Sherman, Chicago, Ill., Dec. 4-5
- Mid-America Elec. Convention, Mun. Audit., Kan. City, Mo., Dec. 9-11 (DL*: Aug. 1, Wilbert O'Neal, Vendo Co., 7400 E. 12, Kan. City, Mo.)

1959

- IRE Nat'l Convention, New York City, Mar. 23-26
- SW Regional Conf., Dallas, Tex., Apr. 16-18
- Nat'l Aero & Nav. Elec. Conf., Dayton, Ohio, May 11-13
- WESCON, San Francisco, Calif., Aug. 18-21
- Nat'l Electronics Conf., Chicago, Ill., Oct. 12-14
- East Coast Aero. & Nav. Conf., Baltimore, Md., Oct. 26-28
- PGED Meeting, Shoreham Hotel, Washington, D. C., Oct. 29-31
- Radio Fall Meeting, Syracuse, N. Y., Nov. 9-11
- Eastern Joint Computer Conf., Hotel Statler, Boston, Mass., Nov. 30-Dec. 3

* DL = Deadline for submitting abstracts.

L. S. McDOWELL IS THE FIRST WOMAN TO BECOME LIFE MEMBER

On January 1, 1958, Louise S. McDowell (M'23-SM'43) was the first woman to become a Life Member of the IRE. The IRE bylaws provide that the Board of Directors shall waive the dues of each and every member of the IRE who has attained the age of 65 years and been a member for 35 years. These members are then designated "Life Members," and at the present time there are 131 IRE



L. S. McDOWELL

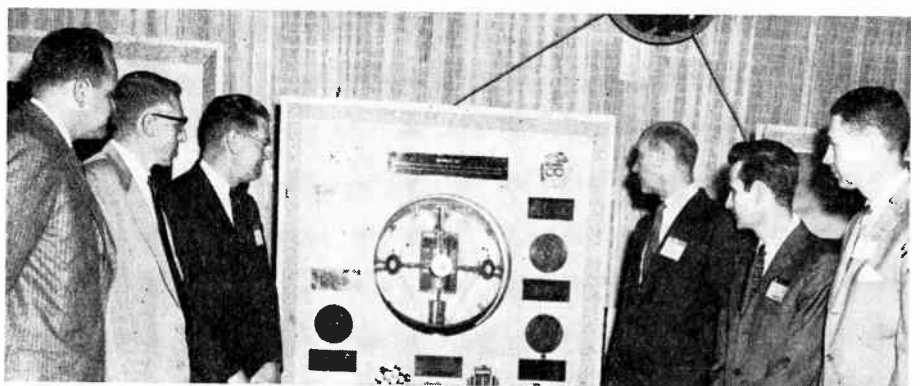
Life Members.

Dr. McDowell is professor emerita of physics at Wellesley College. She has been associated with Wellesley since 1909, and from 1913 until retirement in 1945 head of the physics department. Beginning in 1917, she also taught a semester course in electromagnetic waves and radio communication which offered to undergraduates experimental lectures and laboratory work as well. During 1918 and 1919 on leave from Wellesley, Dr. McDowell did physical research on crystal detectors and vacuum tube oscillators in the Radio Section of the National Bureau of Standards. In 1921, she did further research at Cruft Laboratory of Harvard University.

Dr. McDowell obtained the Ph.D. degree from Cornell University in 1909 where she had received her master's degree in 1907; her bachelor's degree from Wellesley was awarded in 1898. She is a fellow of the American Physical Society, and has had several papers published in the *Physical Review* of the American Physical Society. In 1947 she retired from active life after serving as assistant editor of *Very High Frequency Techniques*.

MAECON PROVES SUCCESSFUL

The IRE Mid-America Electronics Convention was held at the Municipal Auditorium in Kansas City, Mo., November 13-14, 1957, with headquarters at the Hotel Muehlebach. It was the ninth annual convention sponsored by the IRE Kansas City Section.



Shown at MAECON looking at a model of an earth satellite are (left to right): K. V. Newton, IRE Region Six Director; R. M. Somers, Bendix Aviation Corp.; L. H. Montgomery, Vanderbilt Univ.; J. T. Henderson, IRE President; P. C. Constant, Jr., IRE Kansas City Section chairman; and W. H. Ashley, Jr., convention chairman.

The convention drew approximately 1500 engineers and scientific-minded personnel, from more than 13 states.

There were 77 exhibit booths with displays of some of the latest electronic instruments, products and associated equipment. The featured exhibit was a complete technical model of America's earth satellite which was displayed by the Naval Research Laboratories.

There were ten technical sessions covered by 28 technical paper presentations. J. T. Henderson, IRE National President, gave the opening address, and also spoke on "The IRE Today" at the annual banquet. Dr. Simon Ramo, executive vice-president of the Ramo-Wooldridge Corp., was the guest banquet speaker and spoke on "The Increasing Role of Electronics in Missile Systems." The banquet was attended by nearly 300 persons.

TEMPORARY MEMBERSHIPS FOR RESEARCH NOW AVAILABLE

For the second year, the Institute of Mathematical Sciences at New York University offers temporary memberships to mathematicians and other scientists holding the Ph.D. degree who intend to study and do research in the fields in which the Institute is active. These fields include functional analysis, ordinary and partial differential equations, mathematical physics, fluid dynamics, electromagnetic theory, numerical analysis and digital computing, and various specialized branches, such as linear programming, hydromagnetics, and reactor theory. Membership will be awarded for one year, but it may be renewed. Special arrangements can be made for applicants who expect to be on leave of absence from their institutions.

Temporary members may participate freely in the research projects, the advanced graduate courses and the research seminars of the Institute, and they will have the opportunity of using the computational facilities which include an IBM 704 computer and a Univac. They will receive a stipend commensurate with their status.

Requests for information and for application blanks should be addressed to the Membership Committee, Institute of Mathematical Sciences, 25 Waverly Place, New York 3, N. Y.

1958 Transistor & Solid State Circuits Conference

UNIVERSITY OF PENNSYLVANIA AND SHERATON HOTEL, PHILADELPHIA, PA.

FEBRUARY 20-21, 1958

FEBRUARY 20

9:30 a.m.—Noon

Irvine Auditorium

COMPUTER CIRCUITS

Chairman: T. R. Finch, Bell Tel. Labs.
The Advantages of Linear Selection in Transistor-Core Memories, R. E. McMahon, Lincoln Lab., M.I.T.

Transistor Resistor Logic Circuit Analysis, Q. W. Simkins, Bell Tel. Labs.

Ten Megapulse Transistorized Pulse Circuits for Computer Application, W. N. Carroll and R. A. Cooper, IBM.

High-Speed, Graded-Base Transistor, Digital Circuit Techniques, R. H. Baker, Lincoln Lab., M.I.T.

Higher-Speed Computer Circuits, A. K. Rapp and M. M. Fortini, Philco Corp.

University Museum

SURVEY

Chairman: J. A. Rajchman, RCA.
Noise in Semiconductors, W. H. Fonger, RCA.

Review of Some Novel State Devices and Their Applications, W. H. Katz, General Electric Co.

2:45-5:15 p.m.

Irvine Auditorium

SWITCHING

Chairman: P. M. Thompson, Defense Research Board, Ottawa, Canada.

New Configurations in Nonsaturating Complementary-Current Switching Circuits, C. M. Campbell, Jr., Burroughs Corp

The Application of Transistors Operated in the Avalanche Mode to the Generation of

Millimicrosecond Pulses, G. B. B. Chaplin, United Kingdom Atomic Energy Authority, England.

The Use of Junction Transistors as a Three-Terminal Temporary Memory for Digital Circuits, G. H. Perry, Royal Radar Research Establishment, England.

Transistor Bilateral Switches, W. M. Cook and P. I. Bargellini, RCA.

A Two-Transistor Gate for Time-Division Switching, J. D. Johannesen and P. B. Myers, Bell Tel. Labs.

3:15-5:15 p.m.

University Museum

NEW TECHNIQUES

Chairman: H. E. Tompkins, Univ. of Pennsylvania.

Low-Level, High-Speed Voltage Comparator, J. W. Higginbotham and H. H. Douglass, Martin Co.

A High-Speed Analog Multiplier with a Linearity Better than +0.3 Per Cent, R. J. Bibby and P. M. Thompson, Defense Research Board, Ottawa, Canada.

A Semiconductor Voltage Regulator for Rotating Generators, J. L. Jensen, Minneapolis-Honeywell Regulator Co.

A Transistorized Overload-Proof Electronic Regulator—TOPEP, P. A. Dodge, General Electric Co.

FEBRUARY 21

9:00 a.m.—Noon

Irvine Auditorium

LINEAR APPLICATION

Chairman: J. G. Linvill, Stanford Univ.
Methods of Cascading Unneutralized Tuned Transistor Amplifiers, R. M. Frazier,

Jr., Westinghouse Electric.

Transistor 70-MC IF Amplifier, V. R. Saari, Bell Tel. Labs.

Optimum Noise Performance of Transistor Input Circuits, R. D. Middlebrook, Calif. Inst. of Technology.

Paper to be announced by J. T. Paupin and/or H. T. Mooers, Minneapolis-Honeywell Regulator Co.

Dielectric Modulators Using Space-Charge Capacitance of Junction Diodes, Carl Hurtig, M.I.T.

University Museum

SURVEY ON SWITCHING and POWER CONTROL

Chairman: J. J. Suran, General Electric Co.

Switching, Gary Clark, Burroughs Corp.
Power Control with Semiconductors, Louis Bright, Westinghouse.

2:00-4:30 p.m.

Irvine Auditorium

NEW DEVICES

Chairman: George Royer, IBM.
Operation of a Low-Temperature Memory Element, C. J. Kraus, IBM.

The Application of the Dynister Diode to Off-On Controllers, P. F. Pittman, Westinghouse Electric.

Diode Amplifiers, H. W. Abbott and L. D. Wechsler, General Electric Co.

Magnetoresistive Amplifiers and Second Harmonic Modulators, H. N. Putschi, General Electric Co.

Photoelectronic Circuit Applications, S. K. Ghandhi, General Electric Co.

Books

Microwave Measurements by E. L. Ginzton

Published (1957) by McGraw-Hill Book Co., 330 W. 42 St., N. Y. 36. N. Y. 476 pages+21 index pages +17 pages of appendix+xvii pages. Illus. 9½×6½. \$12.00.

The author has successfully consolidated a multitude of basic microwave techniques into a book which can serve both as a basic text to a first year graduate course in microwave measurements and as a reference text to microwave engineers. Topics are carefully selected, clearly described, and very well integrated into a valuable unity. The impedance concept, transmission-line theory, and the equivalent-circuit approach are fully treated and utilized in the development of methods suitable for microwave measurements.

The first chapter delves into sources of microwave power, presents a practical discussion of klystrons, microwave triodes, and traveling-wave tubes, and includes the need and devices for isolating laboratory oscillators. Also considered are standard signal and harmonic generators. Chapters 2 and 3 contain a comprehensive evaluation of

methods for detecting and measuring microwave power. Bolometers are extensively covered.

An excellent exposition of the impedance concept is developed in Chapter 4, with stress on graphical procedures. It is followed by a chapter on impedance measurements, which includes an elaborate treatment on the standing-wave detector and practices for achieving precision measurements. The behavior of microwave circuits and equivalent representations are discussed in Chapter 6.

Topics relating to the measurement of wavelength and frequency are dealt with in Chapters 7 and 8. The presentation is extended to wavemeter techniques and frequency standards. Chapters 9 and 10 concern resonant-cavity characteristics and the evaluation of the important parameters, Q and R . The final chapter investigates the measurement of attenuation and describes the power-ratio, substitution, cavity-resonance and scattering-coefficient methods.

There are many figures, footnotes and experimental data coherently introduced into

the text. Perhaps the bibliography may be considered to be rather limited although a large number is not really required. All in all, the book reflects much credit on those concerned with it and will prove to be of great value for any one who desires to become thoroughly familiar with microwave measurements.

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Analytical Design of Linear Feedback Controls by G. C. Newton, Jr., L. A. Gould and J. F. Kaiser

Published (1957) by John Wiley & Sons, Inc., 440 Fourth Ave., N. Y. 16, N. Y. 282 pages+3 index pages+130 pages of appendix+3 pages of bibliography+xi pages. Illus. 9½×6½. \$12.00.

This book covers the theory of the design of linear feedback control systems by the process of minimizing the integral of error squared for step and ramp inputs, or minimizing rms error for stochastic (random) in-

puts to linear mathematical models of the actual systems. Lagrangian multipliers are used to account for certain restraints, such as those placed on the amplitude of signals in order to maintain essentially linear operation.

The minimization procedure leads to a form of the Wiener-Hopf integral equation. The solution of this equation supplies the data for design of the compensating element, and for calculating the minimum possible rms error. This information is intended to be used as a guide in the trial and error design for the actual system.

The book is intended for readers who have had some graduate study in control systems, or are prepared to do collateral reading. It is assumed that the reader has already obtained an insight into the conventional frequency approach, and to the practical design of feedback control systems. There is a brief coverage of basic material in the appendices.

The book is terse. The basic thesis is developed in 286 pages. Of necessity the development is mathematical, and the description of the minimization procedure involves complicated integral expressions. Essentially there is no deviation from the basic thesis, and no exposition on practical aspects. Where examples are used, they are stripped to mathematical models in all cases except that of the example which makes up Chapter 9. However, the authors are careful to point out the assumptions they introduce and the restrictions on the methods they advocate.

There is little reference to somewhat similar work done by others, such as the work on minimization of the integral of time-weighted absolute value of error response to step inputs done by R. C. Lathrop and D. Graham.

It is felt that development of the minimization expressions in the frequency domain rather than the time domain would have resulted in expressions more readily interpreted by control people. The end results would have been the same, providing that key expressions were transformed back to the time domain.

The book is recommended for reading by every person wishing to be sophisticated in the area of feedback controls. The presentation is straightforward and clean cut. It provides a unified coverage of material not available elsewhere except in scattered journal reports.

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Nomograms of Complex Hyperbolic Functions, 2nd ed., by Jorgen Rybner

Published (1955) by Jul. Gjellerups Forlag, Copenhagen, Denmark. 99 pages. 12×8½. Dan. Kr. 44.00.

The second edition of this book incorporates a number of improvements over the first edition, as well as some additional nomograms. The notation of complex arguments has been changed to the common English usage. The ring binding has been changed from the top to the side, making the book more convenient to use.

Thirteen separate nomograms for $\cosh(A+jB) = p+jq$ cover the range $0 \leq A \leq 4$, $0 \leq B \leq \pi/2$. With one exception, the scales for A are given in both nepers and decibels, while B is expressed in both radians and

degrees. $\sinh(A+jB) = p+jq$ is treated similarly in thirteen nomograms.

$\tanh(A+jB) = r\angle\theta$ is treated in twenty separate nomograms covering the range $0 \leq A \leq 3$, $0 \leq B \leq \pi/2$, A in nepers and decibels, B in radians, and θ in degrees.

In addition, nomograms are given for conversion of complex numbers from rectangular to polar form, and vice versa, for reflection loss and reflection phase shift in networks, new nomograms for interaction loss and phase shift, and for resonance circuits and filters. An introductory section of 39 pages discusses the use of the nomograms, and gives a collection of formulas for circular and hyperbolic functions, and for four-terminal networks and transmission lines. The text is given in both Danish and English.

This book will be found of value in transmission line, wave propagation, filter and other problems which involve complex hyperbolic functions. Their accuracy is unusually high, insuring at least three-figure accuracy over much of the range. Some spot checks gave errors of only a few parts in 10^{-4} . The accuracy and convenience of these nomograms should make them a useful addition to the library of the electronics engineer.

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Solid State Physics, Vol. IV, ed. by F. Seitz and D. Turnbull

Published (1957) by Academic Press Inc., 111 Fifth Ave., N. Y. 3, N. Y. 521 pages +19 index pages +xiv pages. Illus. 9½×6½. \$12.00.

This is Volume IV of the series of texts covering advances in research and applications in solid state physics edited by F. Seitz and D. Turnbull. The topics selected for this volume are "Ferroelectrics and Antiferroelectrics" by Werner Kanzig; "Theory of Mobility of Electrons in Solids" by F. J. Blatt; "The Orthogonalized Plane-Wave Method" by T. O. Woodruff; "Bibliography of Atomic Wave Functions" by R. S. Knox; and "Techniques of Zone Melting and Crystal Growing" by W. G. Pfann.

Kanzig has attempted to present a systematic review of the field of ferroelectricity as seen by the solid state physicist with principal emphasis on the behavior of single crystals. This monograph is quite long, containing nearly 200 pages and subdivided into 13 chapters. These chapters include the "Phenomenological Behavior of Ferroelectrics: Experimental," "Thermodynamic Theory of Ferroelectric Crystals," "Optical Properties of Ferroelectrics in the Visible Range," "Domain Structure and Hysteresis," "Thermodynamic Behavior of Antiferroelectrics," "Thermodynamic Theory of Antiferroelectrics," "Optical Properties of Antiferroelectrics," "Antiferroelectric Domains," "The Static and Dynamic Structure of Ferroelectric and Antiferroelectric Crystals," "Isotope Effects," "Ferroelectricity and Antiferroelectricity of Solid Solutions," and a chapter on "Molecular Models."

This review is comprehensive, systematic and authoritative. It refers to 378 articles in the literature. It is well organized, well illustrated and represents a valuable reference for workers in the field.

The monograph on the "Theory of Mobility of Electrons in Solids" by F. J. Blatt is also very long. It contains 167 pages and 328 references to original literature. The

article is broken down into 6 chapters including an introductory chapter, a chapter each on "Statistics of Free Electrons," "Boltzmann Equation," "Solution of the Boltzmann Equation for Nonspherical Energy Surfaces and Anisotropic Relaxation Times," "Scattering Mechanisms," and "Effects Arising from Lack of Thermal Equilibrium."

The emphasis in this article is primarily on the theoretical approach but a certain amount of experimental work is cited in order to establish the validity of the theoretical deductions. It is concerned primarily with transport phenomena and the effects of electric and magnetic fields and of thermal gradients separately and simultaneously. The one electron approximation neglecting correlation and exchange effects is employed throughout. This review is unusually good and will serve as a valuable reference for workers in the field.

The article on "The Orthogonalized Plane-Wave Method" by T. O. Woodruff is primarily an elaboration of Part X of an article in the first volume of this series by Reitz. This article contains 44 pages and three chapters. The first chapter is devoted to a description of the method, the second to a survey of some applications of the method, and the third is a calculation of an example in which this method is applied to the silicon crystal. The principal merit of this article is in its detailed outline of the calculation of the specific solid state problem by a method of approximation which has shown promise of giving quantitative results with reasonably rapidly convergent solutions. This article will prove useful to those concerned with the calculations of wave functions and energy eigenvalues of an electron in an arbitrary crystal potential.

The article "Bibliography of Atomic Wave Functions" by R. S. Knox is a compilation of references to the literature on atomic wave functions which have been computed. This compilation makes use of five earlier compilations which have been corrected, expanded and brought up to date. The article includes an alphabetical list of atoms and ions with the literature references. 117 articles in the literature have been employed in this compilation.

The article on "Techniques of Zone Melting and Crystal Growing" by W. G. Pfann contains nearly 100 pages and 187 literature references. It is organized in eight chapters including "Distribution and Coefficient and Normal Freezing," "Principles of Zone Refining," "Practice of Zone Refining," "Zone Leveling," "Methods of Perturbing the Concentration," "Temperature-Gradient Zone Melting," and "Crystal Growth and Dislocations."

This is an article describing techniques employed by research men in the preparation of crystalline materials for research purposes. It discusses the techniques in a manner rarely found in standard texts and highly desirable from the point of view of the research man. Pfann has done an outstanding job in compiling in a very readable form material which is difficult to obtain and organize from the literature.

Volume IV is a very welcome addition to this highly interesting series of monographs on special topics in solid state physics.

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Scanning the Transactions

It has been suggested that the average IRE member, although he is not interested in reading highly specialized papers outside his own field, would nevertheless, welcome a report on some of the significant or unusual work that is going on in other fields which appears in IRE publications he does not normally see.

With this objective in mind we are hereby inaugurating a new monthly feature in which the Managing Editor, with the aid of TRANSACTIONS editors, will single out and interpret for the general reader, appropriate papers appearing in current issues of the TRANSACTIONS of the 28 IRE Professional Groups. Further information about the issues from which these papers are selected will be found in the "Abstracts of IRE TRANSACTIONS" section that immediately follows.

The title of this new section is actually incomplete. We plan to cover not only the TRANSACTIONS but the STUDENT QUARTERLY and the WESCON and NATIONAL CONVENTION RECORDS as well. As a case in point we refer readers to the first item below.

Comments from readers on the utility (or futility) of this endeavor will be welcomed by the IRE Editorial Board.—*The Editor*

Life in a laboratory was revealed to the surprised readers of the STUDENT QUARTERLY in the most unusual form yet to appear in an IRE publication. Twelve verses, ranging over the laboratory scene from Conferences to Applied Mathematics, indicate that the author, already distinguished as a leading engineer, as a past Editor of the IRE and as a prolific and articulate writer of science fiction and nonfiction, must now take a bow as a poet of no small talent. The verses were so delightful and stimulating that we feel compelled to offer a sample below. (J. R. Pierce, "Life in a laboratory," IRE STUDENT QUARTERLY, December, 1957.)

Bosses

Bosses are people up a fantastic tree
Which stretches rootlets into the fertile earth
And bears some fragrant blossoms at its top.
Well-digested achievement upward flows,
And what flows down? Dirty jobs from on high
Sediment themselves among the mucky roots
And interrupt the uneven course of thought.
But bosses have the dirty end as well:
The men who can't do better, God help them;
The unhappy ones (who isn't?) who blame the boss;
The happy ones, who need more things and men
To make their little millennium in a year,
The ones in a rut, who go on and on and on,
And who can stop what he has once set going?
And the bosses themselves, who wonder if they are right—
That is, good bosses do.
And then, the endless splicing of red tape
To see that all is done as is allowed,
And things are run to please yet higher bosses,
Or bosses dead, whose muddled thoughts are sacred,
Or The Machine, transcending all the bosses,
With meshed parts, plant men, accountants, et cetera, such
As grind along how no one understands
Nor dares to interrupt.

Credit

You can seek credit. Maybe you can get it.
Don't bother whether for your work or others';
Credit is credit; never mind the source.
Getting things done is a different kettle of fish.
If you want another to do it, he'll do it faster
With your ideas a part of his very substance,
Digested flesh of his brain, grown fruit of his labor.
If you want another to help you, he'll do it better
If he believes that his is the greater part.
Besides which, credit itself may be overrated;
Do reputations grow on credit alone?
Only when the seeker of credit is clever.
And why quibble about his reputation then?

Direction

Every one needs good advice; a few men want it,
But how can one get it? That is the troublesome question.
You can't go by quantity. I've met some great advisers
Whose advice was neither pertinent nor right.
Can the boss advise? He doesn't know the details,
And sometimes misses the problem quite as much,
And yet, he may have an inner feeling for things
Which can be translated hardly into sense;
If you are clever, there may be advice in the boss—
If he's a good boss; that is, if he's a good man.
And that is the point. Advice is where you find it.
Choose the good, I say, from any source.
But if you know the good when once you see it,
After all, do you really need advice?

Sending signals backwards offers intriguing possibilities as a means of self-correcting the delay distortion that occurs in transmission circuits. Suppose that a magnetic tape recorder is placed at the midpoint of a transmission system to record the signals that have traversed the first half of the route. Suppose further that the recorded signals are then played backwards into the second half of the system. The delay distortion of the two halves of the system would then cancel, since the components of the signal delayed the most in the first half of the circuit would get a head start when they are fed into the second half. If necessary, a second time-reversing recorder could be installed at the terminus of the system to revert the segments of the signal to their original sequence. This ingenious scheme is of particular interest in the use of standard telephone circuits for data transmission and slow-speed television, where delay distortion requirements are much more severe than for the voice transmissions for which the circuits were originally designed. Bell Laboratories has used this time-reversal technique in experimental transmissions of slow-speed pictures over a 5-kilocycle 16,000-mile loop between Murray Hill and Los Angeles with impressive results. Perhaps the network theorists will soon be adding time inverters to their bag of analytical tools, and the circuit designers, magnetic recorders to their supply of standard circuit elements. (B. P. Bogert, "Demonstration of delay distortion correction by time reversal techniques," IRE TRANSACTIONS ON COMMUNICATION SYSTEMS, December, 1957.)

Unionization of engineers has come up for discussion for the first time in any IRE publication. Two articles, one presenting the union viewpoint and the other written by a management representative in labor relations, point up the fact that approximately 11 per cent of the country's more than 500,000 engineers are represented in collective bargaining by unions and that their numbers will, in all likelihood, continue to increase. Both are agreed as to why there are engineering unions today. They trace it directly to the widespread growth

of vast engineering organizations within individual companies since World War II, coupled with the more recent scrambling for hard-to-find engineers at rapidly increasing salaries. In some instances this has led to salary inequities, a diminishing of the engineer's accustomed identity and treatment as an individual and a professional, and a hardening or impairment of the traditional communication arteries which held the engineer in close and direct contact with management. Missing from the discussion, though, were the views of those opposed to engineering unions. (J. Amann, "Unionization of engineers—I," IRE TRANS. ON ENGINEERING MANAGEMENT, December, 1957. H. H. Rains, "Unionization of engineers—II," *loc. cit.*)

Steinmetz, whose life is the subject of an absorbing article in the December STUDENT QUARTERLY, was one of the great mathematical wizards of his era. For those readers with a similar bent, we offer a problem posed to him by an associate who was trying to stump him: If you bore a hole two inches in diameter through the side of a circular solid rod two inches in diameter, how much material is removed? The answer, which Steinmetz gave without hesitation after jotting a few figures on a pad, is given below.¹ (C. D. Wagoner, "Steinmetz revisited: The myth and the man," IRE STUDENT QUARTERLY, December, 1957.)

Coded pictures have been proposed as a means of speeding up digital facsimile transmissions over telephone circuits. The coding scheme has its basis in the fact that most documents that are transmitted, whether they be pictures, drawings or printed matter, have substantial patches of all-white or all-black in them. Therefore, a run of all-white or all-black dots in part of a scanning line could be represented by a simple code which indicated the number of dots in the sequence and whether they were black or white. The number of binary digits required for this code would on the average be less than if each dot were transmitted individually in the customary fashion. Thus, simple documents could be automatically handled faster than the complex ones. The equipment required for this, although it has not been built, has been given enough thought to prove that it would be feasible, although more complex. This proposal represents an interesting engineering application of information theory which, in its ramifications, conceivably could find use in special types of television systems, as well. (W. S. Michel, W. C. Fleckenstein, and E. R. Kretzmer, "A coded facsimile system," 1957 IRE WESCON CONVENTION RECORD, Part 2.)

The impact of computers on network theory may well prove to be revolutionary. Not only can a computer solve problems faster, cheaper and more reliably than a man armed with a slide rule and desk calculator, but it promises to eliminate what has heretofore been the major restrictions in the application of network theory to practical design problems. No longer does the designer have to avoid using a difficult method he doesn't understand or that isn't "practical" to solve. The chances are good that the computer programming staff will be able to code it, making it immediately available to all. The result will be a virtual elimination of the frustrating 20-year lag between theory and application, and a flourishing of complex techniques that might otherwise be considered purely academic. Even more important, circuit theory as we know it today will in time disappear, to become part of a broader field which we might call system theory. The engineer of the future, instead of tinkering with this and that circuit or component and then trying to fit them all together somehow, will set out with yet unborn techniques to design the entire system as a whole with the aid of a computer. In a broader sense, the computer will require that engineering schooling and training place an increasingly greater emphasis on creativity and fundamental knowledge, as the standardized

details and specialized techniques are relegated more and more to punch cards. The machine, rather than replacing man, will require that he be more of a man and less of a machine. (T. R. Bashkow and C. A. Desoer, "Digital computers and network theory," 1957 IRE WESCON CONVENTION RECORD, Part 2.)

Aluminum, which is being used these days in everything from house sidings to automobile brakes, is now being used to boost the power handling capabilities of very high power germanium transistors. A fabrication scheme has been devised for evaporating aluminum and condensing it on a hot germanium wafer to form an aluminum emitter or collector junction. The evaporated aluminum technique is superior for high power applications to the standard fused indium junctions because aluminum provides higher conductivities and emitter injection efficiencies. Moreover, it is possible to obtain more accurate control of certain important dimensional characteristics of the junction when it is formed by an evaporation process. Transistors with aluminum junctions are capable of switching currents of 10 amperes with a power handling capacity of 500 watts, which bodes well for the future of the transistor in the industrial control field. (H. W. Henkels and G. Strull, "Very high-power transistors with evaporated aluminum electrodes," IRE TRANS. ON ELECTRON DEVICES, October, 1957.)

The information-handling capacity of humans has been the subject of some novel tests to determine how fast a person can read aloud. Some details of the tests were reported here last year.² The tests showed that the highest capacity of a human as an information channel was about 43 bits per second, and that this figure represents a fundamental mental limitation of the human being and not a physical limitation connected with the speed of uttering words. These reading-rate tests are a first small step in efforts to measure the least information rate necessary in order to transmit a signal, such as a speech or picture signal, well enough so as to be perfectly satisfactory to a hearer or viewer. At present, a channel capacity of 50,000 bits per second is used in sending voice signals over a telephone circuit, and 50,000,000 bits per second in sending television signals. However, no one is suggesting that anything like 43 bits per second are all that is necessary, since innumerable other factors that cannot be determined by reading rates are also involved. As an interesting sidelight, the tests showed that reading rates were about the same for different languages. Also, some small comfort can be taken in the finding that engineers are faster readers than porters. (J. R. Pierce and J. E. Karlin, "Reading rates and information rates of a human channel," 1957 IRE WESCON CONVENTION RECORD, Part 2, p. 60.)

Transistor circuits. If anyone needs to be convinced of the important impact that transistors are having on network theorists, they need only to look at the 236-page September issue of the CIRCUIT THEORY TRANSACTIONS, the second largest issue ever produced by a Professional Group. In the opening editorial of the issue, PGCT Chairman, H. J. Carlin, quoted a statement by E. W. Herold that has appeared twice before in the PROCEEDINGS.^{3,4} Nevertheless it bears repeating: "The chemical synthesis of an improved compound can do more to revolutionize the performance of an electronic system than years of painstaking circuit work." To which Carlin adds, "The circuit theorist recognizes this situation but is prepared to take the new elements given him by materials scientists and to modify his methods to exploit these elements in an optimum manner." That the network specialist is indeed modifying his methods because of the transistor, and to good

¹ J. R. Pierce and J. E. Karlin, "Information rate of a human channel," *Proc. IRE*, vol. 45, p. 368; March, 1957.

² "Poles and Zeros," *Proc. IRE*, vol. 45, p. 1457; November, 1957.

³ E. W. Herold, "Future circuit aspects of solid-state phenomena," *Proc. IRE*, vol. 45, p. 1463; November, 1957.

¹ The answer is 5.333 cubic inches.

advantage, is attested to by this impressive group of 31 papers.

Ferrite mixers for microwave frequencies, which have been the subject of some theoretical speculation during the last two years, have now undergone experimental tests, with the best conversion efficiencies ranging from about -15 db for the sum frequency output to -47 db for the difference frequency. While this doesn't match the -6 db figure reported for ferrites when used as frequency doublers,⁵ further improvements can be expected as the technique is refined. Indeed, the first ferrite frequency doublers showed only a -60 db efficiency. In any event, this experimental verification should give added stimulus to the use of ferrites for mixing and doubling, especially at high power levels where they

promise to prove superior to crystals. (P. N. Vartanian and E. N. Skomal, "Mixing in ferrites at microwave frequencies," 1957 IRE WESCON CONVENTION RECORD, Part 1.)

X-raying germanium wafers has been proposed as a simple and straightforward method to determine how thick they are. X-ray absorption measurements can reveal the thickness of a 2-mil (0.002-inch) wafer to within 0.1 mil. Conceivably, this method could be used to control an electrolytic etching operation so as to cut off the electrolysis automatically at the correct thickness. The scheme, while by no means revolutionary, is nevertheless an interesting example of the many ways in which the absorption of waves (whether they be electromagnetic or ultrasonic) can be used to determine important physical characteristics of materials. (A. R. Moore, "A method of accurate thickness determination of germanium wafers suitable for transistor production," IRE TRANS. ON ELECTRON DEVICES, October, 1957.)

⁵ J. L. Melchor, W. P. Ayres, P. H. Vartanian, "Microwave frequency doubling from 9 to 18 kmc in ferrites," Proc. IRE, vol. 45, pp. 643-646; May, 1957.

Abstracts of IRE Transactions

The following issues of "Transactions" have recently been published, and are now available from the Institute of Radio Engineers, Inc., 1 East 79th Street, New York 21, N. Y. at the following prices. The contents of each issue and, where available, abstracts of technical papers are given below.

Sponsoring Group	Publication	Group Members	IRE Members	Non-Members*
Circuit Theory Communications	Vol. CT-4, No. 3	\$2.50	\$3.75	\$7.50
Systems	Vol. CS-5, No. 3	0.95	1.40	2.85
Electron Devices Engineering	Vol. ED-4, No. 4	0.80	1.20	2.40
Management	Vol. EM-4, No. 4	0.70	1.05	2.10

* Public libraries and colleges may purchase copies at IRE Member rates.

Circuit Theory

VOL. CT-4, NO. 3, SEPTEMBER, 1957

Pandora's Black Boxes—H. J. Carlin (p. 60)

Abstracts of Active-Network Papers (p. 62)

Foreword to Active-Network Papers—

J. G. Truxal (p. 69)

Survey of Some Properties of Linear Networks—E. F. Bolinder (p. 70)

An attempt is made to give a brief exposé of some modern works on linear network properties. The concepts treated are the following: passivity, stability, efficiency, and non-reciprocity; n -terminal-pair networks and two-terminal-pair networks in particular are studied at a fixed frequency.

Active RC Networks—R. D. Thornton (p. 78)

If all available amplifying devices can be approximated by linear models with capacitive, terminal, energy storage, there are bounds on the allowed natural frequencies of circuits constructed from these devices. These bounds are readily determined from the eigenvalues of a frequency matrix and can be related to the maximum power that can be dissipated by the device per unit energy stored in the terminal capacity. Synthesis of unilateral and constant- k amplifiers is considered, and concepts such as the gain-bandwidth product and the maximum frequency of oscillation are related to the bounds on allowed natural frequencies.

About Such Things as Unistors, Flow Graphs, Probability, Partial Factoring, and Matrices—S. J. Mason (p. 90)

The purpose here is to point out three things. 1) Topological circuit analysis, in which

we look for trees, and topological flow-graph analysis, in which we look for loops, are intimately related, since both have to do with simultaneous linear algebraic equations. The intimate relationship becomes an identity when we deal with Markoff probability diagrams, for which the circuit model of the problem and the flow-graph model of the problem are one and the same. 2) The expression for a flow-graph transmission in terms of the branch transmissions can often be made much more compact by a process called partial factoring. Fortunately, this process has a simple topological interpretation, so that the compact form is obtainable by inspection of the flow-graph. 3) Simultaneous linear matrix equations may be conveniently expressed in flow-graph form, whereupon the solution is obtainable by standard flow-graph reduction techniques.

Multipole Analysis of Active Networks—L. A. Zadeh (p. 97)

To replace the conceptual framework of network theory as based on the building blocks of two-terminal elements, a framework is suggested that is built on the premise that a network element is a black box with finitely many—but not necessarily two—accessible terminals. The greater generality and abstractness of the multipole method give it a considerably broader range of applicability than that possessed by the two-pole method.

Transformation Theory Applied to Linear Active and/or Nonbilateral Networks—E. A. Guillemin (p. 106)

A nonpassive and/or nonbilateral (linear) network can be represented analytically as a passive bilateral one in which the variables are subjected to an appropriate linear transformation. In contrast to the "dependent source" method of analysis, transformation theory offers not only a very general and ele-

gant way of dealing with both the nonbilateral as well as the active character of devices, but through the existence of a considerable number of interpretive mechanisms such as geometric visualization in multidimensional spaces and the concept of normal coordinate transformations, it represents a relatively untapped storehouse of manipulative artifices that may ultimately provide a clearer understanding of this broader class of networks.

Separation Transformations for Square Matrices—H. E. Meadows, Jr. and B. J. Dasher (p. 111)

A class of transformations of square matrices which may be regarded as a generalization of matrix transposition and complex conjugation is defined by a set of five postulates. These transformations, termed "separation transformations," make evident certain characteristics of form for square matrices by resolving every square matrix into two additive component matrices called the "consonant" and "dissonant" parts. This property may be valuable in the study of active linear networks since the impedance matrices, for example, of these networks may display no obvious special characteristic of form.

Separation transformations and the related consonant and dissonant parts of square matrices have some interesting manipulative properties. These properties lead to an extension of the concept of orthogonality of matrices.

An example to illustrate the possible use of the relations derived for separation transformations shows a generalization of Mason's invariant for active linear networks subjected to lossless, linear, reciprocal coupling.

The A Matrix, New Network Description—T. R. Bashkow (p. 117)

Both the loop and node methods of network analysis produce a system of second-order differential equations. A method of analysis is proposed which produces a set of first-order differential equations. With this method, the network equations obtained can be expressed in the form $F + dy/dt = Ay$, where F and y are column matrices and A is a square matrix. The variables, y , are currents through inductances and voltages across capacitances; the forcing functions F are proportional to voltage and current sources. The elements of A are inductances, capacitances, and resistances, or combinations thereof. Characteristic roots (natural frequencies) of the network are identical with the eigenvalues of the A matrix.

Some Simplifications for Analysis of Linear Circuits—G. L. Matthaei (p. 120)

Any linear, passive, or active two-terminal pair network is describable in terms of six, interrelated "characteristic polynomials." A method for finding them is presented which requires less labor than is usually involved in finding a set of the conventional circuit param-

in detail, and design procedures set up for these schemes. A comparison is made of the various schemes; in particular, direct and feedback stabilization are compared on the basis of battery drain, ac gain, and variation of operating point with battery voltage.

The stabilization of direct-coupled stages is also discussed, and the design of a bias circuit for a two-stage direct-coupled pair is taken up in detail.

Nonlinear techniques for temperature stabilization are also discussed. These are useful in special applications such as high-power output stages, where the temperature changes are extreme, or in low-level circuits where extremely stable operation is required, *e.g.*, in oscillators.

Thermal Stability of Junction Transistors and Its Effect on Maximum Power Dissipation—H. C. Lin (p. 202)

When the junction temperature of a transistor increases, the collector current increases, as a result of increases in 1) saturation currents and 2) dc conductances. Thermal instability occurs when junction temperature and collector current increase in regenerative and uncontrollable fashion. The limit depends on factors both within and external to the transistor. The internal factors are the thermal resistance, the current amplification factor, and the base lead resistance. The external factors are ambient temperature, collector voltage, circuit resistances, and the thermal coupling between the transistor and temperature compensation elements, if any. Circuits with greater temperature stability permit a higher maximum power dissipation. The factors are discussed which determine the thermal stability and consequently, the maximum dissipation of transistors. The criteria for stability are derived mathematically and some thermal compensation techniques are treated.

A Survey of Magnetic and Other Solid-State Devices for the Manipulation of Information—J. A. Rajchman (p. 210)

A review is made of the art of manipulating digital information by means of magnetic devices. Also included are some remarks on other solid-state devices. There is a brief introductory discussion of semiconductor diodes and of the unique properties of the transistor. The storage and switching capabilities of magnetic cores made of square hysteresis loop materials are discussed with some detail. This discussion includes: random access memories made of individual cores or ferrite apertured plates, various types of decoding and encoding switches, shift registers, current and voltage driven circuits, the principle of current steering, transistor coupled circuits, the principle of the transfluxor, the application of the transfluxor to nondestructive read-out memories and channel commutators, the principle of transfluxor current steering, and some examples of multiapertured transfluxors. The potentialities of some phenomena as yet not widely exploited are discussed: ferroelectric, electro-optical and magnetoresistive effects.

Counting Circuits Employing Ferroelectric Devices—R. M. Wolfe (p. 226)

A new type of counting circuit utilizing ferroelectric devices has been developed. This circuit, although similar to the older energy storage type of counter, overcomes most of the disadvantages of the older circuit. Whereas the older circuit required standardization of the input pulse to stabilize the counting ratio, *i.e.*, the number of input pulses per output pulse, the use of a ferroelectric device to meter charge removes the need for such standardization. A second ferroelectric device used to integrate the packets of charge developed by the first removes the lower bound on the repetition rate of pulses to be counted.

Circuits have been built with counting ratios up to 40 to 1. They have operated satisfactorily under conditions of changing voltage, temperature, and pulse spacing. Several counters may be connected in cascade to provide higher counting ratios.

A High-Speed Two-Winding Transistor-Magnetic-Core Oscillator—A. J. Meyerhoff and R. M. Tillman (p. 228)

Recent articles in the literature have described voltage-controlled square-wave oscillators using transistors and square-loop magnetic cores and generally incorporating four windings. These oscillators give output frequency directly proportional to applied voltage; hence they are useful as solid-state dc to dc converters, telemetering oscillators, and many other devices. Each application is based on the fact that the volt seconds applied to a core are proportional to the flux switched, which is essentially constant for the core.

This paper is primarily devoted to the fundamentals and applications of a novel two-winding transistor-core oscillator and derived circuits. The two-winding circuit is capable of true square-wave output at 700 kc, the upper frequency limit being determined by the present state of the art of transistor and core development.

A review is given first of the usual four-winding oscillator, tracing its operating cycle step by step and showing the circuit to be derivable directly from a fundamental transistor-core switching circuit.

Then the two-winding oscillator is discussed. With this circuit, the two separate base windings are eliminated through cross-coupling of each collector to the base of the opposite transistor. During switching time, the collector winding of the OFF transistor supplies the necessary regenerative voltage to the base of the ON transistor. A parallel RC in each base circuit speeds up the turn-off action by application of inverse current to the ON base. Direct electrical cross-connection from the ON base to the OFF collector means that at switch-over the inverse transient voltage, due to fly-back, will momentarily place the OFF transistor into inverse saturated conduction, thereby presupplying it with holes so that it can take on its load in the forward direction extremely rapidly when the ON transistor shuts off. In this circuit, self-starting is inherent, due to the direct connections from base to negative supply.

The circuit operation is analyzed in detail and worst-case design equations are derived. A bibliography of the literature is included.

Millimicrosecond Transistor Current Switching Circuits—H. S. Yourke (p. 236)

If transistor switching circuits are to have response times limited by the bandwidths of the transistors operating as amplifiers and by diffusion or transit time delay, it becomes necessary to avoid operation in saturation. Since a low collector to base voltage, or operation near saturation, has a detrimental effect on transistor bandwidth, it is desirable to avoid this operating region as well.

Where nonsaturating circuits are used with transistors having cutoff frequencies of several hundred megacycles, transistor and circuit capacitances become the primary limitation on speed. To minimize the delays due to capacitance, it is desirable to operate with voltage swings as small as reliability consideration will permit.

A new mode of operation has been developed whereby well-specified currents can be switched reliably with small voltage swings. The complementary current switching technique described provides a means of constructing relatively simple logical circuits in which transistors are operated well out of saturation in a region of maximum bandwidth. This technique offers several advantages besides high-speed switching. The resulting logical circuits have complemented outputs, and reset their own levels. There is no requirement on the upper limit of α and dc stability factors are essentially unity. The circuits are simple and relatively noise free. A few basic circuits and working examples are presented in the paper. Application and extension of this current switching technique results in a large body of new and useful logical circuits.

Some New Transistor Bistable Elements for Heavy Duty Operation—N. F. Moody and C. D. Florida (p. 241)

Bistable elements of fast switching speed (0.2 μ sec), capable of delivering load currents up to 100 ma and having a low-output impedance, are required in many electronic circuits. Such an element is particularly useful in digital computers employing passive routing.

The paper shows that circuits which use both *p-n-p* and *n-p-n* transistors are well suited for such duties. It also describes both non-saturated and saturated forms.

Part I devotes itself to nonsaturated circuits, and the analysis is mathematical in approach. The general properties thus deduced are applicable to all members of the circuit family.

Part II turns to the problems introduced by saturation and is a general theoretical discussion of wide application. It leads to a concept denoted controlled saturation; this is applied to switching circuits in order to minimize the penalty of lost speed which saturation can cause.

Part III applies the theoretical work of the preceding parts to a fast trigger circuit in which saturation is permitted. It concludes by showing that this basic saturated circuit can be developed into a variety of forms.

A Decade Ring Counter Using Avalanche-Operated Junction Transistors—J. E. Lindsay (p. 262)

The avalanche mode of operation for junction transistors is encountered at higher-than-normal collector voltages. In this avalanche region of operation the electrical character of the junction transistor is profoundly altered because of a voltage sensitive current-multiplication occurring at the collector junction. Current controlled *N*-type negative resistance characteristics suitable for bistable operation are obtained. Important features of these characteristics can be treated analytically to obtain results suitable for design purposes.

Twelve experimental avalanche-operated junction transistors have been used in a decade ring counter and driver. This represents a saving of two-to-one in semiconductor devices, as contrasted to the use of conventionally operated junction transistors for the same function. A like saving of other components is obtained. The ring counter uses a new method of count transfer which provides improved reliability and higher counting speed capability. The driver and counter achieve operation to 500 kilocycles using transistors having a frequency of α_c cutoff in the range 30 to 40 kilocycles for conventional operation. The counter operates to 300 kilocycles over a temperature range from below -50° to 50°C without compensation or optimized design.

Transient Response Characteristics of Unijunction Transistors—J. J. Suran and B. K. Eriksen (p. 267)

Carrier transport in unijunction transistors is due primarily to electric fields rather than diffusion gradients. Thus, the high-frequency and transient response characteristics of unijunction transistors are considerably different from the characteristics associated with diffusion type devices.

The high-frequency and transient response characteristics of silicon unijunction transistors are described. A previously published solution of the electrodynamic equations, taking into account field and recombination effects, is used to calculate theoretical frequency and transient response characteristics which are subsequently compared to experimental measurements.

It is shown that:

1) Electric field effects lead to resonance characteristics which are somewhat similar to those encountered in wave interference phenomena.

2) The frequency response characteristics of unijunction transistors are predominantly determined by the electric field gradient for high fields and by recombination effects for low fields.

3) The large-signal transient response of unijunction transistors is characterized by at least two time constants, one related to transit time and the other to minority carrier lifetime.

4) The maximum large-signal switching speeds and minimum trigger energy of regenerative unijunction transistor circuits depend upon both the electric field and lifetime characteristics of the device.

An Improved Square-Wave Oscillator Circuit—J. L. Jensen (p. 276)

Inductively coupled square-wave transistor oscillators using a saturating output transformer subject the transistor to rather severe transient conditions and require an expensive transformer. The improved circuit, however, uses a separate saturating feedback transformer and a conventional output transformer. The described circuit has improved performance with less severe duty on the transistors, permits the use of inexpensive transformers, and allows the adaptation to a variety of operating requirements.

A Phase-Regulated Transistor Power Supply—D. E. Deutch and H. J. Paz (p. 279)

Transistors have been utilized effectively for class A regulation of power supplies. However, the power-handling capacity and high-temperature performance of these power supplies are basically restricted because of the power-temperature limitation of transistors.

This paper describes a type of regulated transistor power supply in which the dissipation in the regulator transistors is extremely small. This enables low-power transistors to control large amounts of power and permits substantial improvement of power supply capabilities at high temperature over that of the Class A regulated supply.

The principle of operation of this supply is similar to that used in thyristor regulation. The regulator transistors are operated as rectifying switches whose conduction period is varied in phase with respect to the ac input. Regulation is obtained by controlling the conduction phase of the transistors in response to load and input voltage variation.

A transistor switch circuit for this power supply is described together with general design and operating considerations for its power supply application. The performance of a 12-volt, 0- to 1-ampere developmental phase regulated power supply is discussed.

Abstracts of Transistor Conference Papers Not in This Issue (p. 66)

Correction (p. 284)

Correspondence (p. 285)

Reviews of Current Literature—Finite Duration Signals With Maximum Filtered Energy—J. A. Ville and J. Bouzitat (in French) (p. 293)

Mode Conversion Phenomena in the Case of Multilayer Conductors and its Effect on the Transmission Through Individual or Through Connected Partial Sections—Horst-Edgar Martin (in German) (p. 293)

Experimental Study of Tapped Delay-Line Filters—D. W. Lytle (p. 294)

Piecewise-Linear Network Theory—T. E. Stern (p. 294)

Double Tuned Filter Circuits for Wide Relative Pass-Band—F. Carassa (in Italian) (p. 294)

Analysis of Electric Circuits Containing Nonlinear Resistance—L. A. Pipes (in English) (p. 294)

Wave Dispersion in Disk Transmission Lines—Gerhard Piefke (in German) (p. 294)

Concerning the Chain Connection of Two Multipoles—W. Ruppe (in German) (p. 294)

Calculation of Current Distribution in a Linear Network—Joannis Vratsanos (in German) (p. 294)

Communications Systems

VOL. CS-5, NO. 3, DECEMBER, 1957

20/20 Visualization—J. E. Schlaikjer (p. 1)
Demonstration of Delay Distortion Correc-

tion by Time-Reversal Techniques—B. P. Bogert (p. 2)

Experiments relating to methods of correcting delay distortion by time-reversal have been made utilizing a slow-speed picture transmission system. The improvements in picture quality by phase correction of a 3 kc telephone loop 30.4 miles long and a 5 kc loop from Murray Hill, N. J., to Los Angeles, Calif., and back are demonstrated. The total distance that the signal was transmitted over the 5 kc loop was 16,600 miles and there were 16 type L carrier links involved. By way of an introduction, the improvement in the impulse response of networks and transmission circuits is discussed.

Quadruple-Diversity Tropospheric Scatter Systems—W. G. Long and R. R. Weeks (p. 8)

Operations Research and Communications Systems Planning—R. V. Higdon (p. 20)

A discussion is presented outlining the general concept of operations research for those who are not familiar with it. A necessarily brief description is given of efforts to apply these concepts to specifying effective communications for complex organizations or weapons systems.

High-Speed Frequency-Shift Keying of LF and VLF Radio Circuits—H. G. Wolff (p. 29)

Present VLF transmitters are limited in transmission speed to approximately 20 words per minute because of the bandwidth limitations of the High-Q antenna circuit. To permit an increase in transmission speed, an unique method has been developed which makes use of the variation of reactance of the antenna circuit in synchronism with frequency shift modulation of the carrier. The method makes possible the transmission of teletype or high speed Morse signals at speeds of 100 words per minute or more. This increase by a significant factor in present traffic handling capabilities of VLF stations can be accomplished by increasing the cost of the station less than ten per cent.

An Electronic Multicoupler and Antenna Amplifier for the VHF-Range—K. Fischer (p. 43)

A single-stage distributed amplifier for the frequency range from 25 to 223 mc/s may be used as an antenna amplifier for compensation of cable-attenuation or, in connection with a divider network, as a multicoupler for feeding six receivers from a common antenna. Single-stage amplification results in not only low noise level due to the parallel tube circuitry employed but also in a low cross-modulation figure. Second order distortions are minimized by special push-pull operation without doubling the number of tubes. Another advantage of the distributed amplifier is its reliability, which is further improved by dividing the power supply into two independent sections.

Contributors to This Issue (p. 49)

Electron Devices

VOL. ED-4, NO. 4, OCTOBER, 1957

Very High-Power Transistors with Evaporated Aluminum Electrodes—H. W. Henkels and G. Strull (p. 291)

The principles involved in the design of high-power and very high-power transistors are considered in brief. The important factors in high-gain, high-current transistor design are the emitter-injection efficiency, the emitter and collector planarity, and the base-bias high-current falloff. The fabrication techniques involved in the production of transistors to maximize the injection efficiency and planarity (by evaporation of aluminum electrodes) and minimize base bias drop (by choice of optimum emitter geometry), are discussed. The characteristics of devices capable of handling currents in the range from 1 to 10 amperes at very high common-emitter current gains ranging from 50 to above 300 are described.

An Equivalent Circuit for Microwave Noise

at the Potential Minimum—A. E. Siegman and S. Bloom (p. 295)

It has been suggested that an inductive element should be added to Watkins RC equivalent circuit for the microwave noise current fluctuations at the potential minimum of a diode, and that this added element gives closer agreement with more recent work which shows a pronounced peak in noise current near the plasma resonance, $\alpha = \frac{1}{2}$. This paper presents an approximate analytical argument for the inclusion of an inductive element, based on the density-function method of analysis, which predicts the proper value for the inductance and yields a curve of reduction factor vs frequency in agreement with more detailed theories. The value of the inductance is such as to resonate with the capacitance of the potential minimum at $\alpha = \frac{1}{2}$. A discussion of the linearity of the potential minimum and of the idealized potential-minimum model is also included.

A Novel Approach to Microwave Duplexer Tube Design—L. Gould, E. V. Edwards, and I. Reingold (p. 300)

An encapsulated input window with an independent gas fill has been incorporated in the design of a broad-band duplexer tube. This design has been effective in separating the interdependence of the high-power characteristics of the tr tube. Recovery time and arc loss are determined predominantly by the input window design, whereas spike leakage energy and flat leakage power are determined by the tube body design. The two portions of the tube are designed independently for optimum performance. The effects of gas pressure and nature of the gas on the behavior of the high-power characteristics have been investigated. The factors determining adequate tube operation are discussed, and experimental data are presented to verify the advantages of the encapsulated structure.

Multicolor Storage Tube—C. D. Belintema, S. T. Smith, and L. L. Vant-Hull (p. 303)

Multicolor storage tubes for applications with low frame rates have been built by modification of direct-viewing storage tubes. A perforated shadow mask is placed between the three writing guns and the storage surface. This shadow mask allows electrons from each writing gun to strike discrete storage areas, each containing a single aperture in register with a color dot on the view plate. In this way, it is possible to write and store electrical signals independently in adjacent color areas. Factors causing color impurity are described, together with the steps taken to minimize their effects. A tube has been built that shows good color purity in a 6-inch-diameter circle; it has 75 total color dots per inch resolution, 8 foot-lamberts brightness, and about 1-minute persistence. Other possible multicolor storage tube designs are discussed.

Experimental Notes and Techniques (p. 309)

Contributors (p. 311)

Index to IRE Transactions on Electron Devices—Volume ED-4, 1957 (follows p. 313)

Engineering Management

VOL. EM-4, NO. 4, DECEMBER, 1957

The Climate of Research in the University—C. W. Gartlein (p. 109)

Unionization of Engineers—I—Joseph Amann (p. 113)

Unionization of Engineers—II—H. H. Rains (p. 116)

The Nation's Need for Greater Scientific and Technical Strength—Means for its Attainment—M. J. Kelly (p. 122)

Dynamic Project-Oriented Industrial Organization—Henry Imus (p. 128)

The Establishment and Operation of a Semiautonomous Field Organization—J. D. Finley (p. 132)

Abstracts and References

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NOTE: The Institute of Radio Engineers does not have available copies of the publications mentioned in these pages, nor does it have reprints of the articles abstracted. Correspondence regarding these articles and requests for their procurement should be addressed to the individual publications, not to the IRE.

Acoustics and Audio Frequencies.....	516
Antennas and Transmission Lines.....	516
Automatic Computers.....	517
Circuits and Circuit Elements.....	517
General Physics.....	519
Geophysical and Extraterrestrial Phenomena.....	520
Location and Aids to Navigation.....	521
Materials and Subsidiary Techniques..	521
Mathematics.....	523
Measurements and Test Gear.....	523
Other Applications of Radio and Electronics.....	525
Propagation of Waves.....	525
Reception.....	525
Stations and Communication Systems..	526
Subsidiary Apparatus.....	526
Television and Phototelegraphy.....	527
Transmission.....	527
Tubes and Thermionics.....	527
Miscellaneous.....	528

The number in heavy type at the upper left of each Abstract is its Universal Decimal Classification number and is not to be confused with the Decimal Classification used by the United States National Bureau of Standards. The number in heavy type at the top right is the serial number of the Abstract. DC numbers marked with a dagger (†) must be regarded as provisional.

U.D.C. NUMBERS

Extensions and changes in U.D.C. numbers published in P.E. Notes, up to and including P.E. Note 609, will be introduced in Abstracts and References where applicable, notably the subdivisions of 621.372.8 waveguides published in P.E. Note 594. U.D.C. publications are obtainable from The International Federation for Documentation, Willem Witsenplein 6, The Hague, Netherlands, or from The British Standards Institution, 2 Park Street, London, W.1, England.

JOURNAL REFERENCES

References to Russian publications will henceforth be based on the Russian title which will be abbreviated on the principles of The World List of Scientific Periodicals. The main changes are as follows:

Dokl. Ak. Nauk S.S.S.R. (formerly C.R. Acad. Sci. U.R.S.S.),
Izv. Ak. Nauk S.S.S.R. (formerly Bull. Acad. Sci. U.R.S.S.).

ACOUSTICS AND AUDIO FREQUENCIES

534.2-13:536.3	1
Effect of Heat Radiation on Sound Propagation in Gases—P. W. Smith, Jr. (<i>J. Acoust. Soc. Amer.</i> , vol. 29, pp. 693-698; June, 1957.)	
534.21-8-14	2
Ultrasonic Propagation Measurement in Sea Water up to 400 kc/s—T. Hashimoto and Y. Kikuchi. (<i>J. Acoust. Soc. Amer.</i> , vol. 29, pp. 702-707; June, 1957.) Methods of measurement for horizontal and for vertical propagation are described. Measured values of absorp-	

tion were 10-20 db/km at 28 kc increasing to 120 db/km at 400 kc.

534.23 3
Sound Transmission through Thin Cylindrical Shells—P. W. Smith, Jr. (*J. Acoust. Soc. Amer.*, vol. 29, pp. 721-729; June, 1957.) An analysis of the impedance presented by a thin cylindrical elastic shell to a pressure or normal stress as a function of the axial wavelength and the angular dependence of the forces.

534.23:537.227 4
Vibrations of Ferroelectric Cylindrical Shells with Transverse Isotropy: Part I—Radially Polarized Case—J. F. Haskins and J. L. Walsh. (*J. Acoust. Soc. Amer.*, vol. 29, pp. 729-734; June, 1957.) Expressions for the coupled mechanical vibrations and electrical admittance of ferroelectric tubes having transverse isotropy are derived and the results supported by experimental data.

534.232 5
Experimental Investigation of Conical Horns Used with Underwater Sound Transducers—W. R. Owens and C. M. McKinney. (*J. Acoust. Soc. Amer.*, vol. 29, pp. 744-748; June, 1957.) A simple conical horn lined with pressure-release material is very effective in increasing the axial sensitivity of transducers and improving directivity. Design curves are given.

534.232:534.24 6
Effect of a Reflecting Plane on the Power Output of Sound Sources—U. Ingard and G. L. Lamb, Jr. (*J. Acoust. Soc. Amer.*, vol. 29, pp. 743-744; June, 1957.) The effect of a rigid reflecting plane on the output from a sound source above it is expressed as a "power amplification factor." This is calculated for a number of elementary sound sources and power output is determined as a function of source height.

534.414 7
Acoustic Impedance of a Helmholtz Resonator at Very High Amplitude—D. A. Bies and O. B. Wilson, Jr. (*J. Acoust. Soc. Amer.*, vol. 29, pp. 711-714; June, 1957.) A Helmholtz resonator terminating a 10-inch diameter tube has been investigated for sound pressure levels 100-170 db. With increasing sound pressure the same general rise in acoustic resistance and resonance frequency was observed for two different mountings.

534.612 8
Acoustical Radiation Pressure due to Incident Plane Progressive Waves on Spherical

Objects—G. Maidanik. (*J. Acoust. Soc. Amer.* vol. 29, pp. 738-742; June, 1957.)

534.75 9
On the Fusion of Sounds Reaching Different Sense Organs—D. E. Broadbent and P. Ladefoged. (*J. Acoust. Soc. Amer.*, vol. 29, pp. 708-710; June, 1957.) Experiments with synthetically produced speech show that fusion occurs when the first formant is presented to one ear and the second formant to the other, but not if the formants are given different fundamental frequencies.

534.78 10
Constant-Ratio Rule for Confusion Matrices in Speech Communication—F. R. Clarke. (*J. Acoust. Soc. Amer.*, vol. 29, pp. 715-720; June, 1957.) "Three experiments are reported which give support to an empirical rule which may be used for predicting the entries in a closed confusion matrix for any subset of items drawn from a master set of items with a known confusion matrix."

534.78 11
The Intelligibility of Synthetic Speech—O. Warns. (*Frequenz*, vol. 11, pp. 169-175; June, 1957.) The results of subjective tests on the intelligibility of synthetic logatoms are analyzed. For the German language 700-1100 interchangeable speech elements would be adequate, requiring an information rate of 40 bits per second.

621.395.625.3:621.397.5 12
Video Tape Recorder Design—(See 294.)

ANTENNAS AND TRANSMISSION LINES

621.315.212 13
The Characteristic Impedance of Coaxial Cables—F. Raggi. (*Note Recensioni Notiz.*, vol. 6, pp. 174-188; March/April, 1957.) Note summarizing the factors which determine the characteristic impedance of coaxial cables.

621.315.212:621.397.24 14
A New 4-Mc/s Coaxial Line Equipment—C.E.L. No. 6A—M. E. Collier and W. G. Simpson. (*P.O. Elec. Eng. J.*, vol. 50, Pt. 1, pp. 24-34; April, 1957.) The equipment described is suitable for the transmission of either 16 telephony supergroups (960 circuits) or a 405-line television signal.

621.315.212:621.397.24 15
A 4-Mc/s Coaxial Line Equipment—C.E.L. No. 4A—E. Davis. (*P.O. Elec. Eng. J.*, vol. 50, Pt. 2, pp. 92-97; July, 1957.) A description of

equipment suitable for the transmission of either 17 telephony supergroups (1020 circuits) or a television signal of 3-mc video bandwidth. See also 14 above.

621.372.2 16
Return Loss: Part 1—T. Roddam. (*Wireless World*, vol. 63, pp. 521-524; November, 1957.) The use of the concept of return loss instead of standing wave ratios is recommended in dealing with reflections of short pulses on long loss-free incorrectly terminated lines.

621.372.8:621.372.5 17
Noisy and Noise-Free Two-Port Networks Treated by the Isometric Circle Method—E. F. Bolinder. (*Proc. IRE*, vol. 45, pp. 1412-1413; October, 1957.)

621.372.823 18
Circular Electric Wave Transmission through Serpentine Bends—H. G. Unger. (*Bell Sys. Tech. J.*, vol. 36, pp. 1279-1291; September, 1957.) An analysis of the propagation in a circular waveguide with equally spaced discrete supports and deformed elastically into a serpentine bend under its own weight.

621.372.831.4 19
Slots in an Imperfectly Conducting Waveguide—B. Chatterjee. (*Indian J. Phys.*, vol. 40, pp. 278-282; May, 1957.) The shunt conductance of a slot initially increases with departure from perfect conductivity of the guide wall but decreases rapidly in almost direct proportion to further decreases in conductivity.

621.372.852.21 20
Theory of Curved Circular Waveguide containing an Inhomogeneous Dielectric—S. P. Morgan. (*Bell Sys. Tech. J.*, vol. 36, pp. 1209-1251; September, 1957.) General equations are derived for all modes in a curved circular waveguide containing an inhomogeneous dielectric. The results are applied to the problem of preventing mode conversion from TE_{01} to TM_{11} . Design equations are given for various compensators with criteria for keeping the power level of spurious modes at a minimum.

621.372.853.1 21
Circular Electric Wave Transmission in a Dielectric-Coated Waveguide—H. G. Unger. (*Bell Sys. Tech. J.*, vol. 36, pp. 1253-1278; September, 1957.) The mode conversion from the TE_{01} wave to the TM_{11} wave in a curved circular waveguide may be reduced by applying a thin uniform dielectric coating to the inner wall. Design curves are given for both uniform bends of small radius and for large bending radii which may occur in a normally straight guide.

621.372.853.1 22
Normal Mode Bends for Circular Electric Waves—H. G. Unger. (*Bell Sys. Tech. J.*, vol. 36, pp. 1292-1307; September, 1957.) The TE_{01} - TM_{11} degeneracy is removed by a thin dielectric coating, and a further reduction in the mode conversion at a bend is obtained by tapering the curvature along the guide. Details are given of the bend loss for $\lambda=5.4$ mm. See also 21 above.

621.396.674:621.396.93 23
A Versatile Multiport Biconical Antenna—R. C. Honey and E. M. T. Jones. (*Proc. IRE*, vol. 45, pp. 1374-1383; October, 1957.) This antenna can be used as a wide-band direction finder, as it excites in the feeding waveguide modes whose ratios are azimuth dependent. It also has uses as a multiplexer.

621.396.677 24
Bi-directional F.M. Antennas—H. B. Dent. (*Wireless World*, vol. 63, pp. 534-536; Novem-

ber, 1957.) Description of stacked horizontal half-wave dipoles which are simple to construct and erect.

621.396.677.43 25
Rhombic Antennas—F. J. Norman and J. F. Ward. (*Electronic Radio Eng.*, vol. 34, pp. 398-403; November, 1957.) "The design of aperiodic rhombic antennas is examined and a method derived whereby a set of charts of open scale yields all the antenna parameters of practical significance for high-frequency operation. The angle of fire and the gain with respect to a dipole in free space are displayed for an adequate range of antenna side lengths and included angles. Corrections are given for the height above ground and a simple method to find the shape of the main lobe is suggested."

621.396.677.8:523.16 26
The Mullard Radio Astronomy Observatory, Cambridge—Ryle. (See 107.)

621.396.677.833:523.16 27
World's Largest Radio Telescope—(See 108.)

621.396.677.85 28
Calculated Intensity and Phase Distribution in the Image Space of a Microwave Lens—G. W. Farnell. (*Can. J. Phys.*, vol. 35, pp. 777-783; June, 1957.) Intensity and constant-phase contours and an energy-flow diagram are shown for a 3.2-cm- λ lens with exit pupil of 25-cm radius distant 105 cm from the image point. Calculations are based on scalar diffraction theory. Results of measurements show close agreement.

621.396.677.85 29
Study of Optical Diffraction Images at Microwave Frequencies—M. P. Bachynski and G. Bekefi. (*J. Opt. Soc. Amer.*, vol. 47, pp. 428-438; May, 1957.) "Experimental investigations of the intensity distribution in the region of the focus of microwave lenses are described. The circularly symmetric lenses, made from polystyrene plastic, were illuminated by a linearly polarized beam of radiation of 1.25-cm wavelength. Most of the measurements are presented in the form of intensity contours in planes both containing the principal ray and lying perpendicular to it. Images formed by nearly perfect optical systems and by systems suffering from various third-order monochromatic aberrations were examined. In most cases the results are compared with calculations made from the scalar-diffraction theory of optical systems. In general, good agreement between theory and experiment is found."

AUTOMATIC COMPUTERS

681.142 30
Controlling the Digital Computer—R. W. Hamming. (*Sci. Mon.*, vol. 85, pp. 169-175; October, 1957.) A nonmathematical discussion of the programming and application of computers for scientific purposes.

681.142 31
An Experimental 50-Mc/s Arithmetic Unit—R. M. Walker, D. E. Rosenheim, P. A. Lewis, and A. G. Anderson. (*IBM J. Res. Devel.*, vol. 1, pp. 257-278; July, 1957.) Detailed description of a unit which performs a repetitive multiplication program and checks the results for errors.

681.142 32
The Design of the Ferranti Pegasus Computer: Part 2—G. Emery. (*Electronic Eng.*, vol. 29, pp. 420-425; September, 1957.) The detailed engineering aspects of the design problem are discussed. Part 1: 3753 of 1957 (Braunholtz).

681.142 33
A 32000-Word Magnetic-Core Memory—E. Foss and R. S. Partridge. (*IBM J. Res. Devel.*, vol. 1, pp. 102-109; April, 1957.) The storage matrix consists of $128 \times 256 \times 36$ ferrite cores and has a read-write cycle of 12 μ sec. Its construction is described, together with the driver and sense amplifier circuits.

681.142 34
A Positive-Integer Arithmetic for Data Processing—R. W. Murphy. (*IBM J. Res. Devel.*, vol. 1, pp. 158-170; April, 1957.)

681.142 35
Irredundant Disjunctive and Conjunctive Forms of a Boolean Function—M. J. Ghazala (Gazale). (*IBM J. Res. Devel.*, vol. 1, pp. 171-176; April, 1957.) A thorough algebraic method is described for determining the complete set of irredundant normal and conjunctive forms. The procedure is mechanical and the method can be applied for programming computers.

681.142 36
Electronic Computers—W. Taeger. (*Frequenz*, vol. 11, pp. 185-191; June, 1957.) The application of analog computers to the solution of control-system problems is discussed.

681.142 37
Approximating Nonlinear Functions by Shunt-Loading Tapped Potentiometers in Analogue Computing Machines—D. W. C. Shen. (*Electronic Eng.*, vol. 29, pp. 434-439; September, 1957.)

681.142:621.314.7 38
The Multipurpose Bias Device: Part 1—The Commutator Transistor—B. Dunham. (*IBM J. Res. Devel.*, vol. 1, pp. 116-129; April, 1957.) A study of the application of the Rutz commutator transistor to three-input, one-output logical problems for handling by automatic computer systems. The Rutz commutator is a single-emitter amplitude-sensitive device with three separate input wires applied to the emitter. Its design will be detailed in a subsequent paper.

681.142:621.314.7 39
Two-Collector Transistor for Binary Full Addition—Rutz. (See 315.)

681.142:621.395.625.3 40
A Mathematical Model for Determining the Probabilities of Undetected Errors in Magnetic Tape Systems—M. Schatzoff and W. B. Harding. (*IBM J. Res. Devel.*, vol. 1, pp. 177-184; April, 1957.)

681.142:621.395.625.3 41
The Magnetic Tape Store for Pegasus—T. G. H. Braunholtz and D. Hogg. (*Electronic Eng.*, vol. 29, pp. 484-489; October, 1957.)

681.142:621.395.625.3 42
The Recording of Digital Information on Magnetic Drums—D. G. N. Hunter and D. S. Ridler. (*Electronic Eng.*, vol. 29, pp. 490-496; October, 1957.) "Methods of representing binary digital information on magnetic drums are discussed with regard to their reliability, cost, and technical merits."

CIRCUITS AND CIRCUIT ELEMENTS

621.3:061.3 43
International Components Symposium—(*Electronic Radio Eng.*, vol. 34, pp. 428-431; November, 1957.) Summary of papers read at the Royal Radar Establishment, Malvern, in September, 1957. Reliability, efficient use of space, liquid cooling techniques, and optimum component shapes for automatic assembly are discussed.

- 621.3.011.3 44
Calculation of Inductance of Toroids with Rectangular Cross Section and Few Turns—R. F. Schwartz. (PROC. IRE, vol. 45, pp. 1416-1417; October, 1957.)
- 621.3.049.7:621.39.03:061.3 45
"Solid Circuits"—(Wireless World, vol. 63, pp. 516-517; November, 1957.) Discussion of the International Symposium on Electronic Components held at Malvern, England. A "solid circuit" forming the equivalent of several transistors connected by resistors and capacitors is obtained by depositing films of conductive, resistive, and dielectric materials on a small block of semiconductor material. The solution of problems regarding the operation of components at high temperatures is mentioned.
- 621.3.049.75 46
Printed Circuits in Receiver Construction—W. I. Flack. (J. Telev. Soc., vol. 8, pp. 176-185; January/March, 1957.) Outline of development of the printed circuit, and description of modern production techniques.
- 621.3.049.75 47
Pro and Con on Seven Different Methods of Printed Wiring—A. E. Stones. (Electronic Inds. Tele-Tech., vol. 16, pp. 64-66, 158; March, 1957.) The basic techniques for each method are described and compared. A table of relevant U.S. patents is included.
- 621.314.6 48
A General Circuit Theorem on Rectification—J. W. Gewartowski. (PROC. IRE, vol. 45, p. 1410; October, 1957.) Nonlinear capacitors and inductors cannot effect rectification unless nonlinear resistance is present in the circuit.
- 621.318.424 49
New Method of Evaluating Ferro-inductors—W. J. Polydoroff. (Electronic Inds. Tele-Tech., vol. 16, pp. 78-79, 150; April, 1957.) Formulas for calculating the insertion loss and the resistance increase due to the iron core are derived. The practical factors governing optimum coil design are investigated.
- 621.318.57:621.387 50
Cold-Cathode Voltage-Transfer Circuits—J. H. Beesley. (GEC Telecommun., no. 23, pp. 6-19; February, 1957.) Practical techniques used in the application of cold-cathode triodes are given in detail. A number of circuit diagrams are included.
- 621.319.4:537.311.33 51
Charge and Discharge of a Non-linear Condenser through a Linear Nondissipative Inductance—A. Mozumder. (Z. angew. Math. Phys., vol. 8, pp. 261-280; July 25, 1957.) Macdonald (J. Chem. Phys., vol. 22, pp. 1317-1322; August, 1954) has shown that for a capacitor with a semiconductor as dielectric the capacitance is proportional to $\sinh \alpha V / \alpha V$ where V is the voltage across the capacitor and α is a constant. A circuit is analyzed in which such a capacitor is connected in series with a lossless inductance and a direct-voltage source, and a comparison is made with an exponential capacitor ($C\alpha \exp |\alpha V|$). Applications to the generation of rectangular and triangular waveforms are indicated. See also 958 of 1955 (Macdonald and Brackman).
- 621.319.42:621.3.049.75 52
Evaluating Base Materials for Printed Capacitors—J. J. Logan. (Electronic Inds. Tele-Tech., vol. 16, pp. 72-73., 160; August, 1957.) Definition of terms specifying the losses of base materials used for printed circuits which affect the size and Q factor of printed capacitors.
- 621.372.412.002.2:549.514.51:621.793.14 53
A Vacuum Plant for the Frequency Calibration of Quartz Vibrators—J. Green, L. Holland, and B. D. Power. (Electronic Eng., vol. 29, pp. 440-444; September, 1957.) See also 503 of 1956 (Awender, et al.).
- 621.372.5 54
A Network Theorem—E. Green. (Marconi Rev., vol. 20, pp. 35-38; 2nd Quart., 1957.) The impedance level of half a symmetrical network can be changed without altering the frequency response; the use of this theorem for the solution of network problems is discussed and illustrated by an example.
- 621.372.5:621.372.8 55
Noisy and Noise-Free Two-Port Networks Treated by the Isometric Circle Method—Bolinder. (PROC. IRE, vol. 45, pp. 1412-1413; October, 1957.)
- 621.372.5:621.375.2.018.75 56
On the Design of Four-Terminal Interstages for Pulse Applications—A. K. Choudhury and N. B. Chakrabarti. (Indian J. Phys., vol. 40, pp. 193-210; April, 1957.) The limits set by the input and output capacitance on the time response and the conditions for no overshoot are determined. Methods for achieving the necessary pole distributions are described and circuit networks suggested.
- 621.372.52:621.314.7 57
The Mathematical Treatment of Transistor Feedback Circuits—W. Glaser. (Nachr.-Tech., vol. 7, pp. 159-162; April, 1957.) Formulas are tabulated giving in convenient form the parameters of transistor networks for four types of feedback circuit.
- 621.372.54.029.64 58
Design and Development of Strip-Line Filters—E. H. Bradley. (IRE TRANS., vol. MTT-4, pp. 86-93; April, 1956. Abstract, PROC. IRE, vol. 44, p. 956; July, 1956.)
- 621.372.543.2:538.652 59
Concentric-Shear-Mode 455-kc/s Electro-mechanical Filter—R. W. George. (RCA Rev., vol. 18, pp. 186-194; June, 1957.) An experimental filter of simplified design is described which consists of four magnetostrictive ferrite disk resonators.
- 621.372.55:621.396.4:621.376.3 60
A Broad-Band Variable Group-Delay Equalizer—R. Hamer and R. C. Wilkinson. (P.O. Elec. Eng. J., vol. 50, Pt. 2, pp. 120-123; July, 1957.) The equalizer has been developed for use in fm microwave systems. It is inserted in the 70-mc IF signal path in long radio-relay systems. The performance is adequate for the transmission of frequency-division-multiplex telephony of at least 600 channels, or subcarrier color-television transmission.
- 621.373.029.64:538.569.4 61
Comments on Frequency Pulling of Maser Oscillators—C. H. Townes. (J. Appl. Phys., vol. 28, pp. 920-921; August, 1957.) The physical origin is illustrated of the theoretically predicted reduction in frequency pulling with increasing number of beam molecules, and reasons are given for its failure to occur in practice.
- 621.373.029.64:538.569.4:538.221 62
A Solid-State Microwave Amplifier and Oscillator using Ferrites—M. T. Weiss. (Phys. Rev., vol. 107, p. 317; July 1, 1957.) Experimental results obtained with an oscillator based on the proposal by Suhl (3076 of 1957). The active element is a piece of magnetized ferrite at room temperature.
- 621.373.421 63
Sensitivity of a Self-Excited Oscillator—I. S. Shpigel, M. D. Raizer, and E. A. Myae. (Zh. Tekh. Fiz., vol. 27, pp. 387-390; February, 1957.) Theoretical and experimental investigation of the characteristics of a tube feedback oscillator suitable for nuclear resonance detection.
- 621.373.5:621.396.621 64
Crystal Oscillators in Communication Receivers—A. G. Manke. (IRE TRANS., vol. PGVC-7, pp. 10-15; December, 1956. Abstract, PROC. IRE, vol. 45, p. 258; February, 1957.)
- 621.373.52:621.373.431.1 65
Unijunction Transistor forms Flip-Flop—E. Keonjian and J. J. Suran. (Electronics, vol. 30, pp. 165-167; September 1, 1957.) The construction and performance are described of a multivibrator circuit for a stable or monostable operation (see also 2878 of 1955). Its active element is the double-base diode, a 3-terminal $p-n$ junction device [see 3562 of 1956 (Suran)].
- 621.373.52.018.756 66
Pulse Generator uses Junction Transistors—E. J. Fuller. (Electronics, vol. 30, pp. 176-179; September 1, 1957.) A transistor circuit is described giving pulses of 1 to 10- μ sec. duration at repetition rates of 50-5000 pulses per second with internal delays of 1-100 μ sec.
- 621.373.52.018.78 67
Distortion in Transistor Amplifiers—P. Tharma. (Mullard tech. Commun., vol. 3, pp. 62-64; March, 1957.) An analysis of the distortion in low-level grounded-emitter stages are due to input-circuit nonlinearity and to variations of collector-to-base current gain.
- 621.373.52.029.4 68
Low-Frequency Transistor Oscillators—L. G. Gripps. (Mullard tech. Commun., vol. 3, pp. 44-58; March, 1957. Electronic Applic. Bull., vol. 17, pp. 113-128; May, 1957.) Theoretical treatment of a junction-transistor oscillator for frequencies of a few kc. Frequency and amplitude stability, conversion efficiency and the conditions governing starting, are considered. A practical circuit design is derived and experimental results are given.
- 621.374.32 69
Build-Up of Large Signals with Elimination of Reflections in Magnetostrictive Storage Lines—D. Maeder. (Z. angew. Math. Phys., vol. 8, pp. 326-327; July 25, 1957.) Greater reliability and increased storage capacity are obtained by substituting twelve energizing coils for the usual one. With this arrangement, a steel-wire delay line can be used. See also 2385 of 1957.
- 621.374.33:621.314.7 70
A Transistor Gating Matrix for a Simulated Warfare Computer—W. H. MacWilliams, Jr. (Bell Lab. Rec., vol. 35, pp. 94-99; March, 1957.) Brief description of a circuit, devised in 1949, which used a matrix of 4×10 point-contact transistors. Amplification of signals was also achieved.
- 621.374.5 71
Signal-Enhanced Delay Line—T. I. Humphreys. (Electronic Inds. Tele-Tech. vol. 16, pp. 70-71, 167; August, 1957.) To maintain pulse shape the high-frequency response of the delay line described is improved by selective amplification.
- 621.374.5:621.396.962.3 72
Pulse Compression—R. Krönert. (Nachr.-Tech., vol. 7, pp. 148-152, 162; April, 1957.) A method is described for compressing frequency-modulated rf pulses, i.e., shortening them and increasing their amplitude by passing them

through a delay-distortion network consisting of a chain of lattice quadrupoles. The theory outlined is based on work by Cauer, published posthumously. Its practical application in the field of radar should result in higher resolving power for a given snr.

621.375:621.372.51 73
Minimizing Mismatch Loss—H. E. Hollmann. (*Electronic Inds. Tele-Tech.* vol. 16, pp. 74–75, 165; August, 1957.) Simple formulas and curves are given.

621.375.2+621.375.4 74
Upper Limits of Output Power in Vacuum-Tube and Transistor A.C. Amplifiers—L. M. Vallese. (*Commun. and Electronics*, no. 29, pp. 87–92; March, 1957.) Simple analysis and comparison based on idealized characteristics.

621.375.2 75
Stacked Valve Circuits—J. B. Earnshaw. (*Electronic Radio Eng.*, vol. 34, pp. 404–406; November, 1957.) An analysis by means of feedback theorems and modified equivalent circuits. Application of the method to the cascade amplifier and the cathode-follower circuits is given in detail.

621.375.2.029.3 76
Single-Ended Push-Pull Output Stages—(*Electronic Applic. Bull.*, vol. 17, pp. 81–106; May, 1957.) The development of low-dc-resistance pentodes and high-resistance moving-coil loudspeakers has made possible the construction of transformerless output stages several types of which are described. The paper is based on the work of W. Aschermann and J. Rodrigues de Miranda (see 3727 of 1957).

621.375.2.029.4 77
A Low-Frequency Selective Amplifier—C. K. Battye. (*J. Sci. Instr.*, vol. 34, pp. 263–265; July, 1957.) The frequency is variable in steps from 1 to 1000 cps. The selectivity can be set up to $Q=100$. The amplifier is dc coupled; a twin-T network shunted by a capacitor acts as a selective network in the negative feedback line.

621.375.2.029.55 78
PT-15 P.A. Unit—J. N. Walker. (*Short Wave Mag.*, vol. 14, pp. 624–630; February, 1957.) Description of a band-switching rf amplifier for 80, 40, and 20 m, which uses a pair of tubes Type PT 15 in parallel.

621.375.221.029.62:621.396.4:621.376.3 79
A Broad-Band Intermediate-Frequency Amplifier for Use in Frequency-Modulation Microwave Radio-Relay Systems—R. Hamer and C. H. Gibbs. (*P.O. Elec. Eng. J.*, vol. 50, Pt. 2, pp. 124–126; July, 1957.) A 70-mc amplifier is described which is suitable for the transmission of 600-channel frequency-division-multiplex telephony or subcarrier color-television signals in fm microwave radio-relay systems. A test-tone/noise ratio of 70 db is not significantly degraded after transmission through five amplifiers in tandem.

621.375.227.029.3 80
400-Watt Audio Amplifier—G. R. Woodville. (*Wireless World*, vol. 63, pp. 543–546; November, 1957.) The circuit described includes small output tubes in parallel push-pull connection.

621.375.3 81
Self-Balancing Magnetic Amplifiers of the Differential-Feedback Type—W. A. Geyger. (*Commun. and Electronics*, no. 29, pp. 39–46; March, 1957.) A 60-cps magnetic amplifier for extending the range of a moving-coil ink recorder is described.

621.375.4.029.3:629.13 82
The Use of Transistors in Airborne Audio Equipment—V. P. Holec. *IRE TRANS.*, vol. AU-4, pp. 90–93; July/August, 1956. Abstract, *PROC. IRE*, vol. 44, p. 1641; November, 1956.)

621.375.43.029.3:621.314.7 83
Negative-Feedback Transistor Amplifiers—H. R. Lowry. (*Radio U Telev. News*, vol. 57, pp. 55–58, 109; May, 1957.) Design data are given for high-fidelity af amplifiers.

621.375.9.029.64:538.569.4 84
Microwave Amplification by MASER Techniques—W. V. Smith. (*IBM J. Res. Devel.*, vol. 1, pp. 232–238; July, 1957.) Elementary analysis of maser operation, including its application to wide-band, short-transit-time amplification.

621.376:621.316.7.078 85
Demodulator-Limiter for Control System Signals—N. L. Johanson. (*Electronics*, vol. 30, p. 155; September 1, 1957.) Description of transistor circuit for automatic control systems which acts as limiter during modulation or demodulation.

621.376.239 86
Magnetically Keyed, Phase-Sensitive Demodulators—R. B. Mark, W. X. Johnson, and P. R. Johannessen. (*Commun. and Electronics*, no. 29, pp. 1–6; March, 1957.) The operation and performance of a pulse-shaping circuit using magnetic reactors is described. The properties of three types of phase-sensitive demodulator are compared. Diode demodulators have linear characteristics, magnetic amplifier demodulators have high input impedance, and transistor demodulators combine good linearity with low noise level.

621.376.4:621.314.7 87
Transistorized Phase Discriminators—A. N. De Sautels. (*Commun. and Electronics*, no. 29, pp. 19–26; March, 1957.) Half-wave and full-wave phase discriminators are described with two- or three-terminal dc outputs. An analysis of the operating characteristics of transistors in discriminator circuits is given; temperature stability and power limitations are discussed.

GENERAL PHYSICS

535.33-1 88
Interferometry for the Far Infrared—J. Strong. (*J. Opt. Soc. Amer.*, vol. 47, pp. 354–357; May, 1957.)

535.61-1 89
Infrared Radiation and its Detection—(*Electronic Radio Eng.*, vol. 34, pp. 412–415; November, 1957.) A comparison of the sensitivity and time constant of available detectors of infrared radiation. Thermal detectors of thermocouple, bolometer, and pneumatic type and photoelectric detectors are discussed.

537.311.1:536.21:537.311.33 90
The Lorenz Number—P. J. Price. (*IBM J. Res. Devel.*, vol. 1, pp. 147–157; April, 1957.) The theory of the Lorenz number of a conducting crystal is developed for the "band" and "one-electron" models of the electron assembly. With certain approximations, the Lorenz number is found to be equal to the mean square fluctuation of the thermoelectric power.

[537.311.1+536.212.2]:539.13 91
Some Scattering Problems in Conduction Theory—P. G. Klemens. (*Can. J. Phys.*, vol. 35, pp. 441–450; April, 1957.) An expression derived for the scattering of electrons by inhomogeneous slowly varying strain fields is

applied to scattering by dislocations and stacking faults.

537.5 92
Free-Path Formulae for the Coefficient of Diffusion and Velocity of Drift of Electrons in Gases—L. G. H. Huxley. (*Aust. J. Phys.*, vol. 10, pp. 118–129; March, 1957. Correction, *ibid.*, vol. 10, p. 329; June, 1957.)

537.5:538.6 93
Type of Plasma Oscillations in a Magnetic Field—S. I. Braginski. (*Dokl. Ak. Nauk S.S.S.R.*, vol. 115, pp. 475–478; July 21, 1957.) Mathematical analysis based on a model of ideal electron and ion gases.

537.5:538.63 94
Free-Path Formulae for the Electronic Conductivity of a Weakly Ionized Gas in the Presence of a Uniform and Constant Magnetic Field and a Sinusoidal Electric Field—L. G. H. Huxley. (*Aust. J. Phys.*, vol. 10, pp. 240–245; June, 1957.) "A general free path formula is given for the drift velocity of electrons in a weakly ionized gas in a sinusoidal electric field. Most special cases of interest, including the magnetic deflection of an electron stream in a gas, are readily derivable from the general formula. The results find application in microwave and ionospheric studies of the motion of electrons in gases as well as in experiments on the magnetic deflection of an electron stream." See also 92 above.

537.525.8 95
Oscillations in Direct-Current Glow Discharges—A. M. Pilon. (*Phys. Rev.*, vol. 107, pp. 25–27; July 1, 1957.) Experimental results are given concerning the stable oscillations with the same period which occur in the current and in the light emitted by the positive column.

538.244.2 96
Magnetization in the Presence of Magnetic Viscosity—M. I. Rozovski. (*Zh. Tekh. Fiz.*, vol. 27, pp. 355–359; February, 1957.) A mathematical expression is derived for solving problems of magnetization of magnetically viscous samples, in particular those of cylindrical shape. See also 3697 of 1956 (Tikhonov and Samarski).

538.566:535.42 97
Diffraction of Electromagnetic Waves by Ribbon and Slit: Part 1—Y. Nomura and S. Katsura. (*J. phys. Soc. Japan*, vol. 12, pp. 190–200; February, 1957.) Rigorous solutions are presented for a wave incident on a plane normal to the edge of the ribbon or slit, but with arbitrary angles of incidence and polarization. For diffraction by circular plate and hole, see 3235 of 1955.

538.566:535.422]+534.26 98
Diffraction of a Spherical-Wave Pulse by a Half-Plane Screen—J. R. Wait. (*Can. J. Phys.*, vol. 35, pp. 693–696; May, 1957.) Fourier-integral treatment for a point source.

538.569.4 99
Distortions of Magnetic Resonances by Additional and Excessive Oscillatory Fields—H. R. Lewis, A. Pery, W. Quinn, and N. F. Ramsey. (*Phys. Rev.*, vol. 107, pp. 446–449; July 15, 1957.) A theoretical explanation is given of the shift of the resonance frequency which occurs as a result of the presence of an extraneous rf electric field. See also 1386 of 1956 (Ramsey).

538.569.4:539.15.098 100
The Dependence of the Amplitude of the First Harmonic of Nuclear-Magnetic-Resonance Absorption on the Amount of Detuning

- I. S. Shpigel, M. D. Raizer, and E. A. Myae. (*Zh. Tekh. Fiz.*, vol. 27, pp. 351-354; February, 1957.)
- 538.569.4:546.171.1 101
Equivalence between the Line Width and the Rate of Energy Relaxation in the Inversion Spectrum of Ammonia—K. Tomita. (*Progr. theoret. Phys.*, vol. 17, pp. 513-515; March, 1957.)
- 538.6 102
On the Equilibrium Configurations of Oblate Fluid Spheroids under the Influence of a Magnetic Field—S. P. Talwar. (*Proc. nat. Inst. Sci. India*, Pt. A, vol. 22, pp. 316-323; September 26, 1956.)
- 538.6 103
Toroidal Oscillations of a Spherical Mass of Viscous Conducting Fluid in a Uniform Magnetic Field—K. Stewartson. (*Z. angew. Math. Phys.*, vol. 8, pp. 290-297; July, 25 1957.) See also 3352 of 1956.
- 539.1:541.124 104
Theoretical Treatment of the Kinetics of Diffusion-Limited Reactions—T. R. Waite. (*Phys. Rev.*, vol. 107, pp. 463-470; July 15, 1957.) The diffusion-limited reaction $A + B \rightarrow AB$ has been solved for a random initial distribution of A and B particles.
- GEOPHYSICAL AND EXTRATERRESTRIAL PHENOMENA**
- 523.16:551.510.535 105
Radio-Star Ridges—M. Dagg. (*J. Atmos. Terr. Phys.*, vol. 11, no. 2, pp. 118-127; 1957.) The distinctive amplitude variations known as "ridges" can probably be explained in terms of divergent-lens effects in the E region. See also 2058 of 1956 (Wild and Roberts).
- 523.16:551.510.535 106
A Consideration of Radio-Star Scintillations as Caused by Interstellar Particles Entering the Ionosphere: Part 1—Daily and Seasonal Variations of the Scintillation of a Radio Star. Part 2—The Accretion of Interstellar Particles as a Cause of Radio-Star Scintillations—G. A. Harrower. (*Can. J. Phys.*, vol. 35, pp. 512-535; May, 1957.) An analysis is made of measurements of scintillations of the rf source in Cassiopeia recorded at Ottawa during 1954 at a frequency of 50 mc. The data show certain daily maxima occurring at solar times dependent on the date of the year and grouped unsymmetrically in a way which suggests that they are due to the infall of interstellar particles from outside the solar system. The velocities of certain of these particles are derived by simple applications of vector addition employing the known velocity of the earth. See 2116 of 1957.
- 523.16:621.396.677.8 107
The Mullard Radio Astronomy Observatory, Cambridge—M. Ryle. (*Nature, London*, vol. 180, pp. 110-112; July 20, 1957.) The observatory was formally opened in July, 1957. Two instruments then under construction were a radio-star interferometer for 1.7 m λ , and a pencil-beam system for investigating continuous galactic radiation at 7.9 m λ . The aperture synthesis technique applied in the two systems is described. See also 3749 of 1957.
- 523.16:621.396.677.833 108
World's Largest Radio Telescope—(*Overseas Eng.*, vol. 31, pp. 15-18; August, 1957.) An illustrated description of the design and construction of the 250-foot fully steerable paraboloid of the Jodrell Bank instrument with details of the driving system and drive control equipment.
- 523.5 109
The Distribution of the Orbits of Sporadic Meteors—A. A. Weiss. (*Aust. J. Phys.*, vol. 10, pp. 77-102; March, 1957.) Radio observations at Adelaide during 1952-1956, are analyzed. A distribution of orbits is derived which is consistent with radar and visual observations in the northern hemisphere.
- 523.5:621.396.11.029.62 110
Variations in the Intrinsic Strength of the 1956 Quadrantid Meteor Shower—C. O. Hines and E. L. Vogan. (*Can. J. Phys.*, vol. 35, pp. 703-711; June, 1957.) Analysis of the occurrence rate of meteoric signals detected on a vhf forward-scatter east-west path in Canada. See also 3392 of 1955 (Forsyth and Vogan).
- 523.5:621.396.11.029.62:551.510.535 111
A Theory of Long-Duration Meteor-Echoes based on Atmospheric Turbulence with Experimental Confirmation—L. A. Manning and V. R. Eshleman. (*J. Geophys. Res.*, vol. 62, pp. 367-371; September, 1957.) Comments on 1417 of 1957 (Booker and Cohen). The experimental evidence is examined with the conclusion that the theory does not accurately represent the properties of meteoric echoes.
- 523.5:621.396.96 112
Meteor Activity in the Southern Hemisphere—A. A. Weiss. (*Aust. J. Phys.*, vol. 10, pp. 299-309; June, 1957.) Activity and radiants of meteor showers are discussed and compared with similar data for the northern hemisphere. See also 109 above and 2938 of 1955.
- 523.74:551.510.535 113
Ionospheric Indices of Solar Activity—W. J. G. Beynon and G. M. Brown. (*J. Atmos. Terr. Phys.*, vol. 11, no. 2, pp. 128-131; 1957.) It is suggested that a simple index based on E-layer measurements at a single station is adequate, and that the additional effort required to provide the index I_F based on F₂-layer measurements at three stations is not justified. See also 1397 of 1956 (Minnis).
- 523.75 114
Observation of a New Type of Flare—R. J. Bray, R. E. Loughhead, V. R. Burgess, and M. K. McCabe. (*Aust. J. Phys.*, vol. 10, pp. 319-323; June, 1957.) A mass of very bright material was ejected from a flare about 28° from the sun's limb. Except for the velocity, the mass possessed all the properties of a small flare.
- 550.372 115
The Effective Electrical Constants of Soil at Low Frequencies—J. R. Wait. (*Proc. IRE*, vol. 45, pp. 1411-1412; October, 1957.) A possible explanation is presented for the large apparent dielectric constants ($\approx 10^3$) which occur at frequencies of the order of 15 kc.
- 550.389.2 116
I. G. Y. Rocket Program—N. W. Spencer. (*Sci. Mon.*, vol. 85, pp. 130-142; September, 1957.) An outline of the work of the IGY subcommittee of the U.S. Technical Panel for Rocketry. A table is given listing organizations participating and their objectives.
- 551.510.52:551.510.535 117
A Possible Troposphere-Ionosphere Relationship—S. J. Bauer. (*J. Geophys. Res.*, vol. 62, pp. 425-430; September, 1957.) A relation is suggested between F₂-layer characteristics and the passage of meteorological fronts through the troposphere. An hypothesis for dynamical coupling between the two regions is outlined.
- 551.510.53 118
Electric Field Measurements in the Stratosphere—C. G. Stergis, G. C. Rein, and T. Kangas. (*J. Atmos. Terr. Phys.*, vol. 11, no. 2, pp. 77-82; 1957.) Above the exchange layer the field decreases monotonically up to the limit (90,000 feet) of measurements made in 1955 and 1956. The measured and calculated values are in good agreement.
- 551.510.53:551.594.21 119
Electric Field Measurements above Thunderstorms—C. G. Stergis, G. C. Rein, and T. Kangas. (*J. Atmos. Terr. Phys.*, vol. 11, no. 2, pp. 83-90; 1957.) In measurements at heights of 70,000 to 90,000 feet above central Florida a positive upward-flowing current of about 1.3 a was found.
- 551.510.535 120
Models of the Lower Ionosphere as may be Inferred from Absorption Results—P. Bandyopadhyay. (*Indian J. Phys.*, vol. 31, pp. 297-308; June, 1957.) Values of derivative and non-derivative absorption and their variations with $\cos \chi$ are calculated for the D-region models of Nertney (2306 of 1953), Piggott (unpublished), and Mitra (see 2087 of 1954) and for the E-region model of Jones (1661 of 1955). Satisfactory agreement with experimental results is found for Mitra's model of the D region but not for Jones's model of the E region.
- 551.510.535 121
A Study of "Spread-F" Ionospheric Echoes at Night at Brisbane: Part 3—Frequency Spreading—D. G. Singleton. (*Aust. J. Phys.*, vol. 10, pp. 60-76; March, 1957.) Diurnal and seasonal variations in spreading of the penetration frequency are compared with similar world-wide data. The observations are interpreted in terms of scattering from clouds of enhanced ionization near the F₂-layer maximum and a seasonal vertical movement of these clouds is suggested, the extent of which increases with latitude. Parts 1 and 2: 119 of 1957 (McNicol, et al.).
- 551.510.535 122
Severe Ionospheric Storm—(*Wireless World*, vol. 63, p. 553; November, 1957.) Notes on the disturbances of August 29-September 6, 1957.
- 551.510.535:523.75:621.396.11.029.62 123
Disturbances in the Lower Ionosphere Observed at V.H.F. following the Solar Flare of 23 February 1956 with Particular Reference to Auroral-Zone Absorption—D. K. Bailey. (*J. Geophys. Res.*, vol. 62, pp. 431-463; September, 1957.) The effects of the flare on ionospheric-scatter links in the band 30-40 mc at high latitudes are reported. An abrupt increase in oblique-incidence signal intensity, occurring almost simultaneously with the arrival of cosmic rays, was followed during the next three days by abnormally high levels at night and low levels during the day. Background cosmic noise measurements showed increased absorption at night and greatly increased absorption during daylight. The penetration into the D region of moderately heavy solar atomic ions is suggested as an explanation of the absorption phenomena.
- 551.510.535:523.78 124
Solar Eclipse of 30th June 1954 and its Effect upon the Ionosphere—S. N. Mitra. (*Indian J. Phys.*, vol. 31, pp. 309-323; June, 1957.) The investigations at Delhi reported include vertical-incidence ionospheric measurements, the recording of variations of sw and mf signals, and the recording of solar noise on 204 mc. Evidence of three distinct "corporeal eclipses" was obtained both on the ionization density of the F layer and on the absorption in the nondeviating region. These were found to occur 2, 4, and 6½ hours before the optical eclipse. Theoretical arguments and past observations indicate that these corporeal

emissions may have originated from the so-called M region of the sun.

551.510.535:523.78:621.396.11 125
Ionospheric Research—A. P. Dale. (*RSGB Bull.*, vol. 32, pp. 499–501; May, 1957.) Note on signal-strength changes during the annular solar eclipse on December 25, 1954, and the control days for transmitters both in South Africa and in other countries.

551.510.535:550.385 126
Disturbances in the F₁ and E Regions of the Ionosphere Associated with Geomagnetic Storms—T. Sato. (*J. Geomag. Geoelect.*, vol. 9, pp. 57–60; March, 1957.) The E- and F₁-layer variations which occur during geomagnetic disturbances are examined for different phases of the solar cycle and for a number of latitudes. The data are discussed in relation to the electron drifts associated with geomagnetic disturbances. See also 127 below.

551.510.535:550.385 127
Disturbances in the Ionospheric F₂ Region associated with Geomagnetic Storms: Part 2—Middle Latitudes—T. Sato. (*J. Geomag. Geoelect.*, vol. 9, pp. 1–22; March, 1957.) Disturbances at middle latitudes are divided into negative and positive types, characteristic of high and low latitudes, respectively. These results are discussed in terms of vertical drift of electrons and the disturbance daily variations in the geomagnetic field. The bearing of the *S_q* dynamo current on seasonal and latitude variations of disturbances is discussed. Part 1: 3139 of 1957.

551.510.535:621.396.812.3 128
Ionospheric Irregularities Causing Random Fading of Very Low Frequencies—Bowhill. (See 251.)

551.510.535:621.396.9:523.3 129
Ionospheric Studies by the Lunar Technique—B. C. Blevins. (*Nature, London*, vol. 180, pp. 138–139; July 20, 1957.) Equipment operating near Ottawa comprises a 10-kw 488-mc transmitter, keyed "on" for 2 seconds and "off" for 4 seconds, feeding a 28-foot paraboloid via a horn, and orthogonal dipoles with a similar reflector feeding a dual-conversion receiver (IF 32 and 4 mc). Synchronous detection is used to give an af output signal equal in frequency to the Doppler shift of the signal reflected from the moon. Preliminary results indicate the presence of fading due to libration, long- and short-period Faraday rotation, and long-term fading without Faraday rotation.

551.594.21/25 130
The Electrification of Precipitation and Thunderstorms—R. Gunn. (*Proc. IRE*, vol. 45, pp. 1331–1358; October, 1957.) A review article. Cosmic rays, radioactivity, and other agencies produce ion pairs which are transferred to cloud droplets or ice crystals and establish a droplet charge distribution greatly influenced by differences in conductivity for positive and negative ions. Rain formed from these droplets may be electrified, usually both positive and negative drops being present. Processes are considered which charge this rain and may eventually lead to a lightning stroke. The conditions necessary to establish gross free charge distributions by regeneration are specified and shown to be met under frequently occurring meteorological situations. Forty-seven references.

551.594.5 131
Rotational Temperatures Measured in Aurorae at Churchill, Manitoba—R. Montalbetti. (*Can. J. Phys.*, vol. 35, pp. 831–836; August, 1957.) The measurements indicate

there is no latitude effect. A vertical temperature gradient of 6°K/km is deduced. See also 3871 of 1957 (Montalbetti and Jones).

551.594.6:523.745 132
A Study of the Audio-Frequency Radio Phenomenon Known as "Dawn Chorus"—G. McK. Allcock. (*Aust. J. Phys.*, vol. 10, pp. 286–298; June, 1957.) Experimental evidence supports the hypothesis that "dawn chorus" signals are generated by the entry into the ionosphere of clouds of positively charged particles of solar origin. Propagation appears to take place in the extraordinary magneto-ionic mode along the earth's magnetic lines of force.

LOCATION AND AIDS TO NAVIGATION

621.396.932 133
Electronic Clock-Coder for Marine Radio Beacons—A. C. MacKellar and A. J. B. Baty. (*Brit. Commun. Electronics*, vol. 4, pp. 476–477; August, 1957.) Crystal control is used to give more reliable service.

621.396.932.2 134
The TALBE: a V.H.F. C.W. Radio Aid for Air/Sea Rescue—W. Kiryluk. (*J. Brit. IRE*, vol. 17, pp. 489–500; September, 1957.) Describes the development and construction of a "talk-and-listen beacon," together with prior work on an unmodulated dinghy transmitter.

621.396.932.2 135
An Introduction to Radio Aids to Air/Sea Rescue—G. W. Hosie. (*J. Brit. IRE*, vol. 17, pp. 481–488; September, 1957.) Developments since 1940, are surveyed, and the mf, cw, and vhf radar beacons in general use during the war are discussed, together with post-war equipment. A crystal-controlled vhf beacon of low duty cycle is suggested, and also a crash location beacon.

621.396.962.3:621.374.5 136
Pulse Compression—Krönert. (See 72.)

621.396.965.8 137
Optimizing the Dynamic Parameters of a Track-While-Scan System—J. Sklansky. (*RCA Rev.*, vol. 18, pp. 163–185; June, 1957.)

MATERIALS AND SUBSIDIARY TECHNIQUES

535.215:546.48.241.1 138
Preparation and Photoconductive Properties of Cadmium Telluride Films—G. G. Kretschmar and L. E. Schilberg. (*J. Appl. Phys.*, vol. 28, pp. 865–867; August, 1957.) A thin film gave a high dark resistance, falling by 10 to 200 times with 2-foot candle illumination. A film prepared in indium vapor gave a dark resistance of 1–10 mΩ falling to a few hundred kΩ.

535.37 139
Critical Comment on a Method for Determining Electron Trap Depths—C. H. Haake. (*J. Opt. Soc. Amer.*, vol. 47, pp. 649–652; July, 1957.) "A critical analysis of Garlick and Gibson's method (3421 of 1948) based on a mathematical determination of the applicable temperature range and on experimental evidence shows that the trap depths obtained are lower than those found by other methods. Especially the frequency-of-escape constants calculated subsequently contrast strongly to those determined by separate measurements."

535.37 140
Energy Transport by Cascade and Resonance Processes in Doubly Activated Phosphors—E. W. Claffy and C. C. Klick. (*J. Electrochem. Soc.*, vol. 104, pp. 445–447; July, 1957.)

535.376 141
Review of Articles on Luminescence for 1955–1956—G. R. Fonda. (*J. Electrochem. Soc.* vol. 104, pp. 524–530; August, 1957.) Review covering articles published in English, German, and French. One-hundred and fifty-six references.

535.376:546.472.21 142
Electroluminescence of ZnS Single Crystals—G. F. Neumark. (*Sylvania Technologist*, vol. 10, pp. 29–34; April, 1957.) Electroluminescence in ZnS depends on the number and type of traps in the crystal. Impact ionization appears to be the predominant mechanism for the excitation. Thirty-one references.

537.226/.228.1:546.431.824–31:534.232 143
An Investigation of some Barium Titanate Compositions for Transducer Applications—D. Schofield and R. F. Brown. (*Can. J. Phys.*, vol. 35, pp. 594–607; May, 1957.) The addition of Co to 5 per cent Ca, 95 per cent Ba titanate compositions, produces a large reduction in the dielectric loss in high electric fields without significant effect on the piezoelectric characteristics. Preliminary results were given earlier (3160 of 1957).

537.226/.227:534.1.087 144
The Use of Ferroelectric Ceramics for Vibration Analysis—R. C. Kell, G. A. Luck, and L. A. Thomas. (*J. Sci. Instr.*, vol. 34, pp. 271–274; July, 1957.)

537.227:546.431.824–31 145
Preparation of BaTiO₃ Single Crystals in Coal Gas Atmosphere—K. Kawabe and S. Sawada. (*J. Phys. Soc. Japan*, vol. 12, p. 218; February, 1957.)

537.227:546.431.824–31 146
Heating Effects in Single Crystal Barium Titanate—D. S. Campbell. (*J. Electronics Control*, vol. 3, pp. 330–338; September, 1957.) The coercive field increases with frequency up to a certain limiting frequency above which it falls due to heating effects. This gives a criterion for the maximum frequency at which crystals can be expected to operate in a matrix storage system.

537.227:546.431.824–31 147
Quasi-static Hysteresis in Barium-Titanate Single Crystals—K. Zen'iti, K. Husimi, and K. Kataoka. (*J. Phys. Soc. Japan*, vol. 12, p. 432; April, 1957.)

537.227:546.431.824–31 148
On the 180°-Type Domain Wall of BaTiO₃ Crystal—W. Kinase and H. Takahashi. (*J. Phys. Soc. Japan*, vol. 12, pp. 464–476; May, 1957.) At room temperature the domain width is about 10⁻⁴ cm and its energy is 1.4 erg/cm². The structure of the domains and their reversing process are also discussed.

537.228.5:546.36 149
Stark Effect on Caesium-133 Hyperfine Structure—R. D. Haun, Jr and J. R. Zacharias. (*Phys. Rev.*, vol. 107, pp. 107–109; July 1, 1957.) The change of the hyperfine-structure separation energy caused by an electric field has been measured in ¹³³Cs by the atomic-beam magnetic-resonance method and is compared with other experimental and theoretical data.

537.311.33 150
Generation of an E.M.F. in Semiconductors with Nonequilibrium Current Carrier Concentrations—J. Tauc. (*Rev. mod. Phys.*, vol. 29, pp. 308–324; July, 1957.) A general formulation of the problem is presented. Solutions are obtained for two special cases for which the impurity-concentration change occurs over a distance either long or short

- compared with the diffusion length of current carriers; these are bulk and barrier-layer photovoltaic effects, respectively. Practical implications are discussed. One-hundred and two references.
- 537.311.33 151
Statistics of the Charge Distribution for a Localized Flaw in a Semiconductor—W. Shockley and J. T. Last. (*Phys. Rev.*, vol. 107, pp. 392–396; July 15, 1957.) The charge situation is described by a set of energy levels which are independent of the Fermi level but are temperature-dependent. The charge of the flaw increases by one electron unit of negative charge as the Fermi level is raised successively above each level of the set and, conversely, as it is lowered.
- 537.311.33 152
Scattering of Current Carriers in Semiconductors with Ionic Type of Bond—T. A. Kontorova. (*Zh. Tekh. Fiz.*, vol. 27, pp. 269–274; February, 1957.) The scattering of carriers in the optical and acoustic modes is investigated and their free path is calculated. Approximate formulas for the carrier mobility are derived. The dependence of mobility on temperature is examined.
- 537.311.33 153
High-Frequency Relaxation Processes in the Field-Effect Experiment—C. G. B. Garrett. (*Phys. Rev.*, vol. 107, pp. 478–487; July 15, 1957.) A theoretical treatment is given of two dispersion phenomena in the semiconductor field-effect experiment [see, e.g., 3532 of 1951 (Montgomery)]: 1) dispersion arising from the finite time required to generate minority carriers, and 2) relaxation of the fast surface states.
- 537.311.33:538.632 154
On the Electrical Properties of Degenerate Semiconductors—E. Haga. (*J. Phys. Soc. Japan*, vol. 12, p. 217; February, 1957.) Theoretical derivation of quantitative data on resistivity and the Hall coefficient.
- 537.311.33:538.632 155
Resistivity and Hall Coefficient of Semiconductors—K. Shogenji and S. Uchiyama. (*J. Phys. Soc. Japan*, vol. 12, p. 434; April, 1957.) Calculations assuming scattering of current carriers by acoustic and optical modes of lattice vibration, but neglecting scattering by impurity centers.
- 537.311.33:546.23:621.314.6 156
The Surface Potential of Selenium and its Relation to the Rectification and the Photovoltaic Effects—U. Yoshida and A. Suzuki. (*J. Phys. Soc. Japan*, vol. 12, pp. 459–463; May, 1957.) The changes with time of the surface potential and the rectification ratio after heat treatment are reduced by coating with a thin film of synthetic resin.
- 537.311.33:546.24 157
Electrical Properties of Tellurium at the Melting Point and in the Liquid State—A. S. Epstein, H. Fritzsche, and K. Lark-Horovitz. (*Phys. Rev.*, vol. 107, pp. 412–419; July 15, 1957.) The experimental results show that semiconductor properties persist in the liquid state, but as the temperature is raised a gradual transition to metallic behavior occurs.
- 537.311.33:546.27 158
Electrical Properties of Boron Single Crystals—W. C. Shaw, D. E. Hudson, and G. C. Danielson. (*Phys. Rev.*, vol. 107, pp. 419–427; July 15, 1957.) The electrical resistivity, Hall coefficient, and thermoelectric power of microscopic crystals have been measured as functions of temperature. A value of 1.55 ± 0.05 ev is deduced for the energy gap.
- 537.311.33:546.28+546.289 159
Expansions in Reactor Irradiated Germanium and Silicon—M. C. Wittels. (*J. Appl. Phys.*, vol. 28, p. 921; August, 1957.) The lattice expansions observed were greater in Ge than Si, as expected from theory. The retained damage in Ge was dependent on the irradiation temperature.
- 537.311.33:546.28 160
Donor Electron Spin Relaxation in Silicon—E. Abrahams. (*Phys. Rev.*, vol. 107, pp. 491–496; July 15, 1957.) The effects of spin-orbit coupling on the relaxation time for donor electron spins are considered.
- 537.311.33:546.28 161
Damage to Silicon Produced by Bombardment with Helium Ions—U. F. Gianola. (*J. Appl. Phys.*, vol. 28, pp. 868–873; August, 1957.) Helium ions at 3×10^4 ev were used. The surface layer was found to be converted to a quasi-stable amorphous form, which becomes partially crystalline on annealing. The amorphous material is soluble in aqueous hydrofluoric acid and has about 1/10th the thickness of the affected Si.
- 537.311.33:546.28 162
Oxygen Content of Silicon Single Crystals—W. Kaiser and P. H. Keck. (*J. Appl. Phys.*, vol. 28, pp. 882–887; August, 1957.) The oxygen content of pulled Si crystals is correlated with the infrared absorption at 9 microns. Methods of altering the oxygen concentration are discussed.
- 537.311.33:546.289 163
Study of the Minority-Carrier Mobility in Germanium—M. Shtenbek and P. I. Baranski. (*Zh. Tekh. Fiz.*, vol. 27, pp. 221–232; February, 1957.) Report of investigation on *n*-type single-crystal Ge. The transit time, the mobility, and the coefficients of longitudinal and transverse diffusion of minority carriers are calculated.
- 537.311.33:546.289 164
Experimental Investigation of the Correlation between Peltier Effect and Thermo-e.m.f. in Germanium—M. Shtenbek and P. I. Baranski. (*Zh. Tekh. Fiz.*, vol. 27, pp. 233–237; February, 1957.) This correlation is investigated in the impurity and intrinsic conduction bands for samples of *n*- and *p*-type Ge of differing specific resistance.
- 537.311.33:546.289 165
Nature of Recombination Centres in Germanium Originated by Low-Temperature Heat Treatment—T. V. Mashovets and S. M. Ryvkin. (*Zh. Tekh. Fiz.*, vol. 27, pp. 238–241; February, 1957.) See also 2794 of 1956.
- 537.311.33:546.289 166
Probability of Capture by Carrier Recombination at Frenkel-Type Defects in *n*-Type Germanium—L. S. Smirnov and V. S. Vasilov. (*Zh. Tekh. Fiz.*, vol. 27, pp. 427–429; February, 1957.) Bombardment of Ge crystals with electrons of energy over 500 kev produces at room temperature stable dislocations of crystal structure, called Frenkel defects, corresponding to several levels in the forbidden zone, which act as effective recombination centers of holes and electrons.
- 537.311.33:546.289 167
Electrical Properties of Nickel-Doped Germanium at Low Temperatures—Y. Kanai and R. Nii. (*J. Phys. Soc. Japan*, vol. 12, pp. 125–133; February, 1957.) Anomalous behavior was found at temperatures in the range 120–170°K, the resistivity increasing as the temperature was reduced. The electrical properties could be explained by use of the model proposed by Hung (*Phys. Rev.*, vol. 79, pp. 727–728; August 15, 1950.)
- 537.311.33:546.289 168
Peripheral Inhomogeneities of the Alloyed Germanium *p-n* Junction—M. Kikuchi. (*J. Phys. Soc. Japan*, vol. 12, pp. 133–139; February, 1957.) The local photocurrent exhibits peaks, the positions of which depend on the bias voltage. A model for the junction is proposed.
- 537.311.33:546.289 169
Observation of the Drift of Germanium Surface by Field-Effect Experiment—M. Kikuchi. (*J. Phys. Soc. Japan*, vol. 12, p. 436; April, 1957.) The surface conductance and photoconductance were measured at various time intervals after the etching of *n*-type Ge.
- 537.311.33:546.289 170
Alloying Properties of Germanium Free of Edge Dislocations—C. W. Mueller. (*RCA Rev.*, vol. 18, pp. 205–212; June, 1957.) The main factors involved in alloying In on dislocation-free Ge are considered. The controlled alloying method described gives extremely flat and uniform junctions.
- 537.311.33:546.289 171
The Dissolution of Germanium by Molten Indium—B. Goldstein. (*RCA Rev.*, vol. 18, pp. 213–220; June, 1957.) Experimental results of an investigation of dissolution as a function of crystal axis orientation, temperature, and amount of Ge already contained in the molten In solvent.
- 537.311.33:546.289 172
Preferential Diffusion of Sb along Small-Angle Boundaries in Ge and the Dependence of this Effect on the Direction of the Dislocation Lines in the Boundary—F. Karstensen. (*J. Electronics Control*, vol. 3, pp. 305–307; September, 1957.) Experiment shows that preferential diffusion occurs if the grain boundary contains dislocation lines parallel to the direction of diffusion, but does not occur if these are perpendicular to it.
- 537.311.33:546.289 173
Diffusion of Antimony out of Germanium and some Properties of the Antimony-Germanium System—R. C. Miller and F. M. Smits. (*Phys. Rev.*, vol. 107, pp. 65–70; July 1, 1957.) Experimental Sb distributions are shown to be consistent with a rate limitation or potential barrier at the Ge/ambient interface. Introduced external rate limitations provide data for calculating partition and sticking coefficients for the system and estimating the binding energy of Sb in Ge. See also 1478 of 1957.
- 537.311.33:546.289 174
Distribution and Cross-Sections of Fast States on Germanium Surfaces in Different Gaseous Ambients—A. Many and D. Gerlich. (*Phys. Rev.*, vol. 107, pp. 404–411; July 15, 1957.) Simultaneous measurements of surface recombination velocity and trapped charge density in the fast states as a function of surface potential show that the energy distribution of the fast states consists of four discrete sets of levels. Only one of these sets is significant in the recombination process.
- 537.311.33:546.289 175
The Depth of Surface Damage Produced by Lapping Germanium Monocrystals—D. Baker and H. Yemm. (*Brit. J. Appl. Phys.*, vol. 8, pp. 302–303; July, 1957.) The depth of damage is estimated from the variation of the effective diffusion distance of minority carriers as the disturbed layer is removed by etching.
- 537.311.33:546.289:534.13-8 176
Ultrasonic Attenuation by Free Carriers in Germanium—G. Weinreich. (*Phys. Rev.*, vol. 107, pp. 317–318; July 1, 1957.) The close re-

relationship with the acoustoelectric effect is noted and the amount of attenuation is predicted from the observed magnitude of this effect. See also 2499 of 1957 (Blatt).

537.311.33:546.289:537.32 177
Magnetic Field Dependence of the Seebeck Effect in Germanium—M. C. Steele. (*Phys. Rev.*, vol. 107, pp. 81–83; July 1, 1957.) The thermoelectric power of *n*-type Ge single crystals increases with magnetic field at temperatures from 78° to 278°K. The thermal conductivity is constant for magnetic fields between zero and 11500 oersteds.

537.311.33:546.289:538.6 178
Investigation of Thermomagnetic Effects in *p*-Type Germanium—I. V. Mochan, Yu. N. Obratsov, and T. V. Krylova. (*Zh. Tekh. Fiz.*, vol. 27, pp. 242–259; February, 1957.) The transverse and longitudinal Nernst-Ettingshausen and Hall effects are measured on samples of *p*-type Ge of specific resistance 69 Ω cm at room temperature, in the impurity conduction band. In the temperature range 80°–240°K and a field of 5000 G the transverse Nernst-Ettingshausen effect appears to be due to hole transfer by phonons.

537.311.33:546.289:538.63 179
On the Measurements of the Galvanomagnetic Effect in Semiconductors at Microwave Frequencies—T. Fukuroi and M. Date. (*Sci. Rep. Res. Inst. Tohoku Univ., Ser. A.*, vol. 9, pp. 190–195; June, 1957.) The resonant cavity method is used to make measurements at 9800 mc at temperatures down to 1.5°K. The results obtained for the magnetoresistance of pure Ge are compared with those of Fritzche (153 of 1956).

537.311.33:546.289:538.632 180
Galvanomagnetic Theory for *n*-Type Germanium and Silicon: Hall Theory and General Behaviour of Magnetoresistance—L. Gold and L. M. Roth. (*Phys. Rev.*, vol. 107, pp. 358–364; July 15, 1957.) The magnetoresistance $\Delta\rho/\rho$, and Hall coefficient R_H for *n*-type Ge and Si are calculated from the resistivity tensor. The angular dependence of $\Delta\rho/\rho$ is compared with experimental data. The field dependence of $\Delta\rho/\rho$ and of R_H are considered for various current and field orientations.

537.311.33:546.289:539.1 181
Diffusion-Limited Annealing of Radiation Damage in Germanium—T. R. Waite. (*Phys. Rev.*, vol. 107, pp. 471–478; July 15, 1957.) The theory given in 104 above has been applied to experimental data [see, e.g., 1469 of 1954 (Brown, et al.)]; reasonable agreement was found.

537.311.33:546.682.19:535.215 182
Photoelectromagnetic Effect in Indium Arsenide—J. R. Dixon. (*Phys. Rev.*, vol. 107, pp. 374–378; July 15, 1957.) Experimental studies on *n*- and *p*-type single crystals at room temperature are described. The dependence of the photoelectromagnetic short-circuit current on magnetic induction is consistent with the theory of Kurnick and Zitter (2429 of 1956). Bulk lifetimes are found to be about 6×10^{-8} for *n*-type, and 5×10^{-10} for *p*-type material; estimates of surface recombination velocity for *n*-type material are $0-10^3$ cm for an etched surface, and 10^5 cm for a ground surface.

537.311.33:621.3.049.7 183
Technique for Connecting Electrical Leads to Semiconductors—C. L. Anderson, H. Christensen, and P. Andreatch. (*J. Appl. Phys.*, vol. 28, p. 923; August, 1957.) Two techniques are described which give adhesion between certain soft metals and semiconductors at temperatures well below the eutectic point.

537.311.33:621.314.63 184
Minority Carrier Lifetime in *p-n* Junction Devices—M. Byczkowski and J. R. Madigan. (*J. Appl. Phys.*, vol. 28, pp. 878–881; August, 1957.) Minority-carrier lifetime is conveniently determined by studying the switching time in junction diodes. Some theoretical and experimental results are given.

537.533:546.883 185
Electrostatic Emission from Tantalum Single Crystals—N. A. Gorbaty, L. V. Reshetnikova, E. P. Sytaya, and G. N. Shuppe. (*Zh. Tekh. Fiz.*, vol. 27, pp. 296–298; February, 1957.) Field emission patterns for Ta single crystals appear identical to those obtained for W and Mo.

538.22 186
Effective Gyromagnetic Ratio for Triangular Ferrimagnetic States—A. Eskowitz and R. K. Wangsness. (*Phys. Rev.*, vol. 107, pp. 379–380; July 15, 1957.)

538.22 187
Magnetic Properties of Perovskites Containing Strontium: Part 1—Strontium-Rich Ferrites and Cobaltites—H. Watanabe. (*J. phys. Soc. Japan*, vol. 12, pp. 515–522; May, 1957.) Magnetic susceptibilities and electrical conductivities for samples sintered in vacuo differ from those sintered in oxygen. An interpretation of experimental results is given.

538.22:538.569.4:546.763-31 188
Antiferromagnetic Resonance in Cr_2O_3 —E. S. Dayhoff. (*Phys. Rev.*, vol. 107, pp. 84–91; July 1, 1957.) Theory and experimental data are given for the antiferromagnetic resonance spectrum of single-crystal Cr_2O_3 for 12–2.8 mml and magnetic field intensities from zero to 30,000 oersteds.

538.22:538.613 189
Magnetography—the Microscopy of Magnetism—F. G. Foster. (*Bell Lab. Rec.*, vol. 35, pp. 175–178; May, 1957.) The Kerr magneto-optical effect is applied to the microscopy of magnetic domain structure.

538.221 190
Transverse Impedance Transformation for Ferromagnetic Media—F. R. Morgenthaler. (*Proc. IRE*, vol. 45, p. 1407; October, 1957.) The transformation relates to media magnetized transversely, and is valid for TE_{m0} modes with the magnetization in the *E*-field direction.

538.221 191
Domain Wall Orientations in Silicon-Iron Crystals—C. D. Graham, Jr., and P. W. Neurath. (*J. Appl. Phys.*, vol. 28, pp. 888–891; August, 1957.) The stable orientation of a 180° ferromagnetic domain wall in a cubic crystal is calculated and the results are compared with experimentally determined orientations.

538.221:538.122 192
Experimental Investigation of the Magnetic Field Distribution due to Artificial Surface Defects in Ferromagnetic Substances—N. N. Zatselin. (*Zh. Tekh. Fiz.*, vol. 27, pp. 368–373; February, 1957.)

538.221:539.23 193
Magnetization Reversal in Thin Films at Low Fields—R. L. Conger and F. C. Essig. (*J. Appl. Phys.*, vol. 28, pp. 855–858; August, 1957.) Statistical theory is presented for reversing fields less than the anisotropy field under the assumption that reversal takes place by domain wall motion; experimental data supporting the theory are given. See also 1513 of 1957.

538.221:[621.318.124+621.318.134] 194
Dielectric Spectroscopy of Ferromagnetic

Semiconductors—P. A. Miles, W. B. Westphal, and A. von Hippel. (*Rev. mod. Phys.*, vol. 29, pp. 279–307; July, 1957.) Methods of measuring the electric and magnetic spectra, within the range from dc to optical frequencies, are described and results discussed. In addition to a general review some new experimental data including the rf spectra of a single-crystal Ni ferrite are presented.

538.221:[621.318.124+621.318.134] 195
On the Origin of the Magnetic Anisotropy Energy of Ferrites—K. Yosida and M. Tachiki. (*Progr. Theoret. Phys.*, vol. 17, pp. 331–359; March, 1957.) The anisotropy energy for Ni ferrites comes mainly from Fe^{3+} ions for magnetite from Fe^{2+} and Fe^{3+} ions and for Mn ferrites from Fe^{3+} and Mn^{2+} ions. The large anisotropy energy of Co ferrites arises from the pseudo-quadrupole and anisotropic exchange reactors among Co and Fe ions.

538.221:[621.318.124+621.318.134] 196
A Theory of the Uniaxial Anisotropy Induced by Magnetic Annealing in Ferrites—S. Taniguchi. (*Sci. Rep. Res. Inst. Tohoku Univ., Ser. A*, vol. 9, pp. 196–214; June, 1957.)

538.221:621.318.134 197
Magnetic and Magnetostrictive Properties of Magnesium-Nickel Ferrites—P. O. Hoffmann. (*J. Amer. Ceram. Soc.*, vol. 40, pp. 250–252; July 1, 1957.) A study of mixed Ni-Mg ferrites of various compositions shows them to be inferior to Ni ferrite.

538.221:621.318.134 198
Magnetic Properties and Associated Microstructure of Zinc-Bearing Square-Loop Ferrites—G. G. Palmer, R. W. Johnston, and R. E. Schultz. (*J. Amer. Ceram. Soc.*, vol. 40, pp. 256–262; August 1, 1957.) A series of Mn-Mg ferrites in which Zn is substituted for Mg has been prepared and tested in a successful attempt to obtain a material having a lower coercive force and higher magnetic saturation than standard rectangular-loop ferrites used extensively in digital computers.

538.221:621.318.134:538.6 199
Rotation of the Plane of Polarization in a Longitudinal Magnetic Field (Faraday Effect) in the Millimetre Wavelength Range—D. I. Mash. (*Zh. Tekh. Fiz.*, vol. 27, pp. 360–363; February, 1957.) Results of tests on ferrites are summarized and discussed.

538.632 200
Temperature Dependence of the Hall Coefficients in some Silver Palladium Alloys—F. E. Allison and E. M. Pugh. (*Phys. Rev.*, vol. 107, pp. 103–105; July 1, 1957.)

666.1.037.5 201
Fundamentals of Glass-to-Metal Bonding: Part 3—Temperature and Pressure Dependence of Wettability of Metals by Glass—R. M. Fulrath, S. P. Mitoff, and J. A. Pask. (*J. Amer. Ceram. Soc.*, vol. 40, pp. 269–274; August 1, 1957.) Part 2: 3576 of 1957 (Mitoff).

MATHEMATICS

512.25 202
A Least-Squares Solution of Linear Equations with Coefficients Subject to a Special Type of Error—J. K. Mackenzie. (*Aust. J. Phys.*, vol. 10, pp. 103–109; March, 1957.)

MEASUREMENTS AND TEST GEAR

529.786+531.711 203
The Units of Time and Length—L. Essen. (*Nature, London*, vol. 180, pp. 137–138; July 20, 1957.) Difficulties in an ideal system using an atomic frequency standard to define the unit of time are discussed. A practical solution would be to define time in terms of the caesium

- line and length in terms of the radiation of a suitable light source. A system in which time interval is based on an atomic unit and epoch on astronomical measurements has been satisfactory during two years of operation at the National Physical Laboratory.
- 529.786 204
The Caesium Resonator as a Standard of Frequency and Time—L. Essen and J. V. L. Parry. (*Phil. Trans. A.*, vol. 250, pp. 45-69; August 8, 1957.) The construction, operation, and testing of the standard are described. The present experimental model can be used to define frequency with a standard deviation of ± 1 part in 10^{10} . The design of a resonator with sharper resonance less than 100 cps wide appears possible and should improve the definition. See also 2471 of 1956.
- 529.786:538.569.4 205
Recent Developments in Measurement of Time—C. H. Townes. (*Nuovo Cim.*, vol. 5, Supplement No. 1, pp. 222-229; 1957. In English.) The use of the molecular oscillator described in 100 of 1955 (Gordon, *et al.*) as a frequency standard is discussed.
- 621.3.018.41(083.74)+529.786]:538.569.4 206
Precise Frequency of the 3,3 Inversion Line of Ammonia—K. Shimoda. (*J. phys. Soc. Japan*, vol. 12, p. 558; May, 1957.)
- 621.3.018.41(083.74):621.385.029.6 207
A New Microwave Frequency Standard by Quenching Oscillator Control—N. Sawazaki and T. Honma. (IRE TRANS., vol. MTT-4, pp. 116-121; April, 1956. Abstract, PROC. IRE, vol. 44, pp. 956-957; July, 1957.)
- 621.317.1.087:519.24 208
The Automatic Classification and Storage of Measurement Results—H. J. Vogt and E. Zimmer. (*Elektronik*, vol. 6, pp. 191-197; July, 1957.) Description of methods and electronic equipment for use in the statistical analysis of manufacturing processes with particular reference to applications in the textile industry.
- 621.317.3:537.311.33 209
Direct-Reading Minority-Carrier-Lifetime Measuring Apparatus—A. R. Engler and C. J. Kevane. (*Rev. Sci. Instr.*, vol. 28, pp. 548-551; July, 1957.) The decay of optically injected excess minority carriers is compared with voltage decay in a RC circuit, and lifetimes (> 10 μ sec) are read directly from a calibrated dial.
- 621.317.3:538.63 210
Geometrical Effects in Transverse Magnetoresistance Measurements—J. R. Drabble and R. Wolfe. (*J. Electronics Control*, vol. 3, pp. 259-266; September, 1957.) "The effect of finite length-to-width ratio and of probe positions on measurements of resistivity in a transverse magnetic field is investigated for various Hall angles. Wick's method (3161 of 1954) is extended to include the case of measurements made between probes symmetrically placed at various distances from the ends. Graphs are included which give the fractional change of resistance for various probe positions and Hall angles for specimens of any length-to-width ratio greater than two."
- 621.317.3:538.632 211
Experimental Use of Hall-Effect Linear Detector for Measurements—V. N. Bogomolov and V. D. Vasil'ev. (*Zh. Tekh. Fiz.*, vol. 27, pp. 260-261; February, 1957.) The circuit described incorporates an *n*-type Ge plate as the Hall detector; an experimental application is briefly described.
- 621.317.3:621.314.63 212
Measurements of Crystal Impedances at Low Levels—H. N. Dawirs and E. K. Damon. (IRE TRANS., vol. MTT-4, pp. 94-96; April, 1956. Abstract, PROC. IRE, vol. 44, p. 956; July, 1956.)
- 621.317.3:621.314.7 213
Transistor Tests Predict High-Frequency Performance—R. L. Pritchard. (*Electronic Inds. Tele-Tech.*, vol. 16, pp. 62-63, 144; March, 1957.) Methods are described for measuring the alpha cutoff frequency, the ohmic base resistance and the collector-base capacitance from which parameters the high-frequency performance may be determined.
- 621.317.3:621.396.822:621.396.62.029.6 214
Absolute Measurement of Receiver Noise Figures at U.H.F.—E. Maxwell and B. J. Leon. (IRE TRANS., vol. MTT-4, pp. 81-85; April, 1956. Abstract, PROC. IRE, vol. 44, p. 956; July, 1956.)
- 621.317.331:621.316.993 215
Measuring Earth Conductivity—M. Strohfeltd. (*Electronic Radio Eng.*, vol. 34, pp. 425-427; November, 1957.) Measurements at an "ideal" site by radio methods gave a much lower value than those obtained by electrode methods. Some correlation exists between measurements by the two methods when applied to the variation of conductivity with distance.
- 621.317.335.3.029.64 216
A Rod Method of Measuring Dielectric Constants. Application to (NH₄)₂H₂IO₂ at 3-cm Wavelength—H. Gränicher and W. Schurter. (*Z. angew. Math. Phys.*, vol. 8, pp. 382-400; September 25, 1957.) A modified version of the method described by Le Bot and Le Montagner (2067 of 1953) was adopted to measure the complex permittivity of rod specimens. The experimental results are discussed.
- 621.317.34.029.63/64 217
Automatic Microwave Transmission Measuring Equipment—J. B. Linker, Jr. and H. H. Grimm. (*Rev. Sci. Instr.*, vol. 28, pp. 559-563; July, 1957.) The phase of a phase-coherent 200-kc reference source by a null-seeking servo phase discriminator, and loss is measured by a commercial ratio meter. A traveling-wave tube produces the phase-coherent 200-kc frequency offset which is passed through a waveguide containing the ferrite or other material to be measured.
- 621.317.343.029.6 218
V.H.F. Line Measurements—F. J. Charman. (*Electronic Eng.*, vol. 29, pp. 499-503; October, 1957.) A method is described of using a single loop directional coupler by which the impedance or admittance of an unknown load may be obtained graphically. The method is compared with that of the impedometer [155 of 1950 (Parzen)]; the parameters measured by the new device are not directly applicable to a Smith chart.
- 621.317.351:621.397 219
Equipment for the Oscillographic Display of the Phase and Amplitude Characteristics of Video and I.F. Networks—W. Kroebel and L. A. Wegner. (*Rundfunktech. Mitt.*, vol. 1, pp. 37-44; April, 1957.) In the equipment described parameters representing phase shift and amplitude distortion are displayed on two cr tubes as a function of modulation frequency in the range 0.1-6.0 mc, together with an electronically produced graticule. Special methods of phase measurements are described and some test results are reproduced.
- 621.317.353.1 220
A New Method of Measuring Nonlinear Distortion—O. Henkler. (*Nachr.-Tech.*, vol. 7, pp. 145-147; April, 1957.) The "combination-factor" method outlined is more suitable, particularly for application to carrier-frequency systems, than the conventional distortion-factor and difference-tone methods. Two test signals of equal amplitude are used with a frequency difference depending on the application. The "combination factor" obtained is the ratio of the amplitude of a certain intermodulation product to that of one of the test signals.
- 621.317.382 221
A Wide-Band Level-Measuring Set—R. C. Bolt. (*A.T.E.J.*, vol. 13, pp. 151-156; April, 1957.) The instrument is suitable for power measurements at various input impedances, in the frequency range 200 cps-612 kc at levels from -50 to +40 db relative to 1 mw.
- 621.317.444:621.385 222
Rectilinearity of Electron-Beam Focusing Fields from Transverse Component Determinations—P. P. Cioffi. (*Commun. and Electronics*, no. 29, pp. 15-19; March, 1957.) An accurate method of measuring the transverse component of the magnetic focusing field using a small search coil is described. The longitudinal field component produced by errors in positioning of the coil is eliminated. For a description of the recording fluxmeter used, see 3174 of 1952.
- 621.317.733.025 223
Component Testing Bridge—C. D. Lindsay. (*Wireless World*, vol. 63, pp. 549-550; November, 1957.) Design of an ac comparator working at 50 cps.
- 621.317.755 224
Calibrated D.C. Oscilloscope—B. Pearce. (*Wireless World*, vol. 63, pp. 539-542; November, 1957.) Design details are given.
- 621.317.755:621.397.5 225
Oscillographs for Television Work—O. H. Davie. (*J. Telev. Soc.*, vol. 8, pp. 225-233; April/June, 1957.) A description of the design and application of ancillary equipment required when using a general-purpose oscilloscope for television measurements.
- 621.317.79.029.64 226
A Focused Spectrometer for Microwave Measurements—E. G. A. Goodall and J. A. C. Jackson. (*Marconi Rev.*, vol. 20, pp. 51-59; 2nd Quart., 1957.) Two variants of spectrometer are described for X-band frequencies. Measurements of transmission and reflection characteristics for incident angles of 15° to 70° on single sandwich-type radome samples are presented.
- 621.317.79.029.64:538.569.4 227
A Frequency-Modulated Microwave Spectrometer for Electron-Resonance Measurements—A. C. Rose-Innes. (*J. Sci. Instr.*, vol. 34, pp. 276-278; July, 1957.) The instrument is designed for use in the 3-cm band. Frequency modulation allows spectra to be recorded with simple equipment; details are given of a special technique for increasing the sensitivity. The instrument is especially suitable for measurements at low temperatures and for recording wide lines.
- 621.317.794 228
Comparison of Subtraction-Type and Multiplier-Type Radiometers—J. Galejs. (PROC. IRE, vol. 45, pp. 1420-1422; October, 1957.)
- 621.317.794.029.64 229
A Calibration Procedure for Microwave Radiometers—R. N. Whitehurst, F. H. Mitchell, and J. Copeland. (PROC. IRE, vol. 45, pp. 1410-1411; October, 1957.) A procedure allowing for the antenna side lobes in estimating radiation from a stellar source. Three measurements are made: one with the fixed antenna

pointing to the west of the source, one towards it, and one with the forward lobes absorbed. See also 2739 of 1957.

621.317.799:621.385.832 230
An Electrostatic Cathode-Ray Tube Tester—R. B. Hale. (*Brit. Commun. Electronics*, vol. 4, p. 496; August, 1957.)

OTHER APPLICATIONS OF RADIO AND ELECTRONICS

621.373.52:612 231
A Simple Physiological Stimulator, using a Transistor Oscillating Circuit—W. T. Catton, L. Molyneux, and B. Schofield. (*Electronic Eng.*, vol. 29, pp. 496–498; October, 1957.)

621.373.52.029.3:53.087.25:616 232
Monitoring of Low-Frequency Phenomena—C. F. Rothe and M. W. Street. (*Science*, vol. 126, pp. 77–78; July 12, 1957.) A transistor regenerative oscillator has been adapted to convert subaudio frequencies into af for monitoring phenomena such as the electrical activity of the heart in a way more convenient than visual observation of instruments.

621.387:654.924.56 233
The Ionization Fire-Alarm. Electronics in the Service of Fire Protection—H. P. Halm. (*Elektronik*, vol. 6, pp. 205–207; July, 1957.) The apparatus described uses an ionization chamber in which the presence of combustion gases causes a change in the normal ionization produced by a radioactive source. Some recent refinements are discussed.

621.387.4:621.374.3 234
Some Electronic Instruments used in Nuclear Spectroscopic Investigations—B. Åström. (*Ark. Fys.*, vol. 12, Pt. 3, pp. 215–236; 1957.) A description is given of two complete sets of equipment: 1) an automatic scintillation spectrometer comprising scintillation detector and single channel pulse height analyzer, 2) an α -particle spectrometer comprising ionization chamber and 50-channel pulse-height analyzer of stacked discriminator type. To facilitate maintenance and improve cooling, all tubes are mounted horizontally and concentrated in a ventilated space.

621.398:551.508.822 235
Telemetering System is Balloon Borne—E. K. Novak. (*Electronics*, vol. 30, pp. 158–164; September 1, 1957.) Description of fm/AM telemetry system for a weather radio-sonde. It provides a 1680-mc carrier with three simultaneous channels one of which is time-multiplexed into 12 additional channels with sampling rate of one sample per minute; the maximum range is approximately 360 miles.

PROPAGATION OF WAVES

621.396.11 236
A New Solution of the Problem of Propagation over a Flat Earth—G. Boudouris. (*Nuovo Cim.*, vol. 5, Supplement No. 1, pp. 71–91; 1957. In French.) Simplifications of classical theory are introduced in fixing the boundary conditions for the problem. This "method of approximate boundary conditions" is more convenient for practical applications.

621.396.11 237
Electromagnetic Fields due to Current Flowing Parallel to Interface of Two Different Media—K. Horiuchi. (*J. Phys. Soc. Japan*, vol. 12, pp. 170–176; February, 1957.) Integral equations are established for various configurations. The results have applications in problems of wave propagation over an inhomogeneous earth, or through a stratified atmosphere.

621.396.11 238
Fading of Radio Waves Scattered by Dielectric Turbulence—R. A. Silverman. (*J. Appl. Phys.*, vol. 28, p. 922; August, 1957.) Note of corrections to 3274 of 1957.

621.396.11 239
Short-Range Echoes Observed on Ionospheric Recorders—R. L. Dowden. (*J. Atmos. Terr. Phys.*, vol. 11, no. 2, pp. 111–117; 1957.) Echoes from the 20–100-km region observed at ionospheric stations near the sea are found to arrive at very low angles of elevation with vertical polarization. They are due to coherent back scatter from sea waves of length $\lambda/2$.

621.396.11:551.510.52 240
A New Technique for the Study of Scatter Propagation in the Troposphere—J. H. Chapman, W. S. Haikkila, and J. E. Hogarth. (*Can. J. Phys.*, vol. 35, pp. 823–830; August, 1957.) Fluctuations of received field strength may be considered to have the characteristics of noise. Measurements on 500-mc near-optical links show the "propagation noise" power varies as $1/f^2$ for 0.1 cps $< f < 10$ cps, f being the difference between carrier and side-band frequencies.

621.396.11:551.510.535 241
Refractive Corrections to Scatter Propagation—A. D. Wheelon. (*J. Geophys. Res.*, vol. 62, pp. 343–349; September, 1957.) An examination of the role of the mean electron density of the ionosphere in scatter propagation. Correlations between the field strength of F-layer scattered signals and the maximum usable frequency for classical propagation along the path are studied.

621.396.11:551.510.535 242
A Method for Obtaining L.F. Oblique-Incidence Reflection Coefficients and its Application to 135.6-kc/s Data in the Alaskan Area—J. E. Bickel. (*J. Geophys. Res.*, vol. 62, pp. 373–381; September, 1957.)

621.396.11:551.510.535 243
The Relation of Forward Scattering of Very High Frequency Radio Waves to Partial Reflection of Medium Frequency Waves at Vertical Incidence—J. B. Gregory. (*J. Geophys. Res.*, vol. 62, pp. 383–388; September, 1957.) Some characteristics of vhf forward scatter, such as temporal variations and the region of the ionosphere responsible, are shown to be similar to those of vertical-incidence reflection at 1.75 mc. It is considered that the two phenomena have a common origin.

621.396.11:551.510.535 244
Studies of Transequatorial Ionospheric Propagation by the Scatter-Sounding Method—O. G. Villard, Jr., S. Stein, and K. C. Yeh. (*J. Geophys. Res.*, vol. 62, pp. 399–412; September, 1957.) Long-delay echoes on a hf radar are interpreted as ground back scatter propagated by two or more successive reflections from the F region without intermediate ground reflection. Ionospheric tilts could lead to this type of propagation, which occurs regularly in equatorial regions.

621.396.11:551.510.535 245
Self-Distortion of Radio Waves in the Ionosphere, near the Gyro Frequency—F. H. Hibberd. (*J. Atmos. Terr. Phys.*, vol. 11, no. 2, pp. 102–110; 1957.) The theory described in 2198 of 1956 is extended to include the effect of the geomagnetic field near the gyro frequency. The reduction in modulation depth varies slowly with frequency and shows no resonance-like variation. The reduction is proportional to radiated power and decreases rapidly as the modulation frequency is increased.

621.396.11:551.510.535 246
Ionospheric Demodulation of Radio Waves at Vertical Incidence—G. J. Aitchison. (*Aust. J. Phys.*, vol. 10, pp. 204–207; March, 1957.) Agreement between observations and theory indicates that demodulation occurs in the E layer, affecting the wave on both upward and downward paths. The actual mechanism of the demodulation requires further investigation. See also 3070 of 1955 (Aitchison and Goodwin).

621.396.11:551.510.535:523.78 247
Ionospheric Research—Dale. (See 125.)

621.396.11.029.6 248
Radio Propagation above 40 Mc/s over Irregular Terrain—J. J. Egli. (*Proc. IRE*, vol. 45, pp. 1383–1391; October, 1957.) The available statistical wave-propagation data on terrain effects as a function of frequency, antenna height, polarization, and distance are analyzed and expressed by empirical formulas and in the form of nomographs and correction curves.

621.396.11.029.6:551.510.535 249
Delayed Signals in Ionospheric Forward-Scatter Communication—G. W. Luscombe. (*Nature, London*, vol. 180, p. 138; June 20, 1957.) Long-delay multipath effects observed at Slough in the reception of 37-mc pulsed transmissions from Gibraltar indicate that the signal with the largest delay was due to round-the-world propagation and that ground back scatter was not involved. See 1217 of 1957 (Crow, *et al.*).

621.396.11.029.62:551.510.535:523.75 250
Disturbances in the Lower Ionosphere Observed at V.H.F. following the Solar Flare of 23 February 1956 with Particular Reference to Auroral-Zone Absorption—Bailey. (See 123.)

621.396.812.3:551.510.535 251
Ionospheric Irregularities Causing Random Fading of Very Low Frequencies—S. A. Bowhill. (*J. Atmos. Terr. Phys.*, vol. 11, no. 2, pp. 91–101; 1957.) An investigation, based on measurements at 75 and 150 kc, into the two component sources of random fading of signals reflected from the ionosphere: 1) scattering in the reflecting layer, 2) diffraction during propagation down to the ground.

RECEPTION

621.376 252
Intermodulation Products for ν -Law Biased Wave Rectifier for Multiple-Frequency Input—E. Feuerstein. (*Quart. appl. Math.*, vol. 15, pp. 183–192; July, 1957.) The intermodulation products obtained by passing the same of $N+1$ sinusoids of amplitudes P_1, \dots, P_N through a rectifier of characteristic

$$I = \begin{cases} 10 & V < B \\ 1\alpha(V-B)^\nu & V > B \quad \nu > 0 \end{cases}$$

have been expressed in terms of contour integrals involving products of Bessel functions [see, *e.g.*, 2169 of 1945 (Rice) and 3506 of 1947 (Bennett)]. These integrals are rewritten as improper integrals on the real line plus constant terms. These integrals converge fast enough in many cases to be useful in numerical integration.

621.376.23:621.396.822 253
Optimum vs. Correlation Methods in Tracking Random Signals in Background Noise—R. C. Davis. (*Quart. appl. Math.*, vol. 15, pp. 123–138; July, 1957.) A comparison of the use of statistical methods of analysis in estimating unknown parameters of probability distribution with the use of correlation methods previously applied to the problem of obtaining maximum snr.

- 621.376.332 254
An Improved F. M. Discriminator—V. B. Hulme. (*Electronic Eng.*, vol. 29, pp. 416-419; September, 1957.) Details are given of a constant-area type circuit which provides a relation to 0.1 per cent between input frequency and output voltage over the range 100 kc-1 mc.
- 621.396.62:029.6:621.396.822:621.317.3 255
Absolute Measurement of Receiver Noise Figures at U.H.F.—E. Maxwell and B. J. Leon. (*IRE TRANS.*, vol. MTT-4, pp. 81-85; April, 1956. Abstract, *Proc. IRE*, vol. 44, p. 956; July, 1956.)
- 621.396.621 256
Receiver Selectivity—B. J. Rogers. (*RSGB Bull.*, vol. 32, pp. 444-448; April, 1957.) Some modern methods of improving the selectivity of communication receivers are described.
- 621.396.621 257
F.M./A.M. "Second Set"—G. D. Browne. (*Mullard tech. Commun.*, vol. 3, pp. 38-43; March, 1957.) Design suggestions for a simple and economical receiver in which all tubes are operative in both systems of reception.
- 621.396.621:621.314.7 258
Design Considerations in the First Stage of Transistor Receivers—L. A. Freedman. (*RCA Rev.*, vol. 18, pp. 145-162; June, 1957.) Noise performance of transistor rf stages using capacitive antennas and mixer stages with loop antennas is discussed with examples. Comparisons are made between transistor stages and corresponding tube stages.
- 621.396.621:621.314.7 259
Circuit Techniques associated with Transistor Broadcast Receivers—J. N. Barry. (*Electronic Eng.*, vol. 29, pp. 408-415 and 478-483; September and October, 1957.) A discussion of transistor circuit problems and their solution. The various stages of the receiver are considered and the economic aspects of using transistors are discussed with reference to the performance of 6 commercial-type portable and car receivers.
- 621.396.621:621.314.7 260
The Thunderbird—A New Transistorized Portable Radio—T. Vanacore. (*Sylvania Technologist*, vol. 10, pp. 35-37; April, 1957.)
- 621.396.621:621.376 261
A New Method of Demodulation for Phase, Frequency and Amplitude—P. Knudu. (*Indian J. Phys.* vol. 40, pp. 231-234; April, 1957.) Limiting and differentiating a modulated sinusoidal wave produces pulses with leading edges separated by an amount dependent upon the instantaneous phase of the modulated wave, and upon its amplitude if the limiting level is above the zero axis. The pulses are converted to variable-amplitude sawtooth waves and passed through a low-pass filter to reproduce the modulating signal. See also 551 of 1956.
- 621.396.621:621.396.822 262
Receiver Detects Signals below Noise Level—W. L. Blair. (*Electronics*, vol. 30, pp. 168-171; September 1, 1957.) The integrating receiver described uses a modified form of Dicke's technique (475 of 1947) with a comparison switching rate of 500 cps and a counter display.
- 621.396.621:029.63/:64 263
Design for a Broadband Microwave Receiver—B. Rosen and R. Saul. (*Electronic Inds. Tele-Tech.*, vol. 16, pp. 81-82, 170; March, 1957.) Brief description of a receiver covering the frequency range 950-11260 mc in four bands. It is suitable for AM, fm, and pm reception and for use as a microwave power meter.
- 621.396.8:621.3.018.41(083.74) 264
Doppler Shift of the Received Frequency from the Standard Station Reflected by the Ionosphere—I. Takahashi, T. Ogawa, M. Yamano, A. Hirai, and M. Takiuchi. (*Proc. IRE*, vol. 45, p. 1408; October, 1957.) Equipment for recording frequency continuously is described, and results of Doppler-shift measurements made on waves reflected from the E region on 4 mc over a 400-km path are given.
- 621.396.8:621.396.931.029.62/:63 265
Propagation Tests of Frequencies for V.H.F. Mobile Radio—E. Shimizu, T. Morinaga, T. Kawano, S. Sato, and M. Hirasaki. (*Rep. elect. Commun. Lab., Japan*, vol. 5, pp. 13-16; January, 1957.) Measurements are given of signal and noise received at a mobile station from fixed transmitters in Tokyo operating at 60, 200, and 470 mc. Less fluctuation was observed than in comparable U. S. measurements, and this is attributable to the wooden houses normal in Japan.
- 621.396.812.3:621.396.666.029.64 266
Some Results with Frequency Diversity in a Microwave Radio System—F. H. Willis. (*Commun. and Electronics*, no. 29, pp. 63-67; March, 1957.) The results of tests with 240-mc frequency separation and an appreciable switching differential are discussed.

STATIONS AND COMMUNICATION SYSTEMS

- 621.39.001.11:621.372.012 267
Signal-Flow Graphs and Random Signals—L. A. Zadeh and W. H. Huggins. (*Proc. IRE*, vol. 45, pp. 1413-1414; October, 1957.) Comments on 1227 of 1957 and author's reply.
- 621.394.3:621.394.828 268
Distortion Correction of Teleprinter Signals by Electronic Means—E. K. Aschmoneit. (*Elektronik*, vol. 6, pp. 199-203 and 244-245; July and August, 1957.) The principles and circuits of some electronic distortion-correcting and regenerative repeaters are described.
- 621.396.41:621.396.324:621.314.7 269
Transistorized Multiplex Radio-Teletypewriter—P. G. Wray. (*Electronics*, vol. 30, pp. 150-154; September 1, 1957.) Lightweight four-channel time-division multiplex equipment for use on board ship is described. Ring counter and digital synchronizer circuits using transistors give an operating speed of 100 words per minute.
- 621.396.41:029.63 270
Ultra-high-Frequency Radio Equipment for 60 Speech Circuits—(*GEC Telecommun.*, no. 22, pp. 34-49; August, 1956.) The Type-SPO 5500 equipment described uses fm and operates in the band 1700-2300 mc. Up to three rf channels each carrying 60 speech channels can be arranged in multiplex.
- 621.394.441 271
An Electronic Error-Correcting Multiplex Telegraph System—(*P.O. Elec. Eng. J.*, vol. 50, Pt. 1, p. 44; April, 1957.)
- 621.396.5:029.6:621.396.822 272
Noise Considerations on Toll Telephone Microwave Radio Systems—T. A. Combellick and M. E. Ferguson. (*Commun. and Electronics*, no. 29, pp. 67-70; March, 1957.) The noise level requirements for microwave radio equipment to be used in multichannel telephone systems are discussed. The magnitude of and relation between the noise generated in the transmitter, in the receiver, or by intermodulation, are examined.
- 621.396.71:029.55 273
The Rugby "B" High-Frequency Transmitting Station—A. Cook and L. L. Hall. (*P.O. Elec. Eng. J.*, vol. 50, Pt. 1, pp. 15-23; April, 1957.) The layout and technical facilities of the station are described. There are 28 hf transmitters of 30-kw power rating in operation and some 70 antennas on a site of 700 acres. See also 2538 of 1956 (Booth and MacLarty).
- 621.396.74:621.397.743 274
Frequency Transposers as Very-Low-Power Transmitters—A. Kolarz. (*Rundfunktech. Mitt.*, vol. 1, pp. 53-57; April, 1957.) A 50-nw relay transmitter for providing a local television service is described. The transposition from received to transmitted frequency is made without the use of an IF. See also 1927 of 1957.
- 621.396.74:029.62:621.376.3 275
Investigation of Coverage Facilities with Frequency-Offset U.S.W. F.M. Operation—E. Belger, E. Paulesn, and L. Dahrendorf. (*Rundfunktech. Mitt.*, vol. 1, pp. 58-64; April, 1957.) The limitations and advantages of this method of obtaining regional coverage are discussed with reference to experimental results. See also 1869 of 1956 (Belger and von Rautenfeld).
- 621.396.931 276
Radio Communication in Railroad Tunnels—H. S. Winbigler. (*Bell Lab. Rec.*, vol. 35, pp. 57-60; February, 1957.) Radiation from a continuous length of twin transmission line suspended from the tunnel wall is received satisfactorily up to 5000 feet from the transmitter, using frequencies in the 159-162-mc band.
- 621.396.932 277
Ships and Coast Stations—P. N. Spooner. (*Short Wave Mag.*, vol. 14, pp. 636-639; February, 1957.) Details of systems, procedure, operating frequencies, and general organization.
- 621.396.945 278
The Guided Radio Telephone—W. H. Hill. (*A. T. E. J.*, vol. 13, pp. 113-118; April, 1957.) This communication system uses currents induced in metallic conductors by the transmitter. A satisfactory portable transmitter/receiver is described for use in coal mines.

SUBSIDIARY APPARATUS

- 621.3-71 279
Removal of Heat from Sealed Miniature Equipment—E. P. Newell. (*Brit. Commun. Electronics*, vol. 4, pp. 468-475; August, 1957.) Experimental investigation has shown that the most satisfactory way of dissipating the heat generated internally is by providing thermal conduction paths from the heat sources to the front panel.
- 621.311.6:537.311.33:535.215 280
Utilizing the Sun's Energy—(*Elec. J.*, vol. 159, pp. 1256-1257; November 1, 1957.) Report on progress in the development of solar batteries of the Si p-n-junction type with description of experimental installations in England.
- 621.311.6:621.314.7 281
A Stabilized D.C. Power Supply using Transistors—T. H. Brown and W. L. Stephenson. (*Electronic Eng.*, vol. 29, pp. 425-428; September, 1957.) A mains-operated unit is described which provides an output voltage variable from 0 to 30 v at currents of up to 1 a.
- 621.314.63:546.289 282
Germanium Rectifiers as Electronic Components—J. T. Cataldo. (*Electronic Inds.*

Tele-Tech., vol. 16, pp. 61-63, 168; August, 1957.) Discussion of advantages and applications. Cooling methods and overload characteristics are considered.

621.316.722.1:621.314.7 283
A Low-Voltage Stabilizer employing Junction Transistors and a Silicon Junction Reference Diode—D. Aspinall. (*Electronic Eng.*, vol. 29, pp. 450-454; September, 1957.)

621.316.722.1:621.314.7 284
Voltage Regulator uses Multivibrators—W. A. Scism. (*Electronics*, vol. 30, pp. 184-186; September 1, 1957.) Voltage changes vary the frequency of an astable transistor multivibrator and the average value of the load voltage is thus kept constant.

621.396.662.029.5 285
Multichannel Drives for Transmitters and Receivers in the H.F. Band—D. J. Fewings. (*Marconi Rev.*, vol. 20, pp. 60-76; 2nd Quart., 1957.) Methods of tuning accurately to a prescribed frequency are described, as applied to 1) a diversity oscillator with manual tuning, 2) an automatically tuned airborne receiver/transmitter drive.

621.396.664:621.376 286
Monitoring the Modulator—P. M. Carment. (*Short Wave Mag.*, vol. 14, pp. 631-632; February, 1957.) A circuit for monitoring the output of a high-power modulator on a pair of headphones.

TELEVISION AND PHOTOTELEGRAPHY

621.397:628.93 287
Techniques of Television Lighting—D. Thayer. (*J. Soc. Mot. Pict. Telev. Eng.*, vol. 66, Pt. 1, pp. 212-216; April, 1957.)

621.397.2:621.372.55 288
Error-Predicting D.C.-Restoring Circuits for Television Signals—E. L. C. White. (*Electronic Eng.*, vol. 29, pp. 472-477; October, 1957.) The performance of direct and negative-feedback types of dc restoring circuit is analyzed. By a combination of slope equalization and error prediction the low-frequency cutoff of the circuit prior to dc restoration may be raised by a large factor. Some experimental results are given.

621.397.24 289
Performance of the A2A Video Transmission System—R. W. Edmonds. (*Bell Lab. Rec.*, vol. 35, pp. 85-88; March, 1957.) Design considerations and performance details of a broadband local wire transmission system for monochrome and color television.

621.397.24:621.315.212 290
A New 4-Mc/s Coaxial Line Equipment—C. E. L. No. 6A—Collier and Simpson. (See 14.)

621.397.24:621.315.212 291
A 4-Mc/s Coaxial Line Equipment—C.E.L. No. 4A—E. Davis. (See 15.)

621.397.242 292
Television Terminals for the L3 System—J. J. Jansen. (*Bell Lab. Rec.*, vol. 35, pp. 179-183; May, 1957.) 600 telephone channels and a 4.2-mc television channel may be transmitted by the coaxial cable system the terminal equipment of which is described.

621.397.5:535.623 293
Some Alternatives to the N.T.S.C. Colour Television System—E. L. C. White. (*J. Telev. Soc.*, vol. 8, pp. 191-206; January/March, 1957.) The NTSC system is compared with the two-subcarrier, the French L.E.P. "3 double-message," and the Valensi systems. For a three-gun picture tube, the first system seems most satisfactory. The signal requirements of single-

gun tubes, such as the chromatron and "apple" tubes, are then discussed; here a symmetrical ratio system may be better.

621.397.5:621.395.625.3 294
Video Tape Recorder Design—(*J. Soc. Mot. Pict. Telev. Eng.*, vol. 66, Pt. 1, pp. 177-188; April, 1957.) Three papers, describing equipment incorporating a system of four magnetic recording heads on a revolving drum for recording transverse tracks on tape traveling at 15 inches per second. See also 4018 of 1957 (Snyder).

Comprehensive Description of the Ampex Video Tape Recorder—C. P. Ginsburg (pp. 177-182).

The Modulation System of the Ampex Video Tape Recorder—C. E. Anderson (pp. 182-184).

Rotary-Head Switching in the Ampex Video Tape Recorder—R. M. Dolby (pp. 184-188).

621.397.5(083.74) 295
Comparison of Four Television Standards—R. D. A. Maurice. (*Electronic Radio Eng.*, vol. 34, pp. 416-421; November, 1957.) "The resolutions of four CCIR standard television systems are compared, some account being taken of the effects of the asymmetric side-band reception. The extent to which some of the distortions may be due to nonlinearity of the phase-frequency characteristic is briefly mentioned."

621.397.611:778.5 296
The Limits of Optical Compensation by Polygonal Prisms in relation to Freedom from Flicker, Registration and Relative Aperture—H. Grabke. (*Rundfunktech. Mitt.*, vol. 1, pp. 65-72; April, 1957.) Theoretical treatment of the problem based on earlier experiments with film scanning equipment (1227 of 1956). The design of a "polygon-ring scanner" is discussed and data for calculating tolerances and color correction of the system are given. The manufacture of such a scanner with 40-60 faces appears feasible; it should produce satisfactory pictures comparable to those obtained by other flying-spot scanners.

621.397.621.2 297
Television Frame Pulse Separator—H. D. Kitchin. (*Wireless World*, vol. 63, pp. 554-559; November, 1957.) A single-pulse circuit for accurate interlacing is described.

621.397.621.2 298
The Return of Electrostatic Focusing—R. R. Pearce. (*J. Telev. Soc.*, vol. 8, pp. 237-248; April/June, 1957.) A survey of the developments in post-war television tubes and techniques with a detailed discussion of the characteristics and relative merits of modern electrostatic guns.

621.397.82 299
The Visibility of Sinusoidal Interference in Television Images—H. Grosskopf and R. Suhrmann. (*Rundfunktech. Mitt.*, vol. 1, pp. 45-52; April, 1957.) The nature of interference patterns is reviewed and the effects of interference due to frequencies which are specially related to line or frame frequency are examined. Curves for evaluating some of these effects are given and the requisite "safe" frequency spacing between adjacent transmitters is compared with that recommended by CCIR.

TRANSMISSION

621.396.61.029.6:621.396.662 300
Transmitter Tuned by Distortion Indicator—C. R. Ellis, K. Owen, and G. R. Weatherup. (*Electronics*, vol. 30, pp. 180-183; September 1, 1957.) The system described gives harmonic distortion of less than 3 per cent rms over the range 200 cps-20 kc when the transmitter

is operated at 225-400 mc, with 80 per cent AM of a 1-kw carrier.

621.396.61.072.9 301
A New Device for the Automatic Radio-Frequency Synchronization of Common-Frequency Broadcasting in the Medium-Wave Band—A. Karaminkov. (*Nachr-Tech.*, vol. 7, pp. 163-166; April, 1957.) In the system proposed synchronization is carried out by radio transmission during breaks in the program. During these interruptions of about 12-seconds duration which are intentionally introduced at intervals of about 1 hour, the carrier of the local transmitter is stopped so that the distant master transmitter can be received for the automatic frequency correction of the local carrier. Using quartz oscillators with long-term stability 1 part in 10^6 an hourly stability within about 1 part in 10^8 can be achieved.

TUBES AND THERMIONICS

621.314.63:621.317.3 302
Measurements of Crystal Impedances at Low Levels—H. N. Dawirs and E. K. Damon. (*IRE TRANS.*, vol. MTT-4, pp. 94-96; April, 1956. Abstract, *Proc. IRE*, vol. 44, p. 956; July, 1956.)

621.314.63:621.372.632 303
The Frequency Dependence of Noise Temperature Ratio in Microwave Mixer Crystals—M. E. Sprinks, G. T. G. Robinson, and B. G. Bosch. (*Brit. J. Appl. Phys.*, vol. 8, pp. 275-277; July, 1957.) A discussion with experimental results of the contribution of the noise temperature ratio of the mixer to the overall noise factor of the receiver. The latter has an intermediate frequency in the range 10-60 mc.

621.314.7 304
Some Aspects of Transistor Progress—H. W. Loeb. (*A.T.E.J.*, vol. 13, pp. 119-134; April, 1957.) Reprint. See 295 of 1957.

621.314.7 305
Heat Sinks for Power Transistors—O. J. Edwards. (*Mullard tech. Commun.*, vol. 3, pp. 59-61; March, 1957.) Sinks of mild steel and aluminum are examined and the effects of thickness, area, and surface treatment are discussed.

621.314.7 306
Design Theory for Depletion-Layer Transistors—W. W. Gärtner. (*Proc. IRE*, vol. 45, pp. 1392-1400; October, 1957.) This new type of high-frequency transistor uses maximum attainable carrier velocities in solids by injecting electrons or holes into the high electric fields prevailing in properly designed depletion layers of reverse-biased $p-n$ junctions. Low- and high-frequency performance, small-signal behavior, power gain, and stability are discussed in a particular theoretical design. The short transit times should be important for solid-state microwave amplification.

621.314.7 307
Design for an Improved High-Frequency Transistor—C. Thornton, J. Roschen, and T. Miles. (*Electronic Inds. Tele-Tech.*, vol. 16, pp. 47-49, 124; July, 1957.) The construction and properties of the Type L-6100 silicon surface-alloy transistor are described. It has a base width of 7×10^{-6} inches and a maximum oscillation frequency of about 16 mc.

621.314.7 308
The Junction Transistor as a Charge-Controlled Device—R. Beaufoy and J. J. Sparkes. (*A.T.E.J.*, vol. 13, pp. 310-327; October, 1957.) Transistor operation is described in terms of the charge in the base region so that the transistor performance is defined in the form of time constants (pc/ μ a). The analysis was developed for large-signal opera-

- tion but yields complete expressions for small-signal admittance parameters. Methods of measurement are outlined.
- 621.314.7 309
Flow Line Analysis—R. B. Hurley. (*Electronic Inds. Tele-Tech.*, vol. 16, pp. 52-54, 140; April, 1957.) A pictorial representation of the expressions derived by Ebers and Moll (884 of 1955) to analyze transistor behavior in various types of switching circuit.
- 621.314.7:546.289 310
Influence of Surface Oxidation on α_{cb} of Germanium $p-n-p$ Transistors—J. T. Wallmark. (*RCA Rev.*, vol. 18, pp. 255-271; June, 1957.) Oxidation of the Ge surface is shown to be a major factor influencing surface recombination and thereby the slow decay of the current transfer ratio α_{cb} in $p-n-p$ transistors. An outline of the underlying processes is given.
- 621.314.7:621.317.3 311
Transistor Tests Predict High-Frequency Performance—Pritchard. (See 213.)
- 621.314.7:621.318.57 312
Determination of Transient Response of a Drift Transistor using the Diffusion Equation—H. B. von Horn and W. Y. Stevens. (*IBM J. Res. Devel.*, vol. 1, pp. 189-191; April, 1957.) The one-dimensional diffusion equation is solved to give the time required for the collector current to reach a steady value in response to a step function of emitter current.
- 621.314.7:621.373.51 313
Unique Properties of the Four-Layer Diode—W. Shockley. (*Electronic Inds. Tele-Tech.*, vol. 16, pp. 58-60, 165; August, 1957.) Description of a new bistable two-terminal semiconductor device and details of some of its applications. See also 3899 of 1956 (Moll, *et al.*).
- 621.314.7:681.142 314
The Multipurpose Bias Device: Part 1—The Commutator Transistor—Dunham. (See 38.)
- 621.314.7:681.142 315
Two-Collector Transistor for Binary Full Addition—R. F. Rutz. (*IBM J. Res. Devel.*, vol. 1, pp. 212-222; July, 1957.) Two versions of a two-collector transistor are described, one using point contacts, and the other using $p-n$ "hook" junctions as collectors. The function of such a transistor as a binary adder and its circuit characteristics are discussed. See also 38 above.
- 621.314.7(083.7) 316
Semiconductor Symbols—P. M. Thompson and J. Bateson. (*Wireless World*, vol. 63, pp. 525-528; November, 1957.) A logical system for diodes, transistors, and other junction devices is proposed.
- 621.383.27 317
Photomultiplier Tubes—J. Sharpe. (*Brit. Commun. Electronics*, vol. 4, pp. 484-492; August, 1957.) The design and applications of the various types of photomultiplier tube are described. A table of representative tubes available in the U. K. is given.
- 621.383.27:621.387.464 318
Improved Performance of Photomultipliers in Scintillation Counters—A. Ashmore, B. Collinge, and S. K. Sen. (*Indian J. Phys.*, vol. 40, pp. 261-264; May, 1957.) A cathode follower reduces the effective capacitance to earth of the collecting electrode of a photomultiplier, enabling bigger voltage pulses to be obtained for the same degree of nonlinearity in the photomultiplier.
- 621.383.4:535.371.07 319
An Improved High-Gain Panel Light Amplifier—B. Kazan. (*Proc. IRE*, vol. 45, pp. 1358-1364; October, 1957.) A grooved photoconductor light-amplifying picture panel is described, whose gain is more than 10 times greater than any previous amplifier and whose threshold for input light is reduced. See also 933 of 1956 (Kazan and Nicoll).
- 621.385:621.317.321 320
A Survey of Methods Used to Determine Contact Potentials in Receiving Tubes—E. R. Schrader. (*RCA Rev.*, vol. 18, pp. 243-254; June, 1957.)
- 621.385:621.317.444 321
Rectilinearity of Electron-Beam Focusing Fields from Transverse Component Determinations—Cioffi. (See 222.)
- 621.385.029.6 322
Investigation of a Special Type of Reflex Klystron—W. N. Shevchik, S. A. Suslov, and Yu. D. Zharkov. (*Zh. Tekh. Fiz.*, vol. 27, pp. 377-386; February, 1957.) A theoretical and experimental investigation of a reflex klystron operating with a large transit angle ($> 2\pi$) in the interaction space is described. Good agreement is found between the theoretical evaluation of the tube efficiency and the experimental results.
- 621.385.029.6 323
On the Nonlinear Behavior of Electron-Beam Devices—F. Paschke. (*RCA Rev.*, vol. 18, pp. 221-242; June, 1957.) The nonlinear space-charge-wave equation is derived and reduced by third-order successive approximation to three simultaneous linear differential equations which are solved for the case of a velocity-modulated electron beam. Nonlinear phenomena in traveling-wave tubes can be treated similarly.
- 621.385.029.6 324
Electron Beam Focusing in Three-Anode Guns for Travelling-Wave Tubes—T. S. Chen and L. Kovach. (*J. Electronics Control*, vol. 3, pp. 287-304; September, 1957.) The electron trajectory in the accelerating region is solved and beam rippling in the drift region discussed. The principle of compensated three-anode guns is developed in the form of design formulas and curves. Experiments confirm that compensated guns result in a reduction of the focusing magnetic field for parallel-flow beams.
- 621.385.029.6 325
The Large-Signal Behaviour of Crossed-Field Travelling-Wave Devices—J. Feinstein and G. S. Kino. (*Proc. IRE*, vol. 45, pp. 1364-1373; October, 1957.) The limits of validity of the conventional small-signal theory are obtained theoretically, and the analysis is extended to follow the interaction to power saturation. Forward-wave and backward-wave amplifiers and a backward-wave oscillator are considered. In the amplifier tubes the gain is inherently low, and suggestions for improving this deficiency are examined.
- 621.385.029.6 326
An Experimental High-Power Pulsed Travelling-Wave Tube—J. F. Gittins, N. H. Rock, and A. B. J. Sullivan. (*J. Electronics Control*, vol. 3, pp. 267-286; September, 1957.) A high-impedance slow-wave structure with good thermal dissipation and suitable for a 100-kv electron beam is used. A saturated efficiency of 34 per cent, power output of 3 mw, and a gain of 35 db are obtained.
- 621.385.029.6:621.372 327
Interdigital and other Slow-Wave Structures—J. C. Walling. (*J. Electronics Control*, vol. 3, pp. 239-258; September, 1957.) A method of calculating the properties of structures consisting of arrays of parallel conductors is developed and a table of numerical values is presented. This is applied to obtain dispersion characteristics, input and beam-coupling impedances for the Karp structure, interdigital line, and tape helix.
- 621.385.029.6:621.376 328
The Modulation of Travelling-Wave Tubes—G. F. Steele. (*Electronic Eng.*, vol. 29, pp. 429-433; September, 1957.) "The simple theory of traveling-wave tube modulation is discussed and some expressions derived for the cases of phase and amplitude modulation. Details are given of the experimental procedure used to measure phase shift and the side-band power resulting from a 60-mc modulation."
- 621.385.029.64 329
Velocity-Jump Amplification at 10000 Mc/s—B. V. Dore. (*Can. J. Phys.*, vol. 35, pp. 742-752; June, 1957.) Description of a vm tube based on an earlier design [2068 of 1951 (Field, *et al.*)]. Theory previously developed for space-charge-wave amplifiers is applied to its operation and conclusions are drawn regarding the operation of coupling helices and the effect of small gaps in the amplifying section of the tube. See also 3721 of 1954 (Agdur).
- 621.385.832:621.317.799 330
An Electrostatic Cathode-Ray-Tube Tester—R. B. Hale. (*Brit. Commun. Electronics*, vol. 4, p. 496; August, 1957.)

MISCELLANEOUS

- 621.39(091) 331
Fifty Years of the Institution of Post Office Electrical Engineers—(*P.O. Elec. Eng. J.*, vol. 49, Pt. 3, pp. 147-274; October, 1956.) A number of papers surveying the history and activities of the Institution and detailing its achievements in all fields of telecommunications.